

ACS ACTUATOR CONTROL SOLUTIONS

SERVO DRIVE AND MOTORS

STEPPER DRIVE AND MOTORS



EtherNet/IP™  Modbus

LINEAR SOLUTIONS MADE EASY

ACS – Actuator Control Solutions

WHAT IS THE ACS?

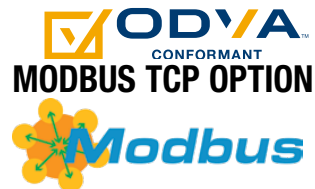
The ACS is an extremely easy-to-use servo or stepper drive & controller developed specifically to be used with electric actuators. Simply select the configured Tolomatic actuator in the software to automatically set-up most of the necessary parameters to create motion in the desired linear units (mm or inch).

BASIC CAPABILITIES:

- Operation Modes
 - » 4, 8, or 16 configurable move commands (absolute, incremental, jog, or home move types) with motion commanded via digital inputs.
 - » Analog input positioning mode (0-10Vdc or 4-20mA)
 - » Pneumatic mode replaces pneumatic valve operation for simple motion
 - » Modbus RTU over RS485 provides infinite positioning
- Adjustable motion profile parameters. Position, velocity, accel, decel, force parameters are independently configurable for up to 16 moves.
- Force limiting
- Zone output based on position
- Configurable digital I/O (24Vdc Opto-isolated, sourcing or sinking)
- Ability to reduce holding current for energy savings [Stepper]
- Compatible with most 24Vdc 2-phase stepper motors [Stepper]
- Brake output

ETHERNET/IP **EtherNet/IP™** OPTION

- Infinite positioning with EtherNet/IP CIP I/O commands
- Dual port with internal switch for daisy chaining
- Analog output echoing actuator position
- ODVA Conformant



- Infinite positioning with Modbus TCP commands
- Dual port with internal switch for daisy chaining
- Analog output echoing actuator position

Motors

SERVO

- NEMA23 & NEMA34

STEPPER

- NEMA11, NEMA17, NEMA23 & NEMA34



ACS – Features

• ETHERNET (OPTION)

Protocols:
• EtherNet/IP • Modbus TCP

• DIGITAL I/O

- 8 Digital Inputs
- 4 Digital Outputs
- 24 VDC Opto-Isolated
- Sourcing or Sinking
- Configurable Inputs

• ANALOG I/O

- 0-10 VDC or 4-20mA
- 1 Analog Input
- 1 Analog Output (optional)

• MOTOR POWER

Servo Drive	Stepper Drive
• 10-60VDC Servo Motors	• 10-52 VDC Stepper Motors
• 10 A Continuous / 20 A Peak	

• FEEDBACK

- For Digital Encoder

• BRAKE OUTPUT

- Active high/low

LED INDICATORS

- Motor Power & Fault indicators

• COM PORT

- USB Com Port

• RS485 COM PORT

- Modbus RTU (Base Model)

• DUAL PURPOSE HEAT SINK

- Removes heat from drive for optimal performance
- Panel mounting

• ACS POWER

Servo Drive	Stepper Drive
• 10-60VDC	• 10-52 VDC
• 10 - 52 VDC Keep-alive Power	
• 24 VDC Brake Power	

EASY TO USE CONFIGURATION SOFTWARE

Windows® compliant

Drive Configuration: Shows settings for Drive, Actuator, Motor, Mode Select, I/O, Fault, Safety/Limits, Home Setup, and Mode Setup. Includes a Configuration String and Motor Mounting options.

Digital I/O: Shows Inputs (Enable, Start Motion, Home, E-Stop, Move Select 1-4) and Outputs (Motion Complete, Home Complete, Fault, Zone).

Motion Manager: Shows Controls (Disable, Enabled, Home, Motion Complete), Motion Profile (Position, Velocity, Accel, Decel, Force), Jog, Absolute Move, and Incremental Move settings.

Drive Status: Shows Drive Status (Enabled, Homed, Motion Complete, Software Stop, Host in Control), Safety Faults (Positive/Negative Limit Switch, Software Stop, Position Error), and Critical Faults (Feedback Error, Over Current, Motor Over Temp, Drive Over Temp, Drive Over Voltage, Drive Under Voltage).

Move Definitions Table:

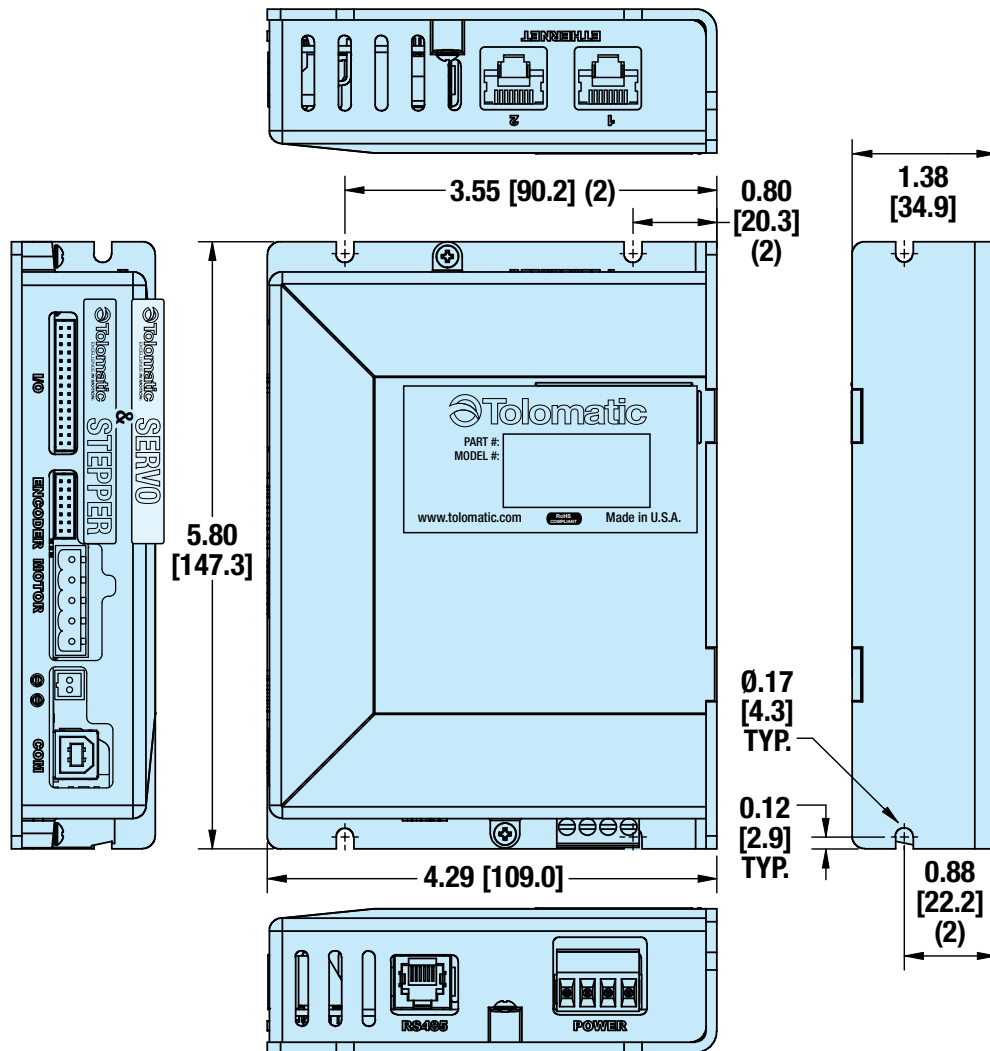
Label	Move Type	Position (in)	Velocity (in/sec)	Accel (in/sec ²)	Decel (in/sec ²)	Force %
1 MOVE1	Absolute	1.000	1.00	100.0	100.0	100.0
2 MOVE2	Absolute	2.000	2.00	90.0	90.0	90.0
3 MOVE3	Absolute	3.000	3.00	80.0	80.0	80.0
4 MOVE4	Absolute	4.000	4.00	70.0	70.0	70.0
5	IncrPos	0.250	1.00	100.0	100.0	100.0
6	IncrPos	0.500	1.00	100.0	100.0	100.0
7	IncrNeg	0.250	1.00	100.0	100.0	100.0
8	IncrNeg	0.500	1.00	100.0	100.0	100.0
9 FASTJOGPOS	JogPos	0.000	4.00	100.0	100.0	100.0
10 SLOWJOGPOS	JogPos	0.000	1.00	100.0	100.0	100.0
11 FASTJOGNEG	JogNeg	0.000	4.00	100.0	100.0	100.0
12 SLOWJOGNEG	JogNeg	0.000	1.00	100.0	100.0	100.0
13	Absolute	1.500	1.00	110.0	110.0	70.0
14	Absolute	2.500	2.00	120.0	120.0	90.0
15	Absolute	3.500	3.00	130.0	130.0	80.0
16	Absolute	4.500	4.00	140.0	140.0	70.0

3D CAD available at www.tolomatic.com
Always use configured CAD solid model
to determine critical dimensions



SPECIFICATIONS

ACS SERVO & STEPPER DRIVE/CONTROLLER DIMENSIONS



ACS Specifications

SERVO

DRIVE POWER	
Current - Continuous (Max)	10A
Current - Peak (Max)	20A
Voltage Nominal	10V - 60V
Over Voltage	65V
Under Voltage	9V
Absolute Maximum Voltage	70V
Logic Current Draw (24V)	200 mA

See ACS Hardware and Installation Guide
(Servo #3604-4181) for more details.

OPERATING CONDITIONS

Ambient Temperature	77°F, 25°C Nominal
Operating Temperature	32 - 104°F, (0 - 40°C)
Storage Temperature	32-158°F, (0-70°C)
Humidity	0 - 90% non-condensing
Weight	0.6 lb (0.27 kg)

STEPPER

DRIVE POWER	
Current - Max	10 Amps
Voltage Nominal	10 - 52V
Over Voltage	55V
Under Voltage	9V
Absolute Maximum Voltage	60V
Logic Current Draw (24V)	200 mA

See ACS Hardware and Installation
Guide (Stepper #3604-4183) for
more details.

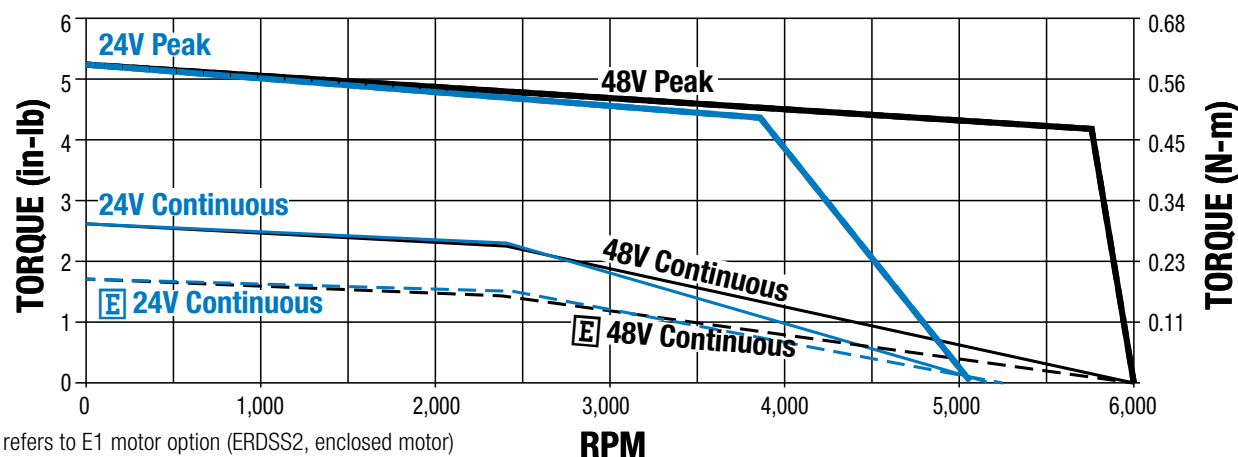
Servo Motors

MOTOR SPECIFICATIONS

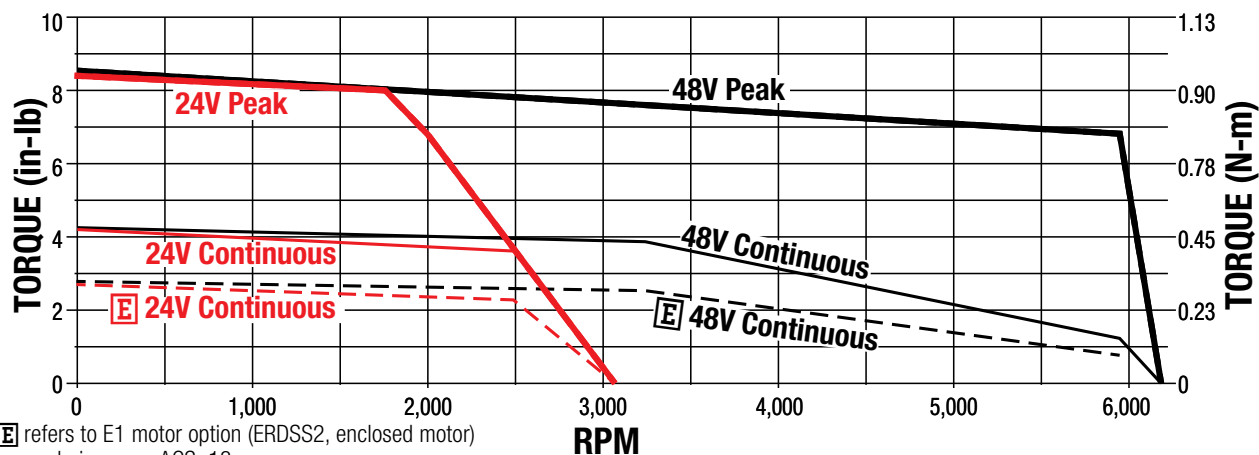
	Units		NEMA 23						NEMA 34			
			AMV2C1A1		AMV2C2A1		AMV2C3A1		AMV2D1A1		AMV2D2A1	
Continuous Torque	in-lbs	<i>N-m</i>	2.613	0.30	4.43	0.50	7.156	0.81	5.988	0.68	9.875	1.12
Peak Torque	in-lbs	<i>N-m</i>	5.225	0.59	8.86	1.00	15.3	1.73	12.0	1.36	19.75	2.23
Resistance	Ohms		0.23		0.205		0.616		0.25		0.208	
Inductance	mH		0.244		0.305		0.915		0.325		0.399	
Torque Constant (Kt)	in-lbs/A	<i>N-m/A</i>	0.3	0.034	0.511	0.058	0.886	0.100	0.692	0.078	1.14	0.129
Back EMF Constant (Ke)	V/kRPM		3.570		6.06		10.5		8.190		13.5	
Max. Continuous Current	Amps		10		10		9.32		10		10	
Max. RPM	RPM		6,000		6,000		6,000		5,000		5,000	
Rotor Inertia	lb-in ²	<i>kg-mm²</i>	0.024	7.02	0.048	14.05	0.048	14.05	0.241	70.53	0.507	148.37
Motor Weight	lb	<i>kg</i>	1.38	0.63	2.05	0.93	2.05	0.93	3.10	1.41	4.60	2.09
Motor Poles	8											
Max Case Temp	185°F (85°C)											
Encoder	Differential 500 lines/rev (2000 counts per rev)											

PERFORMANCE DATA WITH ACS DRIVE/CONTROLLER

SPEED vs TORQUE - NEMA23 MOTOR, AMV2C1A1

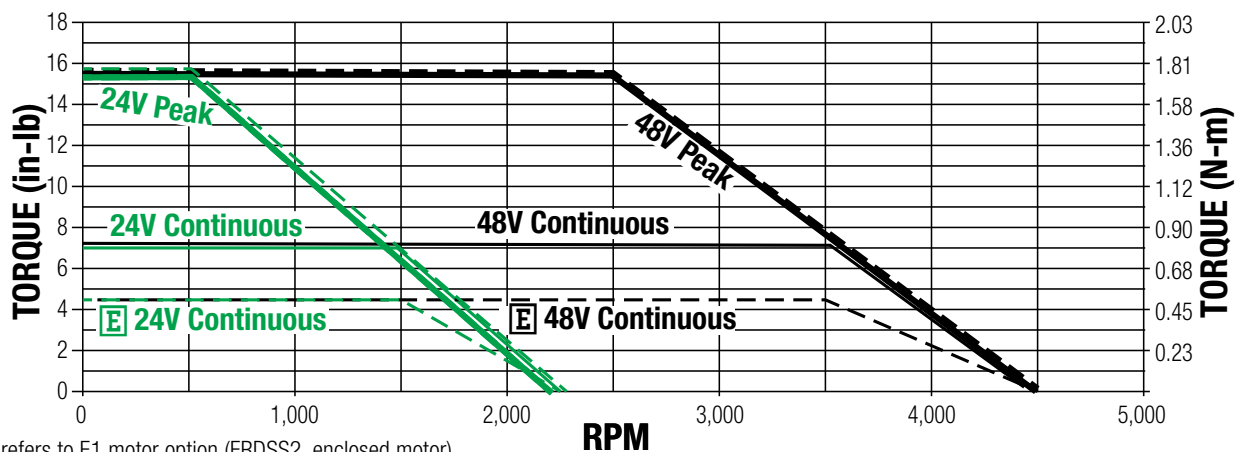


SPEED vs TORQUE - NEMA23 MOTOR, AMV2C2A1

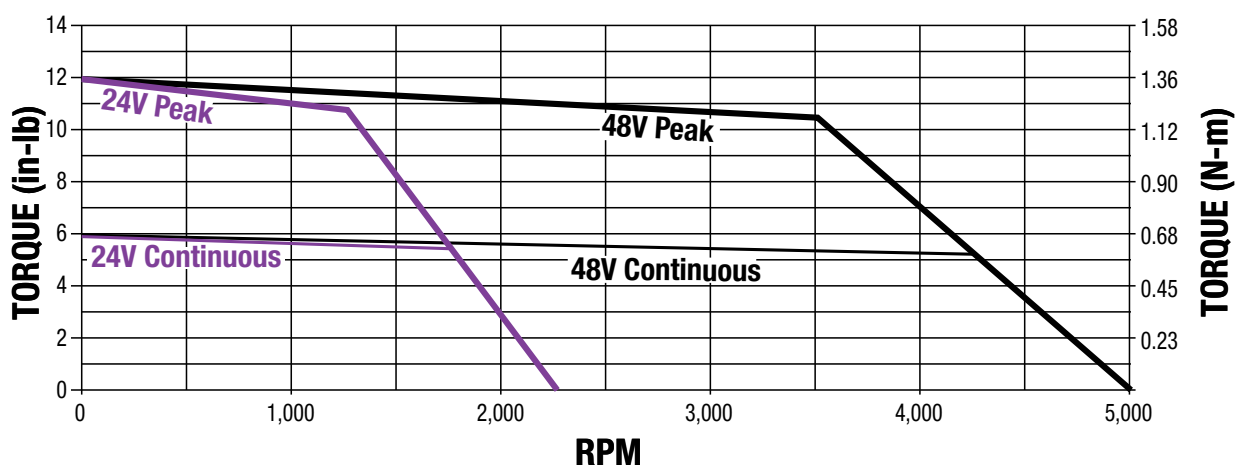


PERFORMANCE DATA WITH ACS DRIVE/CONTROLLER

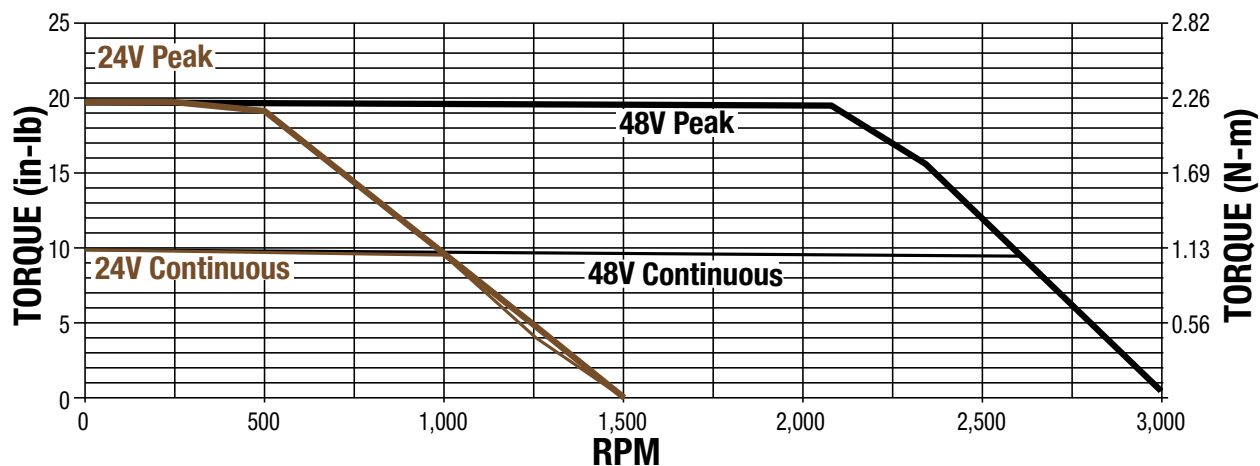
SPEED vs TORQUE - NEMA23 MOTOR, AMV2C3A1



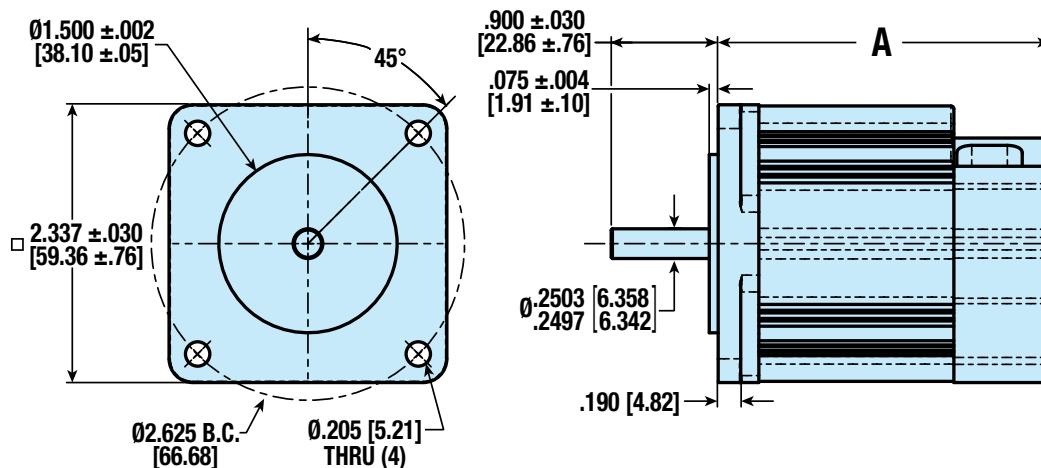
SPEED vs TORQUE - NEMA34 MOTOR, AMV2D1A1



SPEED vs TORQUE - NEMA34 MOTOR, AMV2D2A1



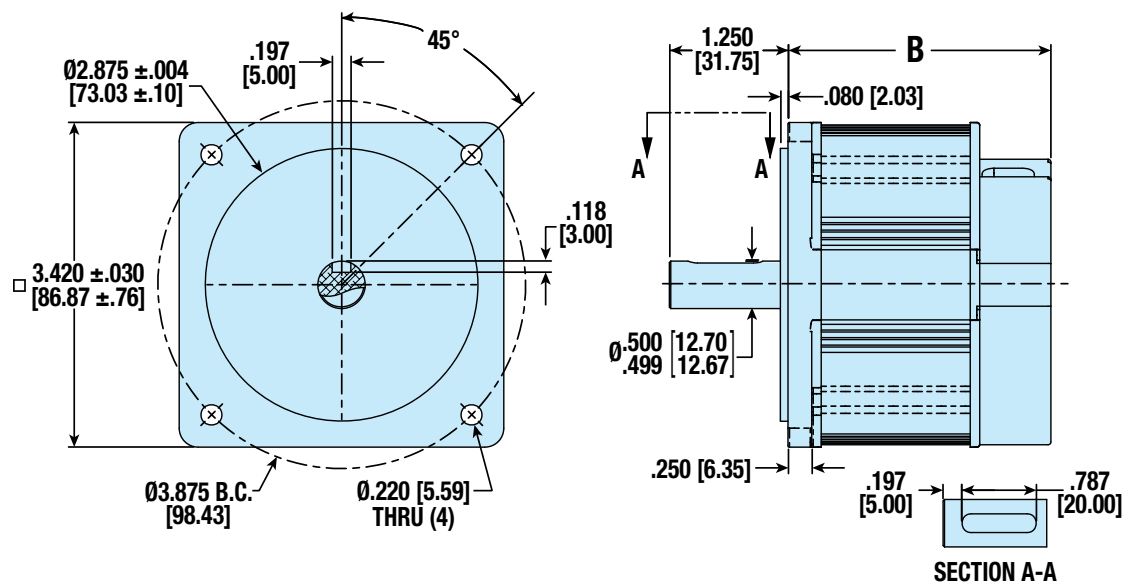
NEMA23 DIMENSIONS



A

2.790" [70.87mm] $\pm$ 0.100" [2.54mm] – AMV2C1A1
3.540" [89.92mm] $\pm$ 0.100" [2.54mm] – AMV2C2A1
3.540" [89.92mm] $\pm$ 0.100" [2.54mm] – AMV2C3A1

NEMA34 DIMENSIONS



B

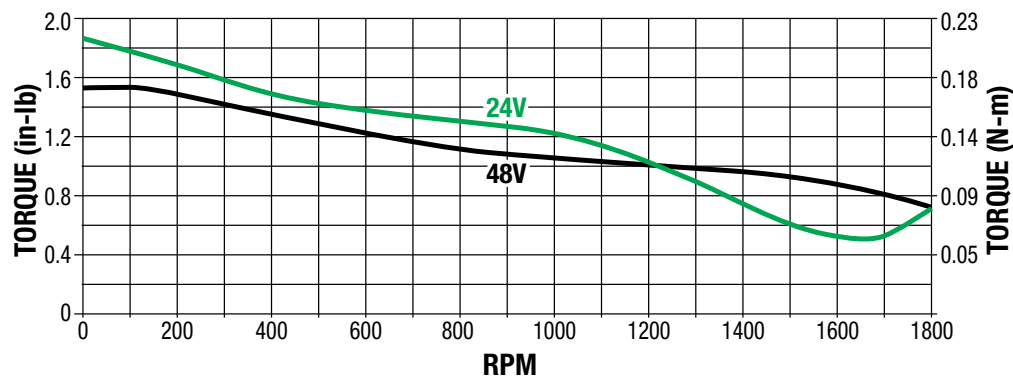
2.770" [70.36mm] $\pm$ 0.100" [2.54mm] – AMV2D1A1
3.510" [89.15mm] $\pm$ 0.100" [2.54mm] – AMV2D2A1

MOTOR SPECIFICATIONS

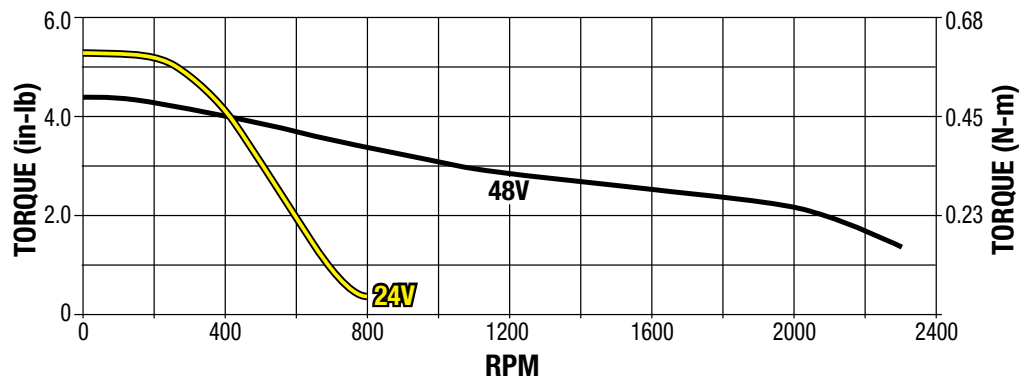
Specifications	Units	NEMA 11	NEMA 17	NEMA 23 1STK	NEMA 23 2STK	NEMA 34 1STK	NEMA 34 2STK
Resistance	Ohms	3.5	2.4	1.5	0.39	0.138	0.188
Inductance	mH	2.3	4.5	3.7	1.53	1.13	2
Rated Current	Amps-Peak/Phase	1	1.5	2	5	10	10
Max. Torque	in-lbs <i>N-m</i>	1.85 <i>0.21</i>	5.26 <i>0.59</i>	7.53 <i>0.85</i>	13.4 <i>1.51</i>	24.3 <i>2.75</i>	53.0 <i>6.0</i>
Maximum RPM		1800	2000	1200	2000	2000	1850
Degree per Step		1.8°	1.8°	1.8°	1.8°	1.8°	1.8°
Rotor Inertia	lb-in ² <i>kg-mm²</i>	0.006 <i>1.76</i>	0.028 <i>8.19</i>	0.075 <i>21.95</i>	0.133 <i>38.92</i>	0.324 <i>94.82</i>	0.546 <i>159.78</i>
Motor Weight	lb <i>kg</i>	0.44 <i>0.20</i>	0.79 <i>0.36</i>	1.21 <i>0.55</i>	2.20 <i>1.00</i>	3.53 <i>1.60</i>	5.95 <i>2.70</i>
Motor Type	Bipolar Stepper, 1.8° per Step						
Encoder	Differential; 500 line/rev (2000 count post quad)/rev						

PERFORMANCE DATA WITH ACS DRIVE/CONTROLLER

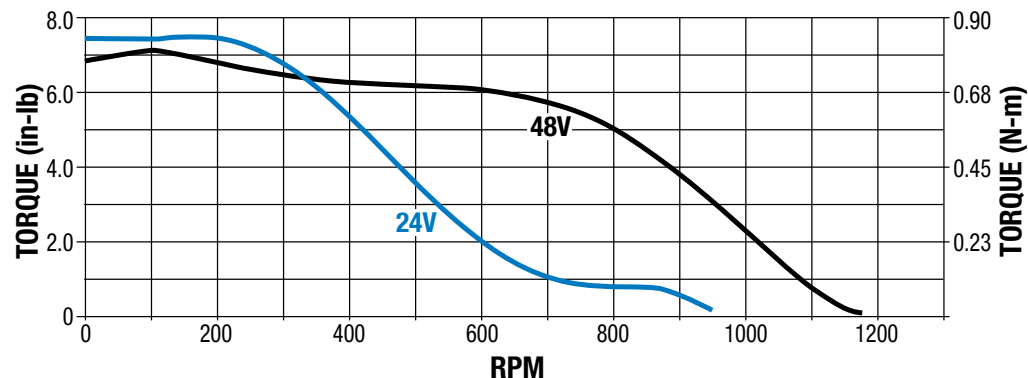
SPEED vs TORQUE - NEMA11 MOTOR - AMS1A1C1



SPEED vs TORQUE - NEMA17 MOTOR - AMS1B1C1



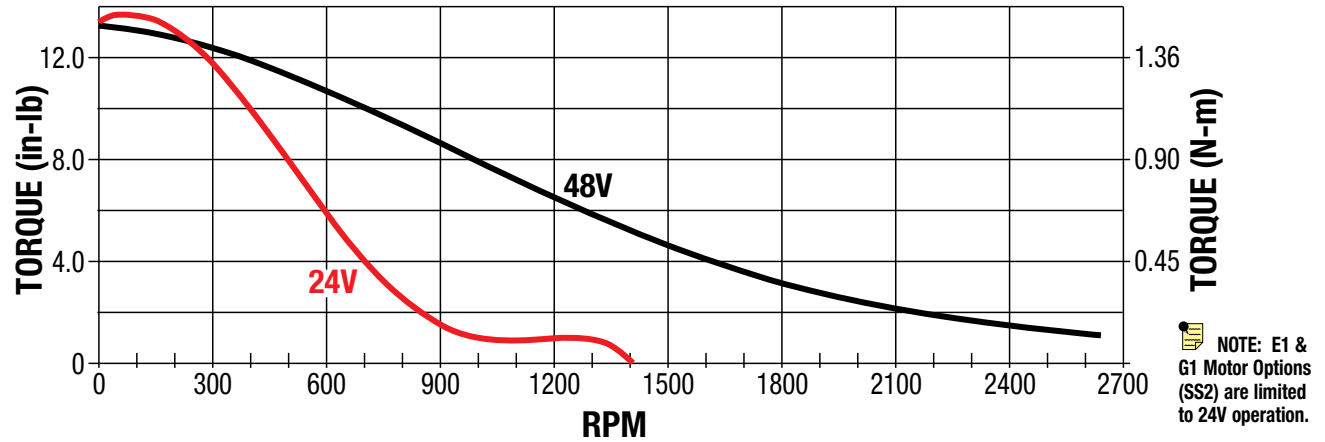
SPEED vs TORQUE - NEMA23 1 STACK MOTOR - AMS1C1C1



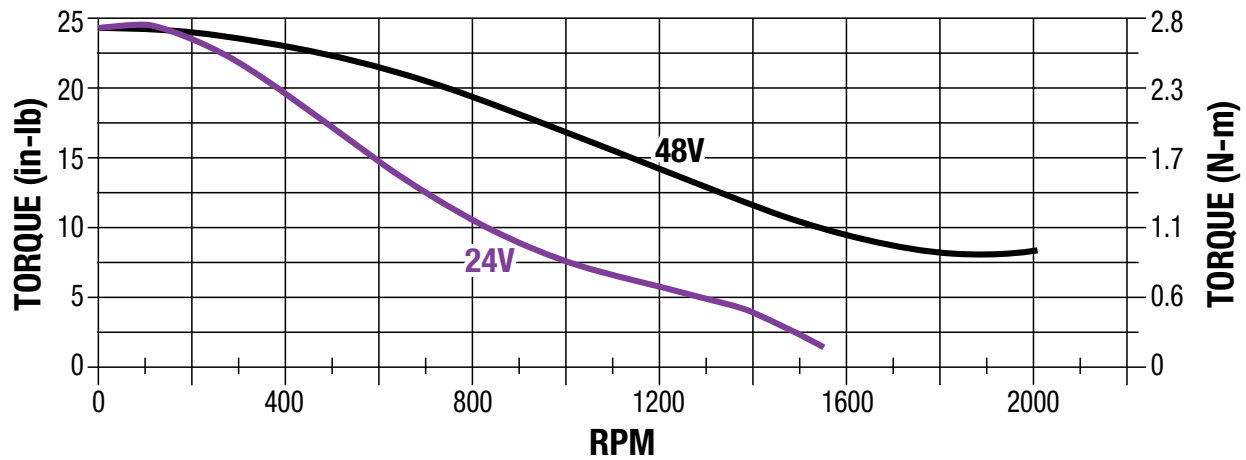
NOTE: E1 & G1
Motor Options (SS2)
are limited to 24V
operation.

PERFORMANCE DATA WITH ACS DRIVE/CONTROLLER

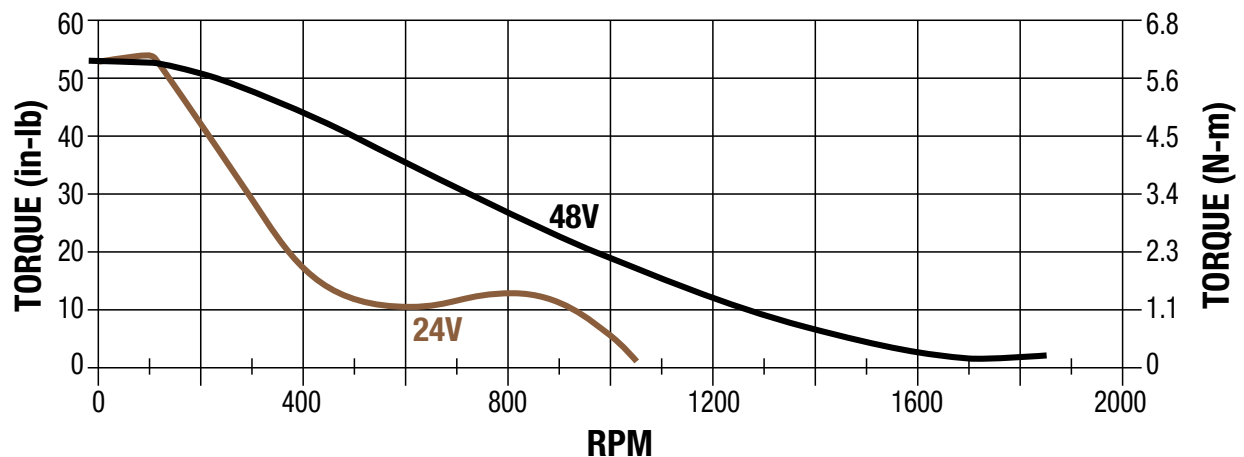
SPEED vs TORQUE - NEMA23 2 STACK MOTOR - AMS1C2C1



SPEED vs TORQUE - NEMA34 1 STACK MOTOR - AMS1D1C1



SPEED vs TORQUE - NEMA34 2 STACK MOTOR - AMS1D2C1



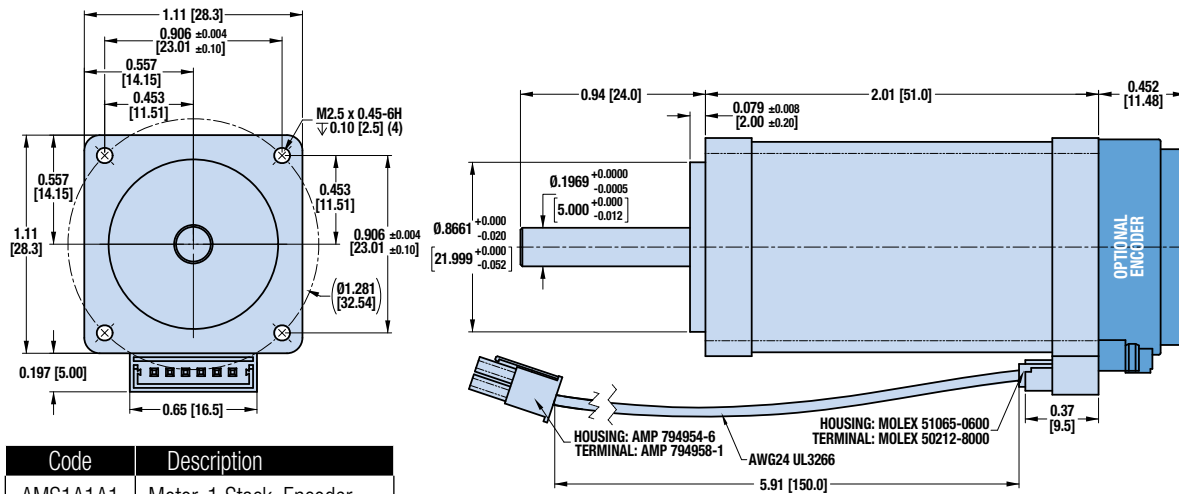
Stepper Motors

3D CAD available at www.tolomatic.com
Always use configured CAD solid model
to determine critical dimensions

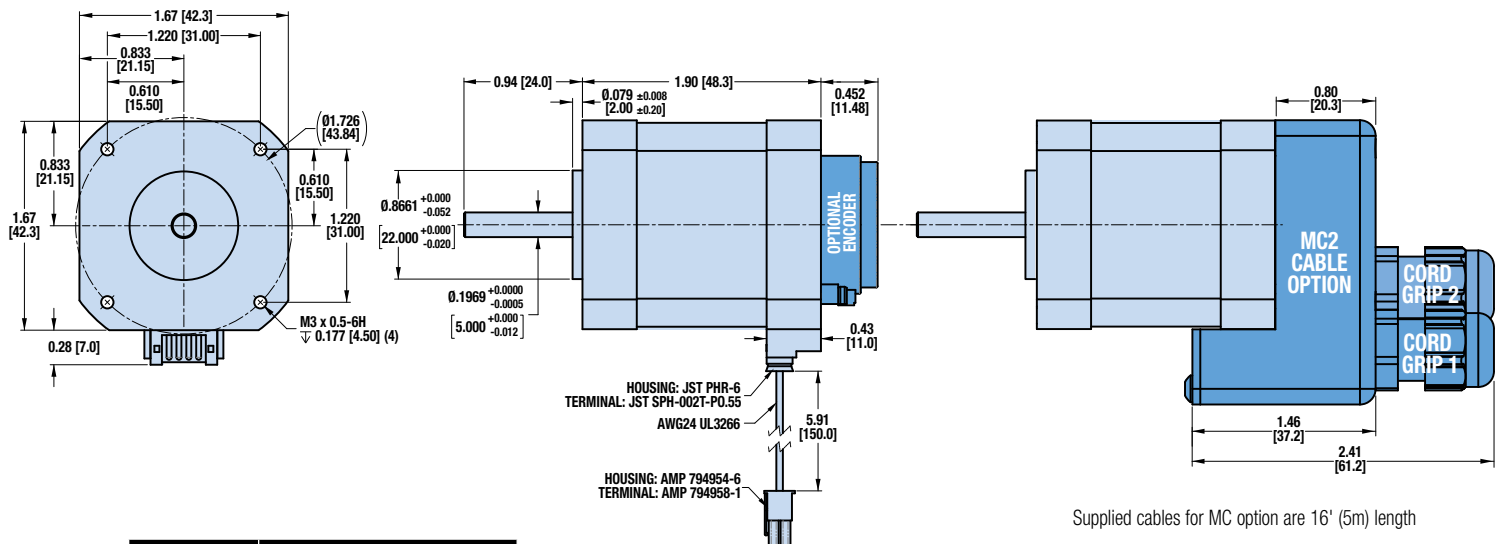


DIMENSIONS

NEMA11 DIMENSIONS



NEMA17 DIMENSIONS



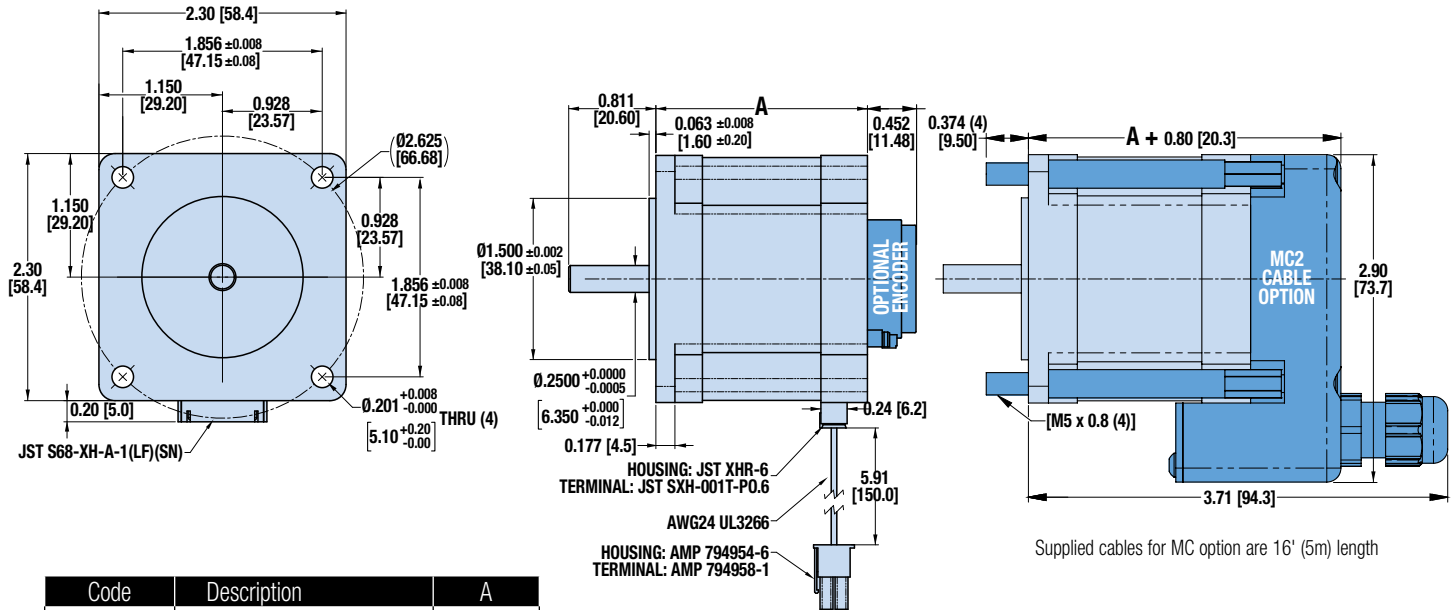
Stepper Motors

3D CAD available at www.tolomatic.com
*Always use configured CAD solid model
 to determine critical dimensions*



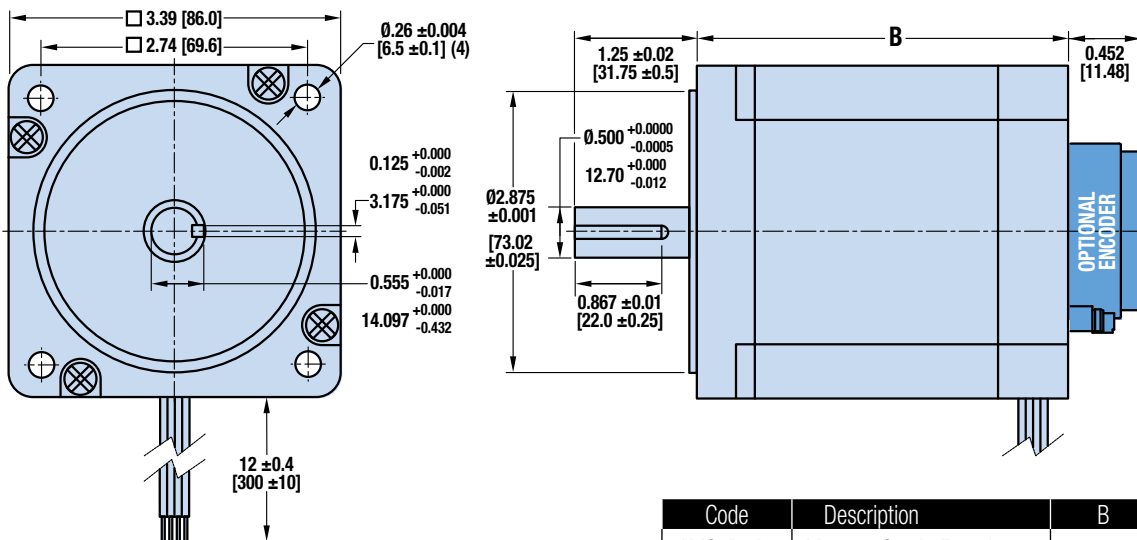
DIMENSIONS

NEMA23 DIMENSIONS



Code	Description	A
AMS1C1A1 AMS1C1E1	Motor, 1 Stack, Encoder	1.97 [50.0]
AMS1C1C1 AMS1C1G1	Motor, 1 Stack, No Encoder	
AMS1C2A1 AMS1C2E1	Motor, 2 Stack, Encoder	3.03 [77.0]
AMS1C2C1 AMS1C2G1	Motor, 2 Stack, No Encoder	

NEMA34 DIMENSIONS



Code	Description	B
AMS1D1A1	Motor, 1 Stack, Encoder	3.82 [97.0]
AMS1D1C1	Motor, 1 Stack, No Encoder	
AMS1D2A1	Motor, 2 Stack, Encoder	4.96 [126.0]
AMS1D2C1	Motor, 2 Stack, No Encoder	

SPECIFICATIONS

The electronic motor brake is available in NEMA 23 & 34 frame sizes.

It fits on 23 & 34 frame stepper and servo motors see dimensional drawings to confirm shaft size and other dimensions.

The brake is recommended for vertical or inclined applications where there can be no backdrive during power off.

When 24 VDC is connected, the brake will be deactivated and the motor can turn freely. It is recommended to use the brake only as a holding brake and not as an emergency brake.

The Electronic Motor Brake comes with a 5m cable with M8 connector.



NEMA FRAME SIZE	HOLDING TORQUE	INPUT SHAFT DIA.	OUTPUT SHAFT DIA.	CONNECTION	CURRENT @24VDC	WEIGHT (W/O CABLE)	IP RATING
	in-lbs	inch	inch			lb	
	[Nm]	[mm]	[mm]		Amp	[kg]	
23	13.28	0.250	0.250	M8	0.45 Amp	0.99	IP55
	[1.5]	[6.35]	[6.35]			[0.45]	
34	15.05	0.500	0.500	M8	0.23 Amp	3.13	IP55
	[1.7]	[12.7]	[12.7]			[1.42]	

Recommended torque clamping Screw 2.5 ft-lbs [3.4 Nm]

Electronic Motor Brakes are primarily sold as part of a complete assembly including actuator and motor. Tolomatic will install and test the completed actuator, Electronic Motor Brake, and motor assembly before shipping. **Call Tolomatic if you wish to install an Electronic Motor Brake on an existing actuator.**

Contact Tolomatic for other motor mounting options.

( Tolomatic assumes no responsibility that an electronic motor brake will fit or perform with your motor or actuator if sold separately.)

Electronic Motor Brake

SIZE: **ALL**

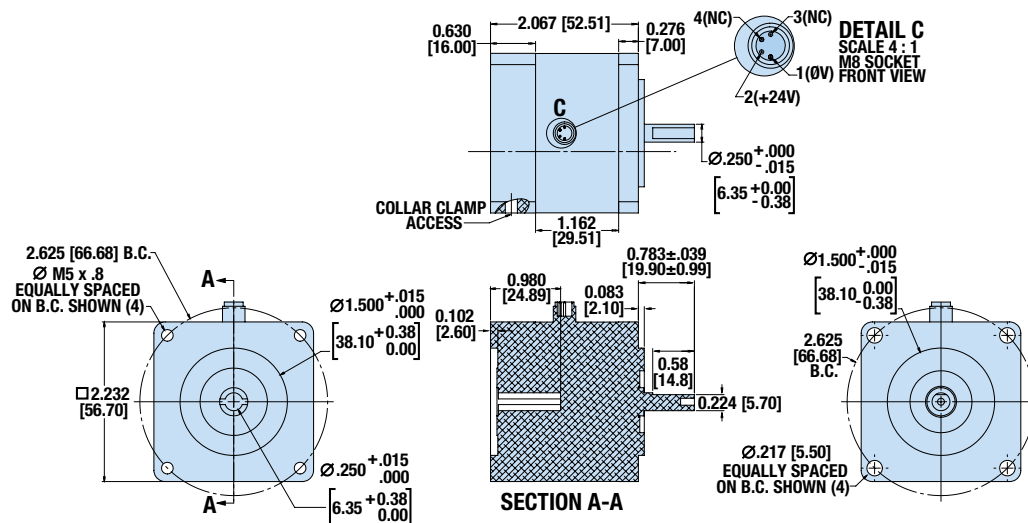
3D CAD available at www.tolomatic.com

Always use configured CAD solid model
to determine critical dimensions

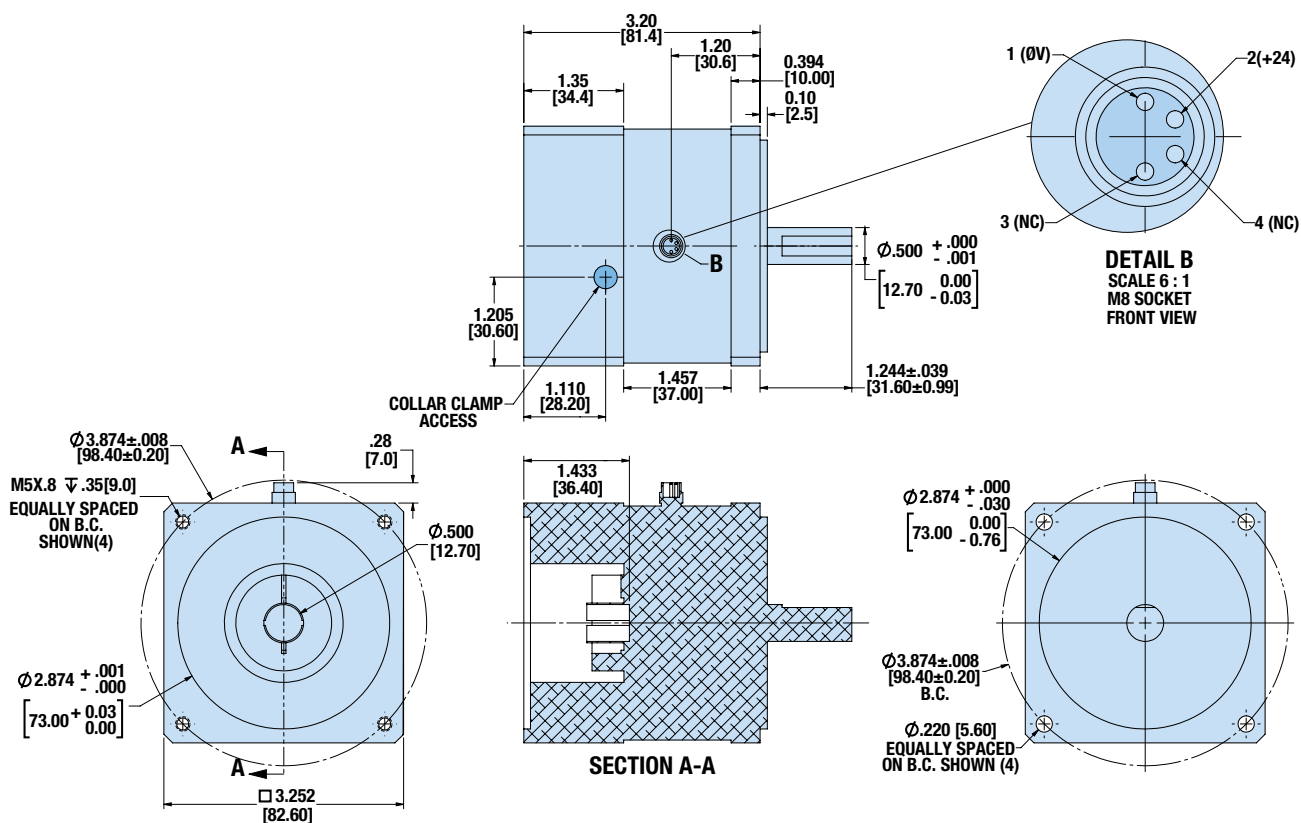


DIMENSIONS

NEMA23 DIMENSIONS



NEMA34 DIMENSIONS



ACS – Service Parts Ordering

ACS DRIVE/CONTROLLER, CABLES & MOTOR REPLACEMENT PARTS

SERVO MOTORS			
Code	Part No.	Frame Size	Description
AMV2C1A1	3604-1845	Nema 23	Motor, 1 Stack, Encoder, Winding B
AMV2C2A1	3604-1847	Nema 23	Motor, 2 Stack, Encoder, Winding B
AMV2C3A1	3604-1846	Nema 23	Motor, 2 Stack, Encoder, Winding A
AMV2D1A1	3604-1849	Nema 34	Motor, 1 Stack, Encoder, Winding B
AMV2D2A1	3604-1851	Nema 34	Motor, 2 Stack, Encoder, Winding B

Servo

Servo-NOTE: Items 1,2,4,5 & 6 from table below are recommended for complete ACS system. Order items 1,2,4,5 & 6 by part numbers

Stepper

Stepper-NOTE: All 6 items from table below are recommended for complete ACS system. Order items 1-6 by part numbers

Part No.	Description
2190-1304	Input Power Connector

STEPPER MOTORS			
Code	Part No.	Frame Size	Description
AMS1A1A1	3604-1780	Nema 11	Motor, 1 Stack, Encoder
AMS1A1C1	3604-1779	Nema 11	Motor, 1 Stack, No Encoder
AMS1B1A1 AMS1B1E1	3604-1776	Nema 17	Motor, 1 Stack, Encoder
AMS1B1C1 AMS1B1G1	3604-1775	Nema 17	Motor, 1 Stack, No Encoder
AMS1C1A1 AMS1C1E1	3604-1778	Nema 23	Motor, 1 Stack, Encoder
AMS1C1C1 AMS1C1G1	3604-1777	Nema 23	Motor, 1 Stack, No Encoder
AMS1C2A1 AMS1C2E1	3604-1955	Nema 23	Motor, 2 Stack, Encoder
AMS1C2C1 AMS1C2G1	3604-1954	Nema 23	Motor, 2 Stack, No Encoder
AMS1D1A1	3604-1957	Nema 34	Motor, 1 Stack, Encoder
AMS1D1C1	3604-1956	Nema 34	Motor, 1 Stack, No Encoder
AMS1D2A1	3604-1962	Nema 34	Motor, 2 Stack, Encoder
AMS1D2C1	3604-1961	Nema 34	Motor, 2 Stack, No Encoder

ACCESSORIES		
	Part No.	Description
1.	3604-9661	ACS Servo Drive/Controller (basic)
	3604-9662	ACS Servo Drive/Controller, EtherNet/IP (Analog Output)
	3604-9663	ACS Servo Drive/Controller, Modbus TCP (Analog Output)
1.	3604-9665	ACS Stepper Drive/Controller
	3604-9666	ACS Stepper Drive/Controller, EtherNet/IP (Analog Output)
	3604-9667	ACS Stepper Drive/Controller, Modbus TCP (Analog Output)
2.	3604-1842	Servo - Motor Power/Encoder Cable (3 m)
	3604-1843	Servo - Motor Power/Encoder Cable (5 m)
	3604-1943	Servo - Motor Power/Encoder Cable (10 m)
2.	3604-1708	Stepper - Motor Power Cable (3 m)
	3604-1709	Stepper - Motor Power Cable (5 m)
	3604-1710	Stepper - Motor Power Cable (10 m)
2.	3604-2228	34 Stepper - Motor Power Cable (3 m)
	3604-2229	34 Stepper - Motor Power Cable (5 m)
	3604-2230	34 Stepper - Motor Power Cable (10 m)

ACCESSORIES		
	Part No.	Description
3.	3604-1768	11,17,23 Stepper - Encoder Cable (3 meter length)
	3604-1769	11,17,23 Stepper - Encoder Cable (5 meter length)
	3604-1969	11,17,23 Stepper - Encoder Cable (10 meter length)
	3604-1971	34 Stepper - Encoder Cable (3 meter length)
	3604-1972	34 Stepper - Encoder Cable (5 meter length)
	3604-1973	34 Stepper - Encoder Cable (10 meter length)
4.	3604-1770	I/O Cable (3 meter length)
	3604-1771	I/O Cable (5 meter length)
	3604-1965	Replacement Brake Cable (3 meter length)
	3604-1949	Replacement Brake Cable (5 meter length)
5.	3604-1966	Replacement Brake Cable (10 meter length)
	3604-9526	Tolomatic Motion Interface CD
6.	3604-1852	Servo - USB Type B Cable
	2180-1163	Shunt Regulator 50W, 24-80 VDC

Servo Ordering

sizeit.tolomatic.com for fast,
accurate actuator selection



DRIVE

ACS V 20 48 UD CR 53

SERVO ORDER CODE	
SV	Tolomatic ACS Servo Drive

CURRENT	
20	20 Amp

VOLTAGE	
48	48 / 24 Volts

DRIVE ORDER CODE	
UD	Standard/Basic Drive with ModBus RTU over RS485
ED	Standard/Basic Drive with EtherNet /IP
MD	Standard/Basic Drive with Modbus TCP

CABLE(S) ORDER CODE	
CR3[_]	Cable(s) of 3m Length
CR5[_]	Cable(s) of 5m Length
CR10[_]	Cable(s) of 10m Length
[2]	Motor and Encoder Cables
[3]	Motor, Encoder and I/O Cables*
[5]	I/O Cables*

*I/O Cables are 3 meter length - for 5 meter I/O cable order via part number (3604-1771)

MOTOR

AM V2 C1 A1

MOTOR ORDER CODE	
AM	Tolomatic Motor

MOTOR TYPE	
V2	Servo Motor

FRAME SIZE	
C1	23 Frame Motor, 1 stack
C2	23 Frame Motor, 2 stack
C3	23 Frame Motor, 2 stack
D1	34 Frame Motor, 1 stack
D2	34 Frame Motor, 2 stack

MOTOR OPTIONS									
Code	Encoder	Gearhead	Brake	SS2	Code	Encoder	Gearhead	Brake	SS2
A1	Yes	—	—	—	B1	Yes	—	Yes	—
A2	Yes	5:1	—	—	B2	Yes	5:1	Yes	—
A3	Yes	10:1	—	—	B3	Yes	10:1	Yes	—
E1	Yes	—	—	Yes					

Stepper Ordering

DRIVE

ACST 10 48 UD CR 53

STEPPER ORDER CODE	
ST	Tolomatic ACS Stepper Drive

CURRENT	
10	Current

VOLTAGE	
48	Voltage

DRIVE ORDER CODE	
UD	Standard/Basic Drive with ModBus RTU over RS485
ED	Standard/Basic Drive with EtherNet /IP
MD	Standard/Basic Drive with Modbus TCP

CABLE(S) ORDER CODE	
CR3[_]	Cable(s) of 3m Length
CR5[_]	Cable(s) of 5m Length
CR10[_]	Cable(s) of 10m Length
[1]	Motor Cable
[2]	Motor and Encoder Cables
[3]	Motor, Encoder and I/O Cables*
[4]	Motor and I/O Cables*
[5]	I/O Cables*

*I/O Cables are 3 meter length - for 5 meter I/O cable order via part number (3604-1771)

MOTOR

AM S1 C1 E1 MC2

MOTOR ORDER CODE	
AM	Tolomatic Motor

MOTOR TYPE	
S1	Stepper Motor

NOTE: MC Cable Option available for 17 & 23 frame 1 stack motors ONLY

FRAME SIZE	
A1	11 Frame Motor
B1†	17 Frame Motor
C1†	23 Frame 1 Stack Motor
C2	23 Frame 2 Stack Motor
D1	34 Frame 1 Stack Motor
D2	34 Frame 2 Stack Motor

MOTOR OPTIONS									
Code	Encoder	Gearhead	Brake	SS2	Code	Encoder	Gearhead	Brake	SS2
A1	Yes	—	—	—	C3	—	10:1	—	—
A2	Yes	5:1	—	—	D1	—	—	Yes	—
A3	Yes	10:1	—	—	D2	—	5:1	Yes	—
B1	Yes	—	Yes	—	D3	—	10:1	Yes	—
B2	Yes	5:1	Yes	—	E1	Yes	—	—	Yes
B3	Yes	10:1	Yes	—	G1	—	—	—	Yes
C1	—	—	—	—					
C2	—	5:1	—	—					

MOTOR COVER ENCODER PROTECTION OPT.	
†MC_	Cord/Cable Grips
0	0 No Cord Grips
1	1 Cord Grips
2	2 Cord Grips
Supplied cables for MC option are 16' (5m) length	

NOTE: Gearhead and Brake available for 23 & 34 frame motors ONLY

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"Foldout" Brochure #9900-9074



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Rodless Cylinders: Band Cylinders, Cable Cylinders, Magnetically Coupled Cylinders/Slides; Guided Rod Cylinder Slides

"Foldout" Brochure #9900-9075



Power Transmission Products

Gearboxes: Float-A-Shaft®, Slide-Rite®, Disc Cone Clutch; Caliper Disc Brakes

"Foldout" Brochure #9900-9076



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