

#### **Single Axis Electric Actuator**

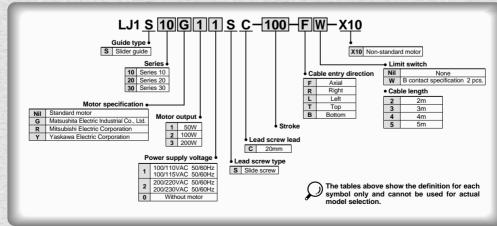
# Series LJ1S

#### Slider Guide

SHELLER	Series	Motor type	Guide type	Mounting orientation	Model	Lead screw lead mm Slide screw	Page
					LJ1S10	20	88
MARSHA		Standard motor	Slider guide	Horizontal	LJ1S20	20	90
	LJ1S	motor			LJ1S30	20	92
Ħ	LJIJ				LJ1S10	20	94
9		Standard motor			LJ1S20	20	96
8					LJ1S30	20	98

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TSUBAKI CABLEVEYOR specification —————	128
■ Construction —	137
■ Mounting ———	140
■ Non-standard Motor Mounting ————	143
■ Deflection Data ————	145

#### **Part Number Designations**





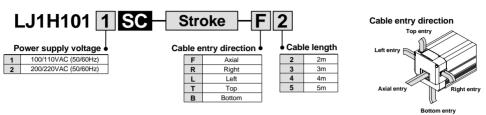
# Series LJ1S10



Slider Guide



#### How to Order



#### **Specifications**

	Standard stroke	mm	100	200	300	400	500	600	700	800	900	1000		
	Body weight	kg	5.4	6.1	6.9	7.7	8.5	9.3	10.0	10.8	11.6	12.4		
	Operating temperature range	°C	5 to 40 (with no condensation)											
Performance	Work load	kg	5											
	Rated thrust	N	24											
	Maximum speed	mm/s	300											
	Positioning repeatability	mm	±0.1											
	Motor					A	C servom	otor (50V	V)					
	Encoder		Incremental system											
Main parts	Lead screw		Slide screw ø20mm, 20mm lead											
	Guide	Slider guide												
	Motor/Screw connection	With coupling												
Controller	Model			LC1-1B1S□-□□ (Refer to page 185 for details.)										

#### Intermediate strokes

For manufacture of strokes other than the standard strokes above, add "-X2" at the end of the part number.

Applicable strokes: 150, 250, 350, 450, 550, 650, 750, 850, 950

Example) LJ1S1011SC-150-F2-X2

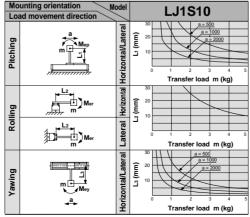
#### Allowable Moment (N·m)

#### Allowable static moment

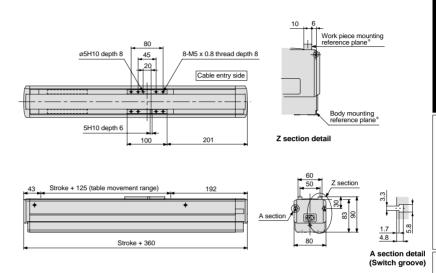
Pitching	1.3
Rolling	1.5
Yawing	0.7

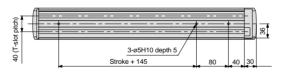
- m : Transfer load (kg)
- a : Work piece acceleration (mm/s²) Me: Dynamic moment
- L : Overhang to work piece center of gravity (mm)

#### Allowable dynamic moment



Refer to page 145 for deflection data.







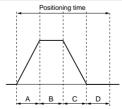
T-slot dimensions

\* The body mounting reference plane and work piece mounting reference plane should be used as standards when mounting onto equipment. Refer to pages starting with 140 for mounting.

#### **Positioning Time Guide**

			Positioning time (sec.)										
Positioning distance (mm)		1	10	100	500	1000							
	10	0.5	1.4	10.4	50.4	100.4							
Speed	100	0.4	0.5	1.4	5.4	10.4							
(mm/s)	150	0.4	0.5	1.1	3.8	7.1							
	300	0.4	0.5	0.8	2.2	3.8							

<sup>\*</sup> Values will vary slightly depending on the operating conditions.



- A: Acceleration time
- B: Constant velocity time
- C: Deceleration time
- D: Resting time (0.1sec.)
- Maximum acceleration: 2000mm/s<sup>2</sup>

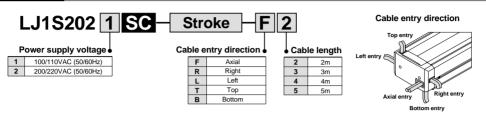


# Series LJ1520





#### How to Order



#### **Specifications**

	Standard stroke	mm	100	200	300	400	500	600	700	800	900	1000	1200	
	Body weight	kg	6.8	7.9	9.0	10.1	11.1	12.2	13.3	14.3	15.4	16.4	18.6	
	Operating temperature range	°C				5 to	o 40 (wit	h no con	densatio	on)				
Performance	Work load	kg	10											
remormanoe	Rated thrust	N	50											
	Maximum speed	mm/s	300											
	Positioning repeatability	mm	±0.1											
	Motor		AC servomotor (100W)											
	Encoder		Incremental system											
Main parts	Lead screw	Slide screw ø20mm, 20mm lead												
	Guide	Slider guide												
	Motor/Screw connection	With coupling												
Controller														

#### Intermediate strokes

For manufacture of strokes other than the standard strokes above, add "-X2" at the end of the part number.

Applicable strokes:150, 250, 350, 450, 550, 650, 750, 850, 950, 1050

Example) LJ1S2021SC-150-F2-X2

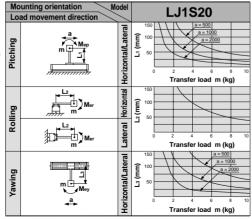
#### Allowable Moment (N·m)

#### Allowable static moment

Pitching	5.5
Rolling	6.0
Yawing	8.5

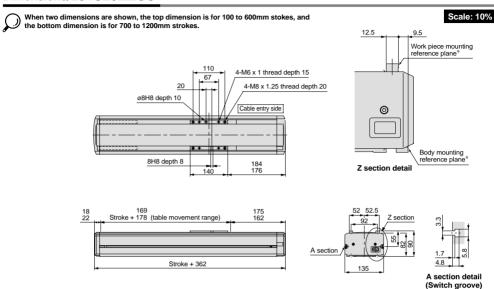
- m : Transfer load (kg)
- : Work piece acceleration (mm/s2)
- Me: Dynamic moment
- L : Overhang to work piece center of gravity (mm)

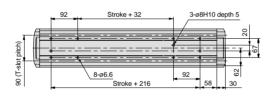
#### Allowable dynamic moment



Refer to page 145 for deflection data.

#### Dimensions/LJ1S202 C





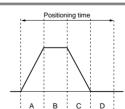


\* The body mounting reference plane and work piece mounting reference plane should be used as standards when mounting onto equipment. Refer to pages starting with 140 for mounting.

#### **Positioning Time Guide**

		Positioning time (sec.)										
Positioning distance (mm)		1	10	100	600	1200						
	10	0.6	1.5	10.5	60.5	120.5						
Speed (mm/s)	100	0.5	0.6	1.5	6.5	12.5						
(mm/s)	150	0.5	0.6	1.2	4.5	8.5						
	300	0.5	0.6	0.9	2.6	4.6						

<sup>\*</sup> Values will vary slightly depending on the operating conditions.



- A: Acceleration time
- B: Constant velocity time
- C: Deceleration time
- D: Resting time (0.4sec.)
- Maximum acceleration: 2000mm/s<sup>2</sup>



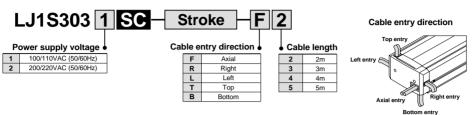
# Series LJ1530







#### How to Order



#### **Specifications**

	Standard stroke	mm	200	300	400	500	600	800	1000	1200	1500			
	Body weight	kg	14.4	16.2	18.0	19.8	21.5	25.7	29.7	33.3	38.7			
	Operating temperature rang	e °C	5 to 40 (with no condensation)											
Performance	Work load	kg					20							
renormance	Rated thrust	N	50											
	Maximum speed	mm/s	300											
	Positioning repeatability	mm	±0.1											
	Motor		AC servomotor (200W)											
	Encoder		Incremental system											
Main parts	Lead screw		Slide screw ø25mm, 20mm lead											
•	Guide		Slider guide											
	Motor/Screw connection		With coupling											
Controller	Model			LC1-1B3S□-□□ ( Refer to page 185 for details.)										

#### Intermediate strokes

For manufacture of strokes other than the standard strokes above, add "-X2" at the end of the part number. Applicable strokes: 250, 350, 450, 550, 650, 700, 750, 850, 900, 950, 1050, 1100, 1150, 1250, 1300, 1350, 1400, 1450 Example) LJ1S3031SC-250-F2-X2

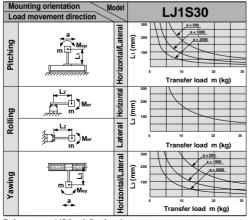
#### Allowable Moment (N·m)

#### Allowable static moment

Pitching	26.6
Rolling	40.2
Yawing	25.8

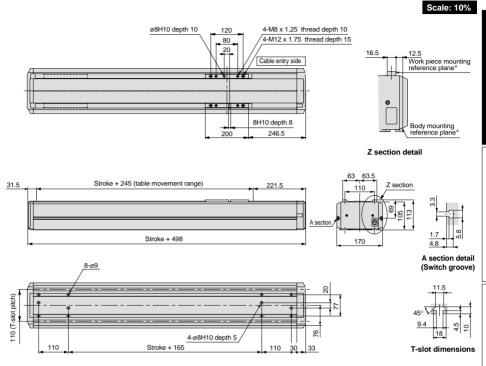
- m : Transfer load (kg)
- a : Work piece acceleration (mm/s²)
- Me: Dynamic moment
- L : Overhang to work piece center of gravity (mm)

#### Allowable dynamic moment



Refer to page 145 for deflection data.

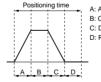
#### Dimensions/LJ1S303□SC



<sup>\*</sup> The body mounting reference plane and work piece mounting reference plane should be used as standards when mounting onto equipment. Refer to pages starting with 140 for mounting.

#### **Positioning Time Guide**

			Positi	oning time	(sec.)	
Positioning of	listance (mm)	1	10	100	750	1500
	10	0.5	2.1	11.1	76.1	151.1
Speed (mm/s)	100	1.1	1.2	2.1	8.6	16.1
(mm/s)	500	1.1	1.2	1.6	4.2	7.2
	1000	1.1	1.2	1.5	2.8	4.3



- A: Acceleration time
- B: Constant velocity time
- C: Deceleration time D: Resting time (0.4sec.)

<sup>\*</sup> Values will vary slightly depending on the operating conditions.

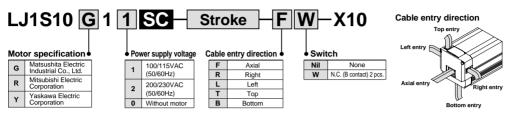
# Series LJ1S10







#### How to Order



#### **Specifications**

	Standard stroke	mm	100	200	300	400	500	600	700	800	900	1000			
	Body weight (without motor)	kg	5.0	5.7	6.5	7.3	8.1	8.9	9.6	10.4	11.2	12.0			
	Operating temperature range	°C		•		5 to 40	) (with no	condens	ation)						
Performance	Work load	kg		5											
	Maximum speed	mm/s	300												
	Positioning repeatability	mm	±0.1												
	Motor AC servomotor (50W)														
	Encoder		Incremental system												
Main parts	Lead screw	Slide screw ø20mm, 20mm lead													
	Guide	de				Slider guide									
	Motor/Screw connection	With coupling													
	Model	D-Y7GL													
Switch	Specifications	Power supply voltage: 4.5 to 28VDC, Current consumption: 10mA or less Control output: Open collector, Load current: 40mA or less, Internal voltage drop: 1.5V or less													

#### Intermediate strokes

Strokes other than the standard strokes above are available by special order. Consult SMC.

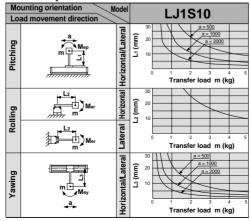
#### Allowable Moment (N·m)

#### Allowable static momen

	••
Pitching	1.3
Rolling	1.5
Yawing	0.7

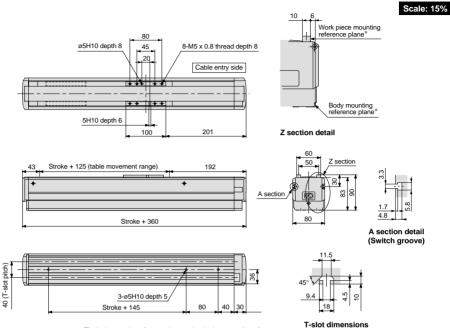
- m : Transfer load (kg)
- a : Work piece acceleration (mm/s²)
- Me: Dynamic moment
- : Overhang to work piece center of gravity (mm)

#### Allowable dynamic moment

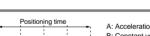


Refer to page 145 for deflection data

#### Dimensions/LJ1S10 1 SC(X10)



\* The body mounting reference plane and work piece mounting reference plane should be used as standards when mounting equipment. Refer to pages starting with 140 for mounting.

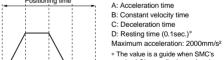


В С D

#### Positioning time (sec.) Positioning distance (mm) 10 100 1000 1 10 0.5 1 4 10.4 50.4 100 4 100 1.4 10.4 Speed (mm/s) 150 0.5 1 1 3.8 7 1 0.4 300 0.4 0.5 0.8 2.2 3.8

\* Values will vary slightly depending on the operating conditions.

**Positioning Time Guide** 



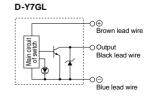
series LCI controller is used and may vary depending on the driver capacity.

#### Non-standard Motors: The following motors will be mounted when a motor mounted type is specified.

	Motor output (W)	Power supply voltage (VAC)	Motor model	Compatible driver model
Matsushita Electric	50	100/115	MOMEATOAA	MSD5A1P1E
Industrial Co., Ltd.	50	200/230	MSM5AZP1A	MSD5A3P1E
Mitsubishi Electric	50	100/115	LIO DOOFO	MR-C10A1
Corporation	50	200/230	HC-PQ053	MR-C10A
Yaskawa Electric	F0	100/115	SGME-A5BF12	SGDE-A5BP
Corporation	50	200/230	SGME-A5AF12	SGDE-A5AP

- \* For motor mounting dimensions, refer to the dimensions for series LJ1H10 on page 143 as a reference for mounting and design.
- \* Refer to pages starting with 205 for driver dimensions, etc. Furthermore, for detailed specifications, etc., contact each motor manufacturer.
- \* For a non-standard motor specification, when the motor is mounted before shipping, the driver is included but the cable that connects the motor and driver is optional. Refer to page 100 for part numbers

#### **Switch Internal Circuit**



# LC6D/LC6C | Switches



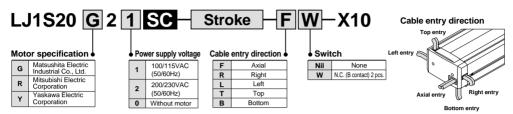
#### **Horizontal Mount**

# Series LJ1520





#### How to Order



#### **Specifications**

	Standard stroke	mm	100	200	300	400	500	600	700	800	900	1000	1200
	Body weight (without motor)	kg	6.3	7.4	8.5	9.6	10.6	11.7	12.8	13.8	14.9	15.9	18.1
	Operating temperature range °C					5 to	o 40 (wit	h no cor	densatio	on)			
Performance	Work load	kg	10										
	Maximum speed	eed mm/s 300											
	Positioning repeatability mm ±0.1												
	Motor				AC serv	omotor/	(100W)						
	Encoder		Incremental system										
Main parts	Lead screw		Slide screw ø20mm, 20mm lead										
	Guide		Slider guide										
	Motor/Screw connection		With coupling										
	Model		D-Y7GL										
Switch	Switch Specifications		Power supply voltage: 4.5 to 28VDC, Current consumption: 10mA or less Control output: Open collector, Load current: 40mA or less, Internal voltage drop: 1.5V or less										

#### Immediate strokes

Strokes other than the standard strokes above are available by special order. Consult SMC.

#### Allowable Moment (N·m)

#### Allowable static moment

Pitching	5.5
Rolling	6.0
Yawing	8.5

- m : Transfer load (kg)
- a : Work piece acceleration (mm/s2)
- Me: Dynamic moment
- L : Overhang to work piece center of gravity (mm)

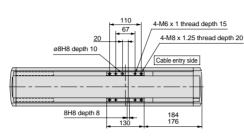
## Allowable dynamic moment Mounting orientation LJ1S20 Load movement direction Transfer load m (kg) -2 (mm) Rolling Transfer load m (kg) Transfer load m (kg)

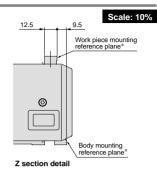
Refer to page 145 for deflection data.

#### Dimensions/LJ1S20 2 SC(X10)

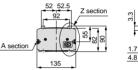


When two dimensions are shown, the top dimension is for 100 to 600mm stokes. and the bottom dimension is for 700 to 1200mm strokes.

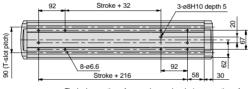














\* The body mounting reference plane and work piece mounting reference plane should be used as standards when mounting onto equipment. Refer to pages starting with 140 for mounting.

Positioning time

В С

T-slot dimensions

#### **Positioning Time Guide**

		Positioning time (sec.)						
Positioning distance (mm)		1	10	100	500	1000		
	10	0.6	1.5	10.5	50.5	120.5		
Speed (mm/s)	100	0.5	0.6	1.5	6.5	12.5		
(mm/s)	150	0.5	0.6	1.2	4.5	8.5		
	300	0.5	0.6	0.9	2.6	4.6		

<sup>\*</sup> Values will vary slightly depending on the operating conditions.

#### A: Acceleration time

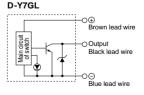
- B: Constant velocity time
- C: Deceleration time
- D: Resting time (0.4sec.)\*
- Maximum acceleration: 2000mm/s<sup>2</sup> \* The value is a guide when SMC's series LCI controller is used and may vary depending on the driver capacity.

#### Non-standard Motors: The following motors will be mounted when a motor mounted type is specified.

	Motor output (W)	Power supply voltage (VAC)	Motor model	Compatible driver model
Matsushita Electric	400	100/115	MSM011P1A	MSD011P1E
Industrial Co., Ltd.	100	200/230	MSM012P1A	MSD013P1E
Mitsubishi Electric	400	100/115	HC-PQ13	MR-C10A1
Corporation	100	200/230	HC-PQ13	MR-C10A
Yaskawa Electric	100	100/115	SGME-01BF12	SGDE-01BP
Corporation		200/230	SGME-01AF12	SGDE-01AP

- \* For motor mounting dimensions, refer to the dimensions for series LJ1S20 on page 143 as a reference for mounting and design.
- \* Refer to pages starting with 205 for driver dimensions, etc. Furthermore, for detailed specifications, etc., contact each motor manufacturer.
- \* For a non-standard motor specification, when the motor is mounted before shipping, the driver is included but the cable that connects the motor and driver is optional. Refer to page 100 for part numbers

#### **Switch Internal Circuit**



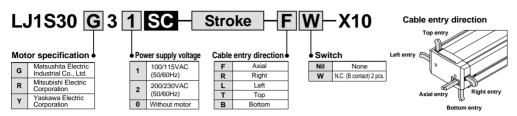
#### Non-standard Motor

#### **Horizontal Mount**

# Series LJ1 S30

Slider Guide **Ground Ball Screw** Ø25mm/20mm lead

#### **How to Order**



#### **Specifications**

	Standard stroke	mm	200	300	400	500	600	800	1000	1200	1500
	Body weight (without motor)	kg	13.3	15.1	16.9	18.7	20.4	24.6	28.6	32.2	37.6
	Operating temperature range °C					5 to 40 (wi	th no cond	densation)	•		•
Performance	Work load kg						20				
	Maximum speed mm/s						300				
	Positioning repeatability mm			±0.1							
	Motor AC servomotor (200W)										
	Encoder		Incremental system								
Main parts	Lead screw		Slide screw ø25mm, 20mm lead								
	Guide		Slider guide								
	Motor/Screw connection		With coupling								
	Model D-Y7GL										
Switch	Switch Specifications		Power supply voltage: 4.5 to 28VDC, Current consumption: 10mA or less Control output: Open collector, Load current: 40mA or less, Internal voltage drop: 1.5V or les						5V or less		

#### Immediate strokes

Strokes other than the standard strokes above are available by special order. Consult SMC.

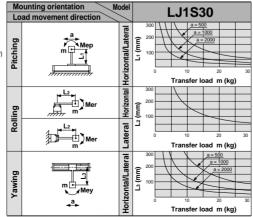
#### Allowable Moment (N·m)

#### Allowable static moment

Pitching	26.6				
Rolling	40.2				
Yawing	25.8				

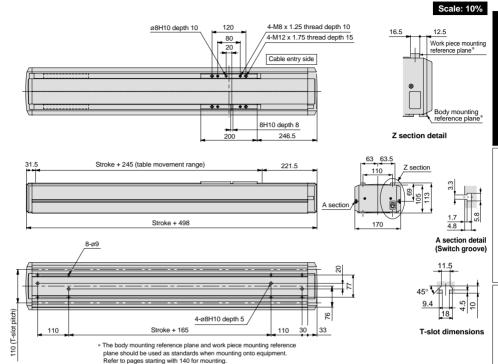
- m : Transfer load (kg)
- a : Work piece acceleration (mm/s²)
- Me: Dynamic moment
- L : Overhang to work piece center of gravity (mm)

#### Allowable dynamic moment



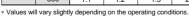
Refer to page 145 for deflection data.

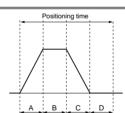
#### Dimensions/LJ1S30 3 SC(X10)



#### **Positioning Time Guide**

			Positioning time (sec.)						
Positioning distance (mm)		1	10	100	750	1500			
	10	0.5	2.1	11.1	76.1	151.1			
Speed (mm/s)	100	1.1	1.2	2.1	8.6	16.1			
(mm/s)	250	1.1	1.2	1.6	4.2	7.2			
	500	1.1	1.2	1.5	2.8	4.3			





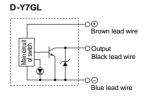
- A: Acceleration time B: Constant velocity time
- C: Deceleration time
- D: Resting time (0.4sec.)\* Maximum acceleration: 2000mm/s<sup>2</sup>
- \* The value is a guide when SMC's series LCI controller is used and may vary depending on the driver capacity.

#### Non-standard Motors: The following motors will be mounted when a motor mounted type is specified.

	Motor output (W)	Power supply voltage (VAC)	Motor model	Compatible driver model
Matsushita Electric	200	100/115	MSM021P1A	MSD021P1E
Industrial Co., Ltd.		200/230	MSM022P1A	MSD023P1E
Mitsubishi Electric		100/115	110 B000	MR-C20A1
Corporation	200	200/230	HC-PQ23	MR-C20A
Yaskawa Electric	askawa Electric	100/115	SGME-02BF12	SGDE-02BP
Corporation	200	200/230	SGME-02AF12	SGDE-02AP

- \* For motor mounting dimensions, refer to the dimensions for series LJ1530 on page 143 as a reference for mounting
- \* Refer to pages starting with 205 for driver dimensions, etc. Furthermore, for detailed specifications, etc., contact each motor manufacturer
- For a non-standard motor specification, when the motor is mounted before shipping, the driver is included but the cable that connects the motor and driver is optional. Refer to page 100 for part numbers.

#### **Switch Internal Circuit**



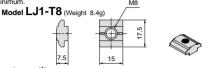
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## Series LJ1

### Options

#### T-nuts for mounting electric actuators

Use T-nuts for T-slot mounting of an actuator. When mounting by means of T-nuts alone, the quantity of nuts indicated below should be used as a



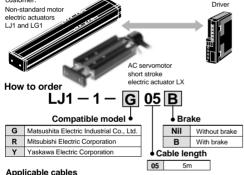
#### T-nut quantity

Model	Quantity			
LJ1g10	200mm stroke or less: 6 pcs.			
	300mm stroke or more: 8 pcs.			
LJ1 <sup>H</sup> 20	8 pcs.			
LJ1H30	8 pcs.			

\* Only series LJ1 10 has the T-nuts built into the body.

#### Non-standard Motor Cables

These are cables for connecting non-standard motors and drivers. Cable lengths other than those shown below should be arranged by the



#### LJ1 (non-standard motor), LXP/LXS (AC servomotor)

( ( ) ( ); <u></u>					
Model	Manufacturer part no.				
LJ1-1-G05*1	MFMCA0050AEB (for motor) MFECA0050EAB (for encoder)				
LJ1-1-G05B	MFECA0050FAB (for motor) MFMCA0050AEB (for encoder) MFMCB0050CET (for brake)				
LJ1-1-R05	(for motor)*2 MR-JCCBL5M (for encoder)				
LJ1-1-Y05*3	DP9320081-2 (for motor) DP9320089-2 (for encoder)				
LJ1-1-Y05B	DP9320083-2 (for motor/brake) DP9320089-2 (for encoder)				

#### LXF (AC servomotor by Mitsubishi Electric Corporation)

Model	Manufacturer part no.								
LJ1-1-RJ-05	MR-JRCBL5M-H (motor/encoder/br	ake)							
•	•								

- \*1 When the Matsushita Electric Industrial Co., Ltd. motor driver is selected, in addition to the cable, a power connector (MOLEX 5569 10R) and an interface connector (Sumitomo/3-M Limited 10126-3000VE) are also required.
- \*2 A cable is not provided for the Mitsubishi Electric Corporation motor and brake, and therefore, the customer should arrange a 4 core, 0.75mm2 electric
- \*3 When the Yaskawa Electric Corporation motor driver is selected, a digital operator and PC are required for selecting the various parameters.
- Please refer to the technical literature of each manufacturer for further details.

#### **Non-standard Motor Driver** Regenerative Absorption Unit/Regenerative Resistor

This is a regenerative absorption unit and regenerative resistor for a nonstandard motor. Make a selection providing an allowance beyond the calculated capacity.

#### How to order



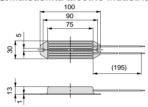
Yaskawa Electric Corporation

#### Applicable types

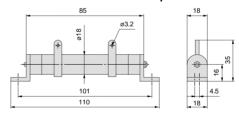
#### LJ1 (non-standard motor), LXP/LXS (AC servomotor)

Model	Manufacturer part no.
LJ1-7-G	DVO P0820
LJ1-7-R	MR-RB013
LJ1-7-Y	JUSP-RG08

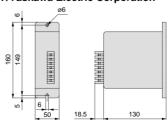
#### LJ1-7-G/Matsushita Electric Industrial Co., Ltd.



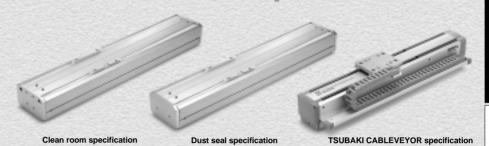
#### LJ1-7-R/Mitsubishi Electric Corporation



#### LJ1-7-Y/Yaskawa Electric Corporation



# Electric Actuator Series LJ1H/LJ1S **Made to Order Specifications**

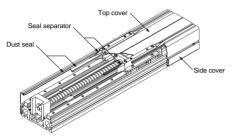


Clean room specification (-X60)	
LJ1H 10/20/30 (Horizontal mount/Vertical mount)	—— Page 104
Dust seal specification (-X70)	
LJ1H 10/20/30 (Horizontal mount/Vertical mount)	110
LJ1S 10/20/30 (Horizontal mount)	116
TSUBAKI CABLEVEYOR specification (-X40)	
LJ1H 10/20/30 (Horizontal mount)	122
LJ1S 10/20/30 (Horizontal mount)	128

# Series LJ1H/LJ1S Made to Order Specifications

#### Clean Room Specification (-X60)

Change of materials, anti-corrosive treatment, use of a special grease, and vacuum cleaning of the inside of the actuator allow operation in a clean room.



#### Particulate Generation Performance

#### Test method

An actuator was placed inside a clean bench and particle concentration was measured at each neighboring point.

Test environment: <Clean bench> Nippon Airtek: VS-1603L

<Size> W x L x H = 620mm x 1550mm x 730mm

<Clean level> Fed-st class 10

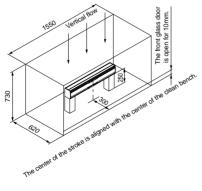
<Down flow velocity> Approx. 0.3m/s

Test equipment: <Test equipment> Laser particle counter

Hitachi Electric Engineering: TS-3500

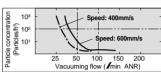
- <Target particle size> 0.17μm or larger
- <Sampling flow rate> 28 Imin (ANR)
- <Sampling time> 1min
- <Holding time> 2min
- <Number of tests> 6

#### Actuator placement and test points

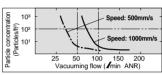


#### Vacuuming Graphs

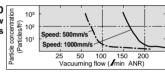




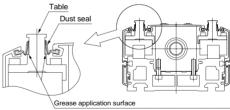
#### LJ1H20 Vacuuming flow characteristics



#### LJ1H30 Vacuuming flow characteristics



#### **Grease Application Areas**



#### (Inner surface of the dust seal and sliding parts of the slider)

#### **⚠** Caution-

#### (1) Maintenance of the greased parts of the dust seal is necessary.

With this specification, a vacuum grease is applied to the sliding parts of the dust seal in order to prevent particulate generation. Maintenance should be performed at 4000km, 4 million reciprocations or within 6 months, whichever occurs

Specified grease: Barrierta IEL/V [fluorine grease (70g) for vacuum equipment manufactured by NOK Kluber]

#### 2 A down flow environment with a flow velocity of 0.3m/s or more is required.

The particulate generation performance of this specification has been tested in the environment shown on the left.

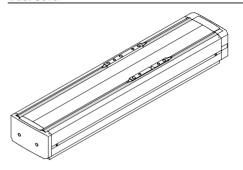
#### **Dust Seal Specification (-X70)**

The dust seal (dust cover) prevents the entry of dust, paper dust and scraps, etc.





#### **Dust Cover**



Note 1) Dust seal material: Polyurethane Consult SMC for details

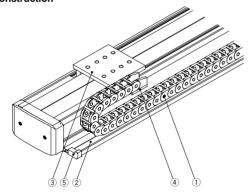
Note 2) Measures for use in an mist environment are not provided.

Also, depending on the environment, it may not be possible to use the dust seal. Consult SMC.

#### TSUBAKI CABLEVEYOR Specification (-X40)

Able to compactly arrange supporting guides for cables and hoses.

#### Construction



#### Parts list

1	No.	Description	Material	Note
	1	TSUBAKI CABLEVEYOR	_	_
	2	Cable side cover	Aluminum alloy	_
	3	Mounting plate	Aluminum alloy	_
Г	4	Cable flange	Aluminum alloy	_
	5	End cap	EP	_

#### Precautions on handling of the TSUBAKI CABLEVEYOR

- 1. When handling, connecting or disconnecting the TSUBAKI CABLEVEYOR:
  - · Wear suitable clothing and appropriate protective gear (safety glasses, gloves, safety shoes, etc.).
  - · Use suitable tools.
  - · Provide support so that the TSUBAKI CABLEVEYOR and parts do not move freely.
- 2. Implement protective measures (safety cover, etc.).
- 3. Be sure to turn off the power and ensure that it cannot be turned on accidentally before installation, removal or maintenance of the equipment.
- 4. In order to prevent secondary accidents, put the surrounding area in good order and operate under safe conditions.
- 5. The total cross-sectional area of the cable inserted into the TSUBAKI CABLEVEYOR should be no more than 60% of the TSUBAKI CABLEVEYOR cross-sectional area.
- 6. The minimum clearance between the cable and TSUBAKI CABLEVEYOR internal width should be "the larger of 10% of the cable O.D. or 2mm"

LJ1<sub>S</sub><sup>H</sup>20

LJ1<sub>S</sub><sup>H</sup>30

#### TSUBAKI CABLEVEYOR cross-sectional dimensions (mm) Series Α В LJ1<sub>s</sub><sup>H</sup>10 10 20



# Example) For LJ1<sub>S</sub><sup>H</sup>10



Correct: 60% or less

ø8 ø8 ø4	
ø4	

10 20

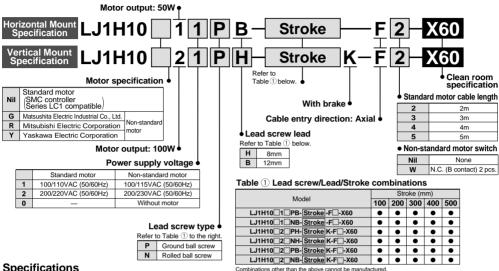
14 40

Incorrect: More than 60%

**High Rigidity Direct Acting Guide Type** Motor Output: 50W/100W

# Series LJ1H10 Clean Room Specification

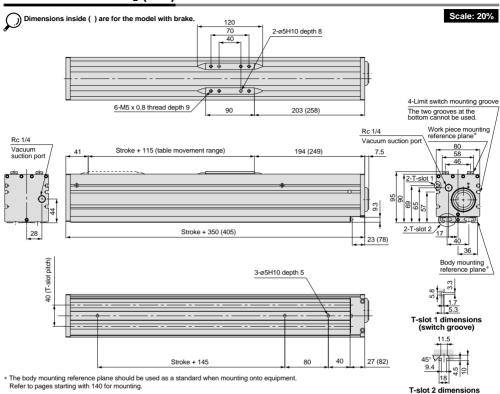
#### How to Order



#### Specifications

Standard stroke mm 100 200 300 400 500 Without With motor (standard) 5 4 62 7.0 77 8.5 brake Without motor (non-standard) 5.0 5.8 6.6 7.3 8.1 Weight kg With motor (standard) 5.9 6.7 7.5 8.2 9.0 With brake 7.1 Without motor (non-standard) 5.5 7.8 8.6 Operating temperature range °C 5 to 40 (with no condensation) Horizontal specification 12mm lead 50W 10 Work load kg Vertical 12mm lead 100W 5 specification 8mm lead 100W 10 Horizontal 12mm lead 50W 600 specification Maximum speed 12mm lead 100W 600 Vertical mm/s specification 8mm lead 100W 400 ±0.05 Positioning Rolled ball screw repeatability mm Ground ball screw +0.02 Horizontal specification AC servomotor (50W) Motor output AC servomotor (100W) with brake Vertical specification Black chroming ø12mm, 12mm lead Rolled ball screw Horizontal specification Ground ball screw ø12mm, 12mm lead Lead Special fluoro resir screw coating and grease Rolled ball screw ø12mm, 12mm/8mm lead Vertical application specification ø12mm, 12mm/8mm lead Ground ball screw Guide High rigidity direct acting guide, Stainless steel rail, AFE grease (made by THK) applied Power supply voltage: 4.5 to 28VDC, Current consumption: 10mA or less Switch Control output: Open collector, Load current: 40mA or less, Internal voltage drop: 1.5V or less Table specification With dust seal Grease for dust seal application Fluorine grease for vacuum equipment made by NOK Kluber Traveling distance of 4000km, 4 million reciprocations, or operation period of 6 months, Grease maintenance schedule Rc 1/4, one each on both axial surfaces Vacuum suction port Seal the unused port with a plug. 50 min (ANR) Suction flow rate

#### Dimensions/LJ1H10□<sup>1</sup><sub>2</sub> (X60)

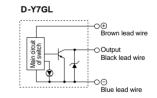


#### **Compatible Motors**

Manufacturer	Motor specification symbol	Brake	Motor output (W)	Power supply voltage (VAC)	Motor model	Controller driver model*
		Without brake		100/110		LC1-1B1H1-□□
SMC controller	Nil	(Horizontal specification)	50	200/220		LC1-1B1H2-□□
LC1 compatible	'*''	With brake	100	100		LC1-1B1V 1-
		(Vertical specification)	100	200		LC1-1B1V□2-□□
Non-standard		Without brake	50	100/115	MSM5AZP1A	MSD5A1P1E
Matsushita Electric Industrial	G	(Horizontal specification)	30	200/230	IVISIVISAZPTA	MSD5A3P1E
	•	With brake	100	100/115	MSM011P1B	MSD011P1E
Co., Ltd. motor		(Vertical specification)	100	200/230	MSM012P1B	MSD013P1E
Non-standard		Without brake	50	100/115	HC-PQ053	MR-C10A1
Mitsubishi Electric	R	(Horizontal specification)		200/230	110-1 0000	MR-C10A
Corporation		With brake	100	100/115	HC-PQ13B	MR-C10A1
motor		(Vertical specification)		200/230	1101 (102	MR-C10A
Non-standard		Without brake	50	100/115	SGME-A5BF12	SGDE-A5BP
Yaskawa Electric	Y	(Horizontal specification)		200/230	SGME-A5AF12	SGDE-A5AP
Corporation		With brake	100	100/115	SGME-01BF12B	SGDE-01BP
motor		(Vertical specification)		200/230	SGME-01AF12B	SGDE-01AP

<sup>\*</sup> Refer to pages starting with 205 for driver dimensions. Furthermore, for detailed specifications, etc., contact each motor manufacturer.

#### **Switch Internal Circuit**



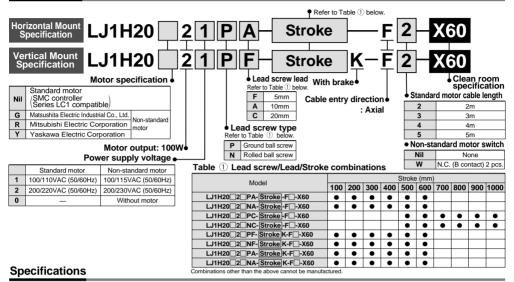
<sup>\*</sup> For a non-standard motor specification when the motor is mounted before shipping, the driver is included but the cable that connects the motor and driver is optional. Refer to page 100 for part numbers

**High Rigidity Direct Acting Guide Type** 

#### Series LJ1 H20 **Motor Output: 100W**

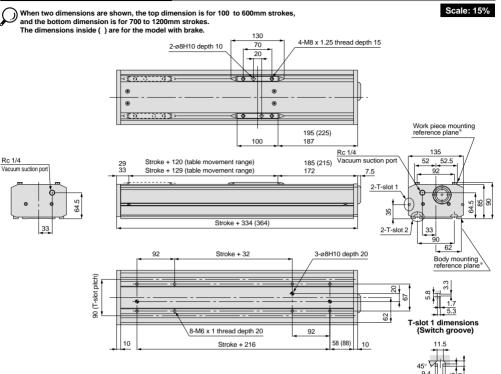
# Clean Room Specification

#### How to Order



	Standa	rd stroke mi	m		100	200	300	400	500	600	700	800	900	1000	
		Without brak	With mo	tor	7.9	9.1	10.3	11.4	12.8	13.9	15.1	16.3	17.5	18.7	
		vvitnout brai	Without	motor	7.4	8.6	9.8	10.9	12.3	13.4	14.6	15.8	17.0	18.2	
Weight	t kg	With brake	With mo	tor	8.6	9.8	11.0	12.1	13.5	14.6		_	_	_	
		vviiii biake	Without	motor	8.1	9.3	10.5	11.6	13.0	14.1		_	17.0	_	
Operati	ing temperatu	re range °C				•	•	5 to 40	(with no	condens	ation)				
		Horizontal	10mm lead				3	0				-	_		
Work Id		specification	20mm lead	1		-	_				•	15			
Work ic	оас кд	Vertical	5mm lead	100W			1	5	•			-	_		
		specification	10mm lead	1				3				-	_		
		Horizontal	10mm lead				5	00				-	_		
Maxim	um speed	specification	20mm lead	100W		-	_		10	00	930	740	600	500	
mm/s		Vertical	5mm lead	10000			2	50				-	_		
		specification	10mm lead				5	00				-	_		
Positio		Rolled ball so	-						±0.						
repeata	ability mm	Ground ball s			±0.02						M				
Motor	Motor output  Horizontal specification								servomo						
WOLOI	output	Vertical speci	ification					AC serv	omotor (1	100W) wit	th brake				
	Black chroming	Horizontal				9		-	_						
Lead	Special fluoro resin		Rolled ball s	screw						Q	ø15mm, 20mm lead				
screw	coating and grease	Vertical	Ground ball	screw			ø15mm,					-	_		
	application	specification					ø15mm,1					orake  grease (made by THK) app asumption: 10mA or less Internal voltage drop: 1.5V or de by NOK Kluber			
Guide					High rig									applied	
Switch															
					Control	output: O	oen collec	tor, Load			ss, Intern	al voltage	drop: 1.5	V or less	
	pecification								With du						
Grease	for dust seal	application													
Grease	maintenance	schedule			Trave	eling dist	ance of						ation per	iod of	
									ns, which						
					Rc 1/4, one each on both axial surfaces Seal the unused port with a plug.										
Vacuum	n suction port	0	F00												
		Stroke.	500mm or I						at either e						
			500mm or i					S	uction at		S				
Suction	n flow rate		500mm/s o						50 min						
		Speed:	500mm/s o	r more					100 mir	i (ANR)					

#### Dimensions/LJ1H20□2 (X60)



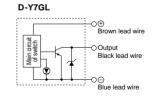
#### **Compatible Motors**

Manufacturer	Motor specification symbol	Brake	Motor output (W)	Power supply voltage (VAC)	Motor model	Controller driver model*	
		Without brake	100	100/110		LC1-1B2H1-□□	
SMC controller		(Horizontal specification)	100	200/220		LC1-1B2H2-□□	
LC1 compatible	Nil	With brake	100	100		LC1-1B2V 1-	
		(Vertical specification)	100	200	_	LC1-1B2V□2-□□	
Non-standard		Without brake	100	100/115	MSM011P1A	MSD011P1E	
Matsushita	G	(Horizontal specification)	100	200/230	MSM012P1A	MSD013P1E	
Electric Industrial		With brake	100	100/115	MSM011P1B	MSD011P1E	
Co., Ltd. motor		(Vertical specification)	100	200/230	MSM012P1B	MSD013P1E	
Non-standard		Without brake	100	100/115	HC-PQ013	MR-C10A1	
Mitsubishi Electric	R	(Horizontal specification)	100	200/230	HC-FQ013	MR-C10A	
Corporation	"	With brake	100	100/115	HC-PQ13B	MR-C10A1	
motor		(Vertical specification)	100	200/230	HC-FQ13B	MR-C10A	
Non-standard		Without brake	100	100/115	SGME-01BF12	SGDE-01BP	
Yaskawa Electric	Y	(Horizontal specification)	100	200/230	SGME-01AF12	SGDE-01AP	
Corporation	'	With brake	100	100/115	SGME-01BF12B	SGDE-01BP	
motor		(Vertical specification)	100	200/230	SGME-01AF12B	SGDE-01AP	

\* The body mounting reference plane should be used as a standard when mounting onto equipment.

#### Switch Internal Circuit

18 T-slot 2 dimensions



<sup>\*</sup> Refer to pages starting with 205 for driver dimensions. Furthermore, for detailed specifications, etc., contact each motor manufacturer.

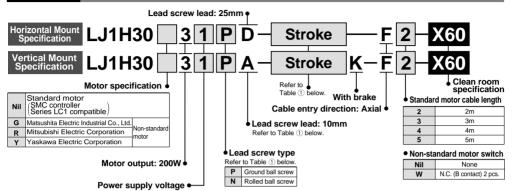
<sup>\*</sup> For a non-standard motor specification when the motor is mounted before shipping, the driver is included but the cable that connects the motor and driver is optional. Refer to page 100 for part numbers.

**High Rigidity Direct Acting Guide Type** 

**Motor Output: 200W** 

# Series LJ1H30 Clean Room Specification

#### How to Order



#### Standard motor Non-standard motor 100/115VAC (50/60Hz) 100/110VAC (50/60Hz) 200VAC (50/60Hz) 200/230VAC (50/60Hz) 2 0 Without motor

Table 1) Lead screw/Lead/Stroke combinations

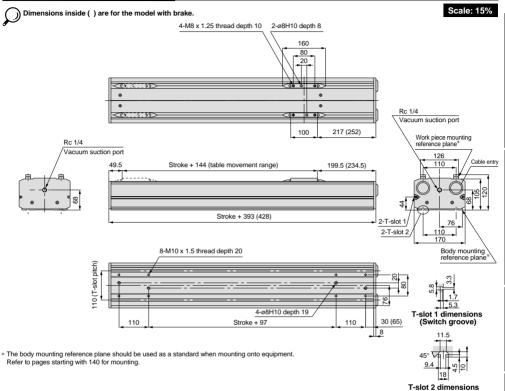
Combinations other than the above cannot be manufactured

Model	Stroke (mm)											
Model	200	300	400	500	600	800	1000	1200	1500			
LJ1H30 3 PD-Stroke-F -X60	•	•	•	•	•	•	•	•	•			
LJ1H30 3 ND-Stroke -F -X60	•	•	•	•	•	•	•	•	•			
LJ1H30 3 PA-Stroke K-F -X60	•	•	•	•	•							
LJ1H30 3 NA-Stroke K-F -X60	•	•	•	•	•							

#### **Specifications**

	Stan	dard stroke m	ım	200	300	400	500	600	800	1000	1200	1500	
			With motor	16.2	18.2	20.2	22.2	24.2	28.7	33.2	37.2	43.2	
	Weight kg  Departing temperat Maximum work load g Maximum speed mm/s Positioning epeatability mm  Motor output  Black chroming spead h Spead fluor resir coating and grease application  Guide	Without brake	Without motor	15.1	17.1	19.1	21.1	23.1	27.6	32.1	36.1	42.1	
weight	: kg		With motor	17.2	19.2	21.2	23.2	25.2	_	_	_		
		With brake	Without motor	16.1	18.1	20.1	22.1	24.1	_		nA or less	_	
Operat	ing temperatu	re range °C		5 to 40 (with no condensation)									
Maxim	um work load	Horizontal specification	25mm lead					60					
kg		Vertical specification	10mm lead 200W			20				_	_		
Maximi	ım speed	Horizontal specification	25mm lead				1000				700	500	
mm/s	ороса	Vertical specification	10mm lead 200W			500		_	_				
		Rolled ball scre	ew					±0.05					
repeata	ability mm	Ground ball sc	rew	±0.02									
Motor	Horizontal specification			AC servomotor (200W)									
		Vertical specific	AC servomotor (200W) with brake										
Lead	Black chroming	Horizontal specification	ø25mm, 25mm lead										
screw	coating and grease	Vertical specification	Ground ball screw	ø20mm, 10mm lead —									
Guide				High rigi	dity direct	acting guid	de, Stainle	ss steel ra	il, AFE gre	DOW) with brake ad  AFE grease (made by THK) app nt consumption: 10mA or less less, internal voltage drop: 1.5V or			
Switch				Control o								5V or less	
Table s	pecification						W	ith dust se	al				
Grease	for dust seal	application			Fluor	ine grease	for vacuu	m equipm	ent made	by NOK K	luber		
Grease	maintenance	schedule		Traveling distance of 4000km, 4 million reciprocations, or operation period of 6 months, whichever comes first									
Vacuui	n suction por	t		Rc 1/4, one each on both axial surfaces Seal the unused port with a plug, suction at both ends									
Suction	n flow rate	Speed: 500 mr	n/s or less					∫min (AN					
Juction	I HOW Tale	Speed: 500 mr	n/ or more				200	min (AN	IR)				

#### Dimensions/LJ1H30□3 (X60)

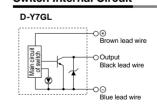


#### **Compatible Motors**

Manufacturer	Motor specification symbol	Brake	Motor output (W)	Power supply voltage (VAC)	Motor model	Controller driver model*	
		Without brake	200	100/110		LC1-1B3H1-□□	
SMC controller	Nil	(Horizontal specification)	200	200		LC1-1B3H2-□□	
LC1 compatible	'*''	With brake	200	100		LC1-1B3VA1-□□	
		(Vertical specification)	200	200		LC1-1B3VA2-□□	
Non-standard		Without brake	200	100/115	MSM021P1A	MSD021P1E	
Matsushita	G	(Horizontal specification)	200	200/230	MSM022P1A	MSD023P1E	
Electric Industrial		With brake	200	100/115	MSM021P1B	MSD021P1E	
Co., Ltd. motor		(Vertical specification)	200	200/230	MSM022P1B	MSD023P1E	
Non-standard		Without brake	200	100/115	HC-PQ23	MR-C20A1	
Mitsubishi Electric	R	(Horizontal specification)	200	200/230	HO-FQ23	MR-C20A	
Corporation	"	With brake	200	100/115	HC-PQ23B	MR-C20A1	
motor		(Vertical specification)	200	200/230	HC-FQ23B	MR-C20A	
Non-standard		Without brake	200	100/115	SGME-02BF12	SGDE-02BP	
Yaskawa Electric	Y	(Horizontal specification)	200	200/230	SGME-02AF12	SGDE-02AP	
Corporation	'	With brake	200	100/115	SGME-02BF12B	SGDE-02BP	
motor		(Vertical specification)	200	200/230	SGME-02AF12B	SGDE-02AP	

<sup>\*</sup> Refer to pages starting with 205 for driver dimensions. Furthermore, for detailed specifications, etc., contact each motor

#### Switch Internal Circuit



<sup>\*</sup> For a non-standard motor specification when the motor is mounted before shipping, the driver is included but the cable that connects the motor and driver is optional. Refer to page 100 for part numbers.

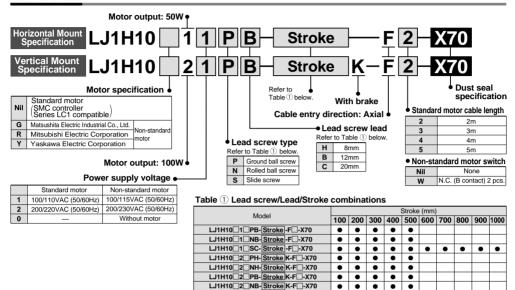
**High Rigidity Direct Acting Guide Type** 

Motor Output: 50W/100W

# Series LJ1H10

# Dust Seal Specification

#### How to Order

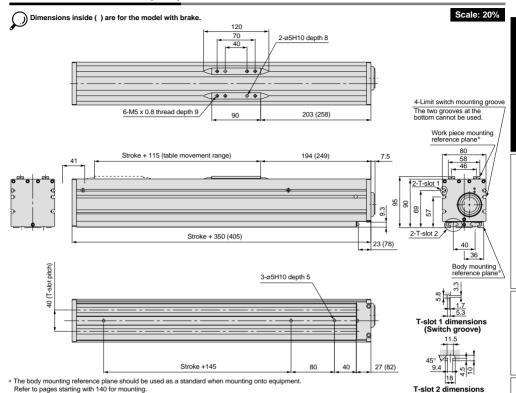


Combinations other than the above cannot be manufacture

#### **Specifications**

	Stan	dard stroke				100	200	300	400	500	600	700	800	900	1000
		Without br		With mot		5.4	6.2	7.0	7.7	8.5	_	_	_	_	_
	Ball	Without bi	ake	Without n	notor	5.0	5.8	6.6	7.3	8.1	_	_	_	_	_
Weight kg	screw	With brake		With mot	or	5.9	6.7	7.5	8.2	9.0	_	_	_	_	_
weight kg		With brake		Without n	notor	5.5	6.3	7.1	7.8	8.6	_	_	_	_	_
	Slide	Without br	ake l	With mot	or	5.3	6.2	7.2	8.0	8.8	9.7	10.5	11.3	12.2	13.0
	screw	TTILLIOUT DI	۵.,۱۵	Without n	notor	4.9	5.8	6.8	7.6	8.4	9.3		10.9	11.8	12.6
Operating ter	mperatu	ıre range °	С						5 to 40	) (with no	condens	sation)			
	Horizontal 12mm lead 50V			50W					1	0					
Work load kg		specification	n 20	0mm lead	ad 50W 10										
WOIR IOAG RG	,	Vertical		2mm lead			5					- - -			
		specification		8mm lead				3 10.1 10.9 11.8 12  densation)							
		Horizontal		2mm lead	50W					60	00				
Maximum sp	eed	specification	_	0mm lead	50W					50	00				
mm/s		Vertical		2mm lead		600				_					
		specification	_	8mm lead	100W			400							
Positioning repe	atahility	Rolled ball				±0.05									
mm	atability	Ground ba		ew						±0.					
		Slide screv		181 -1			±0.								
Motor output		Horizontal										or (50W) DW) with brake nm lead			
		Vertical sp		ation ed ball sc											
		Harizontal													
Lead screw		specification	Grot	una bali s	crew										
Leau Sciew			Silde	ed ball sc			4 0	12mm/8		2011111, 2	I IIIII lea	u			
		Vertical specification													
		apecinication	Grou	una bali s	crew		ø12mm,	1∠mm/8							
Guide							High rigidity direct acting guide Power supply voltage: 4.5 to 28VDC, Current consumption: 10mA or less								
Switch						Control				to 28VDC current: 4					V or less
Table specifi	cation									With du			- 3-		
Grease for di		applicatio	n							Special					
J. 5456 101 41	Jou	app./oution								Opodiai	abricant				

#### Dimensions/LJ1H10 $\square_2^1$ (X70)

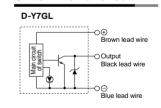


#### **Compatible Motors**

Manufacturer	Motor specification symbol	Brake	Motor output (W)	Power supply voltage (VAC)	Motor model	Controller driver model*	
		Without brake	50	100/110	_	LC1-1B1 1- 1-	
SMC controller		(Horizontal specification)	50	200/220		LC1-1B1 2-	
LC1 compatible	Nil	With brake	100	100		LC1-1B1V 1-	
20 : companio		(Vertical specification)	100	200	I	LC1-1B1V 2-	
Non-standard		Without brake	50	100/115	MSM5AZP1A	MSD5A1P1E	
Matsushita	G	(Horizontal specification)	50	200/230	IVISIVISAZPTA	MSD5A3P1E	
Electric Industrial	G	With brake	100	100/115	MSM011P1B	MSD011P1E	
Co., Ltd. motor		(Vertical specification)	100	200/230	MSM012P1B	MSD013P1E	
Non-standard		Without brake	50	100/115	HC-PQ053	MR-C10A1	
Mitsubishi Electric	R	(Horizontal specification)	30	200/230	HC-FQ055	MR-C10A	
Corporation	K	With brake	100	100/115	HC-PQ13B	MR-C10A1	
motor		(Vertical specification)	100	200/230	HO-FQ 13B	MR-C10A	
Non-standard		Without brake	50	100/115	SGME-A5BF12	SGDE-A5BP	
Yaskawa Electric	Y	(Horizontal specification)	50	200/230	SGME-A5AF12	SGDE-A5AP	
Corporation	f	With brake	100	100/115	SGME-01BF12B	SGDE-01BP	
motor		(Vertical specification)	100	200/230	SGME-01AF12B	SGDE-01AP	

<sup>\*</sup> Refer to pages starting with 205 for driver dimensions. Furthermore, for detailed specifications, etc., contact each motor

#### **Switch Internal Circuit**



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<sup>\*</sup> For a non-standard motor specification when the motor is mounted before shipping, the driver is included but the cable that connects the motor and driver is optional. Refer to page 100 for part numbers.

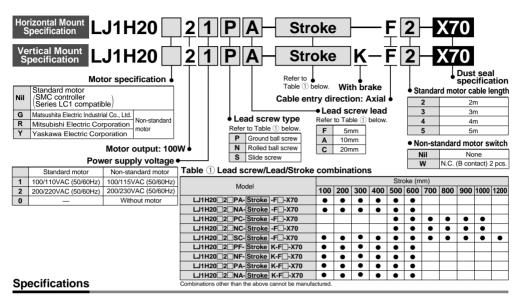
High Rigidity Direct Acting Guide Type

**Motor Output: 100W** 

# Series LJ1H20

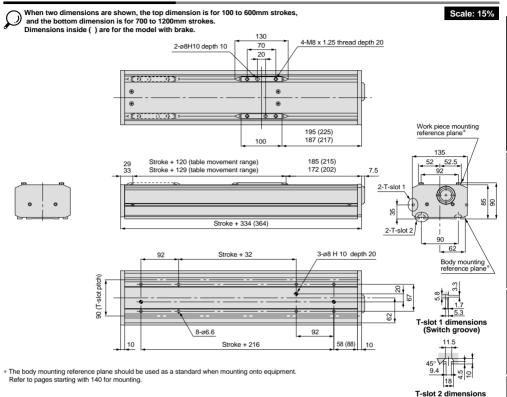
# Dust Seal Specification

#### How to Order



	Sta	ndard stro	ke mr	n		100	200	300	400	500	600	700	800	900	1000	1200	
				With moto	r	7.9	9.1	10.3	11.4	12.8	13.9	15.1	16.3	17.5	18.7	_	
	Ball	Without I	brake	Without m	otor	7.4	8.6	9.8	10.9	12.3	13.4	14.6	15.8	17.0	18.2	_	
Material Lan	screv			With moto	r	8.6	9.8	11.0	12.1	13.5	14.6	_				_	
Weight kg		With bra	ke	Without m	otor	8.1	9.3	10.5	11.6	13.0	14.1						
	Slide	Maril		With moto	r	9.0	10.0	11.1	12.2	13.3	14.3	15.3	17.2	19.1	20.6	24.7	
	screw	Without I	orake	Without m	otor	7.5	8.5	9.6	10.8	12.3	13.8	16.3	16.8	18.6	20.4	24.2	
Operating ter	mpera	ture range	°C						5 t	o 40 (wi	th no co	ndensati	on)				
			Ball	10mm lead				3	0					_			
		specification	screw	20mm lead				_				15 —					
Work load kg	g	.,		20mm lead	100W						15						
			Ball	5mm lead					5			_					
		-1	screw	10mm lead		8 500						_					
			Ball	10mm lead		500											
Maximum sp	eed	enocification	screw	20mm lead		<u> </u>						930   740   600   500   —					
mm/s		·	Slide screw	10mm lead	100W	500											
11111/5			Ball	5mm lead					50				<del>_</del>				
		specification		10mm lead				5	00								
Positioning		Rolled ba								±0		_					
repeatability	mm	Ground b		W						±0							
<u> </u>		Slide scre								±C							
Motor output	:	Horizonta				-	AC servo		100141)		vomotor	(100W)					
		Vertical s	pecifica	ation		- '		15mm. 1			=						
		Horizontal		d/Grand ball	screw		Ø	iomm, i	omm lea	ad .		15mm, 2	20mm lo				
Lead screw		specification	on Clide	screw				_		~20m	س m. 20m	- ,	20111111111	au			
Lead Sciew		Vertical	Silde	sciew			a1	5mm, 5r	om lood	Ø2011	IIII, ZUIII	lii leau					
		specification	Rolle	d/Grand ball	screw					ı							
Guide					ø15mm, 10mm lead — — High rigidity direct acting quide												
						Power supply voltage: 4.5 to 28VDC, Current consumption: 10mA or less											
Switch	itch					Control output: Open collector, Load current: 40mA or less, Internal voltage drop: 1.5V or less								or less			
Table specific	Table specifications					With dust seal											
Grease for du	ust sea	al applicat	ion							Spe	cial lubri	cant					

#### Dimensions/LJ1H20□2 (X70)

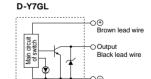


#### **Compatible Motors**

Manufacturer	Motor specification symbol	Brake	Motor output (W)	Power supply voltage (VAC)	Motor model	Controller driver model*	
		Without brake	400	100/110	_	LC1-1B2[]1-[]	
SMC controller	<b></b>	(Horizontal specification)	100	200/220	_	LC1-1B2[2-[	
LC1 compatible	Nil	With brake	100	100	_	LC1-1B2V 1- 1	
		(Vertical specification)	100	200	_	LC1-1B2V 2- 0	
Non-standard		Without brake	100	100/115	MSM011P1A	MSD011P1E	
Matsushita	G	(Horizontal specification)	100	200/230	MSM012P1A	MSD013P1E	
Electric Industrial	٦	With brake	100	100/115	MSM011P1B	MSD011P1E	
Co., Ltd. motor		(Vertical specification)	100	200/230	MSM012P1B	MSD013P1E	
Non-standard		Without brake	100	100/115	HC-PQ13	MR-C10A1	
Mitsubishi Electric	R	(Horizontal specification)	100	200/230	no-Pais	MR-C10A	
Corporation		With brake	100	100/115	HC-PQ13B	MR-C10A1	
motor		(Vertical specification)	100	200/230	10-FQ13B	MR-C10A	
Non-standard		Without brake	100	100/115	SGME-01BF12	SGDE-01BP	
Yaskawa Electric	Y	(Horizontal specification)	100	200/230	SGME-01AF12	SGDE-01AP	
Corporation	1	With brake	100	100/115	SGME-01BF12B	SGDE-01BP	
motor		(Vertical specification)	100	200/230	SGME-01AF12B		

<sup>\*</sup> Refer to pages starting with 205 for driver dimensions. Furthermore, for detailed specifications, etc., contact each motor manufacturer

#### **Switch Internal Circuit**



Blue lead wire

<sup>\*</sup> For a non-standard motor specification when the motor is mounted before shipping, the driver is included but the cable that connects the motor and driver is optional. Refer to page 100 for part numbers.

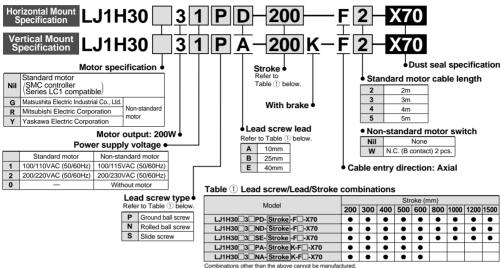
**High Rigidity Direct Acting Guide Type** 

**Motor Output: 200W** 

# Series LJ1H30

# Dust Seal Specification

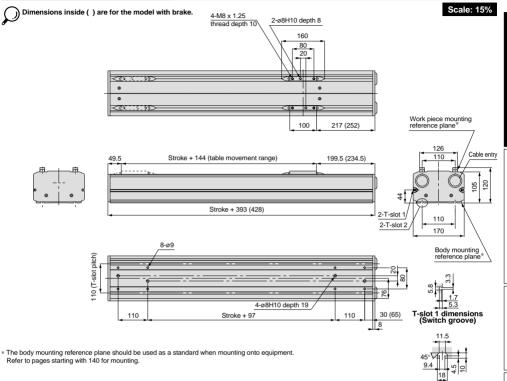
#### How to Order



#### **Specifications**

	Stand	ard stro	ke mm		200	300	400	500	600	800	1000	1200	1500	
		Withou	4 1 1	With motor	16.2	18.2	20.2	22.2	24.2	28.7	33.2	37.2	43.2	
	Ball	vvitnou	t brake	Without motor	15.1	17.1	19.1	21.1	23.1	27.6	32.1	36.1	42.1	
Waight ka	screw	With br		With motor	17.2	19.2	21.2	23.2	25.2			_		
Weight kg		vvith bi	аке	Without motor	16.1	18.1	20.1	22.1	24.1			_		
	Slide	10/54b	4 1 1	With motor	14.9	17.0	19.0	21.1	23.2	27.3	31.5	35.6	41.9	
	screw	Withou	t brake	Without motor	13.8	15.9	17.9	20.0	22.1	26.2	30.4	34.5	40.8	
Operating ten	nperatu	ire rang	je °C					5 to 40 (wi	th no cond	densation)				
	Ho		Ball screw	25mm lead					60					
Work load kg	spec	cification	Slide screv	v 40mm lead 200W					30					
•	spec	ertical dification	Ball screw	10mm lead										
M			Ball screw 25mm lead 1000									700	500	
Maximum spe mm/s				v 40mm lead 200W	1	500								
11111/5	Spec	ertical cification	Ball screw	10mm lead			500				-	_		
Positioning	Ro	lled ball	screw			±0.05								
repeatability	Gro	ound bal	screw			±0.02								
mm	Slic	de screw							±0.1					
Motor output		rizontal s							vomotor (					
wotor output	Ve	rtical spe					A	C servomo			ke			
		orizonta		I/Ground ball screw					nm, 25mm					
Lead screw	sp	ecificatio	Olido	screw					nm, 40mm	lead				
	sp	Vertical ecificatio	n Rolled	I/Ground ball screw		ø20mn	n, 10mm le				-	_		
Guide							l	High rigidit	y direct ac	cting guide				
Switch					Control o			e: 4.5 to 28 Load curre						
Table specific	ations							W	ith dust se	al				
Grease for du	ıst seal	applica	ation					Spe	ecial lubric	ant				

#### Dimensions/LJ1H30□3 (X70)



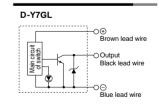
#### **Compatible Motors**

Manufacturer	Motor specification symbol	Brake	Motor output (W)	Power supply voltage (VAC)	Motor model	Controller driver model*	
		Without brake	000	100/110	_	LC1-1B3 1-	
SMC controller	<b></b> .	(Horizontal specification)	200	200	_	LC1-1B3□2-□□	
LC1 compatible	Nil	With brake	200	100	_	LC1-1B3VA1-□□	
		(Vertical specification)	200	200	_	LC1-1B3VA2-□□	
Non-standard		Without brake	200	100/115	MSM021P1A	MSD021P1E	
Matsushita	G	(Horizontal specification)	200	200/230	MSM022P1A	MSD023P1E	
Electric Industrial	١ ٩	With brake	200	100/115	MSM021P1B	MSD021P1E	
Co., Ltd. motor		(Vertical specification)	200	200/230	MSM022P1B	MSD023P1E	
Non-standard		Without brake	200	100/115	HC-PQ23	MR-C20A1	
Mitsubishi Electric	R	(Horizontal specification)	200	200/230	no-PQ23	MR-C20A	
Corporation	"	With brake	200	100/115	HC-PQ23B	MR-C20A1	
motor		(Vertical specification)	200	200/230	HC-FQ23B	MR-C20A	
Non-standard		Without brake	200	100/115	SGME-02BF12	SGDE-02BP	
Yaskawa Electric	l v	(Horizontal specification)	200	200/230	SGME-02AF12	SGDE-02AP	
Corporation	1	With brake	200	100/115	SGME-02BF12B	SGDE-02BP	
motor		(Vertical specification)	200	200/230	SGME-02AF12B		

<sup>\*</sup> Refer to pages starting with 205 for driver dimensions. Furthermore, for detailed specifications, etc., contact each motor manufacturer.

#### **Switch Internal Circuit**

T-slot 2 dimensions



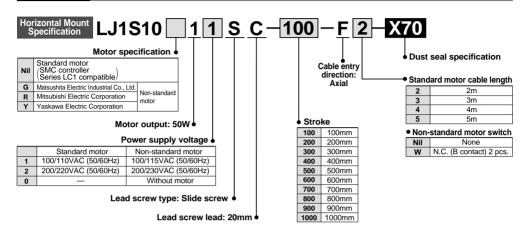
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<sup>\*</sup> For a non-standard motor specification when the motor is mounted before shipping, the driver is included but the cable that connects the motor and driver is optional. Refer to page 100 for part numbers

## Made to Order Series LJ9S10 Dust Seal Specification

Slider Guide Type **Motor Output: 50W** 

#### How to Order



#### **Specifications**

Standa	ard stroke mm	100	200	300	400	500	600	700	800	900	1000		
Weight kg	With motor (Standard)	5.4	6.1	6.9	7.7	8.5	9.3	10.0	10.8	11.6	12.4		
Weight kg	Without motor (Non-standard)	5.0	5.7	6.5	7.3	8.1	8.9	9.6	10.4	11.2	12.0		
Operating temperatu	ire range °C				5 to 4	(with no	condens	sation)					
Work load kg		5											
Maximum speed mn	n/s	300											
Positioning repeatab	±0.1												
Motor output		AC servomotor (50W)											
Lead screw		Slide screw ø20mm, 20mm lead											
Guide						Slider	guide						
Switch		Control o	Power soutput: Op	upply vol	tage: 4.5 t tor, Load	o 28VDC current: 4	, Current 0mA or le	consumptes, Intern	tion: 10m/ al voltage	A or less drop: 1.5	5V or less		
Table specifications		With dust seal											
Grease for dust seal	Grease for dust seal application				Special lubricant								

#### 70 2-ø5H10 depth 8 40 4-Limit switch mounting groove 6-M5 x 0.8 thread depth 9 The two grooves at the bottom cannot be used 90 203 Work piece mounting reference plane Stroke + 115 (table movement range) 194 2-T-slot 2 Stroke + 350 40 23 36 40 (T-slot pitch) Body mounting reference plane 3-ø5H10 depth 5 T-slot 1 dimensions (Switch groove) Stroke + 145 80 40 27 \* The body mounting reference plane should be used as a standard when mounting onto equipment. T-slot 2 dimensions

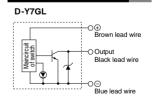
#### **Compatible Motors**

Refer to pages starting with 140 for mounting.

Manufacturer	Motor specification symbol	Brake	Motor output (W)	Power supply voltage (VAC)	Motor model	Controller driver model*
SMC	Nil	Without brake	50	100/110	_	LC1-1B1S1-□□
controller LC1 compatible	NII	(Horizontal specification)	50	200/220	_	LC1-1B1S2-□□
Non-standard Matsushita	G	Without brake	50	100/115	MSM5AZP1A	MSD5A1P1E
Electric Industrial Co., Ltd. motor	, G	(Horizontal specification)	50	200/230	MISMISAZETA	MSD5A3P1E
Non-standard Mitsubishi Electric	R	Without brake	50	100/115	HC-PQ053	MR-C10A1
Corporation motor	, K	(Horizontal specification)	30	200/230	1101 0000	MR-C10A
Non-standard Yaşkawa Electric	Y	Without brake	50	100/115	SGME-A5BF12	SGDE-A5BP
Corporation motor	<b>'</b>	(Horizontal specification)	50	200/230	SGME-A5AF12	SGDE-A5AP

<sup>\*</sup> Refer to pages starting with 205 for driver dimensions. Furthermore, for detailed specifications, etc., contact each motor

#### **Switch Internal Circuit**



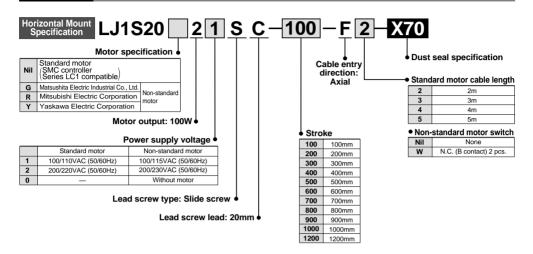
<sup>\*</sup> For a non-standard motor specification when the motor is mounted before shipping, the driver is included but the cable that connects the motor and driver is optional. Refer to page 100 for part numbers.

Slider Guide Type **Motor Output: 100W** 

# Series LJ1520

Dust Seal Specification

#### How to Order



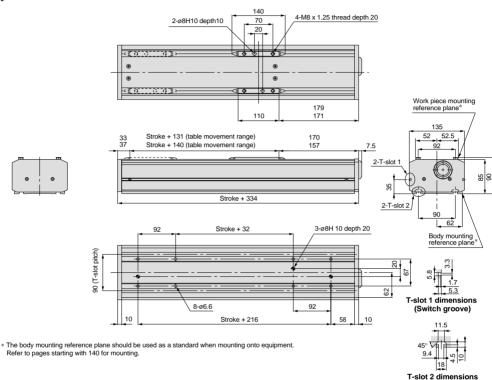
#### **Specifications**

Standa	rd stroke mm	100	200	300	400	500	600	700	800	900	1000	1200	
Weight kg	With motor (Standard)	6.8	7.9	9.0	10.1	11.1	12.2	13.3	14.3	15.4	16.4	18.6	
Weight kg	Without motor (Non-standard)	6.3	7.4	8.5	9.6	10.7	11.7	12.8	13.8	14.9	15.9	18.1	
Operating temperatu	re range °C				5 to	40 (with	no con	densatio	n)				
Work load kg		10											
Maximum speed mm	/s	300											
Positioning repeatab	±0.1												
Motor output		AC servomotor (100W)											
Lead screw		Slide screw ø20mm, 20mm lead											
Guide						Sli	der guid	le					
Switch	Control	Power output: C						sumptior Internal v			or less		
Table specifications						Wit	h dust s	eal					
Grease for dust seal	Grease for dust seal application					Spec	cial lubri	cant					

#### Dimensions/LJ1S20 2 SC (X70)

When two dimensions are shown, the top dimension is for 100 to 600mm strokes, and the bottom dimension is for 700 to 1200mm strokes.

Scale: 15%

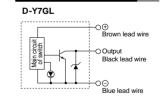


#### **Compatible Motors**

Manufacturer	Motor specification symbol	Brake	Motor output (W)	Power supply voltage (VAC)	Motor model	Controller driver model*
SMC controller	Nil	Without brake	100	100/110	_	LC1-1B2S1-
LC1 compatible	NII	(Horizontal specification)	100	200/220	_	LC1-1B2S2-
Non-standard Matsushita		Without brake	100	100/115	MSM011P1A	MSD011P1E
Electric Industrial Co., Ltd. motor	G	(Horizontal specification)	100	200/230	MSM012P1A	MSD013P1E
Non-standard Mitsubishi Electric	_	Without brake	100	100/115	HC-PQ13	MR-C10A1
Corporation motor	R	(Horizontal specification)	100	200/230	no-ruis	MR-C10A
Non-standard Yaskawa Electric		Without brake	100	100/115	SGME-01BF12	SGDE-01BP
Corporation motor	Y	(Horizontal specification)	100	200/230	SGME-01AF12	SGDE-01AP

<sup>\*</sup> Refer to pages starting with 205 for driver dimensions. Furthermore, for detailed specifications, etc., contact each motor manufacturer.

#### **Switch Internal Circuit**



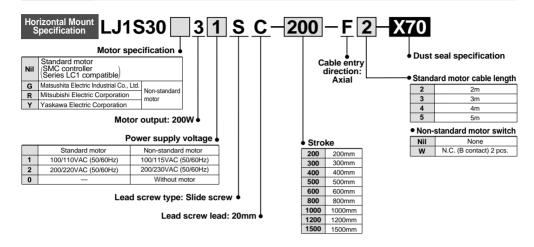
<sup>\*</sup> For a non-standard motor specification when the motor is mounted before shipping, the driver is included but the cable that connects the motor and driver is optional. Refer to page 100 for part numbers.

**Slider Guide Type Motor Output: 200W** 

Series LJ1530

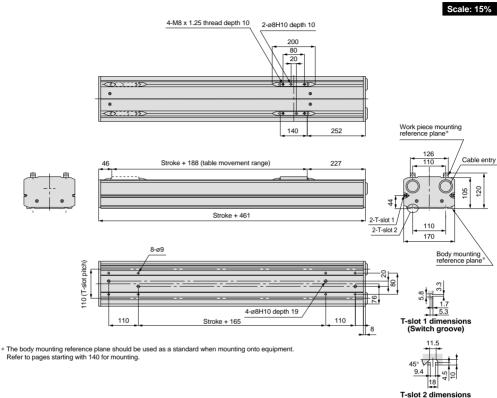
Dust Seal Specification

#### How to Order



#### **Specifications**

Standa	ard stroke mm	200	300	400	500	600	800	1000	1200	1500			
Weight kg	With motor (Standard)	14.4	16.2	18.0	19.8	21.5	25.7	29.7	33.3	38.7			
weight kg	Without motor (Non-standard)	13.3	15.1	16.9	18.7	20.4	24.6	28.6	32.2	37.6			
Operating temperatur	e range °C				5 to 40 (wi	th no cond	densation)						
Work load kg		20											
Maximum speed mm/	/s	300											
Positioning repeatabi	lity mm	±0.1											
Motor output		AC servomotor (200W)											
Lead screw		Slide screw ø25mm, 20mm lead											
Guide					S	Slider guid	е						
Switch		Control or						mption: 10i ernal volta	mA or less ge drop: 1.	5V or less			
Table specifications					W	ith dust se	al						
Grease for dust seal a	Grease for dust seal application				Special lubricant								



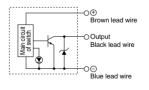
#### **Compatible Motors**

Manufacturer	Motor specification symbol	Brake	Motor output (W)	Power supply voltage (VAC)	Motor model	Controller driver model*	
SMC controller		Without brake	200	100/110	_	LC1-1B3S1-□□	
LC1 compatible	Nil	(Horizontal specification)	200	200		LC1-1B3S2-□□	
Non-standard Matsus-hita		Without brake	200	100/115	MSM021P1A	MSD021P1E	
Electric Industrial Co., Ltd. motor	G	(Horizontal specification)	200	200/230	MSM022P1A	MSD023P1E	
Non-standard Mitsubishi Electric		Without brake	200	100/115	HC-PQ023	MR-C20A1	
Corporation motor	R	(Horizontal specification)	200	200/230	HC-PQ023	MR-C20A	
Non-standard Yaskawa Electric	Y	Without brake	200	100/115	SGME-02BF12	SGDE-02BP	
Corporation motor	T	(Horizontal specification)	200	200/230	SGME-02AF12	SGDE-02AP	

#### \* Refer to pages starting with 205 for driver dimensions. Furthermore, for detailed specifications, etc., contact each motor manufacturer.

#### **Switch Internal Circuit**





<sup>\*</sup> For a non-standard motor specification when the motor is mounted before shipping, the driver is included but the cable that connects the motor and driver is optional. Refer to page 100 for part numbers.

**High Rigidity Direct Acting Guide Type** 

**Motor Output: 50W** 

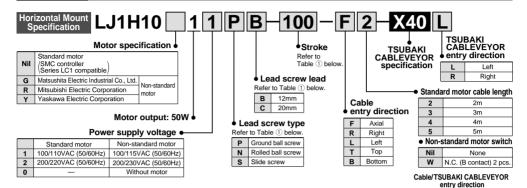
# Series LJ1H10

**TSUAKI CABLEVEYOR** Specification

Top entry

Bottom entry

#### How to Order



#### Table 1 Lead screw/Lead/Stroke combinations

Model					Stroke	e (mm	)				Left entry
iviodei	100	200	300	400	500	600	700	800	900	1000	
LJ1H10 1 PB-StrokeX40	•	•	•	•	•						
LJ1H10 1 NB-StrokeX40	•	•	•	•	•						
LJ1H10 1 SC-Stroke -X40	•	•	•	•	•	•	•	•	•	•	Axial entry
Combinations other than the above cannot be manufacti	ured.										,

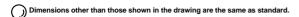
#### **Specifications**

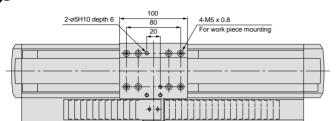
Standard stroke mm			100	200	300	400	500	600	700	800	900	1000
Weight kg	With motor (Standard)	Ball screw	6.0	6.9	7.9	8.7	9.6	_			_	_
		Slide screw	6.1	7.1	8.3	9.2	10.1	11.1	12.0	13.0	14.0	14.9
	Without motor (Non-Standard)	Ball screw	5.6	6.5	7.5	8.3	9.2	_	_	_	_	_
		Slide screw	5.7	6.7	7.9	8.8	9.7	10.7	11.6	12.6	13.6	14.5
Mounting orientation			Horizontal									
Operating temperature range °C			5 to 40 (with no condensation)									
Work load kg	Ball screw	12mm lead		10 —								
	Slide screw	20mm lead	10									
Maximum speed mm/s	Ball screw	12mm lead	600 —									
	Slide screw	20mm lead	500									
Positioning repeatability mm	Rolled ball screw		±0.05					_				
	Ground ball screw		±0.02							_		
	Slide screw		±0.1									
Motor output			AC servomotor (50W)									
Lead screw	Rolled ball screw		ø12mm, 12mm lead					_				
	Ground ball screw		9 12111111, 12111111 lead						_			
	Slide screw		ø20mm, 20mm lead									
Guide			High rigidity direct acting guide									
Switch			Power supply voltage: 4.5 to 28VDC, Current consumption: 10mA or less Control output: Open collector, Load current: 40mA or less, Internal voltage drop: 1.5V or less									
TSUBAKI CABLEVEYOR			TKP0130-2BR18 manufactured by TSUBAKIMOTO CHAIN CO.									
Side cover			Cover with switch groove									

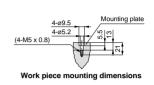
Scale: 25%

### 123

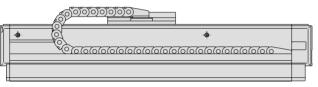
### Dimensions/LJ1H10□1 (X40)







50





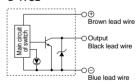
### **Compatible Motors**

Manufacturer	Motor specification symbol	Brake	Motor output (W)	Power supply voltage (VAC)	Motor model	Controller driver model	
SMC controller		Without brake	50	100/110	_	LC1-1B1 1-	
LC1 compatible	Nil	(Horizontal specification)	30	200/220	_	LC1-1B1□2-□□	
Non-standard Matsushita		Without brake	50	100/115	MSM5AZP1A	MSD5A1P1E	
Electric Industrial Co., Ltd. motor	G	(Horizontal specification)	30	200/230	IVISIVISAZPTA	MSD5A3P1E	
Non-standard Mitsubishi Electric	R	Without brake	50	100/115	HC-PQ053	MR-C10A1	
Corporation motor	K	(Horizontal specification)		200/230	HC-PQ053	MR-C10A	
Non-standard Yaskawa Electric	Y	Without brake	50	100/115	SGME-A5BF12	SGDE-A5BP	
Corporation motor	Y	(Horizontal specification)	30	200/230	SGME-A5AF12	SGDE-A5AP	

### \* Refer to pages starting with 205 for driver dimensions. Furthermore, for detailed specifications, etc., contact each motor

### **Switch Internal Circuit**

### D-Y7GL



<sup>\*</sup> This drawing shows the TSUBAKI CABLEVEYOR with left hand entry.

<sup>\*</sup> For a non-standard motor specification when the motor is mounted before shipping, the driver is included but the cable that connects the motor and driver is optional. Refer to page 100 for part numbers.

### Made to Order

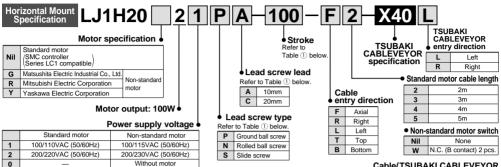
**High Rigidity Direct Acting Guide Type** 

**Motor Output: 100W** 

# Series LJ1H20

TSUBAKI CABLEVEYOR **Specification** 

### How to Order

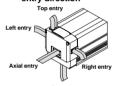


#### Table 1 Lead screw/Lead/Stroke combinations

Model						oke (n					
Model	100	200	300	400	500	600	700	800	900	1000	1200
LJ1H20 2 PA-Stroke - X40	•	•	•	•	•	•					
LJ1H20 2 NA-StrokeX40	•	•	•	•	•	•					
LJ1H20 2 PC-Stroke - X40					•	•	•	•	•	•	
LJ1H20 2 NC-Stroke - X40					•	•	•	•	•	•	
LJ1H20 2 SC-Stroke - X40	•	•	•	•	•	•	•	•	•	•	•

Combinations other than the above cannot be manufactured

### Cable/TSUBAKI CABLEVEYOR entry direction



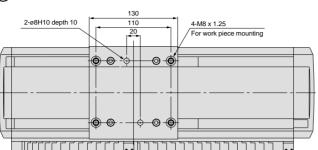
### **Specifications**

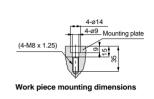
Standa	rd stroke mm		100	200	300	400	500	600	700	800	900	1000	1200
	With motor	Ball screw	8.7	9.9	11.1	12.3	13.5	14.7	15.9	17.1	18.3	19.5	_
Woight kg	(Standard)	Slide screw	10.0	11.2	12.4	13.6	14.8	16.0	17.2	18.4	19.6	20.8	23.2
Weight kg	Without motor	Ball screw	8.2	9.4	10.6	11.8	13.0	14.2	15.4	16.6	17.8	19.0	_
	(Non-Standard)	Slide screw	9.5	10.7	11.9	13.1	14.3	15.5	16.7	17.9	19.1	20.3	22.7
Mounting orientation							Н	orizonta	ıl				
Operating temperature range °C						5 to	40 (with	no cor	densati	ion)			
	Ball screw	10mm lead			30								
Work load kg	Dali Sciew	20mm lead		-	_				15	5			_
· ·	Slide screw	20mm lead						15					
Maximum anaad	mum speed Ball screw				500								
Maximum speed mm/s	Dali Sciew	20mm lead		_	_		1000 930 740 600			600	500	_	
11111/0	Slide screw	20mm lead						500					
	Rolled ball scre	W	±0.05										
Positioning repeatability	Ground ball scr	ew	±0.02										
	Slide screw		±0.1										
Motor output			AC servomotor (100W)										
	Rolled ball scre	w		ø1	15mm, 1	0mm le	ad						
Lead screw	Ground ball scr	ew			_			Ø	15mm, 2	20mm le	ead		_
	Slide screw							n, 20mn					
Guide						High	n rigidity	direct a	icting gu	uide			
Switch	Switch			Power supply voltage: 4.5 to 28VDC, Current consumption: 10mA or less Control output: Open collector, Load current: 40mA or less, Internal voltage drop: 1.5V or less								ss √ or less	
TSUBAKI CABLEVEYO	TSUBAKI CABLEVEYOR		TKP0130-2BR28 manufactured by TSUBAKIMOTO CHAIN CO.										
Side cover			Cover with switch groove										

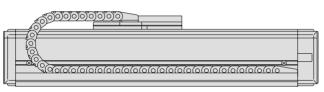
Scale: 25%

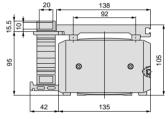
### Dimensions/LJ1H20□2 (X40)









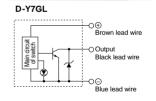


### **Compatible Motors**

Manufacturer	Motor specification symbol	Brake	Motor output (W)	Power supply voltage (VAC)	Motor model	Controller driver model*
SMC controller	Nil	Without brake	100	100/110	_	LC1-1B21
LC1 compatible	NII	(Horizontal specification)	100	200/220	-	LC1-1B2[]2-[]
Non-standard Matsushita	G	Without brake	100	100/115	MSM011P1A	MSD011P1E
Electric Industrial Co., Ltd. motor	G	(Horizontal specification)	100	200/230	MSM012P1A	MSD013P1E
Non-standard Mitsubishi Electric	R	Without brake	100	100/115	HC-PQ13	MR-C10A1
Corporation motor	K	(Horizontal specification)	100	200/230	HC-FQ13	MR-C10A
Non-standard Yaskawa Electric	Y	Without brake	100	100/115	SGME-01BF12	SGDE-01BP
Corporation motor	ř	(Horizontal specification)	100	200/230	SGME-01AF12	SGDE-01AP

### \* Refer to pages starting with 205 for driver dimensions. Furthermore, for detailed specifications, etc., contact each motor manufacturer.

### **Switch Internal Circuit**



<sup>\*</sup> This drawing shows the TSUBAKI CABLEVEYOR with left hand entry.

<sup>\*</sup> For a non-standard motor specification when the motor is mounted before shipping, the driver is included but the cable that connects the motor and driver is optional. Refer to page 100 for part numbers.

### Made to Order

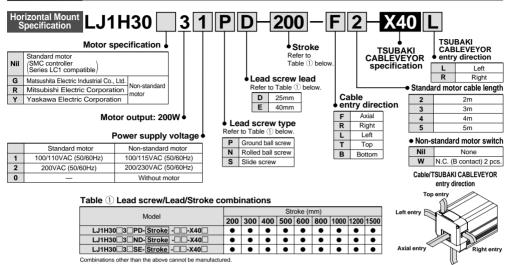
**High Rigidity Direct Acting Guide Type** 

**Motor Output: 200W** 

# Series LMH30

**TSUBAKI CABLEVEYOR** Specification

### How to Order



### **Specifications**

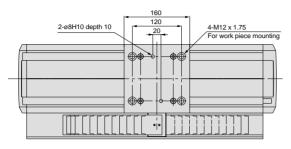
Bottom entry

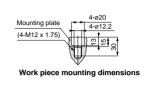
Standard	stroke mm		200	300	400	500	600	800	1000	1200	1500		
	With motor	Ball screw	17.5	19.7	21.9	24.1	26.2	31.1	36.0	40.3	46.9		
Weight kg	(Standard)	Slide screw	16.4	18.7	20.9	23.2	25.4	29.9	34.5	39.0	45.8		
weight kg	Without motor	Ball screw	16.4	18.6	20.8	23.0	25.1	30.0	34.9	39.2	45.8		
	(Non-Standard)	Slide screw	15.3	17.6	19.8	22.1	24.3	28.8	33.4	37.8	44.7		
Mounting orientation							Horizonta	l					
Operating temperature range °C					5	to 40 (wi	th no con	densatior	1)				
Work load kg	Ball screw	25mm lead					60						
work load kg	Slide screw	40mm lead					30						
Maximum speed	Ball screw	25mm lead				1000				700	500		
mm/s	Slide screw	40mm lead	500										
Daaitianing repeatability	Rolled ball scre	Rolled ball screw			±0.05								
Positioning repeatability mm	Ground ball scr	ew	±0.02										
	Slide screw						±0.1						
Motor output			AC servomotor (200W)										
	Rolled ball scre	ew	ø25mm, 25mm lead										
Lead screw	Ground ball scr	ew				Ø23II	IIII, ZJIIIII	i ieau					
	Slide screw					ø30m	ım, 40mm	ı lead					
Guide						High rigidit	y direct ac	cting guide	)		, and the second		
Switch	Power supply voltage: 4.5 to 28VDC, Current consumption: 10mA or less Control output: Open collector, Load current: 40mA or less, Internal voltage drop: 1.5V or les												
SUBAKI CABLEVEYOR			TKP0180-2BR28 manufactured by TSUBAKIMOTO CHAIN CO.										
Side cover	ide cover			Cover with switch groove									

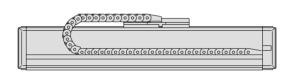
Scale: 20%

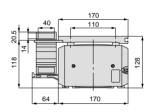
### Dimensions/LJ1H30□3 (X40)

Dimensions other than those shown in the drawing are the same as standard.







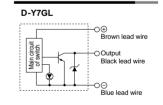


### **Compatible Motors**

Manufacturer	Motor specification symbol	Brake	Motor output (W)	Power supply voltage (VAC)	Motor model	Controller driver model*	
SMC controller	Nil	Without brake	200	100/110	_	LC1-1B3 1-	
LC1 compatible	NII	(Horizontal specification)	200	200	_	LC1-1B3□2-□□	
Non-standard Matsushita	G	Without brake	200	100/115	MSM021P1A	MSD021P1E	
Electric Industrial Co., Ltd. motor	G	(Horizontal specification)	200	200/230	MSM022P1A	MSD023P1E	
Non-standard Mitsubishi Electric	_	Without brake	200	100/115	HC-PQ23	MR-C20A1	
Corporation motor	R	(Horizontal specification)	200	200/230	nc-ruzs	MR-C20A	
Non-standard Yaskawa Electric	V	Without brake	200	100/115	SGME-02BF12	SGDE-02BP	
Corporation motor	Corporation motor Y (Horizontal speci	(Horizontal specification)	200	200/230	SGME-02AF12	SGDE-02AP	

- \* Refer to pages starting with 205 for driver dimensions. Furthermore, for detailed specifications, etc., contact each motor
- For a non-standard motor specification when the motor is mounted before shipping, the driver is included but the cable that connects the motor and driver is optional. Refer to page 100 for part numbers.

### **Switch Internal Circuit**



<sup>\*</sup> This drawing shows the TSUBAKI CABLEVEYOR with left hand entry.

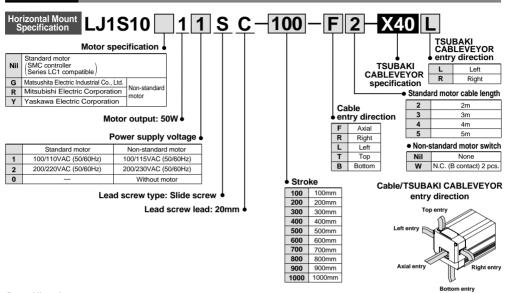
### Made to Order

Slider Guider Type **Motor Output: 50W** 

# Series LJ1 S10

### **TSUBAKI CABLEVEYOR** Specification

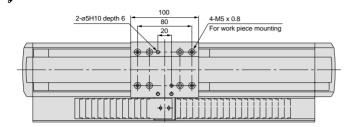
### **How to Order**

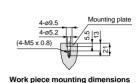


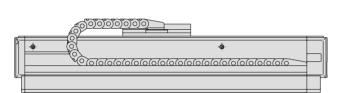
### **Specifications**

Standar	d stroke mm	100	200	300	400	500	600	700	800	900	1000
Wainht Ion	With motor (Standard)	6.2	7.0	8.0	8.9	9.8	10.7	11.5	12.5	13.4	14.3
Weight kg	Without motor (Non-Standard)	5.8	6.6	7.6	8.5	9.4	10.3	11.1	12.1	13.0	13.9
Mounting orientation						Horiz	ontal				
Operating temperatur	e range °C				5 to 40	(with no	conder	sation)			
Work load kg							5				
Maximum speed mm/	's					3	00				
Positioning repeatabi	lity mm	±0.1									
Motor output		AC servomotor (50W)									
Lead screw		ø20mm, 20mm lead									
Guide		Slide guide									
Switch			ower sup output: O								
TSUBAKI CABLEVEYOR			TKP0130-2BR18 manufactured by TSUBAKIMOTO CHAIN CO.								
Side cover			Cover with switch groove								

Scale: 20%







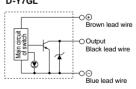
50 103 95

80

### **Switch Internal Circuit**

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### D-Y7GL



### **Compatible Motors**

Manufacturer	Motor specification symbol	Brake	Motor output (W)	Power supply voltage (VAC)	Motor model	Controller driver model*
SMC controller		Without brake	50	100/110	_	LC1-1B1S1-
LC1 compatible	Nil	(Horizontal specification)	30	200/220	_	LC1-1B1S2-
Non-standard Matsushita		Without brake	50	100/115	MSM5AZP1A	MSD5A1P1E
Electric Industrial Co., Ltd. motor	G	(Horizontal specification)	30	200/230	WOWDAZFIA	MSD5A3P1E
Non-standard Mitsubishi Electric	R	Without brake	50	100/115	HC-PQ053	MR-C10A1
Corporation motor	K	(Horizontal specification)	30	200/230	HC-FQ055	MR-C10A
Non-standard Yaskawa Electric	, ,	Without brake	50	100/115	SGME-A5BF12	SGDE-A5BP
Corporation motor	Y	(Horizontal specification)	50	200/230	SGME-A5AF12	SGDE-A5AP

- \* Refer to pages starting with 205 for driver dimensions. Furthermore, for detailed specifications, etc., contact each motor manufacturer.
- \* For a non-standard motor specification when the motor is mounted before shipping, the driver is included but the cable that connects the motor and driver is optional. Refer to page 100 for part numbers.

<sup>\*</sup> This drawing shows the TSUBAKI CABLEVEYOR with left hand entry.

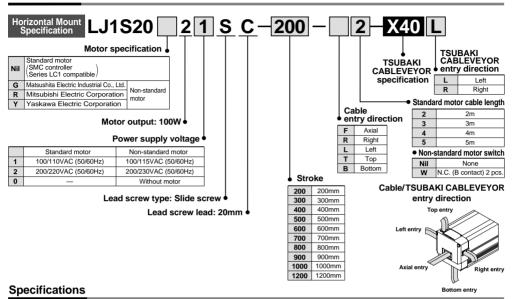
### Made to Order

### Slider Guide Type **Motor Output: 100W**

# Series LJ1 S20

### **TSUBAKI CABLEVEYOR** Specification

### How to Order

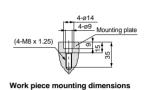


Standard stroke mm	Standard stroke mm		200	300	400	500	600	700	800	900	1000	1200
Wainht Ion	With motor (Standard)	7.8	9.0	10.3	11.5	12.6	13.8	15.0	16.2	17.4	18.5	20.9
Weight kg	Without motor (Non-Standard)	7.3	8.5	9.8	11.0	12.1	13.3	14.5	15.7	16.9	18.0	20.4
Mounting orientation						H	orizont	al				
Operating temperature	re range °C				5 to	40 (wit	h no co	ndensat	ion)			
Work load kg							10					
Maximum speed mm	/s	300										
Positioning repeatab	ility mm	±0.1										
Motor output		AC servomotor (100W)										
Lead screw		ø20mm, 20mm lead										
Guide		Slide guide										
Switch									nsumpti Internal v			
TSUBAKI CABLEVEY	TSUBAKI CABLEVEYOR			TKP0130-2BR28 manufactured by TSUBAKIMOTO CHAIN CO.								
Side cover			Cover with switch groove									

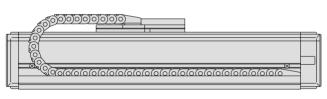
### Dimensions/LJ1S20 2 SC (X40)

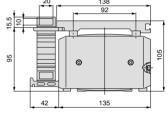


140 2-ø8H10 depth 10 110 4-M8 v 1 25 20 For work piece mounting ᢒ−ᢆᠪ ⊕-(•



Scale: 20%



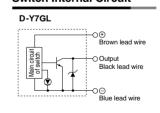


### **Compatible Motors**

Manufacturer	Motor specification symbol	Brake	Motor output (W)	Power supply voltage (VAC)	Motor model	Controller driver model
SMC controller	Nil	Without brake		100/110	_	LC1-1B2S1-□□
LC1 compatible	INII	(Horizontal specification)	100	200/220	_	LC1-1B2S2-□□
Non-standard Matsushita	G	Without brake		100/115	MSM011P1A	MSD011P1E
Electric Industrial Co., Ltd. motor	٦	(Horizontal specification)	100	200/230	MSM012P1A	MSD013P1E
Non-standard Mitsubishi Electric		Without brake		100/115		MR-C10A1
Corporation motor	R	(Horizontal specification)	100	200/230	HC-PQ013	MR-C10A
Non-standard Yaskawa Electric	.,	Without brake	100	100/115	SGME-01BF12	SGDE-01BP
Corporation motor			100	200/230	SGME-01AF12	SGDE-01AP

<sup>\*</sup> Refer to pages starting with 205 for driver dimensions. Furthermore, for detailed specifications, etc., contact each motor

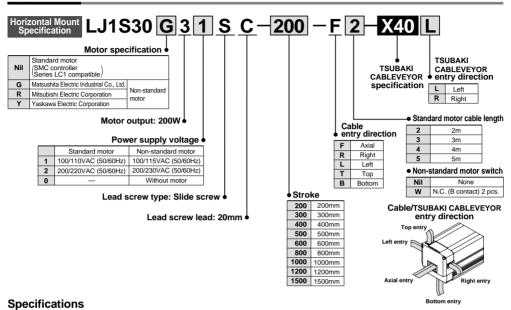
### **Switch Internal Circuit**



<sup>\*</sup> This drawing shows the TSUBAKI CABLEVEYOR with left hand entry.

<sup>\*</sup> For a non-standard motor specification when the motor is mounted before shipping, the driver is included but the cable that connects the motor and driver is optional. Refer to page 100 for part numbers.

### How to Order



#### Standard stroke mm 200 300 400 500 600 1500 800 1000 1200 With motor (Standard) 15.9 17.9 19.9 21.9 23.8 28.3 32.7 36.6 42.6 Weight kg Without motor (Non-Standard) 22.7 41.5 14.8 16.8 18.8 20.8 27 2 31.6 35.5 Mounting orientation Horizontal Operating temperature range °C 5 to 40 (with no condensation) Work load kg 20 Maximum speed mm/s 300 Positioning repeatability mm ±0.1 AC servomotor (200W) Motor output

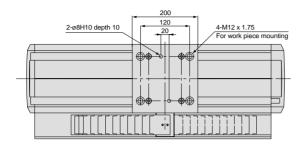
ø25mm, 20mm lead Lead screw Guide Slide guide Power supply voltage: 4.5 to 28VDC, Current consumption: 10mA or less Switch Control output: Open collector, Load current: 40mA or less, Internal voltage drop: 1.5V or less TKP0180-2BR28 manufactured by TSUBAKIMOTO CHAIN CO. **TSUBAKI CABLEVEYOR** 

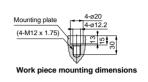
Cover with switch groove

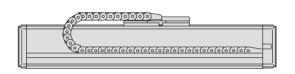
### Dimensions/ LJ1S30 3 SC (X40)

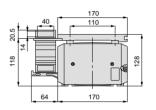
Dimensions other than those shown in the drawing are the same as standards.

Scale: 20%









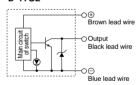
### **Compatible Motors**

Manufacturer	Motor specification symbol	Brake	Motor output (W)	Power supply voltage (VAC)	Motor model	Controller driver model
SMC controller	Nil	Without brake	200	100/110		LC1-1B3S1-□□
LC1 compatible	NII	(Horizontal specification)	200	200/220	_	LC1-1B3S2-□□
Non-standard Matsushita	G	Without brake	000	100/115	MSM021P1A	MSD021P1E
Electric Industrial Co., Ltd. motor	٠ G	(Horizontal specification)	200	200/230	MSM022P1A	MSD023P1E
Non-standard Mitsubishi Electric	R	Without brake	000	100/115	LIO DO000	MR-C20A1
Corporation motor	"	(Horizontal specification)	200	200/230	HC-PQ023	MR-C20A
Non-standard Yaskawa Electric	Υ	Without brake	200	100/115	SGME-02BF12	SGDE-02BP
	(Horizontal specification)	200	200/230	SGME-02AF12	SGDE-02AP	

#### \* Refer to pages starting with 205 for driver dimensions. Furthermore, for detailed specifications, etc., contact each motor manufacturer.

### **Switch Internal Circuit**

### D-Y7GL

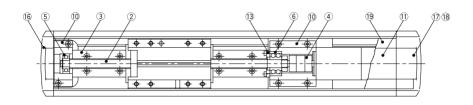


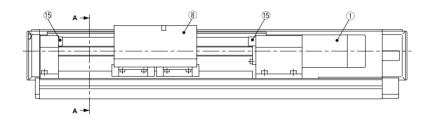
<sup>\*</sup> This drawing shows the TUBAKI CABLE VEYOR with left hand entry.

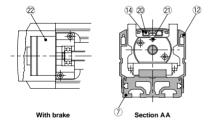
<sup>\*</sup> For a non-standard motor specification when the motor is mounted before shipping, the driver is included but the cable that connects the motor and driver is optional. Refer to page 100 for part numbers.

### Construction

### **LJ1H10**



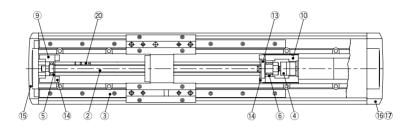


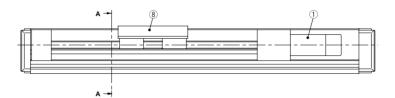


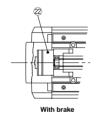
No.	Description	Material	Note
1	AC servomotor	_	50W/100W
2	Lead screw	_	Ball screw/Slide screw
3	High rigidity direct acting guide	_	
4	Coupling	_	
5	Bearing R	_	
6	Bearing F	_	
7	Body A	Aluminum alloy	
8	Table	Aluminum alloy	
9	Housing A	Aluminum alloy	
10	Housing B	Aluminum alloy	
11	Top cover	Aluminum alloy	
	•	•	

No.	Description	Material	Note
12	Side cover	Aluminum alloy	
13	Bearing retainer	Aluminum alloy	
14	Sensor rail	Aluminum alloy	
15	Bumper	IIR	
16	End cover A	PC	
17	End cover B	PC	
18	Inner cover	PC	
19	Motor cover	PC	
20	Auto switch	_	
21	Magnet	Rare earth magnet	
22	Brake	_	

# LJ1H**20**









Section AA

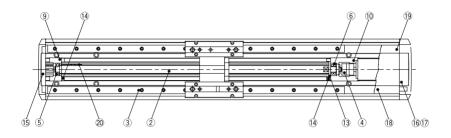
No.	Description	Material	Note
1	AC servomotor	_	100W
2	Lead screw	_	Ball screw/Slide screw
3	High rigidity direct acting guide		
4	Coupling	_	
5	Bearing R	_	
6	Bearing F	-	
7	Body A	Aluminum alloy	
8	Table	Aluminum alloy	
9	Housing A	Aluminum alloy	
10	Housing B	Aluminum alloy	
11	Top cover	Aluminum alloy	

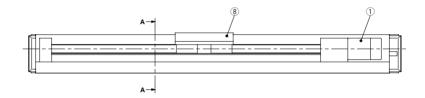
No.	Description	Material	Note
12	Side cover	Aluminum alloy	
13	Bearing retainer	Aluminum alloy	
14	Bumper	IIR	
15	End cover A	PC	
16	End cover B	PC	
17	Inner cover	PC	
18	Motor cover R	PC	
19	Motor cover L	PC	
20	Auto switch	_	
21	Magnet	Rare earth magnet	
22	Brake	_	

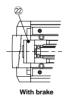
### Series LJ1H

### Construction

## LJ1H**30**







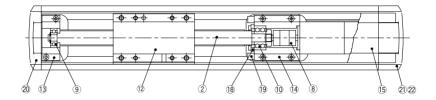


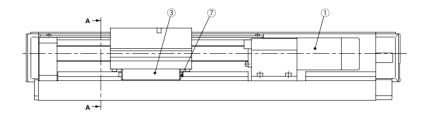
No.	Description	Material	Note
1	AC servomotor	_	200W
2	Lead screw	_	Ball screw/Slide screw
3	High rigidity direct acting guide	_	
4	Coupling	_	
5	Bearing R	_	
6	Bearing F	_	
7	Body A	Aluminum alloy	
8	Table	Aluminum alloy	
9	Housing A	Aluminum alloy	
10	Housing B	Aluminum alloy	
11	Top cover	Aluminum alloy	

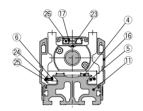
No.	Description	Material	Note
12	Side cover	Aluminum alloy	
13	Bearing retainer	Carbon steel	Electroless nickel plated
14	Bumper	IIR	
15	End cover A	PC	
16	End cover B	PC	
17	Inner cover	PC	
18	Motor cover A	PC	
19	Motor cover B	PC	
20	Auto switch	_	
21	Magnet	Rare earth magnet	
22	Brake		

### Construction

## LJ1S10







Section AA

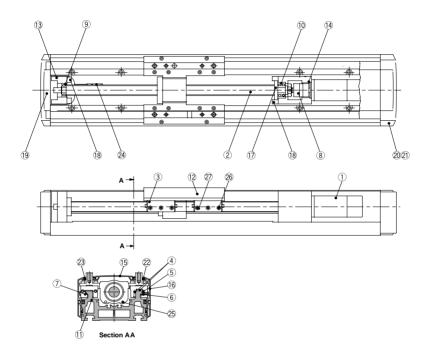
No.	Description	Material	Note
1	AC servomotor	_	50W
2	Lead screw	_	Slide screw
3	Guide frame	Aluminum alloy	
4	Guide plate A	Special resin	
5	Guide plate B	Special resin	
6	Push bar	Carbon steel	Zinc plated
7	Frame cover	Stainless steel	
8	Coupling	_	
9	Bearing R	_	
10	Bearing F	_	
11	Body A	Aluminum alloy	
12	Table	Aluminum alloy	
13	Housing B	Aluminum alloy	

No.	Description	Material	Note
14	Housing A	Aluminum alloy	
15	Top cover	Aluminum alloy	
16	Side cover	Aluminum alloy	
17	Sensor rail	Aluminum alloy	
18	Bearing retainer	Aluminum alloy	
19	Bumper	IIR	
20	End cover A	PC	
21	End cover B	PC	
22	Inner cover	PC	
23	Magnet	Rare earth magnet	
24	Hexagon socket head set screw	Chrome molybdenum steel	M3 x 8
25	Nut	Mild steel	M3
26	Auto switch	_	

### Series LJ1S

### Construction

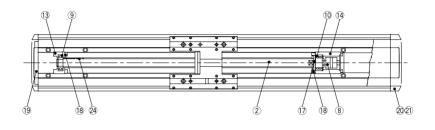
## LJ1S**20**

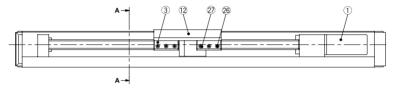


No.	Description	Material	Note
1	AC servomotor	_	100W
2	Lead screw	_	Slide screw
3	Guide frame	Aluminum alloy	
4	Guide plate A	Special resin	
5	Guide plate B	Special resin	
6	Push bar	Carbon steel	Zinc plated
7	Frame cover	Stainless steel	
8	Coupling		
9	Bearing R	_	
10	Bearing F	_	
11	Body A	Aluminum alloy	
12	Table	Aluminum alloy	
13	Housing A	Aluminum alloy	

No.	Description	Material	Note
14	Housing B	Aluminum alloy	
15	Top cover	Aluminum alloy	
16	Side cover	Aluminum alloy	
17	Bearing retainer	Aluminum alloy	
18	Bumper	IIR	
19	End cover A	PC	
20	End cover B	PC	
21	Inner cover	PC	
22	Motor cover R	PC	
23	Motor cover L	PC	
24	Auto switch		
25	Magnet	Rare earth magnet	
26	Hexagon socket head set screw	Chrome molybdenum steel	M4 x 8
27	Nut	Mild steel	M4

## LJ1S30







Section AA

No.	Description	Material	Note
1	AC servomotor	_	200W
2	Lead screw		Slide screw
3	Guide frame	Aluminum alloy	
4	Guide plate A	Special resin	
5	Guide plate B	Special resin	
6	Push bar	Carbon steel	Zinc plated
7	Frame cover	Stainless steel	
8	Coupling	_	
9	Bearing R	_	
10	Bearing F	_	
11	Body A	Aluminum alloy	
12	Table	Aluminum alloy	
13	Housing A	Aluminum alloy	

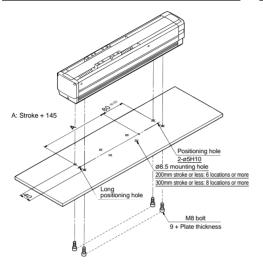
No.	Description	Material	Note
14	Housing B	Aluminum alloy	
15	Top cover	Aluminum alloy	
16	Side cover	Aluminum alloy	
17	Bearing retainer	Carbon steel	Electroless nickel plated
18	Bumper	IIR	
19	End cover A	PC	
20	End cover B	PC	
21	Inner cover	PC	
22	Motor cover R	PC	
23	Motor cover L	PC	
24	Auto switch	_	
25	Magnet	Rare earth magnet	
26	Hexagon socket head set screw	Chrome molybdenum steel	M5 x 8
27	Nut	Mild steel	M5

# Series LJ1

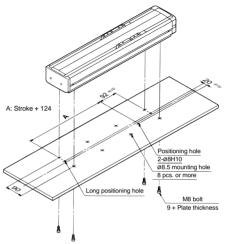
## Mounting

### **T-slot Bottom Mount**

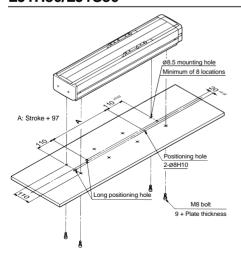
### LJ1H10/LJ1S10



### LJ1H20/LJ1S20

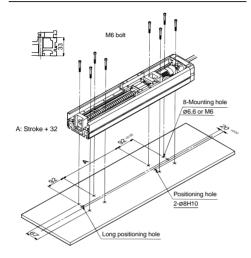


### LJ1H30/LJ1S30

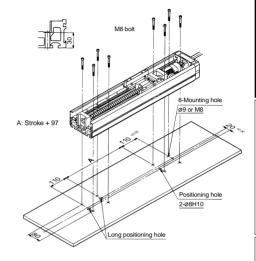


- Note 1) Although T-nuts (LJ1-T8) for mounting are included with the body for LJ1H10/LJ1S10, they are optional for other models. (See page 100.)
- Note 2) To insert the T-nuts, remove the covers at both ends of the body and insert them into the T-slots.
- Note 3) When positioning of the body is required, also perform pin hole machining.

### LJ1H20/LJ1S20



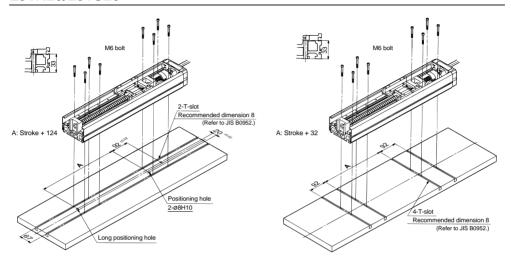
### LJ1H30/LJ1S30



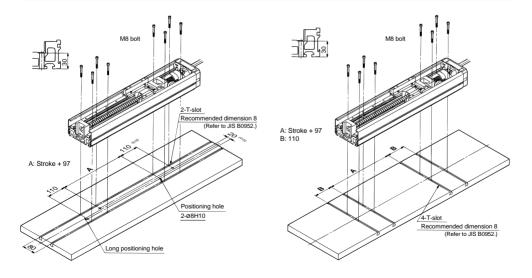
### Series LJ1

### **Top Mount (Using T-slots on the Mounting Frame)**

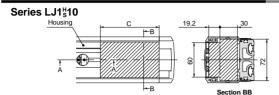
### LJ1H20/LJ1S20

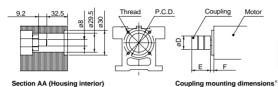


### LJ1H30/LJ1S30



### Standard/TSUBAKI CABLEVEYOR Specifications





### Motor mounting area dimensions

Manufacturer	Mitsubishi Electric Corporation Yaskawa Electric Corporation	Matsushita Electric Industrial Co., Ltd.
Thread size	M4 x 0.7	M3 x 0.5
Effective thread length (mm)	8	6
Quantity	2	4
P.C.D.	46	45

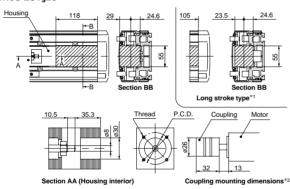
#### Motor mounting area

\* When mounting a coupling on the motor, mount it within the dimensional range shown on the left.

#### Dimensions

	С	D	Е	F	
With brake (mm)	101	26	32	8.5	
Without brake (mm)	0.2	10	27.5	17	

### Series LJ1#20



#### Motor mounting area dimensions

Manufacturer	Mitsubishi Electric Corporation Yaskawa Electric Corporation	Matsushita Electric Industrial Co., Ltd.
Thread size	M4 x 0.7	M3 x 0.5
Effective thread length (mm)	8	6
Quantity	2	4
P.C.D.	46	45

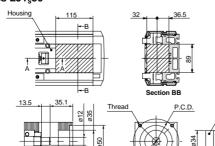
### Motor mounting area

\*1 For the motor mounting area dimensions of the models below, refer to the long stroke type dimensions.

LJ1H20□□□NC	700 to 1000mm stroke
LJ1H20□□□SC	700 to 1200mm stroke
LJ1S20□□□SC	700 to 1200mm stroke

\*2 When mounting a coupling on the motor, mount it within the dimensional range shown on the left.

### Series LJ1#30



### Motor mounting area

\* When mounting a coupling on the motor, mount it within the dimensional range shown on the left.

Motor mounting area dimensions

Manufacturer	Mitsubishi Electric Corporation Yaskawa Electric Corporation	Matsushita Electric Industrial Co., Ltd.
Thread size	M5 x 0.8	M4 x 0.7
Effective thread length (mm)	6	6
Quantity	4	4
P.C.D.	70	70

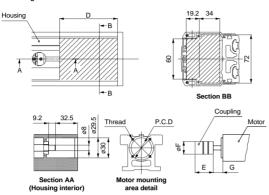
Coupling mounting dimensions\* Section AA (Housing interior)

**SMC** 

### Series LJ1

### Clean Room Specification/Dust Seal Specification

### Series LJ1510



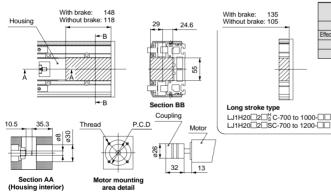
#### Motor mounting area dimensions

Manufacturer	Mitsubishi Electric Corporation Yaskawa Electric Corporation	Matsushita Electric Industrial Co., Ltd.
Thread size	M4 x 0.7	M3 x 0.5
Effective thread length (mm)	8	6
Quantity	2	4
P.C.D.	46	45

#### Dimensions

	D	Е	F	G
With brake (mm)	171	32	26	9.5
Without brake (mm)	116	27.5	19	15

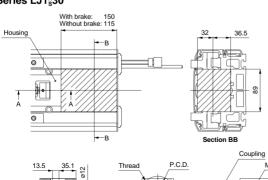
### Series LJ1<sup>H</sup>20



### Motor mounting area dimensions

Manufacturer	Mitsubishi Electric Corporation Yaskawa Electric Corporation	Matsushita Electric Industrial Co., Ltd.
Thread size	M4 x 0.7	M3 x 0.5
Effective thread length (mm)	8	6
Quantity	2	4
P.C.D.	46	45

### Series LJ1#30



Motor mounting area detail

### Motor mounting area dimensions

Manufacturer	Mitsubishi Electric Corporation Yaskawa Electric Corporation	Matsushita Electric Industrial Co., Ltd.		
Thread size	M5 x 0.8	M4 x 0.7		
Effective thread length (mm)	6	6		
Quantity	4	4		
P.C.D.	70	70		

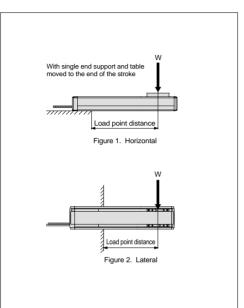
144

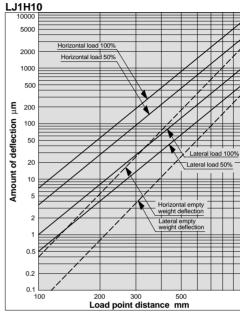
Section AA (Housing interior)

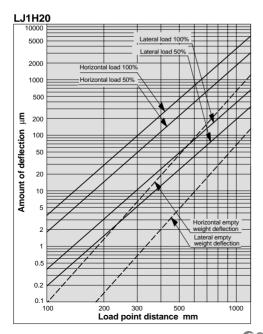
8

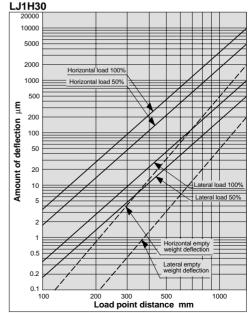
### **Deflection Data/LJ1H**

The load and the amount of deflection at load point W are shown in the graphs below for each series.









### Series LJ1

### **Deflection Data/LJ1S**

The load and the amount of deflection at load point W are shown in the graphs below for each series.

