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9 – OsiSense® XCC Opto-electronic rotary encoders

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Applications			Counting indication	1			
						The state of the s	
Diameter of ho	ousing		Ø 40 mm	Ø 58 mm	Ø 58 mm parameterable (multi-resolution) (1)	Ø 90 mm	
Shaft		Solid	Ø6mm	Ø 6 mm and Ø 10 mm	Ø 10 mm	Ø 12 mm	
		Through	Ø 6 mm	Ø 14 mm Ø 6, 8, 10 and 12 mm (with reduction collar)	Ø 14 mm Ø 6, 8, 10 and 12 mm (with reduction collar)	Ø 30 mm Ø 12, 20 and 25 m (with reduction collar)	
Resolution	Incremental	100 points	100 points	100 points	-	100 points	
	encoders	256 points	-	_	256 to 4096 points	-	
		360 points	360 points	360 points	360 to 5760 points	360 points	
		500 points	500 points	500 points	500 to 8000 points	500 points	
		1000 points	1000 points	1000 points	_	1000 points	
		1024 points	1024 points	1024 points	1024 to 16,384 points	1024 points	
		2500 points	_	2500 points	_	2500 points	
		3600 points	_	-	_	3600 points	
		4096 points	_	_	_	_	
		5000 points	_	5000 points	5000 to 80,000 points	5000 points	
		10,000 points	_	-	-	10,000 points	
	Absolute encoders	4096 points/8192 turns (12-bit/13-bit)	-	-	-	-	
		8192 points	_	-	-	-	
		8192 points/4096 turns (13-bit/12-bit)	-	-	-	-	
Output	Incremental	Type R (N)	5 V, RS 422, 4.5 to	_	-	5 V, RS 422, 4.5 to	
stage/supply	encoders		5.5 V			5.5 V	
(2)		Type K (N)	Push-pull, 11 to 30 V	-	-	Push-pull, 11 to 30	
		Type X	_	5 V, RS 422, 4.75 to 30 V	5 V, RS 422, 4.75 to 30 V	_	
		Type Y	-	Push-pull, 5 to 30 V	Push-pull, 5 to 30 V	_	
	Absolute encoders	Type KB (N) or KG (N)	-	-	-	_	
		Type SB (N) or SG (N)	_	_	-	_	
		Type C	-	-	-	_	
		Type F	-	-	-	-	
Connection		Pre-cabled, radial	•	-	-	-	
		Connector, radial, M23 Terminal block, radial	-	• -	•	•	
		Terminal block, radial				-	
Catalog Numb	ers		XCC14••••	XCC15••••	XCC15••••M•••	XCC19•••••	

(1) Parameterable version: multiplication of the basic resolution of the disc using dip switches, the factory setting being that of the lowest value.

- (2) Characteristics of the output stage/supply types:
 Type R (N): 5 V output driver, RS 422, 4.5 to 5,5 V.

 - Type K (N): push-pull output driver, 11 to 30 V.
 Type X: 5 V output driver, RS 422, 4.5 to 30 V.
 Type Y: push-pull output driver, 5 to 30 V.
 KB (N) or KG (N) output: push-pull output driver, 11 to 30 V, binary code KB (N) or Gray code KG (N).

Absolute position indication within a revolution

Absolute position indication within a revolution and indication of the number of revolutions



Ø 14 mm $\,$

Ø 6 mm and Ø 10 mm

Ø 6, 8, 10 and 12 mm

(with reduction collar)



Ø 12 mm

Ø 30 mm

Ø 12, 20 and 25 mm

(with reduction collar)







Ø 58 mm	Ø 90 mm	Ø 58 mm	Ø 90 mm	Shaft couplings with springAnti-rotation devicesReduction collars
				- Pre-wired connectors

- Ø 6 mm and Ø 10 mm Ø 12 mm Ø 30 mm Ø 14 mm Ø 6, 8, 10 and 12 mm Ø 16, 20 and 25 mm (with reduction collar) (with reduction collar)
- 4096 points/8192 turns 8192 points 8192 points 8192 points/4096 turns 8192 points/4096 turns
- Push-pull, 11 to 30 V, Push-pull, 11 to 30 V, binary or Gray binary or Gray SSI, 13-bit, 11 to 30 V, SSI, 13-bit, 11 to 30 V, SSI, 25-bit, 11 to 30 V, SSI, 25-bit, 11 to 30 V, binary or Gray binary or Gray binary or Gray binary or Gray

XCC25•••••	XCC29•••••	XCC35•••••	XCC39••••
9/22	9/24	9/28	9/30

XCCR, XCCP, XZC

9/35 to 9/37

- (2) Characteristics of the output stage/supply types (continued):

 Type SB (N) or SG (N): SSI output without parity, 13-bit or 25-bit, 11 to 30 V, binary code SB (N) or Gray code SG (N).

 Type KB (N) or KG (N): push-pull output driver, 11 to 30 V, binary code KB (N) or Gray code KG (N) with multi-turn connecting cable.

 Type C: binary CANopen serial link.

 Type F: binary PROFIBUS serial link, RS 485.

Applications

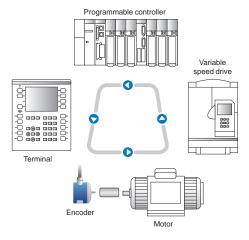
The increase in the power of processing systems, coupled with the requirements for high productivity, has created the need for continuous information in all areas of production regarding:

- Counting, positioning by counting,
- Absolute positioning,
- Speed control.

Example

The positioning of a moving part is fully controlled by the processing system via the encoder.

- Processing units: please refer to our "Premium automation platform" catalog.
- Variable speed drives: please refer to our "Variable speed drives and starters" catalog.



Principle of the opto-electronic rotary encoder

The opto-electronic rotary encoder is an angular position sensor.

Mechanically coupled to a driving spindle of a machine, the shaft of the encoder rotates a disc that comprises a succession of opaque and transparent sectors.

Light from light emitting diodes (LEDs) passes through the transparent sectors of the disc as they appear and is detected by photosensitive diodes.

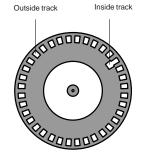
The photosensitive diodes, in turn, generate an electrical signal which is amplified and converted into a digital signal before being transmitted to a processing system or an electronic variable speed drive.

The electrical output of the encoder therefore represents, in digital form, the angular position of the input shaft.

Types of opto-electronic rotary encoder

- Incremental encoders:
 - Counting, positioning by counting, speed.
- Parameterable incremental encoders:
- Multiplication of the basic resolution of the disc using dip switches (the factory setting being that of the lowest value).
- Single turn and multi-turn absolute encoders:
 - Absolute positioning.
- Fieldbus multi-turn absolute encoders:
 - CANopen and PROFIBUS-DP.

Incremental encoder



1/4 period

360° period

1/2 period

Channel A

Channel B

Top 0

Principle

The disc of an incremental encoder comprises two types of track:

- one or several outside tracks (channels A and B), comprising "n" equal angular steps that are alternately opaque and transparent, with "n" being the resolution or number of periods of the encoder.
- an inside track comprising a single window, which serves as the catalog number point and enables reinitialization at each revolution (top 0).

Wiring diagrams and settings

The operation of the photosensitive elements (LEDs + photosensitive diodes) is based on the real-time differential optical reading principle:

- The photosensitive elements of tracks A and B are offset so that each will simultaneously read only its respective slot (channels A and B are 90° electrically offset),
- The electronics operate following the principle of real-time differential measurement.

Channel B (rising edge) arriving before A in the clockwise direction viewed from base side.

Period: 360° electrical.

Cyclic ratio: 180° electrical ± 10%.
Phase displacement: 90° electrical ± 25%.

Advantages of real-time differential optical reading

Reading by offset photosensitive elements

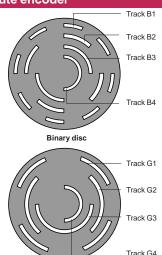
- Radial play of encoder shaft greater than 30%, which is higher than traditional optical reading encoders.
- Maintains a phase displacement of channels A and B within the tolerance limits of the unit

Triple light source emission

- Maintains cyclic ratio, even in the event of:
 - Failure of one of the three light sources,
 - Diminishing efficiency of the light sources (up to 30%),
 - Fine dust deposit on the optical components, reducing signal strength of the photosensitive elements (up to 30%).

These advantages are the reliability factors of the XCC encoders.

Absolute encoder



Gray disc

Principle

The disc of an absolute encoder comprises "n" concentric tracks, equally divided into alternate opaque and transparent segments, and each track has its own transmitter and receiver.

The inside track is half opaque and half transparent. Reading of this MSB (Most Significant Bit) track determines in which half-turn the encoder is situated.

The next track is divided into four quarters, alternately opaque and transparent. The reading of this track, in conjunction with the previous track, determines in which quarter-turn the encoder is situated.

The following tracks enable successive determination of which eighth-turn, sixteenth-turn, etc. the encoder is situated.

The outside track corresponds to the LSB (Least Significant Bit) and provides the final accuracy. It has 2ⁿ points corresponding to the resolution of the encoder. Therefore, for each angular position of the shaft, the disc provides a code. This code can either be binary or Gray.

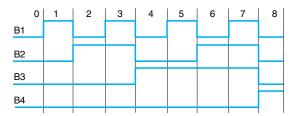
Following one complete revolution of the encoder, the same coded values are repeated.

The multi-turn absolute encoder, in addition to providing the digital position within the revolution, also provides the total number of revolutions.

Absolute encoder (continued)

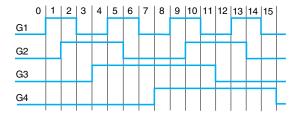
Binary coding

The binary code is directly usable by processing systems (programmable controllers for example) in order to execute calculations or comparisons, but has the disadvantage of having several bits which change state between two positions.

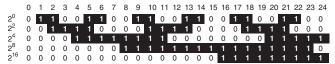


Gray coding

The Gray code offers the advantage of only changing one bit between two consecutive numbers.



Example of Gray code disc



Reintroduction of the first twenty-four decimal values corresponding to the reading of the first five tracks.

Advantages of position detection by an absolute encoder

An absolute encoder continuously provides a code that is an image of the actual position of the moving object being monitored.

On power-up, or restart following a loss of power⁰, the encoder provides data that is directly exploitable by the processing system.

Specifications required to define an encoder

7 specifications to be established

Function

- Incremental encoder Provides counting indication.
- Single turn absolute encoder
 Provides absolute position within each revolution.
- Multi-turn absolute encoder Provides absolute position within each revolution and indicates total number of revolutions.

2 Diameter of housing

- Incremental encoders Ø 40, 58 and 90
- Single turn and multi-turn absolute encoders Ø 58 and 90

3 Diameter of shaft

- Ø 6 mm to 30 mm, depending on model
- Reduction collars

For \varnothing 58 and 90 mm encoders, with \varnothing 14, 15 and 30 mm through shaft, reduction collars are available to reduce the diameters:

- from 14 to 6, 8, 10 and 12
- from 15 to 6, 8, 10, 12 and 14
- from 30 to 12, 16, 20 and 25.

4 Type of shaft

■ Solid shaft

The shaft of the encoder is mechanically linked to a drive shaft using a flexible coupling, which eliminates alignment inaccuracies.

■ Through shaft/Hollow shaft

The encoder is mounted directly on the drive shaft. A flexible mounting kit prevents encoder rotation and compensates for alignment inaccuracies.

5 Connection method

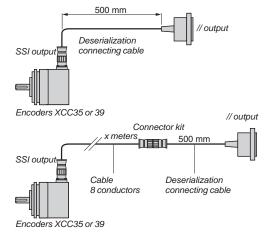
- Pre-cabled with 2 m long shielded cable or M23/M12 connector.
- Radial type connection.

6 Resolution

- Number of points per revolution.
- Number of revolutions (for multi-turn absolute encoders).
- On Ø 58 parameterable incremental encoders, this resolution can be adjusted using dip switches (multiplication factor up to 16 times on 9 basic resolutions).

7 Type of output

- Incremental encoders 5 V output driver, RS-422, 4.75 to 30 V. Push-pull output driver, 5 to 30 V, 11...30 V.
- Single turn absolute encoders (depending on model)
 Push-pull output driver, 11 to 30 V, binary code or Gray code.
 SSI output without parity, 13-bit clock, 11 to 30 V, binary code or Gray code.
- Multi-turn absolute encoders (depending on model)
 SSI output without parity, 25-bit clock, 11 to 30 V, binary code or Gray code.
- Parallel outputs obtainable using converter connecting cables The SSI versions can be converted to a parallel version by using the deserialization connecting cable (see page 9/32).



Specifications required to define an encoder

Installation precautions

Type of cables

In an environment subject to considerable electrical interference, it is recommended that cables with several twisted pairs, reinforced by general shielding, be used.

For the signals, it is recommended that standard 0.14 mm²/0.22 mm² (26/24 AWG) conductors be used.

For 5 V supply encoders.

Due to line voltage drops, it is recommended that the 0 V and + V supply cables have the following minimum cross-sectional areas:

- 0.14 mm² (26 AWG) if the encoder-supply distance is less than 30 m,
- 0.22 mm² (24 AWG) if the encoder-supply distance is greater than 30 m.

Cabling

Separate, by as much as possible, the connecting cables to encoders and power cables. Also, avoid parallel cable runs. Maintain a distance of at least 20 cm and, in the event of cables crossing, ensure that the crossovers are at right-angles.

When using cables with twisted pairs (shielded or non-shielded), group signal cables in common pairs.

In environments subject to electrical interference, we recommend grounding the encoder base using one of the mounting screws.

Connect the control inputs to a potential (absolute encoder).

Connect all 0 V connections back to a star point, i.e. only one and same referential. Ground the shielding throughout 360° using tap-off braids. This is to be done at both ends of each cable. To ground the shielding use at least 4 mm² cable.

As much as possible, ground the 0 V of the supply to the encoders on the supply

As much as possible, ground the 0 V of the supply to the encoders on the supply side. Maximum frequency of signals for SSI depending on distance: Indicative values that can vary depending on the cable specifications.

Distance (m)	Frequency (kHz)	
50	400	
100	300	
200	200	
400	100	

Supply

It is imperative that regulated and smoothed power supplies, with a ripple factor on 24 V of 500 mV and on 5 V of 200 mV, are used that are specifically for the encoder. Schneider Electric ABL7 range power supplies are available. Please refer to our "Power supplies, splitter boxes and interfaces" catalog.

For 5 to 30 V encoders, the supply via a transformer with a 24 V rms rectified and smoothed secondary is prohibited, since the DC voltage obtained is higher than the supply voltage limits of the encoder.

Prior to power-up for the first time, ensure that the rated supply voltage of the encoder is suitable for the supply.

Specifications required to define an encoder, installation, power-up

Connection and power-up precautions

Connection

The plugging-in or unplugging of a connector version encoder must only be done while the supply is disconnected.

Encoder supplied by central unit:

- Disconnect supply to central unit,
- Proceed with connection or disconnection,
- Re-establish supply to central unit.

Encoder supplied by source external to central unit:

- Disconnect supply to central unit, then disconnect supply to encoder,
- Proceed with connection or disconnection,
- Re-establish supply to encoder, then re-establish supply to central unit.

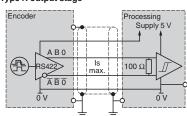
Power-up

For synchronization reasons, the power-up or switching-off of the encoder must coincide with that of its associated electronics.

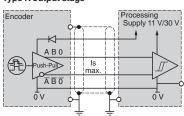
Ø 40 mm encoders

Encoder type			XCC1406Peeee	XCC1406T••••	
Conformity			CE	7.007.007.00	
Temperature	Operation (housing)	°C (°F)	- 20 to + 80 (- 4 to + 176)		
	Storage	°C (°F)	- 30 to + 85 (- 22 to + 185)		
Degree of protection	Conforming to IEC 60529	- (- /	IP 54	IP 52	
/ibration resistance	Conforming to IEC 60068-2-6		10 gn (f = 10 to 500 Hz)	1	
Shock resistance	Conforming to IEC 60068-2-27		30 gn, duration 11 ms		
Resistance to electromagne			Conforming to IEC 61000-4-2: level 3, 8 kV air; 4 kV contact		
nterference	Radiated electromagnetic fields (electromagnetic waves)		Conforming to IEC 61000-4-3: level 3, 10 V/n		
	Fast transients (Start/Stop interference)		Conforming to IEC 61000-4-4: level 3, 2 kV (1 kV for inputs/outputs)	
	Surge withstand		Conforming to IEC 61000-4-5: level 2, 1 kV		
Materials	Base		Aluminium or Zamak		
	Housing		Aluminium or Zamak		
	Shaft		Stainless steel or Aluminium		
	Ball bearings		688AZZ1		
Mechanical specific	cations				
Shaft type		mm	Ø 6, solid shaft (g7)	Ø 6, through shaft (H7)	
Maximum rotational speed	Continuous		9000 rpm	5 0, through shall (117)	
Shaft moment of inertia	Continuous	g.cm ²	10 (0.14 oz.in.)	5 (0.07 oz.in.)	
Forque		N•cm	0.2 (0.28 oz.in.)	0.25 (0.35 oz.in.)	
Maximum load	Radial	N	20	0.20 (0.00 02.111.)	
waxiiiaiii lodd	Axial	N	10		
Floatrical appoirties	4iono				
Electrical specifica	tions		I	In the second second	
Connection			Radial: pre-cabled, 8 x 0.14 mm² shielded, Ø ext = 6 mm, length = 2 m	Pre-cabled 8 x 0.14 mm ² shielded Ø ext = 6 mm, length = 2 m Crimped metal cable entry	
			Crimped metal cable entry	Chimped metal cable entry	
requency		kHz	100	Crimped metal cable entry	
<u> </u>		kHz			
Number of channels	ut stage: 5 V output driver, RS-422		$\frac{100}{3 \text{ channels: A, B, top 0 and complements } \overline{A}, i}$		
Number of channels Encoders with Type R output	ut stage: 5 V output driver, RS-422		$\frac{100}{3 \text{ channels: A, B, top 0 and complements } \overline{A}, i}$		
Number of channels Encoders with Type R output Supply voltage	•		100 3 channels: A, B, top 0 and complements \overline{A} , is 5 V supply 5 V ± 10%		
Number of channels Encoders with Type R output Supply voltage Current consumption, no-loa	•	, 4.5 to 5.	100 3 channels: A, B, top 0 and complements \overline{A} , is 5 V supply 5 V ± 10% Max. ripple: 200 mV		
Number of channels Encoders with Type R output Supply voltage Current consumption, no-load	•	, 4.5 to 5.	100 3 channels: A, B, top 0 and complements \overline{A} , is 5 V supply 5 V ± 10% Max. ripple: 200 mV 100 max.		
Number of channels Encoders with Type R output Supply voltage Current consumption, no-load	ad	, 4.5 to 5.	100 3 channels: A, B, top 0 and complements \overline{A} , is 5 V supply 5 V ± 10% Max. ripple: 200 mV 100 max. 40 max.		
Number of channels Encoders with Type R output Supply voltage Current consumption, no-load Dutput current Dutput levels Encoders with Type K output	ad Low level	, 4.5 to 5. mA mA	100 3 channels: A, B, top 0 and complements \overline{A} , is 5 V supply 5 V ± 10% Max. ripple: 200 mV 100 max. 40 max. (Is = 20 mA) 0.5 V max. (Is = 20 mA) 2.5 V min.		
Number of channels Encoders with Type R output Supply voltage Current consumption, no-load Output current Output levels Encoders with Type K output	Low level High level	, 4.5 to 5. mA mA	100 3 channels: A, B, top 0 and complements \overline{A} , i 5 V supply 5 V ± 10% Max. ripple: 200 mV 100 max. 40 max. (Is = 20 mA) 0.5 V max. (Is = 20 mA) 2.5 V min.		
Number of channels Encoders with Type R output Supply voltage Current consumption, no-load Dutput current Dutput levels Encoders with Type K output Supply voltage	Low level High level ut stage: push-pull output driver, 1	, 4.5 to 5. mA mA	100 3 channels: A, B, top 0 and complements A,I 5 V supply		
Number of channels Encoders with Type R output Supply voltage Current consumption, no-load Dutput current Dutput levels Encoders with Type K output Supply voltage Current consumption, no-load	Low level High level ut stage: push-pull output driver, 1	, 4.5 to 5. mA mA	100 3 channels: A, B, top 0 and complements A, I 5 V supply		
Number of channels Encoders with Type R output Supply voltage Current consumption, no-load Output current Output levels Encoders with Type K output Supply voltage Current consumption, no-load Protection	Low level High level ut stage: push-pull output driver, 1	, 4.5 to 5. mA mA	100 3 channels: A, B, top 0 and complements A, I 5 V supply		
Supply voltage Current consumption, no-log Output current Output levels	Low level High level ut stage: push-pull output driver, 1	, 4.5 to 5. mA mA 1 to 30 V	100 3 channels: A, B, top 0 and complements Ā,Ī 5 V supply 5 V ± 10% Max. ripple: 200 mV 100 max. 40 max. (Is = 20 mA) 0.5 V max. (Is = 20 mA) 2.5 V min. supply 11 V to 30 V. Max. ripple: 500 mV 75 max. Against short-circuits and reverse polarity		

Wiring diagrams
Type R output stage



Type K output stage



Ø 40 mm encoders





Solid sha	ıft, Ø 6 mm				
Resolution	Connection method	Output stage type (1)	Supply voltage	Catalog number	Weight kg (lbs)
100 points	Pre-cabled, radial	5 V, RS-422	4.5 to 5.5 V	XCC1406PR01R	0.355 (0.787)
2 m	2 m	Push-pull	11 to 30 V	XCC1406PR01K	0.355 (0.787)
360 points	Pre-cabled, radial	5 V, RS-422	4.5 to 5.5 V	XCC1406PR03R	0.355 (0.787)
	2 m	Push-pull	11 to 30 V	XCC1406PR03K	0.355 (0.787)
500 points	Pre-cabled, radial	5 V, RS-422	4.5 to 5.5 V	XCC1406PR05R	0.355 (0.787)
	2 m	Push-pull	11 to 30 V	XCC1406PR05K	0.355 (0.787)
1000 points	Pre-cabled, radial	5 V, RS-422	4.5 to 5.5 V	XCC1406PR10R	0.355 (0.787)
	2 m	Push-pull	11 to 30 V	XCC1406PR10K	0.355 (0.787)
1024 points	Pre-cabled, radial	5 V, RS-422	4.5 to 5.5 V	XCC1406PR11R	0.355 (0.787)
	2 m	Push-pull	11 to 30 V	XCC1406PR11K	0.355 (0.787)
Through	shaft, Ø 6 r	nm (2)			
Resolution	Connection method	Output stage type (1)	Supply voltage	Catalog number	Weight kg (lbs)
100 points	Pre-cabled, radial	5 V, RS-422	4.5 to 5.5 V	XCC1406TR01R	0.405 (0.893)
	2 m	Push-pull	11 to 30 V	XCC1406TR01K	0.405 (0.893)
360 points	Pre-cabled, radial	5 V, RS-422	4.5 to 5.5 V	XCC1406TR03R	0.405 (0.893)
	2 m	Push-pull	11 to 30 V	XCC1406TR03K	0.405 (0.893)
500 points	Pre-cabled, radial	5 V, RS-422	4.5 to 5.5 V	XCC1406TR05R	0.405 (0.893)
	2 m	Push-pull	11 to 30 V	XCC1406TR05K	0.405 (0.893)
1000 points	Pre-cabled, radial	5 V, RS-422	4.5 to 5.5 V	XCC1406TR10R	0.405 (0.893)
	2 m	Push-pull	11 to 30 V	XCC1406TR10K	0.405

4.5 to 5.5 V

11 to 30 V

5 V, RS-422

Push-pull

Pre-cabled,

radial

1024 points

(0.893)

0.405

(0.893)

0.405

XCC1406TR11R

XCC1406TR11K

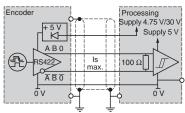
⁽¹⁾ For specifications of the output stage type (indicated by last letter of the catalog number), see page 9/10

see page 9/10.
(2) Anti-rotation device included with encoder.

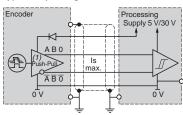
Ø 58 mm encoders

Encoder type			XCC1506Peeee	XCC1510Peeee	XCC1514T ••••		
Conformity			CE	7.00.010.000	ACCIONINGUE		
Temperature	Operation (housing)	°C (°F)	- 30 to + 100 (- 22 to + 212) [e	xcept XCCTSMeeX and XCC	TSMeeY: - 30 to + 70 (- 22 to + 158		
	Storage	°C (°F)	- 30 to + 85 (- 22 to + 185)				
Degree of protection	Conforming to IEC 60529	- (/	IP 65	IP 65 (IP 67 with collar option XCCRB3)	IP 65		
Vibration resistance	Conforming to IEC 60068-2-6		10 gn (f = 55 to 2000 Hz)		•		
Shock resistance	Conforming to IEC 60068-2-27		30 gn, duration 11 ms				
Resistance to electromagnet	ic Electrostatic discharges		Conforming to IEC 61000-	4-2: level 3, 8 kV air, 4 kV	contact		
interference	Radiated electromagnetic fields (electromagnetic waves)		Conforming to IEC 61000-4-3: level 3, 10 V/m				
	Fast transients (Start/Stop interference)		Conforming to IEC 61000-4-4: level 3, 2 kV (1 kV for inputs/outputs)				
	Surge withstand		Conforming to IEC 61000-	4-5: level 2, 1 kV			
Materials	Base		Aluminium				
	Housing		Zamak				
	Shaft		Stainless steel				
	Ball bearings		6000ZZ1		6803ZZ		
Mechanical specific	ations						
Shaft type			Ø 6, solid shaft (g7)	Ø 10 mm, solid shaft	Ø 14, through shaft (H7)		
Maximum rotational speed	Continuous		9000 rpm	9000 rpm	6000 rpm		
Shaft moment of inertia		g.cm ²	10 (0.14 oz.in.)	10 (0.14 oz.in.)	22 (0.31 oz.in.)		
Torque		N•cm	0.4 (0.57 oz.in.)	0.4 (0.57 oz.in.)	0.6 (0.85 oz.in.)		
Maximum load	Radial	N	100	100	50		
	Axial	N	50	50	20		
Electrical specificat	tions						
Connection	Connector		M23, 12-pin male connect	or			
Frequency		kHz	300				
Number of channels			3 channels: A, B, top 0 and complements $\overline{A}, \overline{B}, \overline{0}$				
Encoders with Type X output	t stage: 5 V output driver, RS-422	4.75 to 3	30 V supply				
Supply voltage			4.75 to 30 V				
			Max. ripple: 500 mV				
Current consumption, no-loa	nd	mA	75 max.				
Protection			Against short-circuits and	reverse polarity			
Output current		mA	40 max.				
Output levels	Low level		(Is = 20 mA) 0.5 V max.				
	High level		(Is = 20 mA) 4.5 V min.				
•••	t stage: push-pull output driver, 5	to 30 V s					
Supply voltage			5 to 30 V Max. ripple: 500 mV				
Current consumption, no-loa	ıd	mA	75 max.				
Protection			Against short-circuits and	reverse polarity			
Output current		mA	40 max.				
Output levels (for U supply = 30 V) (1)	Low level		(Is = 20 mA) 0.5 V max.				
	High level		(Is = 20 mA) V supply - 2.5	1/			

Wiring diagrams Type X output stage



Type Y output stage



(1) RS-422 compatible on 5 V supply.

Ø 58 mm encoders





Solid sh	aft, Ø 6 mm				
Resolution	Connection method (1)	Output stage type (2)	Supply voltage	Catalog number	Weight kg (lbs)
100 points	Connector, radial	5 V, RS-422	4.75 to 30 V	XCC1506PS01X	0.495 (1.091)
	M23 male	Push-pull	5 to 30 V	XCC1506PS01Y	0.495 (1.091)
360 points	Connector, radial	5 V, RS-422	4.75 to 30 V	XCC1506PS03X	0.495 (1.091)
	M23 male	Push-pull	5 to 30 V	XCC1506PS03Y	0.495 (1.091)
500 points	Connector, radial M23 male	5 V, RS-422	4.75 to 30 V	XCC1506PS05X	0.495 (1.091)
		Push-pull	5 to 30 V	XCC1506PS05Y	0.495 (1.091)
1000 points	Connector, radial M23 male	5 V, RS-422	4.75 to 30 V	XCC1506PS10X	0.495 (1.091)
		Push-pull	5 to 30 V	XCC1506PS10Y	0.495 (1.091)
1024 points	Connector, radial	5 V, RS-422	4.75 to 30 V	XCC1506PS11X	0.495 (1.091)
	M23 male	Push-pull	5 to 30 V	XCC1506PS11Y	0.495 (1.091)
2500 points	Connector, radial	5 V, RS-422	4.75 to 30 V	XCC1506PS25X	0.495 (1.091)
	M23 male	Push-pull	5 to 30 V	XCC1506PS25Y	0.495 (1.091)
5000 points	Connector, radial	5 V, RS-422	4.75 to 30 V	XCC1506PS50X	0.495 (1.091)
	M23 male	Push-pull	5 to 30 V	XCC1506PS50Y	0.495

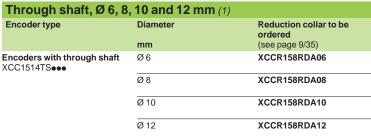
Solid sh	aft, Ø 10 mm				
Resolution	Connection method (1)	Output stage type (2)	Supply voltage	Catalog number	Weight kg (lbs)
100 points	Connector, radial	5 V, RS-422	4.75 to 30 V	XCC1510PS01X	0.465 (1.025)
	M23 male	Push-pull	5 to 30 V	XCC1510PS01Y	0.465 (1.025)
360 points	Connector, radial	5 V, RS-422	4.75 to 30 V	XCC1510PS03X	0.465 (1.025)
	M23 male	Push-pull	5 to 30 V	XCC1510PS03Y	0.465 (1.025)
·	Connector, radial M23 male	5 V, RS-422	4.75 to 30 V	XCC1510PS05X	0.465 (1.025)
		Push-pull	5 to 30 V	XCC1510PS05Y	0.465 (1.025)
1000 points	Connector, radial M23 male	5 V, RS-422	4.75 to 30 V	XCC1510PS10X	0.465 (1.025)
		Push-pull	5 to 30 V	XCC1510PS10Y	0.465 (1.025)
1024 points	Connector, radial	5 V, RS-422	4.75 to 30 V	XCC1510PS11X	0.465 (1.025)
	M23 male	Push-pull	5 to 30 V	XCC1510PS11Y	0.465 (1.025)
2500 points	Connector, radial	5 V, RS-422	4.75 to 30 V	XCC1510PS25X	0.465 (1.025)
	M23 male	Push-pull	5 to 30 V	XCC1510PS25Y	0.465 (1.025)
5000 points	Connector, radial	5 V, RS-422	4.75 to 30 V	XCC1510PS50X	0.465 (1.025)
	M23 male	Push-pull	5 to 30 V	XCC1510PS50Y	0.465 (1.025)

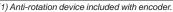
⁽¹⁾ For female connector use XZC C23FDP120S or pre-wired connectors (2, 5 or 10 m), see page 9/33.
(2) For specifications of the output stage type (indicated by last letter of the catalog number), see page 9/12.

Ø 58 mm encoders









⁽¹⁾ Anti-rotation device included with encoder. (2) For female connector use XZC C23FDP120S or pre-wired connectors (2, 5 or 10 m), see



^{&#}x27; page 9/33.
(3) For specifications of the output stage type (indicated by last letter of the catalog number), see page 9/12.

Ø 58 mm encoders

Parameterable versions (1)



Parameterable with solid shaft, Ø 10 mm							
Resolution	Connection method (2)	Output stage type (3)	Supply voltage	Catalog number	Weight kg (lbs)		
256 to 4096 points	Connector, radial M23	5 V, RS-422	4.75 to 30 V	XCC1510PSM02X	0.465 (1.025)		
	male	Push-pull	5 to 30 V	XCC1510PSM02Y	0.465 (1.025)		
360 to 5760 Conne points M23 male		5 V, RS-422	4.75 to 30 V	XCC1510PSM03X	0.465 (1.025)		
	male	Push-pull	5 to 30 V	XCC1510PSM03Y	0.465 (1.025)		
500 to 8000 points	Connector, radial M23 male	5 V, RS-422	4.75 to 30 V	XCC1510PSM05X	0.465 (1.025)		
		Push-pull	5 to 30 V	XCC1510PSM05Y	0.465 (1.025)		
1024 to 16,384 points	Connector, radial M23	5 V, RS-422	4.75 to 30 V	XCC1510PSM11X	0.465 (1.025)		
	male	Push-pull	5 to 30 V	XCC1510PSM11Y	0.465 (1.025)		
5000 to 80,000 points	M23	5 V, RS-422	4.75 to 30 V	XCC1510PSM50X	0.465 (1.025)		
	male	Push-pull	5 to 30 V	XCC1510PSM50Y	0.465 (1.025)		

Parameterable with through shaft, Ø 14 mm (4)							
Resolution	Connection method (2)	Output stage type (3)	Supply voltage	Catalog number	Weight kg (lbs)		
256 to 4096 points	Connector, radial M23	5 V, RS-422	4.75 to 30 V	XCC1514TSM02X	0.435 (0.959)		
	male	Push-pull	5 to 30 V	XCC1514TSM02Y	0.435 (0.959)		
360 to 5760 Connect M23 male		5 V, RS-422	4.75 to 30 V	XCC1514TSM03X	0.435 (0.959)		
	male	Push-pull	5 to 30 V	XCC1514TSM03Y	0.435 (0.959)		
500 to 8000 points	Connector, radial M23 male	5 V, RS-422	4.75 to 30 V	XCC1514TSM05X	0.435 (0.959)		
		Push-pull	5 to 30 V	XCC1514TSM05Y	0.435 (0.959)		
1024 to 16,384 points	M23	5 V, RS-422	4.75 to 30 V	XCC1514TSM11X	0.435 (0.959)		
	male	Push-pull	5 to 30 V	XCC1514TSM11Y	0.435 (0.959)		
5000 to 80,000 points	M23	5 V, RS-422	4.75 to 30 V	XCC1514TSM50X	0.435 (0.959)		
	male	Push-pull	5 to 30 V	XCC1514TSM50Y	0.435 (0.959)		

Parameterable with through shaft, Ø 6, 8, 10 and 12 mm (4)						
Encoder type	Diameter mm	Reduction collar to be ordered (see page 9/35)				
Encoders with through shaft XCC1514TSM●●●	Ø6	XCCR158RDA06				
	Ø8	XCCR158RDA08				
	Ø 10	XCCR158RDA10				
	Ø 12	XCCR158RDA12				



⁽²⁾ For female connector use XZC C23FDP120S or pre-wired connectors (2, 5 or 10 m), see

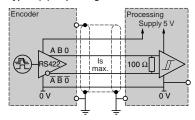


⁽a) For sentate connector use AZC C23r DF 1203 of pre-wired connectors (2, 3 of 10 m), see page 9/33.
(3) For specifications of the output stage type (indicated by last letter of the catalog number), see page 9/12.
(4) Anti-rotation device included with encoder.

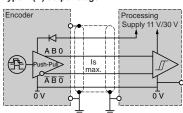
Ø 90 mm encoders

Encoder type			XCC1912P••••	XCC1930T••••				
			(E	VCC 18201 0000				
Conformity Temperature	Operation (housing)	°C (°E)	- 20 to + 80 (- 4 to + 176)					
remperature		°C (°F)	` /					
Dograp of protoction	Storage	C(F)	- 30 to + 85 (- 22 to +185) IP 66	IP 65				
Degree of protection Vibration resistance	Conforming to IEC 60529			12.00				
	Conforming to IEC 60068-2-6		10 gn (f = 10 to 1 kHz)					
Shock resistance	Conforming to IEC 60068-2-27		30 gn, duration 11 ms	10.017 : 417				
Resistance to electromagne interference			Conforming to IEC 61000-4-2: I	· · · · · · · · · · · · · · · · · · ·				
interierence	Radiated electromagnetic fields (electromagnetic waves)		Conforming to IEC 61000-4-3: level 3, 10 V/m					
	Fast transients (Start/Stop interference)		Conforming to IEC 61000-4-4: I	evel 3, 2 kV (1 kV for inputs/outputs)				
	Surge withstand		Conforming to IEC 61000-4-5: I	evel 2, 1 kV				
Materials	Base		Aluminium					
	Housing		Zamak					
	Shaft		Stainless steel					
	Ball bearings		6001ZZ	6807				
Mechanical specific	cations							
Shaft type			Ø 12, solid shaft (g6)	Ø 30, through shaft (H7)				
Maximum rotational speed	Continuous		6000 rpm	3600 rpm				
Shaft moment of inertia		g.cm²	150 (2.08 oz.in.)	500 (6.94 oz.in.)				
Torque		N•cm	1 (1.42 oz.in.)	2.5 (3.54 oz.in.)				
Maximum load	Radial	N	200	80				
	Axial	N	100	50				
Electrical specifica	tions							
Connection	Connector		M23, 12-pin male connector					
Frequency		kHz	100					
Number of channels			3 channels: A, B, top 0 and com	plements $\overline{A}, \overline{B}, \overline{0}$				
Encoders with Type R (N) o	utput stage: 5 V output driver, RS-	l 422, 4.5 t	l o 5.5 V supply					
Supply voltage			5 V ± 10% Max. ripple: 200 mV					
Current consumption, no-lo	ad	mA	100 max.					
Output current		mA	40 max.					
		11174	1 2 1112111					
•	Low level		(Is = 20 mA) 0.5 V max.					
•	Low level High level		(Is = 20 mA) 0.5 V max. (Is = 20 mA) V supply - 2.5 V mi	n.				
Output levels		er, 11 to 3	(Is = 20 mA) V supply - 2.5 V mi	n.				
Output levels Encoders with Type K (N) o	High level	er, 11 to 3	(Is = 20 mA) V supply - 2.5 V mi	n.				
Output levels Encoders with Type K (N) o Supply voltage	High level utput stage: push-pull output drive	er, 11 to 3	(ls = 20 mA) V supply - 2.5 V mi 80 V supply 	n.				
Output levels Encoders with Type K (N) o Supply voltage Current consumption, no-lo	High level utput stage: push-pull output drive		(Is = 20 mA) V supply - 2.5 V mi 80 V supply					
Output levels	High level utput stage: push-pull output drive		(Is = 20 mA) V supply - 2.5 V mi 80 V supply					
Output levels Encoders with Type K (N) o Supply voltage Current consumption, no-lo Protection	High level utput stage: push-pull output drive	mA	(Is = 20 mA) V supply - 2.5 V mi 30 V supply 11 V to 30 V Max. ripple: 500 mV 75 max. Against short-circuits and rever					

Wiring diagrams Type R (N) output stage



Type K (N) output stage



Ø 90 mm encoders







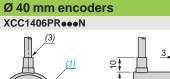


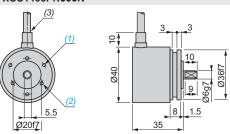
Solid sha	aft, Ø 12 n	nm			
Resolution	Connection method (1)	Output stage type (2)	Supply voltage	Catalog number	Weight kg (lbs)
100 points	Connector,	5 V, RS-422	4.5 to 5.5 V	XCC1912PS01RN	1.360 (3.000)
	radial M23 male	Push-pull	11 to 30 V	XCC1912PS01KN	1.360 (3.000)
360 points	Connector,	5 V, RS-422	4.5 to 5.5 V	XCC1912PS03RN	1.360 (3.000)
	radial M23 male	Push-pull	11 to 30 V	XCC1912PS03KN	1.360 (3.000)
500 points	Connector,	5 V, RS-422	4.5 to 5.5 V	XCC1912PS05RN	1.360 (3.000)
	radial M23 male	Push-pull	11 to 30 V	XCC1912PS05KN	1.360 (3.000)
1000 points	Connector,	5 V, RS-422	4.5 to 5.5 V	XCC1912PS10RN	1.360 (3.000)
	radial M23 male	Push-pull	11 to 30 V	XCC1912PS10KN	1.360 (3.000)
1024 points	Connector,	5 V, RS-422	4.5 to 5.5 V	XCC1912PS11RN	1.360 (3.000)
	radial M23 male	Push-pull	11 to 30 V	XCC1912PS11KN	1.360 (3.000)
2500 points	Connector,	5 V, RS-422	4.5 to 5.5 V	XCC1912PS25RN	1.360 (3.000)
	radial M23 male	Push-pull	11 to 30 V	XCC1912PS25KN	1.360 (3.000)
3600 points	Connector,	5 V, RS-422	4.5 to 5.5 V	XCC1912PS36RN	1.360 (3.000)
-	radial M23 male	Push-pull	11 to 30 V	XCC1912PS36KN	1.360 (3.000)
5000 points	Connector,	5 V, RS-422	4.5 to 5.5 V	XCC1912PS50RN	1.360 (3.000)
	radial M23 male	Push-pull	11 to 30 V	XCC1912PS50KN	1.360 (3.000)
10,000 points	Connector,	5 V, RS-422	4.5 to 5.5 V	XCC1912PS00RN	1.360 (3.000)
	radial M23 male	Push-pull	11 to 30 V	XCC1912PS00KN	1.360 (3.000)
		30 mm (3)	a Cummbu	Catalan numbar	Mainh.
Resolution	Connection method (1)	type (2)	voltage	Catalog number	Weight kg (lbs)
100 points	Connector, radial M23	5 V, RS-422			0.960 (2.116)
	male	Push-pull	11 to 30 V	XCC1930TS01KN	0.960 (2.116)
360 points	Connector,	5 V, RS-422			0.960 (2.116)
	radial M23 male	Push-pull	11 to 30 V	XCC1930TS03KN	0.960 (2.116)
500 points	Connector,	5 V, RS-422			0.960 (2.116)
	radial M23 male	Push-pull	11 to 30 V	XCC1930TS05KN	0.960 (2.116)
1000 points	Connector,	5 V, RS-422			0.960 (2.116)
	radial M23 male	Push-pull	11 to 30 V	XCC1930TS10KN	0.960 (2.116)
1024 points	Connector,	5 V, RS-422			0.960 (2.116)
	radial M23 male	Push-pull	11 to 30 V	XCC1930TS11KN	0.960 (2.116)
2500 points	Connector, radial M23	5 V, RS-422			0.960 (2.116)
	male	Push-pull	11 to 30 V	XCC1930TS25KN	0.960 (2.116)
3600 points	Connector,	5 V, RS-422		XCC1930TS36RN	0.960 (2.116)
	radial M23 male	Push-pull	11 to 30 V	XCC1930TS36KN	0.960 (2.116)
5000 points	Connector,	5 V, RS-422			0.960 (2.116)
	radial M23 male	Push-pull	11 to 30 V	XCC1930TS50KN	0.960 (2.116)
10,000 points		5 V, RS-422			0.960 (2.116)
	radial M23 male	Push-pull	11 to 30 V	XCC1930TS00KN	0.960 (2.116)

Through shaft, Ø 12, 20 and 25 mm (3)						
Encoder type	Diameter mm	Reduction collar to be ordered (see page 9/35)				
Encoders with through shaft	Ø 12	XCCR290RDP12				
XCC1930TS•●●N	Ø 20	XCCR290RDP20				
	Ø 25	XCCR290RDP25				

⁽¹⁾ For female connector use XZC C23FDP120S or pre-wired connectors (2, 5 or 10 m), see page 9/33.
(2) For specifications of the output stage type (indicated by last letter of the catalog number), see page 9/16.
(3) Anti-rotation device included with encoder.

Ø 40 mm, Ø 58 mm and Ø 90 mm encoders

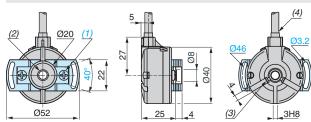




(1) 3 holes M3 x 0.45 at 120° on 28 PCD, depth: 6 mm.

(3) Ø 6 cable, length 2 m, minimum bend radius: 30 mm.

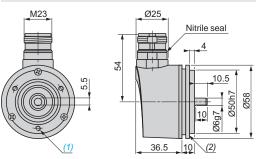
XCC1406TR●●●N



- (1) 2 M4 holes at 120° for cross-headed screws on 30 PCD, depth: 6 mm.
- (2) Through shaft, Ø 6 (H7).
- (3) 2 M2 x 3 flat cross-headed locking screws.
- (4) Ø 6 cable, length 2 m, minimum bend radius: 30 mm.

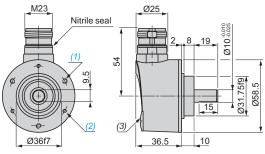
Ø 58 mm encoders

XCC1506PSeeX, XCC1506PSeeY



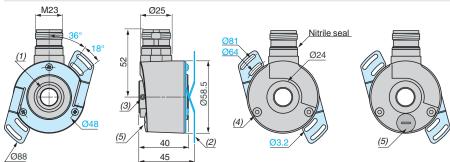
(1) 3 holes M3 x 4 at 120° on 42 PCD, depth: 10 mm. (2) Collar XCCRB1 mounted.

XCC1510PSeeX, 1510PSeeY / XCC1510PSMeeX, 1510PSMeeY



- (1) 3 M4 holes at 120° on 48 PCD, depth: 8 mm. (2) 3 M3 holes at 120° on 48 PCD, depth: 8 mm.
- (3) Blanking plug, for encoders XCC1510PSM••X and 1510PSM••Y only.

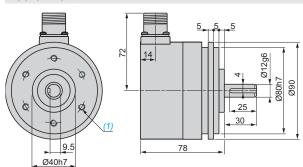
XCC1514TSeeX, 1514TSeeY / XCC1514TSMeeX, 1514TSMeeY



- (1) Through shaft, Ø 14 (H7).
- (2) Flexible mounting kit, 1 x XCCRF5N mounted.
- (3) 2 HC M4 x 4 locking screws. (4) Hole for M3 x 6 self-threading screw.
- (5) Blanking plug, for encoders
- XCC1514TSM X and 1514TSM Y only.

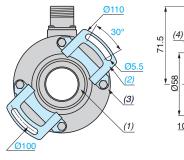
Ø 90 mm encoders

XCC1912PSeeeN



(1) 6 holes M6 x 1 at 120° on 60 PCD, max. depth: 12 mm.

XCC1930TSeeeN



- 10 51 72
- (1) Through shaft, Ø 30 (H7).
- (2) Anti-rotation device, 1 x XCCRF9N, mounted.
- (3) 4 M5 x 6 on 78 PCD.
- (4) 1 CHC M5 x 12 stainless steel A2 locking screw.

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Ø 40 mm, Ø 58 mm and Ø 90 mm encoders

Pre-cabled version encoders (1)

8 x 0.14 mm² shielded cable connections for Ø 40 encoders

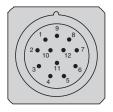
Wire color	BN	RD	VT	BU	YE	OG	GN	ВК
Signal Supply	Ā	+ V	0	0	В	B	Α	0 V
	RD = VT = BU = YE = OG = GN =	Violet	e					

Note: In environments subject to electrical interference, we recommend grounding the encoder base using one of the mounting screws.

Connector version encoders (1)

M23, 12-pin connector connections

Male connector on encoder (pin view)



Pin number	1	2	3	4	5	6	7	8	9	10	11	12	
Signal Supply	Ā	+ V	0	ō	В	B	R	Α	R	0 V	0 V	+ V	

Note: In environments subject to electrical interference, we recommend grounding the encoder base using one of the mounting screws.

R = reserved; do not connect.

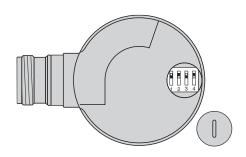
(1) Connect each unused channel to 0 V in series with a 10 k Ω resistor.

Resolutions

Resolutions for parameterable Ø 58 mm encoders XCC1510PSM●●● and XCC1514TSM●●●

Simple multiplication of the basic resolution of the disc using dip switches (1) (Plastic \varnothing 2.5 screwdriver recommended).

The factory setting is for factor X1.



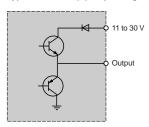
							on			
Interpola factor	tion	Basic	resolu	tion			Positio	n of dip s	witches	
Counting	Speed	256	360	500	1024	5000	1	2	3	4
x 1	x 1	256	360	500	1024	5000				
x 2	x 2	512	720	1000	2048	10,000				
x 3	х 3	768	1080	1500	3072	15,000				
x 4	x 4	1024	1440	2000	4096	20,000				
x 5	-	1280	1800	2500	5120	25,000				
x 8	-	2048	2880	4000	8192	40,000				
x 10	-	2560	3600	5000	10,240	50,000				
x 12	-	3072	4320	6000	12,288	60,000				
x 16	_	4096	5760	8000	16,384	80,000				

⁽¹⁾ Setting the switches to other configurations will result in the encoder providing an unpredictable resolution.

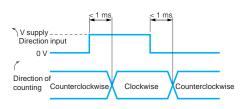
OsiSense® XCC Single turn absolute encoders Ø 58 mm encoders

Encoder type			XCC2506Peeeee	XCC2510Peeee	XCC2514T ••••		
Conformity			CE	•			
Temperature	Operation (housing)	°C (°F)	- 20 to + 90 (- 4 to + 194)			
-	Storage	°C (°F)	- 30 to + 95 (- 22 to + 20	3)			
Degree of protection	Conforming to IEC 60529		IP 65	IP 65 (IP 67 with collar option XCCRB3)	IP 65		
/ibration resistance	Conforming to IEC 60068-2-6		10 gn (f = 10 to 2 kHz)	<u> </u>	<u>'</u>		
Shock resistance	Conforming to IEC 60068-2-27		30 gn, duration 11 ms				
Resistance to electromagneti	ic Electrostatic discharges		Conforming to IEC 6100	00-4-2: level 3, 8 kV air; 4 kV c	ontact		
nterference	Radiated electromagnetic fields (electromagnetic waves)		Conforming to IEC 6100	00-4-3: level 3, 10 V/m			
	Fast transients (Start/Stop interference)		Conforming to IEC 61000-4-4: level 3, 2 kV (1 kV for inputs/outputs)				
	Surge withstand		Conforming to IEC 6100	00-4-5: level 2, 1 kV			
Materials	Base		Aluminium				
	Housing		Zamak				
	Shaft		Stainless steel				
	Ball bearings		6000ZZ1		6803ZZ		
Mechanical specific	ations						
Shaft type			Ø 6, solid shaft (g7)	Ø 10 mm, solid shaft	Ø 14, through shaft (H7		
Maximum rotational speed	Continuous		9000 rpm	9000 rpm	6000 rpm		
Shaft moment of inertia		g.cm ²	10 (0.14 oz.in.)	10 (0.14 oz.in.)	22 (0.31 oz.in.)		
Torque		N•cm	0.4 (0.57 oz.in.)	0.4 (0.57 oz.in.)	0.6 (0.85 oz.in.)		
Maximum load	Radial	N	100	100	50		
	Axial	N	50	50	20		
Electrical specificat	ions				·		
Connection	Connector		M23, 16-pin male conne	I output stage types KG (N), ector. put stage types SB (N), SG (
Frequency			Encoders with parallel output stage types KG (N), KB: 100 kHz on LSB (Least Significant Bit) Encoders with SSI output stage types SB (N), SG (N): 100 kHz to 1 MHz clock				
Encoders with Type KB and	KG (N) output stage: push-pull o	utput driv	ver, 11 to 30 V supply, G	ray code			
Supply voltage			=== 11 to 30 V Max. ripple: 500 mV				
Current consumption, no-loa	d	mA	100 max.				
Protection			Against short-circuits ar	nd reverse polarity			
Output current		mA	20 max.				
Output levels (for U supply = 30 V)	Low level		(Is = 20 mA) 0.5 V max.				
•	High level		(Is = 20 mA) V supply - 2) [\ / main			

Wiring diagrams Type KB and KG (N) output stage



KB and KG (N) Direction input

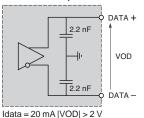


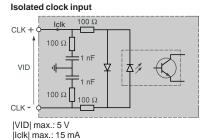
OsiSense® XCC Wiring Diagrams (continued), Single turn absolute encoders

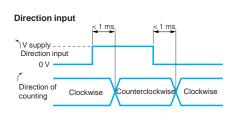
Ø 58 mm encoders

Electrical specifications (continued)	Electrical specifications (continued)						
Encoders with Type SB (N) or SG (N) output stage: SSI output without parity, 13-bit clock, 11 to 30 V supply, binary code (SB) or Gray code (SG)							
Supply voltage		11 to 30 V. Max. ripple: 500 mV					
Current consumption, no-load	mA	100					
Protection		Against short-circuits and reverse polarity					
Output level		Idata = 20 mA VOD > 2 V					

Wiring diagrams RS-422 data output







Catalog number

XCC2506PS81KB

Weight

kg (lbs)

0.495

Catalog numbers



Resolution	Connection method (1)	Output stage type (2)	Supply voltage
Solid shaft	, Ø 6 mm		
8192 points	Connector, radial	Push-pull, binary	11 to 30 \
	M23 male	Push-pull, Gray	11 to 30 \
		SSI, 13-bit, binary	11 to 30 \
		SSI, 13-bit, Gray	11 to 30 \
Solid shaft	Ø 10 mm		

	radial	binary			(1.091)
	M23 male	Push-pull, Gray	11 to 30 V	XCC2506PS81KGN	0.495 (1.091)
		SSI, 13-bit, binary	11 to 30 V	XCC2506PS81SBN	0.490 (1.080)
		SSI, 13-bit, Gray	11 to 30 V	XCC2506PS81SGN	0.490 (1.080)
Solid shaft	, Ø 10 mm				
8192 points	Connector, radial	Push-pull, binary	11 to 30 V	XCC2510PS81KB	0.465 (1.025)
	M23 male	Push-pull, Gray	11 to 30 V	XCC2510PS81KGN	0.465 (1.025)
		SSI, 13-bit, binary	11 to 30 V	XCC2510PS81SBN	0.460 (1.014)
		SSI, 13-bit, Gray	11 to 30 V	XCC2510PS81SGN	0.460 (1.014)
Through sl	haft, Ø 14 mm	n (3)			
8192 points	Connector, radial	Push-pull, binary	11 to 30 V	XCC2514TS81KB	0.435 (0.959)
	M23 male	Push-pull, Gray	11 to 30 V	XCC2514TS81KG	0.435 (0.959)
		SSI, 13-bit, binary	11 to 30 V	XCC2514TS81SB	0.430 (0.948)
		SSI, 13-bit, Gray	11 to 30 V	XCC2514TS81SG	0.430 (0.948)
Through sl	haft, Ø 6, 8, 10	and 12 mm	(3)		

11 to 30 V



	mm	(see page 9/35)
ncoders with through shaft CC2514TS81●●	Ø6	XCCR158RDA06
	Ø8	XCCR158RDA08
	Ø 10	XCCR158RDA10
	Ø 12	YCCR158RDA12

Reduction collar to be ordered

Encoder type

Er ΧC

⁽¹⁾ For female connector use:

⁻ XZC C23FDP120S for encoders Type SBN and SGN

⁻ XZC C23FDP160S for encoders Type KB and KGN,

or pre-wired connectors (2, 5 and 10 m), see page 9/33.

⁽²⁾ For specifications of the output stage type (indicated by last letter of the catalog number), see pages 9/20 and 9/21.

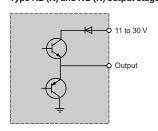
⁽³⁾ Anti-rotation device included with encoder.

OsiSense® XCC Single turn absolute encoders

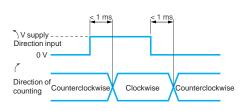
Ø 90 mm encoders

Encoder type			XCC2912Peeee	XCC2930T•••••				
Conformity			CE	110020000000000000000000000000000000000				
Temperature	Operation (housing)	°C (°F)	- 20 to + 85 (- 4 to + 185)					
	Storage	°C (°F)	- 40 to + 85 (- 40 to + 185)					
Degree of protection	Conforming to IEC 60529		IP 66 IP 65					
Vibration resistance	Conforming to IEC 60068-2-6		10 gn (f = 10 to 2 kHz)					
Shock resistance	Conforming to IEC 60068-2-27		30 gn, duration 11 ms					
Resistance to electromagnet interference	ic Electrostatic discharges		Conforming to IEC 61000-4-2: leve	el 3, 8 kV air; 4 kV contact				
	Radiated electromagnetic fields (electromagnetic waves)		Conforming to IEC 61000-4-3: level 3, 10 V/m					
	Fast transients (Start/Stop interference)		Conforming to IEC 61000-4-4: leve	el 3, 2 kV (1 kV for inputs/outputs)				
	Surge withstand		Conforming to IEC 61000-4-5: leve	el 2, 1 kV				
Materials	Base		Aluminium					
	Housing		Zamak					
	Shaft		Stainless steel					
	Ball bearings		6001ZZ	6807				
Mechanical specific	ations							
Shaft type			Ø 12, solid shaft (g6)	Ø 30, through shaft (H7)				
Maximum rotational speed	Continuous		6000 rpm	3600 rpm				
Shaft moment of inertia		g.cm ²	150 (2.08 oz.in.)	500 (6.94 oz.in.)				
Torque		N•cm	1 (1.42 oz.in.)	2.5 (3.54 oz.in.)				
Maximum load	Radial	N	200	80				
	Axial	N	100	50				
Electrical specificat	tions							
Connection	Connector		connector.	age types KB (N), KG (N): M23, 16-pin male types SB (N), SG (N): M23, 12-pin male connecto				
Frequency			Encoders with parallel output stage types KB (N), KG (N): 100 kHz on LSB (Leas Significant Bit) Encoders with SSI output stage types SB (N), SG (N): 100 kHz to 1 MHz clock					
• • • • • • • • • • • • • • • • • • • •	or KG (N) output stage: push-pull	output di	river, 11 to 30 V supply, binary coo	de KB (N) or Gray code KG (N)				
Supply voltage		4	=== 11 to 30 V. Max. ripple: 500 mV					
Current consumption, no-load m			100 max.	-1-26				
Protection			Against short-circuits and reverse	polarity				
Output current		mA	20 max.					
Output levels Low level (Is = 20 mA) 0.5 V max. (for U supply = 30 V)								
	High level		(Is = 20 mA) V supply - 3 V min.					

Wiring diagrams Type KB (N) and KG (N) output stage



KB (N) and KG (N) Direction input

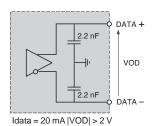


OsiSense® XCC Wiring Diagrams (continued), Single turn absolute encoders

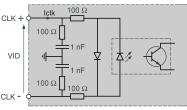
Ø 90 mm encoders

Electrical specifications (continued)							
Encoders with Type SB (N) or SG (N) output stage: SSI output without parity, 13-bit clock, 11 to 30 V supply, binary code SB (N) or Gray code SG (N)							
Supply voltage		11 to 30 V Max. ripple: 500 mV					
Current consumption, no-load	mA	100					
Protection		Against short-circuits and reverse polarity					
Output level		Idata = 20 mA VOD > 2 V					

Wiring diagrams RS-422 data output

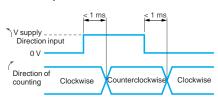


Isolated clock input



|VID| max.: 5 V Iclk max.: 15 mA

Direction input



Catalog numbers



XCC2912PS••••



XCC2930TS••●•



Resolution	Connection method (1)	Output stage type (2)	Supply voltage	Catalog number	Weight kg (lbs)
Solid shaft,	Ø 12 mm				
8192 points	Connector, radial M23 male	Push-pull, binary	11 to 30 V	XCC2912PS81KBN	1.365 (3.001)
		Push-pull, Gray	11 to 30 V	XCC2912PS81KGN	1.365 (3.001)
		SSI, 13-bit, binary	11 to 30 V	XCC2912PS81SBN	1.370 (3.020)
		SSI, 13-bit, Gray	11 to 30 V	XCC2912PS81SGN	1.370 (3.020)

Through s	haft, Ø 30 mn	n (3)			
8192 points	Connector, radial M23 male	Push-pull, binary	11 to 30 V	XCC2930TS81KBN	0.975 (2.150)
		Push-pull, Gray	11 to 30 V	XCC2930TS81KGN	0.975 (2.150)
		SSI, 13-bit, binary	11 to 30 V	XCC2930TS81SBN	0.980 (2.161)
		SSI, 13-bit, Gray	11 to 30 V	XCC2930TS81SGN	0.980 (2.161)

Through shaft, Ø 12, 20 and	1 25 mm (3)	
Encoder type	Diameter mm	Reduction collar to be ordered (see page 9/35)
Encoders with through shaft XCC2930TS81	Ø 12	XCCR290RDP12
	Ø 20	XCCR290RDP20
	Ø 25	XCCR290RDP25

⁽¹⁾ For female connector use:

⁻ XZC C23FDP120S for encoders Type SB (N) and SG (N)

⁻ XZC C23FDP160S for encoders Type KB (N) and KG (N),

or pre-wired connectors (2, 5 and 10 m), see page 9/33.

⁽²⁾ For specifications of the output stage type (indicated by last letter of the catalog number), see pages 9/22 and 9/23.

⁽³⁾ Anti-rotation device included with encoder.

OsiSense® XCC Single turn absolute encoders

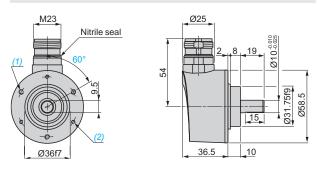
Ø 58 mm and Ø 90 mm encoders

Ø 58 mm encoders

XCC2506PS81KB, XCC2506PS81KGN, XCC2506PS81SBN, XCC2506PS81SGN

M23 Ø25 Nitrile seal 10.5 36.5

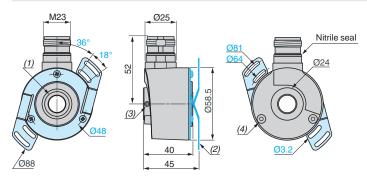
XCC2510PS81KB, XCC2510PS81KGN, XCC2510PS81SBN, XCC2510PS81SGN



- (1) 3 M4 holes at 120° on 42 PCD, depth: 10 mm.
- (2) Collar XCCRB1 mounted.

- (1) 3 M4 holes at 120° on 48 PCD, depth: 8 mm.
- (2) 3 M3 holes at 120° on 48 PCD, depth: 8 mm.

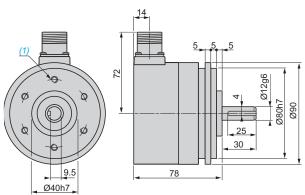
XCC2514TS81KB, XCC2514TS81KGN, XCC2514TS81SB, XCC2514TS81SG



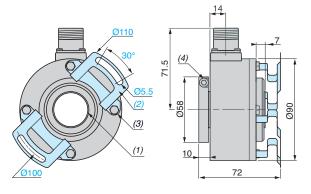
- (1) Through shaft, Ø 14 (H7).
- (2) Flexible mounting kit, 1 x XCCRF5N mounted.
 (3) 2 HC M4 x 4 locking screws.
 (4) Hole for M3 x 6 self-threading screw.

Ø 90 mm encoders

XCC2912PS81KBN, XCC2912PS81KGN



XCC2930TS81SBN, XCC2930TS81SGN



- (1) 6 holes M6 x 1 at 120° on 60 PCD, depth: 12 mm max.
- (1) Through shaft, Ø 30 (H7).
- (2) Anti-rotation device, 1 x XCCRF9N, mounted.
- (3) 4 M5 x 6 on 78 PCD.
- (4) 1 CHC M5 x 12 stainless steel A2 locking screw.

OsiSense® XCC Single turn absolute encoders

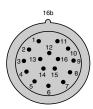
Ø 58 mm and Ø 90 mm encoders

Connector version encoders

Encoders Type KB (N) and KG (N)

M23, 16-pin connector, counterclockwise connections

Male connector on encoder (pin view)



Pin number	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
Signal/Supply If a resolution less than 13 bits (8192 points) is required, only	0 V	+V	d0	d1	d2	d3	d4	d5	d6	d7	d8	d9	d10	d11	d12	Direction (1)

the corresponding number of bits need to be connected:

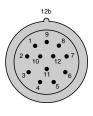
- D5 to D12 for 8 bits (256 points) D3 to D12 for 10 bits (1024 points) D2 to D12 for 11 bits (2048 points)

(1) Clockwise direction, 10 to + v. : Counterclockwise direction, 16 to 0 V.

Encoders Type SB (N) and SG (N)

M23, 12-pin connector, counterclockwise connections

Male connector on encoder (pin view)



Pin number	1	2	3	4	5	6	7	8	9	10	11	12
Signal/Supply	0 V	Data +	· Clk+	R	Direction (1)	n R	R	+V	R	Data –	Clk –	R

R = Reserved (do not connect).

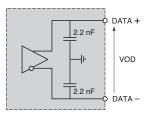
(1) Clockwise direction, 5 to 0 V.

: Counterclockwise direction, 5 to + V.

Ø 58 mm encoders

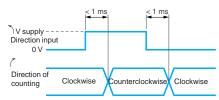
Encoder type	Multi-turn absolute		XCC3506Peeeee	XCC3510Peeee	XCC3514T ••••			
Conformity			C€	'				
emperature	Operation (housing)	°C (°F)	- 20 to + 85 (- 4 to + 185)				
·	Storage	°C (°F)						
Degree of protection	Conforming to IEC 60529		IP 65	IP 65 (IP 67 with collar option XCCRB3)	IP 65			
/ibration resistance	Conforming to IEC 60068-2-6		10 gn (f = 10 to 2 kHz)	·				
Shock resistance	Conforming to IEC 60068-2-27		30 gn, duration 11 ms					
Resistance to electromagnet	ic Electrostatic discharges		Conforming to IEC 6100	0-4-2: level 3, 8 kV air; 4 kV c	ontact			
nterference	Radiated electromagnetic fields (electromagnetic waves)		Conforming to IEC 61000-4-3: level 3, 10 V/m					
	Fast transients (Start/Stop interference)		Conforming to IEC 61000-4-4: level 3, 2 kV (1 kV for inputs/outputs)					
	Surge withstand		Conforming to IEC 61000-4-5: level 2, 1 kV					
Materials	Base		Aluminium					
	Housing		Steel					
	Shaft		Stainless steel Stainless steel					
	Ball bearings		6900ZZ1		6803ZZ			
Mechanical specific	ations							
Shaft type			Ø 6, solid shaft (g7)	Ø 10 mm, solid shaft	Ø 14, through shaft (H7)			
Maximum rotational speed	Continuous		6000 rpm					
Shaft moment of inertia		g.cm ²	10 (0.14 oz.in.)		22 (0.31 oz.in.)			
orque		N•cm	0.4 (0.57 oz.in.)		0.6 (0.85 oz.in.)			
/laximum load	Radial	N	100		50			
	Axial	N	50		20			
Electrical specificat	tions							
Connection	Connector		Encoders with SSI out	put stage types SB (N), SG (N): M23, 12-pin male conne			
requency			Encoders with SSI output stage types SB (N), SG (N): 100 to 500 kHz clock					
Supply voltage			== 11 to 30 V. Max. ripple: 500 mV					
Current consumption, no-loa	ıd	mA	100 max.					
Protection			Against short-circuits ar	d reverse polarity				
Protection Output level			Against short-circuits and reverse polarity Idata = 20 mA VOD > 2 V					

Wiring diagrams RS-422 data output

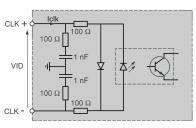


Idata = 20 mA |VOD| > 2 V

Direction input

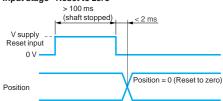


Isolated clock input



|VID| max.: 5 V |Iclk| max.: 15 mA

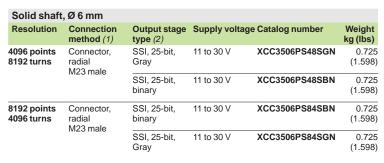
Input stage - Reset to zero



Ø 58 mm encoders

Ø 58 mm multi-turn absolute encoders with SSI output convertible to parallel output

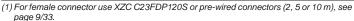
The SSI versions can be converted to a parallel version using the deserialization connecting cable XCCRM23SUB37., see pages 9/32 and 9/33.



Solid shaft	, Ø 10 mm				
Resolution	Connection method (1)	Output stage type (2)	Supply voltage	Catalog number	Weight kg (lbs)
4096 points 8192 turns	Connector, radial M23 male	SSI, 25-bit, Gray	11 to 30 V	XCC3510PS48SGN	0.685 (1.510)
	WZSMale	SSI, 25-bit, binary	11 to 30 V	XCC3510PS48SBN	0.685 (1.510)
8192 points 4096 turns	Connector, radial M23 male	SSI, 25-bit, binary	11 to 30 V	XCC3510PS84SBN	0.685 (1.510)
	WZ3 Male	SSI, 25-bit, Gray	11 to 30 V	XCC3510PS84SGN	0.685 (1.510)

Through s	haft, Ø 14 mm	(3)			
Resolution	Connection method (1)	Output stage type (2)	Supply voltage	e Catalog number	Weight kg (lbs)
8192 points 4096 turns	Connector, radial M23 male	SSI, 25-bit, binary	11 to 30 V	XCC3514TS84SB	0.655 (1.444)
	WZOTTIAIC	SSI, 25-bit, Gray	11 to 30 V	XCC3514TS84SG	0.655 (1.444)

Through shaft, Ø 6, 8, 10	and 12 mm (3)	
Encoder type	Diameter mm	Reduction collar to be ordered (see page 9/35)
Encoders with through shaft XCC3514TS84	Ø6	XCCR158RDA06
	Ø 8	XCCR158RDA08
	Ø 10	XCCR158RDA10
	Ø 12	XCCR158RDA12



⁽²⁾ For specifications of the output stage type (indicated by last letter of the catalog number), see page 9/26.
(3) Anti-rotation device included with encoder.

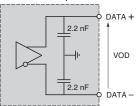




Ø 90 mm encoders

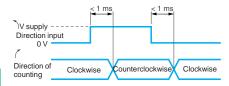
Encoder type			XCC3912Peeeee	XCC3930Teeee				
Conformity			C€					
Temperature	Operation (housing)	°C (°F)	- 20 to + 85 (- 4 to + 185)	- 10 to + 75 (+ 14 to +167)				
	Storage	°C (°F)	- 30 to + 85 (- 22 to + 185)	- 20 to + 85 (- 4 to + 185)				
Degree of protection	Conforming to IEC 60529		IP 66	IP 65				
ibration resistance	Conforming to IEC 60068-2-6		10 gn (f = 10 to 2 kHz)					
Shock resistance	Conforming to IEC 60068-2-27		30 gn, duration 11 ms					
Resistance to electromagnet	ic Electrostatic discharges		Conforming to IEC 61000-4-2: level 3, 8 kV	air; 4 kV contact				
nterference Radiated electromagnetic fields (electromagnetic waves)			Conforming to IEC 61000-4-3: level 3, 10 V	//m				
	Fast transients (Start/Stop interference)		Conforming to IEC 61000-4-4: level 3, 2 kV (1 kV for inputs/outputs)					
	Surge withstand		Conforming to IEC 61000-4-5: level 2, 1 kV					
Materials	Base		Aluminium					
	Housing		Zamak					
	Shaft		Stainless steel					
	Ball bearings		6001ZZ	6807ZZ				
Mechanical specific	ations							
Shaft type			Ø 12, solid shaft (g6)	Ø 30, through shaft (H7)				
Maximum rotational speed	Continuous		6000 rpm	3600 rpm				
Shaft moment of inertia		g.cm ²	150 (2.08 oz.in.)	56 (0.78 oz.in.)				
Torque		N•cm	1 (1.42 oz.in.)	0.8 (1.13 oz.in.)				
Maximum load	Radial	N	200	80				
	Axial	N	100	50				
Electrical specificat	tions							
Connection	Connector		Encoders with SSI output stage types S	B (N), SG (N): M23, 12-pin male connecto				
requency			Encoders with SSI output stage types SB (N), SG (N): 100 to 500 kHz clock					
Encoders with Type SBN or	SGN (Gray) output stage: SSI out	put with	। out parity, 25-bit clock, 11 to 30 V supply,	binary code (SB) or Gray code (SG)				
Supply voltage			== 11 to 30 V Max. ripple: 500 mV					
Current consumption, no-load mA			100 max.					
Protection			Against short-circuits and reverse polarity					
Output level			Idata = 20 mA VOD > 2 V					

Wiring diagrams RS-422 data output

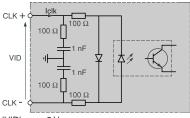


Idata = 20 mA |VOD| > 2 V

Direction input

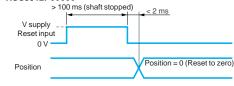


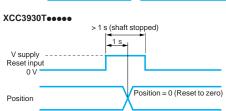
Isolated clock input



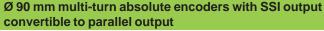
|VID| max.: 5 V |Iclk| max.: 15 mA

Input stage - Reset to zero XCC3912P••••

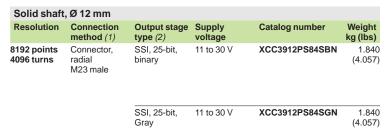


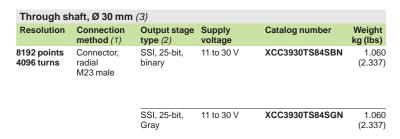


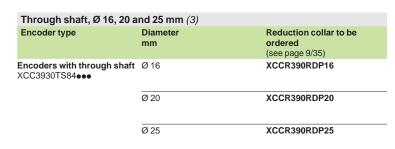
Ø 90 mm encoders

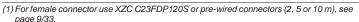


The SSI versions can be converted to a parallel version using the deserialization connecting cable XCCRM23SUB37., see pages 9/32 and 9/33.









^{&#}x27; page 9/33.
(2) For specifications of the output stage type (indicated by last letter of the catalog number), see page 9/28.
(3) Anti-rotation device included with encoder.







Ø 58 mm and Ø 90 mm encoders

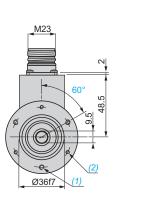
Ø 58 mm encoders

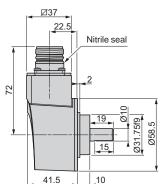
XCC3506PS84SBN, XCC3506PS84SGN

M23 Nitrile seal 10.5 10.5 4 (2) 8 (2) 10.5 4 (2) 4 (2) 4 (2) 4 (2) 4 (2) 4 (2) 4 (2) 4 (2) 4 (2)

(1) 3 M4 holes at 120° on 42 PCD, depth: 10 mm. (2) Collar XCCRB1 mounted.

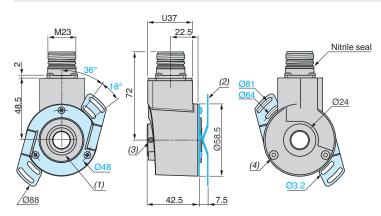
XCC3510PS84SBN, XCC3510PS84SGN





(1) 3 M4 holes at 120° on 48 PCD, depth: 8 mm. (2) 3 M3 holes at 120° on 48 PCD, depth: 8 mm.

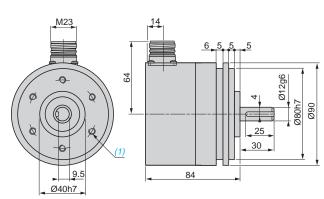
XCC3514TS84SB, XCC3514TS84SG



- (1) Through shaft, Ø 14 (H7).
- (2) Flexible mounting kit, 1 x XCCRF5N mounted.
- (3) 2 HC M4 x 4 locking screws.
- (4) Hole for M3 x 6 self-threading screw.

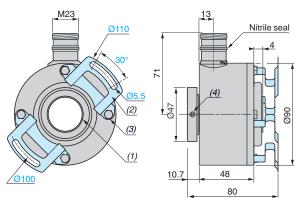
Ø 90 mm encoders

XCC3912PS84S●N



(1) 6 holes M6 x 1 at 120° on 60 PCD, depth: 12 mm max.

XCC3930TS84S●N



- (1) Through shaft, Ø 30 (H7).
- (2) Anti-rotation device, 1 x XCCRF9N, mounted.
- (3) 4 M5 x 6 on 78 PCD.
- (4) 3 HC M5 x 6 stainless steel A2 locking screws.

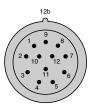
Ø 58 mm and Ø 90 mm encoders

Connector version encoders

Encoder with SSI output (types SBN and SGN)

M23, 12-pin connector, counterclockwise connections

Male connector on encoder (pin view)



Twisted cable pairs + general shielding must be used.

Twisted dable pairs 1 general sinciding mast be assu.												
Pin number	1	2	3	4	5	6	7	8	9	10	11	12
Signal/Supply	0 V	Data +	- Clk+	R	Direction (1)	n Reset	R	+ V	R	Data -	Clk-	R

R = Reserved (do not connect).

(1) Clockwise direction, : Counterclockwise direction.

Selection of code progression direction

The Direction input enables the code progression to match the rotational direction of the encoder shaft (clockwise or counterclockwise).

Clockwise direction: connect pin 5 to 0 V.

Counterclockwise direction: connect pin 5 to + V.

Reset to zero

The Reset input enables the encoder to be set to the zero position.

It is actuated by applying an 11 to 30 Vdc supply to pin 6, while the shaft is stopped, for the following times:

- Over 100 ms for XCC3506, XCC3510 and XCC3912,
- Over 1 s for XCC3930T.

Following a reset to zero, the pin 6 connection must be re-established to 0 V.

Note: In environments subject to electrical interference, we recommend grounding the encoder base using one of the mounting screws.

Ø 58 mm and Ø 90 mm encoders

Connection accessories

Operating temperature

Pin number

2

3

4

6

Connector version multi-turn absolute encoders



0 to + 50 °C (+ 32 to + 122 °F)

The deserialization connecting cable XCCRM23SUB37●● (see page 9/11) enables conversion,

36 x 0.14 mm² shielded cable and SUB-D 37-pin end connector connections

Signal 20 (LSB)

21

2³

25

1 2	2 ;	3 4	4 !	5 (ĵ	7	8 9	9 1	0 1	1 1	2	13	14	15	1	6 1	7 1	8 19	$\sum_{i=1}^{n}$
																		37	$^{\prime \circ}$

Male connector (pin view)

■ Selection of code progression direction

The Direction input enables the code progression to match the rotational direction of the encoder shaft (clockwise or counterclockwise).

Clockwise direction: connect pin 30 to an 11 to 30 Vdc supply. Counterclockwise direction: connect pin 30 to 0 V.

■ Reset to zero

The Reset input enables the encoder to be set to the zero position. It is actuated by applying an 11 to 30 Vdc supply to pin 27 for more than 1 second.

■ Encoder selection

The Select input enables encoder selection when several units are connected in parallel on the same data bus. Encoder selected: apply 0 V potential to pin 28. Encoder not selected: apply 11 to 30 Vdc to pin 28.

■ Data locking

The Latch input, particularly useful for high speed applications, enables the freezing of the encoder data output while reading the code.

Function not actuated: apply 0 V potential to pin 29. Function actuated: apply 11 to 30 Vdc to pin 29.

1	2
8	2 ⁷
9	28
10	2 ⁹
11	2 ¹⁰
12	211
13	2 ¹²
14	2 ¹³
15	214
16	2 ¹⁵
17	2 ¹⁶
18	217
19	2 ¹⁸
20	219
21	2 ²⁰
22	2 ²¹
23	2 ²²
24	2 ²³
25	2 ²⁴ (MSB)
26	R
27	Reset to zero
28	Select
29	Latch
30	Direction (1)
31, 32, 33, 34, 35	R

+ V

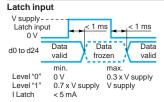
0 V

R = Reserved; do not connect

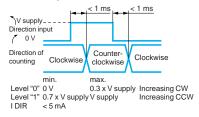
(1) (*) : clockwise direction, *\ \) : counterclockwise direction.

Note: In environments subject to electrical interference, we recommend grounding the encoder base using one of the mounting screws.

Wiring diagrams

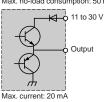


Direction input



Push-Pull

Supply: 11 to 30 V
Max. ripple: 500 mV
Protection against reverse polarity
Max. no-load consumption: 50 mA (30 mA typical on 24 V)

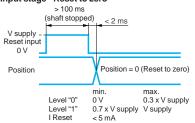


36 37

Level "0" max.: 1.5 V Level "1" min.: V supply - 2.5 V Protection against short-circuits NPN/PNP compatible

Select input V supply Select input < 1 ms 0 V Data d0 to d24 valid impeded min 0.3 x V supply Level "0" Level "1" 0.7 x V supply I Select $< 5 \, \text{mA}$

Input stage - Reset to zero



Note: The Latch and Select inputs must be connected to 0 V to become active.

OsiSense® XCC Rotary encoders

Connection accessories







XCCRM23SUB37PG



XCCPM23161L2

Cables Description	For encoders	Number of wires/c.s.a.	Ø mm	Catalog number	Weight kg (lbs)
Shielded cables with	Incremental	10 wires/0.14 mm ²	6	XCCRX10	5.000 (11.023)
twisted pairs Length: 100 m	Absolute, single turn //	16 wires/0.14 mm ²	6.8	XCCRX16	5.600 (12.346)
UL/CSA	Absolute, single turn and multi-turn SSI, and incremental	1 pair of 0.50 mm ² wires and 3 pairs of 0.14 mm ² wires	8.6	XCCRXS8	11.750 (25.904)

Connectors					
Description	For use with	Number of pins	Туре	Catalog number	Weight kg (lbs)
M23 female connectors	Encoders Incremental, absolute SSI	12	Straight	XZCC23FDP120S	0.040 (0.088)
	Absolute encoders, single turn parallel	16	Straight	XZCC23FDP160S	0.040 (0.088)
Connector kit 1 female + 1 male	SSI jumper cable or incremental encoders	_	_	XZCC23FMDP120S	0.090 (0.198)
SUB-D 37-pin female connector	Absolute encoders, multi-turn parallel	37	Straight	XZCCHFDM370S	0.115 (0.254)

Tomato comitotor	maia tam paranoi			
Deserialization	jumper cables (1)			
Description	Туре		Catalog number	Weight kg (lbs)
	SSI Gray//Gray PNP (PG)		XCCRM23SUB37PG	0.225 (0.496)
jumper cables, straight M23, cable length 0.5 m	SSI Gray//Gray NPN (NG)		XCCRM23SUB37NG	0.225 (0.496)
	SSI Binary//Binary PNP (PB)		XCCRM23SUB37PB	0.225 (0.496)
icrigar 0.5 m	SSI Binary//Binary NPN (NB)		XCCRM23SUB37NB	0.225 (0.496)
Pre-wired conn				
Description	Number of wires	Length	Catalog number	Weight kg (lbs)
M23 F	8 wires	2 m	XCCPM23122L2	0.190 (0.419)
straight	Absolute SSI	5 m	XCCPM23122L5	0.470 (1.036)
		10 m	XCCPM23122L10	0.900 (1.036)
	10 wires	2 m	XCCPM23121L2	0.160 (0.353)
	Incremental	5 m	XCCPM23121L5	0.330 (0.728)
		10 m	XCCPM23121L10	0.620 (1.367)
	16 wires	2 m	XCCPM23161L2	0.175 (0.386)

5 m

10 m

XCCPM23161L5

XCCPM23161L10

Absolute single turn //

Pre-wired connector connections								
XCCPM	l23122L●		XC					
Pin	Function	Color	Pin					
1	0V	BK	1					
2	Data (+)	BN	2					
3	Clk (+)	GN	3					
4	R	_	4					
5	\circ	VT	5					
6	Reset	BU	6					
7	R	_	7					
8	+ V	RD	8					
9	R	_	9					
10	Data (-)	OG	10					
11	Clk (-)	YE	11					
12	R	_	12					

XCCPM231	21L●		
Pin	Function	Color	
1	A/	BN	
2	V Supply	RD	
3	Top 0	VT	
4	Top 0/	BU	
5	В	YE	
6	B/	OG	
7	R	_	
8	Α	GN	
9	R	_	
10	Gnd	BK	
11	Gnd	WH	
12	V Supply	GY	

Pin	Function	Color
1	Gnd	WH
2	V Supply	BN
3	d0	GN
4	d1	YE
5	d2	GY
6	d3	OG
7	d4	BU
8	d5	RD
9	d6	BK
10	d7	VT
11	d8	WH/BN
12	d9	WH/GN
13	d10	WH/YE
14	d11	WH/BK
15	d12	WH/OG
16	\circ	WH/RD

Direction of rotation for pin 5







R: reserved; do not connect



7 16 •]



0.415 (0.915)

0.790 (1.742)

⁽¹⁾ See Overview, page 9/4 and Connections, page 9/32.

OsiSense® XCC Rotary encoders

Mounting and installing accessories

01 (4 11	***		
	gs with spring (1)		
Maximum torque		N•cm	300 (424.83 oz.in.)
Maximum angular m	isalignment		5°
Maximum radial mis	alignment	mm	±1.5
Materials	Collars		Zamak
	Spring		Nickel plated steel
Compression/Expan	sion	mm	±1 max.
Homokinetic ((flexible) shaft couplings	with bello	ws
Maximum torque		N•cm	80 (113.29 oz.in.)
Maximum angular misalignment			4°
Maximum lateral mis	salignment	mm	±0.3
Maximum axial misa	lignment	mm	±0.5
Materials	Bellows		Stainless steel
	Mounting collar		Aluminium
	Screws		Stainless steel
Elastic monol	oloc shaft couplings		
Maximum torque		N•cm	20 (28.32 oz.in.)
Maximum angular m	isalignment		±2.5°
Maximum radial misa	alignment	mm	±0.3
Compression/Expan	sion	mm	± 2 max.
Materials			Glass fiber reinforced polyamide

⁽¹⁾ Not recommended for resolutions higher than 500 points.

Catalog numbers



XCCRAR•••



XCCRAS••••





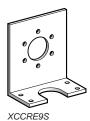
	•	ith solid shaft)		
Туре		Bore diameter (machine side)	Catalog number	Weigh kg (lbs
With spring (1)	6 mm	6 mm	XCCRAR0606	0.125 (0.27
		8 mm	XCCRAR0608	0.125 (0.27
		10 mm	XCCRAR0610	0.125 (0.27
		12 mm	XCCRAR0612	0.120 (0.26
		14 mm	XCCRAR0614	0.120 (0.26
		16 mm	XCCRAR0616	0.120 (0.26
	10 mm	8 mm	XCCRAR1008	0.120 (0.26
		10 mm	XCCRAR1010	0.120 (0.26
		12 mm	XCCRAR1012	0.110 (0.24
		14 mm	XCCRAR1014	0.110 (0.24
		16 mm	XCCRAR1016	0.105 (0.23
	12 mm	8 mm	XCCRAR1208	0.110 (0.24
		12 mm	XCCRAR1212	0.110 (0.24
		14 mm	XCCRAR1214	0.105 (0.23
		16 mm	XCCRAR1216	0.100 (0.22
Homokinetic	6 mm	6 mm	XCCRAS0606	0.020 (0.04
flexible) with		8 mm	XCCRAS0608	0.020 (0.04
pellows		10 mm	XCCRAS0610	0.020 (0.04
		12 mm	XCCRAS0612	0.015 (0.03
	10 mm	8 mm	XCCRAS1008	0.015 (0.03
		10 mm	XCCRAS1010	0.015 (0.03
		12 mm	XCCRAS1012	0.015 (0.03
	12 mm	8 mm	XCCRAS1208	0.010 (0.02
		12 mm	XCCRAS1212	0.010 (0.02
Elastic, monobloc	6 mm	6 mm	XCCRAE0606	0.010 (0.02

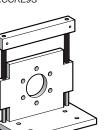
⁽¹⁾ Not recommended for resolutions higher than 500 points.

OsiSense® XCC Rotary encoders

Mounting and installing accessories







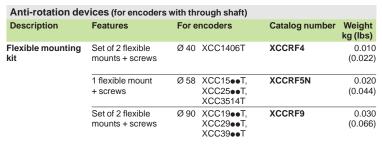




XCCR158RDA08



XCCRG•



	stalling accessories (for encoders with s		
Description	For encoders	Catalog number	Weight kg (lbs)
Set of 3 eccentric clamps	XCC15••P, XCC25••P, XCC35••P	XCCRG5	0.010 (0.022)
+ 3 mounting screws (1) + 3 washers	XCC1912P, XCC2912P, XCC3912P	XCCRG9	0.030 (0.066)
Plain brackets for Ø 58 (2)	XCC1506, XCC2506	XCCRE5S	1.300 (2.866)
	XCC1510P, XCC2510P, XCC3510P	XCCRE5SN	0.130 (0.286)
Plain brackets for Ø 90 (2)	XCC1912P, XCC2912P, XCC3912P	XCCRE9SN	0.290 (0.639)
Brackets with play compensator (2)	XCC1510P, XCC2510P, XCC3510PS••S••	XCCRE5RN	0.345 (0.761)
	XCC1912P, XCC2912P, XCC3912P	XCCRE9RN	0.890 (1.962)
Collar for synchro mounting, for Ø 58 (2)	XCC1510P, XCC2510P, XCC3510P	XCCRB1	0.040 (0.088)
Substitution interface collar for Ø 90 (2)	XCC1912P, XCC2912P, XCC3912P	XCCRB2	0.175 (0.386)
IP 67 sealed collar for Ø 58 (2)	XCC1510P, XCC2510P, XCC3510PS••S•N	XCCRB3	0.030 (0.066)

	with			kg (lbs)
Reduction collars	Incremental encoders Ø 58 Absolute single turn encoders Ø 58 Absolute multi-turn encoders Ø 58	14 to 6	XCCR158RDA06	0.015 (0.033)
		14 to 8	XCCR158RDA08	0.010 (0.022)
		14 to 10	XCCR158RDA10	0.010 (0.022)
		14 to 12	XCCR158RDA12	0.015 (0.033) 0.010 (0.022) 0.010 (0.022) 0.010 (0.022) 0.060 (0.132) 0.030 (0.066) 0.020 (0.044) 0.048
	Incremental encoders Ø 90 Absolute single turn	30 to 12	XCCR290RDP12	0.060
	encoders Ø 90	30 to 20	XCCR290RDP20	
		30 to 25	XCCR290RDP25	
	Absolute multi-turn encoders Ø 90	30 to 16	XCCR390RDP16	
		30 to 20	XCCR390RDP20	0.020



^{(1) 3} M3 x 12 screws for XCCRG5, 3 M4 x 25 screws for XCCRG9.

Reduction collars for encoders with through shaft

For use

Description

Reduction Catalog number Weight

9

(0.705)

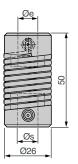
⁽²⁾ Screws included with brackets and collars.

OsiSense® XCC Rotary encoders

Accessories

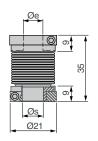


XCCRAR••••



XCC	Øe	Øs	
RAR0606	6	6	
RAR0608	6	8	
RAR0610	6	10	
RAR0612	6	12	
RAR0614	6	14	
RAR0616	6	16	
RAR1008	10	8	
RAR1010	10	10	
RAR1012	10	12	
RAR1014	10	14	
RAR1016	10	16	
RAR1208	12	8	
RAR1212	12	12	
RAR1214	12	14	
RAR1216	12	16	

XCCRAS••••



XCC	Øe	Øs	
RAS0606	6	6	
RAS0608	6	8	
RAS0610	6	10	
RAS0612	6	12	
RAS1008	10	8	
RAS1010	10	10	
RAS1012	10	12	
RAS1208	12	8	
RAS1212	12	12	

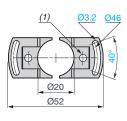


XCCRAE0606

Anti-rotation devices (flexible mounting kit)

XCCRF4

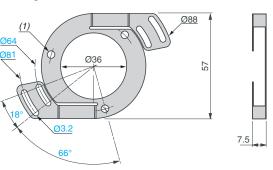
Mounting on Ø 40 mm encoder XCC1406T





XCCRF5N

Mounting on Ø 58 mm encoders XCC1514T, XCC2514T and XCC3514T

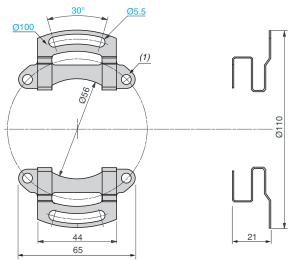


(1) 2 holes Ø 4 at 180° on 30 PCD. TC M4 x 5 screw mounts.

(1) 3 holes Ø 4.1 at 120° on 48 PCD. TC M3 x 6 screw mounts.

XCCRE

Mounting on Ø 90 mm encoders XCC1930T, XCC2930T and XCC3930T



(1) 4 holes Ø 5.2 at 90° on 78 PCD. TH M5 x 6 screw mounts.

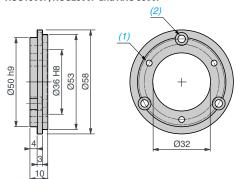
OsiSense® XCC Rotary encoders

Accessories

Collar kits

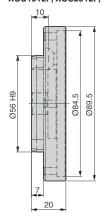
XCCRB1

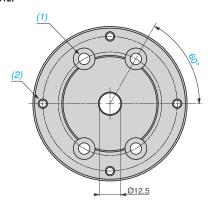
Collar for synchro mounting, for Ø 58 encoders: XCC15eeP, XCC25eeP and XXC 35eeP



XCCRB2

Interface collar for Ø 90 encoders: XCC1912P, XCC2912P, XCC3912P

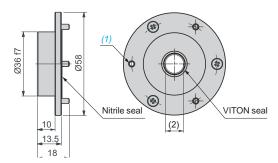




- (1) 3 holes M4 x 0.7 at 120° on 42 PCD. TC M3 x 8 screw mounts.
- (2) 3 counterbored holes for TC M4 x 8 screws at 120° on 48 PCD.

XCCRB3

IP 67 sealed collar for Ø 58 encoders: XCC1510P, XCC2510P and XCC3510PS••S•N

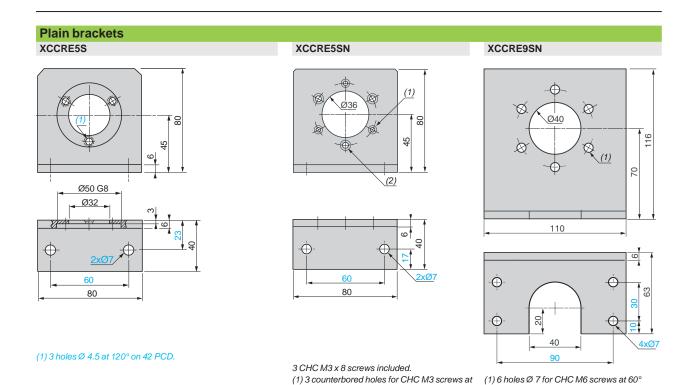


(1) 4 holes Ø 6.6 at 120° on 60 PCD. Countersunk for TZ M6 x 16 screws. (2) 4 holes M5 x 0.8 at 90° on 78 PCD.

- (1) 3 holes M3 x 0.5 at 120° on 48 PCD. TZ M3 x 8 screw mounts.
- (2) Shaft Ø 10 mm.

OsiSense® XCC **Rotary encoders**

Accessories



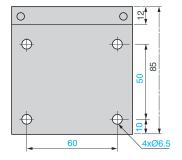
Brackets with play compensator XCCRE5RN

Ø31.8 <u>(2)</u> Ø 48

•

유

• (1)



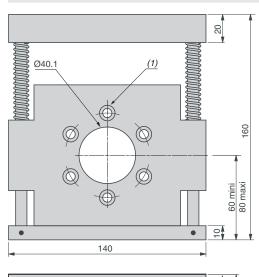
80

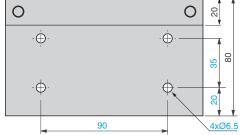
CHC M3 x 12 screws included (1) 3 counterbored holes for CHC M3 screws at 120° on 48 PCD. (2) 3 counterbored holes for CHC M4 screws at 120° on 48 PCD.

XCCRE9RN

120° on 48 PCD.

(2) 3 counterbored holes for CHC M4 screws at 120° on 48 PCD.





(1) 6 counterbored holes for CHC M6 screws at 120° on 60 PCD.

Schneider Electric

OsiSense® XCC Rotary encoders

Accessories

Reduction collars for through shaft

XCCR158RDA ••

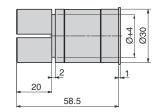
For Ø 58 incremental and absolute single turn and multi-turn encoders $\,$





XCCR290RDP●●

For Ø 90 incremental and absolute single turn encoders



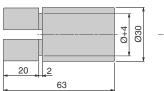


XCC	Ø	
R158RDA06	6	
R158RDA08	8	
R158RDA10	10	
R158RDA12	12	

XCC	Ø	
R290RDP12	12	
R290RDP20	20	
R290RDP25	25	

XCCR390RDP••

For Ø 90 absolute multi-turn encoders





XCC	Ø	
R390RDP16	16	
R390RDP20	20	
R390RDP25	25	

For Encoders with CANopen and PROFIBUS-DP fieldbus, contact the Sensor Competency Center at 1-800-435-2121.