

# SLS RODLESS SCREW DRIVE ACTUATOR

 **ENDURANCE TECHNOLOGY** 



## CONTENTS

SLS Features .....	SLS_2
Critical Speed Capacities .....	SLS_4
Specifications .....	SLS_6
Support Recommendations .....	SLS_7
SLS10 Dimensions .....	SLS_9
Switches .....	SLS_11
Application Data Worksheet .....	SLS_13
Selection Guidelines .....	SLS_14
Ordering .....	SLS_15

# SLS RODLESS SCREW DRIVE ACTUATOR

## ENDURANCE TECHNOLOGY<sup>SM</sup>

Look for this endurance technology symbol indicating our durability design features

This rodless style actuator is designed for carrying light to moderate loads on a wide, rigid base. Based upon our LS pneumatic linear slide, it utilizes a guidance system consisting of two linear guide rods with recirculating ball bearings for stable, smooth and low friction operation. Built-to-order in stroke lengths up to 3 m [120 inches] with multiple screw options available.

### LOAD-BEARING CARRIER DESIGN

- Four recirculating ball bearings provide guidance, low friction loss and long life
- Load and moments are transmitted directly to the actuator body



### WIDE TABLE SURFACE

- Precision machined table surface provides a large surface area for secure mounting

### FORMED END CAP WIPERS

- Prevent contaminants from entering the sealing band area to protect internal components

### MULTIPLE SCREW TECHNOLOGIES •

#### YOU CAN CHOOSE:

- Solid nuts of bronze or engineered resins offering quiet performance at the lowest cost; anti-backlash available



- Ball nuts offer positioning accuracy and repeatability with longer life; low-backlash available



### SCREW SUPPORT BEARINGS

- High thrust bearing assembly design isolates the motor from axial forces

# TOLOMATIC... LINEAR SOLUTIONS MADE EASY

## EXTERNAL BUMPERS

- Bumpers protect the screw and nut assembly from damage at end of stroke

## YOUR MOTOR HERE

### YOU CAN CHOOSE:

- Motor or gearbox supplied and installed by Tolomatic
  - Specify the device to be installed and actuator ships with proper mounting hardware
  - Specify and ship your device to Tolomatic for factory installation
- LMI (inline) motor mount only

## T-SLOT MOUNTING

- Actuator base has two T-Slot channels running the entire length for secure mounting
- Table includes two T-Slot channels for easy attachment of any load



## LIGHTWEIGHT ALUMINUM DESIGN

- Black anodized extrusion design is optimized for rigidity and strength
- External switch channels on both sides allow easy placement and adjustment of position indicating switches

## STAINLESS STEEL SEALING BAND

- Prevents contaminants from entering the screw and nut area for prolonged life
- Fatigue resistant stainless steel bands are specifically made to offer long life and will not elongate



## OPTIONS



### CARRIER OPTIONS

- AUXILIARY CARRIER** Doubles the load capacity and increases bending moments capacity significantly

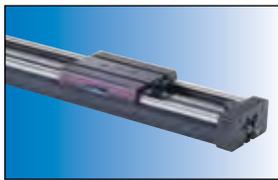
### METRIC OPTION

Provides metric tapped holes for mounting of load to carrier and of actuator



### SWITCHES

Styles include: reed, hall-effect or triac. Select either 5m potted cable with flying leads or 150mm to quick-disconnect coupler with mating 5m cable



# SLS10 Rodless Screw Drive Actuator

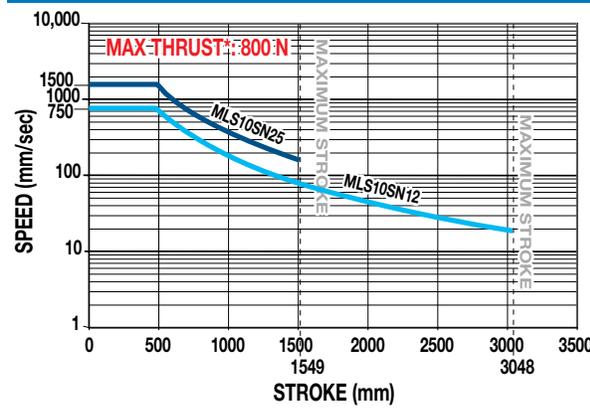
## ACME SCREW SPECIFICATIONS

sizeit.tolomatic.com for fast, accurate actuator selection

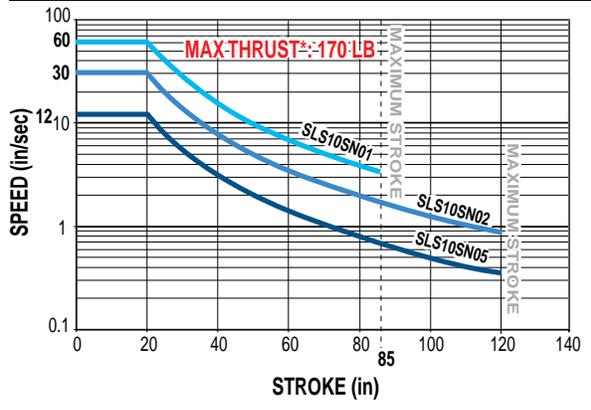


### SLS/MLS10 ACME SCREW CRITICAL SPEED AND PV LIMITS

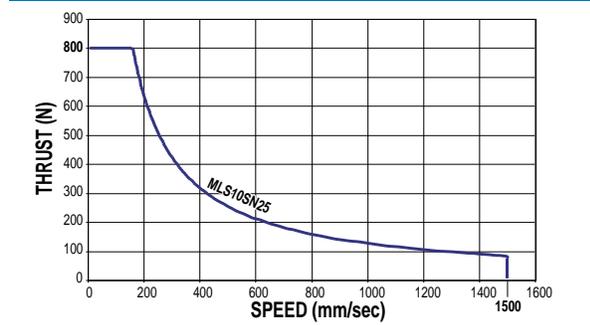
**CRITICAL SPEED WITH 12mm METRIC ACME SCREW**



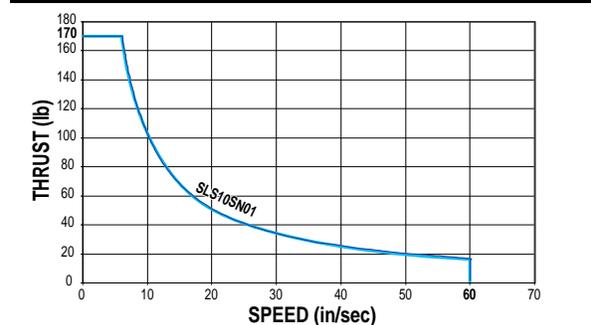
**CRITICAL SPEED WITH 1/2" US CONVENTIONAL ACME SCREW**



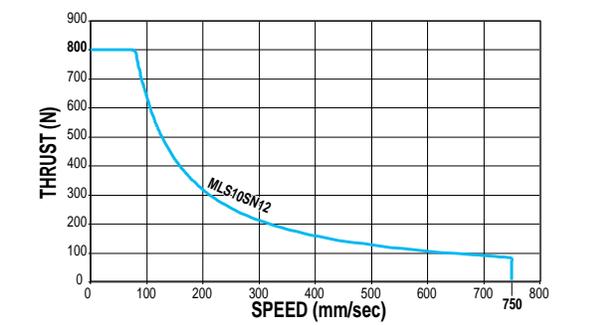
**PV LIMITS: 12mm ACME METRIC SCREW w/25mm LEAD**



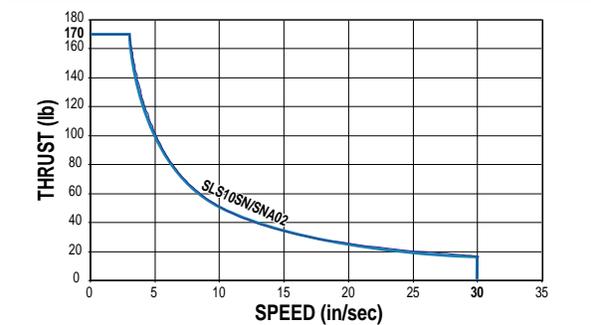
**PV LIMITS: 1/2" 1 TPI US CONVENTIONAL ACME SCREW**



**PV LIMITS: 12mm ACME METRIC SCREW w/12mm LEAD**



**PV LIMITS: 1/2" 2 TPI US CONVENTIONAL ACME SCREW**



SN = Solid Nut  
SNA = Solid Anti-backlash Nut

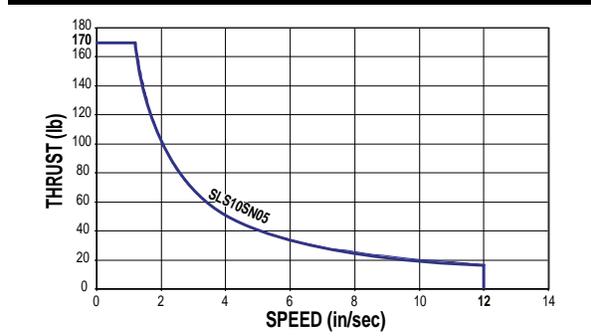
*\* Maximum thrust is the maximum continuous dynamic thrust subject to Thrust x Velocity limitation.*

**PV LIMITS:** Any material which carries a sliding load is limited by heat buildup. The factors that affect heat generation rate in an application are the pressure on the nut in pounds per square inch and the surface velocity in feet per minute. The product of these factors provides a measure of the severity of an application.

$$\left( \frac{P}{\text{Thrust}} \right) \times \left( \frac{V}{\text{Speed}} \right) \leq 0.1$$

$$\left( \frac{\text{Thrust}}{\text{Max. Thrust Rating}} \right) \times \left( \frac{\text{Speed}}{\text{Max. Speed Rating}} \right) \leq 0.1$$

**PV LIMITS: 1/2" 5 TPI US CONVENTIONAL ACME SCREW**

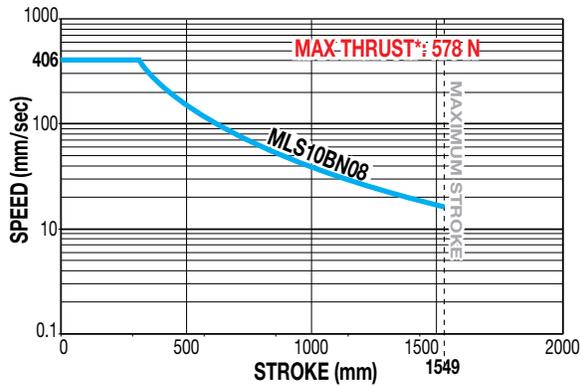


# SLS10 Rodless Screw Drive Actuator

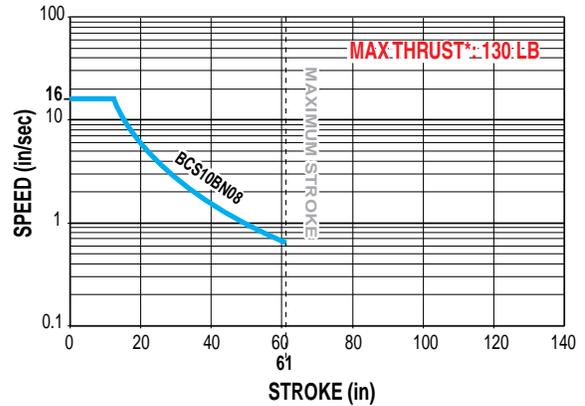
## BALL SCREW SPECIFICATIONS

### SLS/MLS10 BALL SCREW SPECIFICATIONS

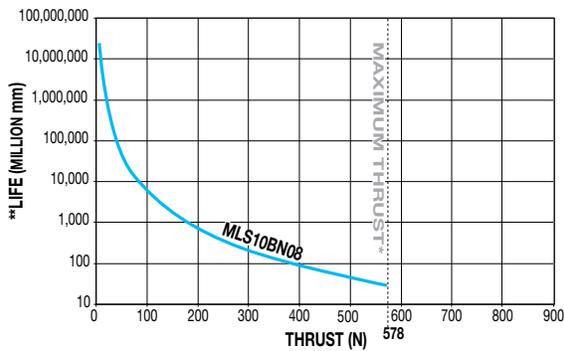
CRITICAL SPEED WITH 10mm METRIC BALL SCREW



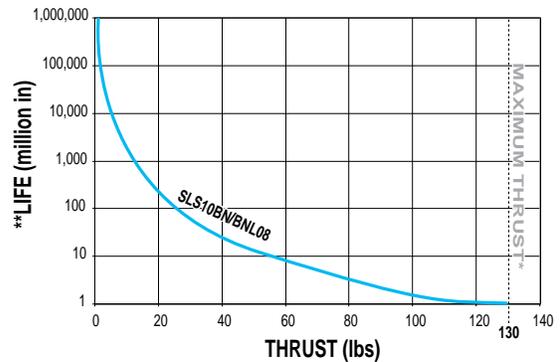
CRITICAL SPEED WITH 3/8" US CONVENTIONAL BALL SCREW



LIFE CALCULATION: 10mm METRIC BALL SCREW w/3.2mm LEAD



LIFE CALCULATION: 3/8" 8TPI US CONVENTIONAL BALL SCREW



**BN = Ball Nut**



**\* Maximum thrust reflects 90% reliability for 25 million linear millimeters of travel.**

**\*\*Life indicates theoretical maximum life of screw only, under ideal conditions and does not indicate expected life of actuator.**

# SLS10 Rodless Screw Drive Actuator

## SPECIFICATIONS

sizeit.tolomatic.com for fast,  
accurate actuator selection



### SPECIFICATIONS RELATED TO ACTUATOR SIZE AND SCREW SELECTION

METRIC LEAD SCREWS										
ACTUATOR SERIES	SCREW DIA. (mm)	SCREW TYPE	LEAD (mm/turn)	LEAD ACCURACY (mm/300)	BACKLASH (mm)	MAXIMUM THRUST (N)	MAXIMUM STROKE (mm)	INERTIA (kg-m <sup>2</sup> x 10 <sup>-6</sup> )		BREAKAWAY TORQUE (N-m)
								BASE ACTUATOR	PER/mm OF STROKE	
								In Line		
MLS10	10	BN	3.2	0.13	0.38	578	1549	37.50	3.47	0.12
	10	BNL	3.2	0.13	0.05	578	1549	37.50	3.47	0.12
	12	SN	12	0.13	0.18	800	3048	6.49	0.41	0.17
	12	SN	25	0.13	0.18	800	1626	15.01	0.41	0.17

US CONVENTIONAL LEAD SCREWS										
ACTUATOR SERIES	SCREW DIA. (in)	SCREW TYPE	TPI (turns/in)	LEAD ACCURACY (in/ft)	BACKLASH (in)	MAXIMUM THRUST* (lb)	MAXIMUM STROKE (in)	INERTIA (lb-in <sup>2</sup> )		BREAKAWAY TORQUE (lb-in)
								BASE ACTUATOR	PER/in OF STROKE	
								In Line		
SLS10	0.375	BN	08	0.004	0.015	130	61	0.0054	0.0005	1.063
	0.375	BNL	08	0.004	0.002	130	61	0.0054	0.0005	1.063
	0.500	SN	01	0.006	0.007	170	85	0.0554	0.0017	1.875
	0.500	SN	02	0.005	0.007	170	120	0.0262	0.0017	1.438
	0.500	SNA	02	0.005	0.003	170	120	0.0262	0.0017	1.438
	0.500	SN	05	0.006	0.007	170	120	0.0180	0.0017	1.250

SCREW CODE	DESCRIPTION
SN	Solid Nut
SNA	Anti-backlash Solid Nut
BN	Ball Nut
BNL	Low-Backlash Ball Nut



Contact Tolomatic for higher accuracy and lower backlash options.  
\* For Acme screws, maximum thrust is the maximum continuous dynamic thrust subject to Thrust x Velocity limitation. For ball screws, maximum thrust reflects 90% reliability for 25 million linear millimeters of travel.

### GENERAL ACTUATOR SPECIFICATIONS

MLS METRIC ACTUATORS					
ACTUATOR SERIES	CARRIER WEIGHT (kg)	BASE WEIGHT (kg) (Including Carrier)	WEIGHT PER/IN OF STROKE (g)	TEMPERATURE RANGE (C°)	IP RATING**
MLS10	0.69	2.74	7.23	4-54	44

SLS US CONVENTIONAL ACTUATORS					
ACTUATOR SERIES	CARRIER WEIGHT (lb)	BASE WEIGHT (lb) (Including Carrier)	WEIGHT PER/IN OF STROKE (lb)	TEMPERATURE RANGE (F°)	IP RATING*
SLS10	1.54	6.05	0.404	40 - 130	44



\* Heat generated by the motor and drive should be taken into consideration as well as linear velocity and work cycle time. For applications that require operation outside of the recommended temperature range, contact Tolomatic.

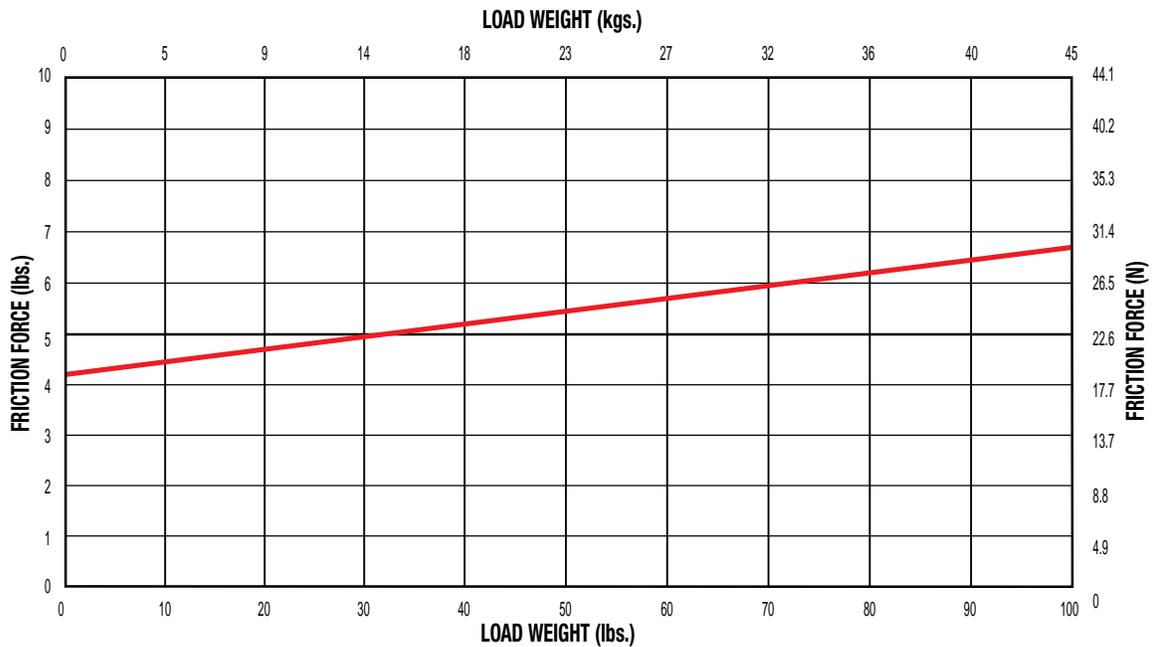
\*\* Protected against ingress of solid particles greater than 1mm (.039 in) and splashing water.

LARGE FRAME MOTORS AND SMALLER SIZE ACTUATORS: Cantilevered motors need to be supported, if subjected to continuous rapid reversing duty and/or under dynamic conditions.

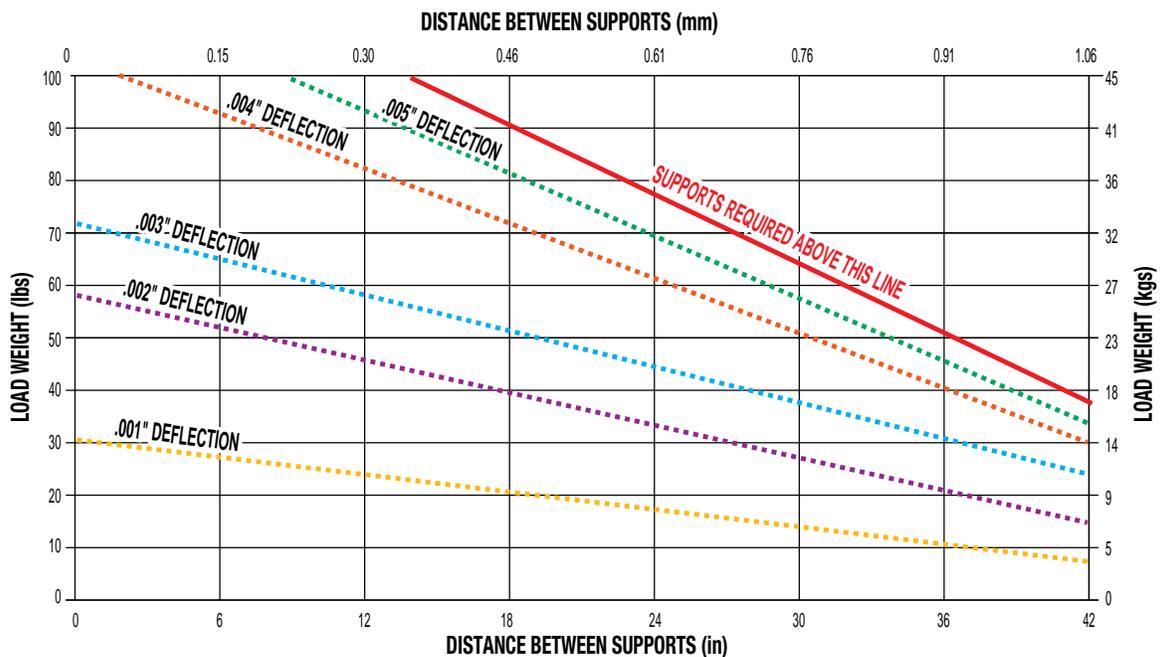
# SLS10 Rodless Screw Drive Actuator

## SPECIFICATIONS

### FRICITION FORCE



### SUPPORT RECOMMENDATIONS



# SLS10 Rodless Screw Drive Actuator

## SPECIFICATIONS

sizeit.tolomatic.com for fast, accurate actuator selection



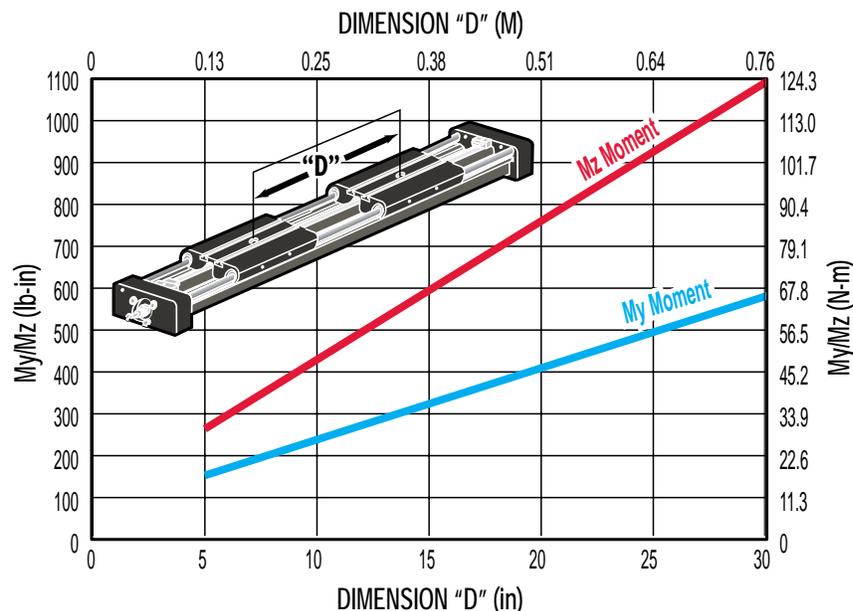
### DYNAMIC BENDING MOMENTS AND LOADS

STANDARD CARRIER	MAXIMUM BENDING MOMENTS AND LOADS		METRIC	US CONVENTIONAL
			MLS10	SLS10
	Mx Moment (Roll)	(N·m : lb-in)	9.0	80
	My Moment (Pitch)	(N·m : lb-in)	9.0	80
	Mz Moment (Yaw)	(N·m : lb-in)	14.1	125
	Fz Moment (Lateral)	(N : lb)	445	100
AUXILIARY CARRIER: Increases rigidity, load-carrying capacity and moments			MLS10	SLS10
	Mx Moment (Roll)	(N·m : lb-in)	18.1	160
	My Moment (Pitch)	(N·m : lb-in)	20.1	178
	Mz Moment (Yaw)	(N·m : lb-in)	31.3	278
	Fz Moment (Lateral)	(N : lb)	890	200
	Minimum Dimension 'D'	(mm : in)	169.7	5.5

**!** Breakaway torque will increase when using the Auxiliary carrier option. When ordering, determine your working stroke and enter this value into the configuration string. Overall actuator length will automatically be calculated.

\*Loads shown in table are at minimum "D" dimension, for ratings with longer "D" dimension see graph below

### AUXILIARY CARRIER: BENDING MOMENT AT 'D' DISTANCE



Rates shown on charts were calculated with these assumptions:  
 1.) Coupling between carriers is rigid.  
 2.) Load is equally distributed between carriers.

3.) Coupling device applies no misalignment loads to carriers.  
 \* Customer must specify Dimension "D" (Distance between carrier center lines) in configuration string.

# SLS10 Rodless Screw Drive Actuator

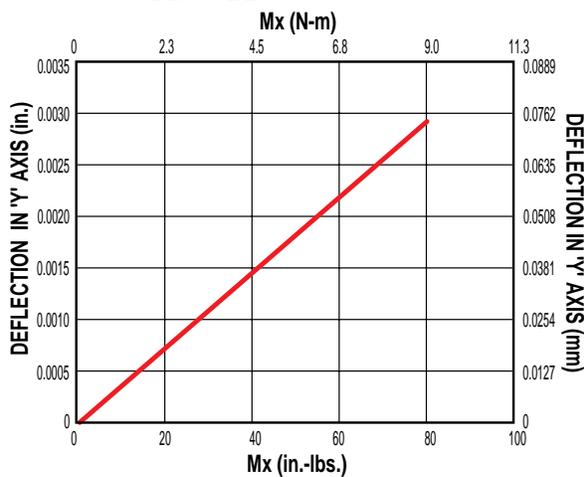
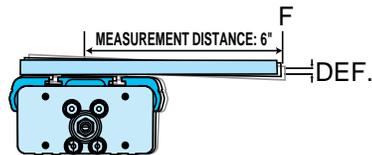
## SPECIFICATIONS

### LOAD DEFLECTION

#### Y-AXIS DEFLECTION

Figures calculated with the following considerations:

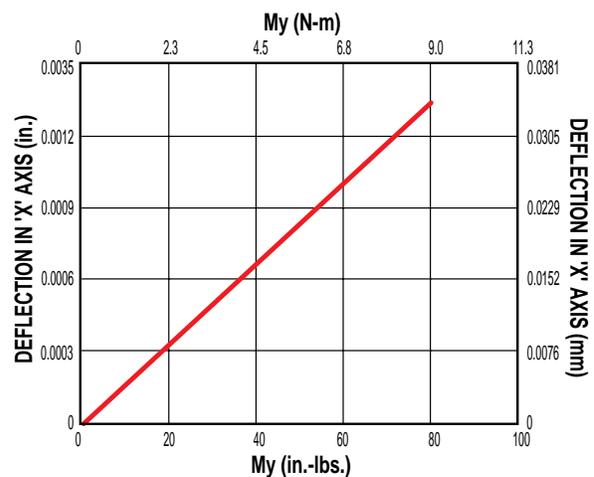
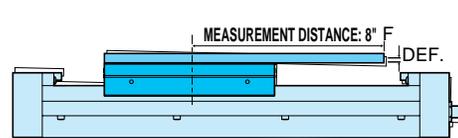
- 1.) Tube supports spaced at minimum distances for each bore size
- 2.) Measurement distance from F to center of carrier is 6 inches



#### X-AXIS DEFLECTION

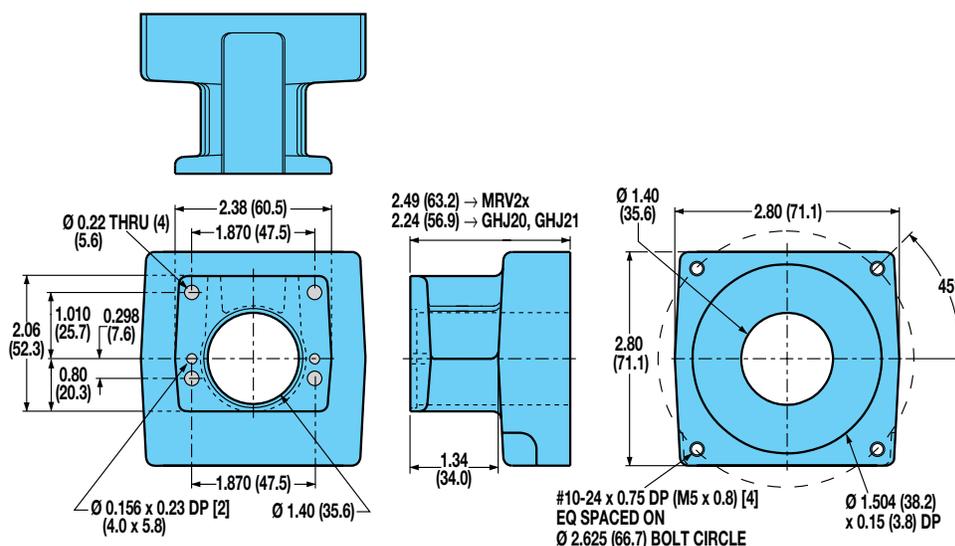
Figures calculated with the following considerations:

- 1.) Tube supports spaced at minimum distances for each bore size
- 2.) Measurement distance from F to center of carrier is 8 inches



## DIMENSIONS

### SLS/MLS10: IN-LINE MOUNT FOR BRUSHLESS MOTORS AND GEARHEADS



**For gearhead dimensions and specifications, refer to literature #3600-4161**

**NOTE: MRB & MRV motors are discontinued contact Tolomatic for information on YMH (Your Motor Here)**

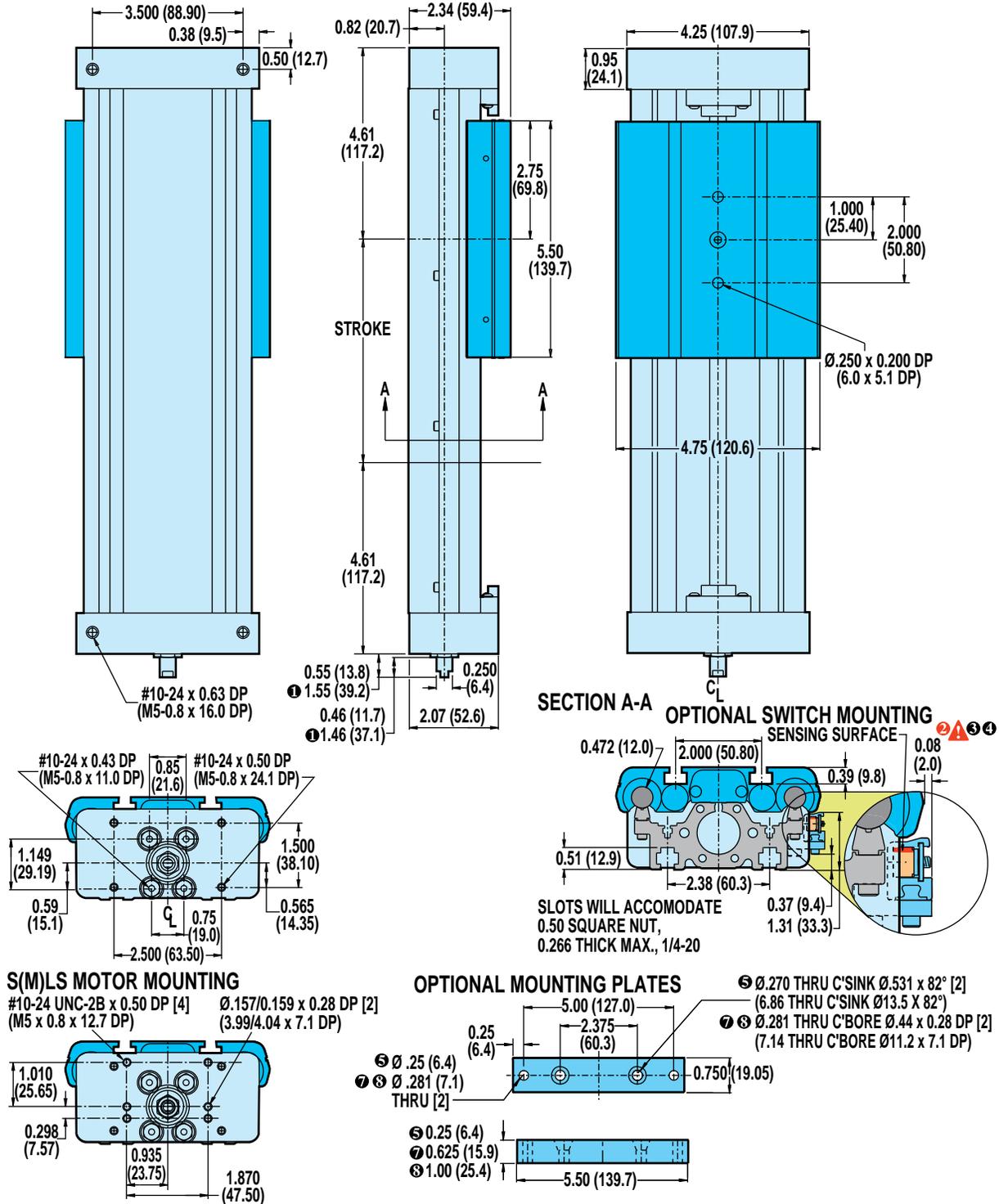
# SLS10 Rodless Screw Drive Actuator

## DIMENSIONS

3D CAD available at [www.tolomatic.com](http://www.tolomatic.com)  
Always use configured CAD solid model to determine critical dimensions



### SLS10/MLS10 ACTUATOR AND OPTIONS DIMENSIONS



1 FOR EXTENDED SHAFT

2 **CAUTION: DO NOT OVERTIGHTEN SWITCH HARDWARE WHEN INSTALLING**

3 NOTE: The scored face of the switch indicates the sensing surface and must face toward the magnet

4 NOTE: Some actuators require switch mounting on a specific side of the actuator. Call Tolomatic 1-800-328-2174

5 KIT #0610-9010 Mounting Plate

6 KIT #0610-9066 Mounting Plate for use with 23 frame

7 KIT #0610-9067 Mounting Plate for use with 34 frame

Unless otherwise noted, all dimensions shown are in inches (Dimensions in parenthesis are in millimeters)

# SLS Rodless Screw Drive Actuator

## SWITCHES



There are 10 sensing choices: DC reed, form A (open) or form C (open or closed); AC reed (Triac, open); Hall-effect, sourcing, PNP (open); Hall-effect, sinking, NPN (open); each with either flying leads or QD (quick disconnect). Commonly used to send analog signals to PLC (programmable logic controllers), TLL, CMOS circuit or other controller device. These switches are activated by the actuator's magnet.

Switches contain reverse polarity protection. QD cables are shielded; shield should be terminated at flying lead end.

If necessary to remove factory installed switches, be sure to reinstall on the same side of actuator with scored face of switch toward internal magnet.

## SPECIFICATIONS

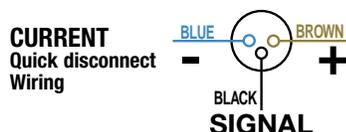
ORDER CODE	REED DC				REED AC		HALL-EFFECT DC			
	RT	RM	BT	BM	CT	CM	TT	TM	KT	KM
LEAD	5m	QD*	5m	QD*	5m	QD*	5m	QD*	5m	QD*
CABLE SHIELDING	Unshielded	Shielded†	Unshielded	Shielded†	Unshielded	Shielded†	Unshielded	Shielded†	Unshielded	Shielded†
SWITCHING LOGIC	"A" Normally Open		"C" Normally Open or Closed		Triac Normally Open		PNP (Sourcing) Normally Open		NPN (Sinking) Normally Open	
MECHANICAL CONTACTS	Single-Pole Single-Throw		Single-Pole Double-Throw		Single-Pole Single-Throw		NO, These Are Solid State Components			
COIL DIRECT	Yes		Yes		Yes		—			
POWER LED	None		None		None		None			
SIGNAL LED	Red		None		None		Red		Red	
OPERATING VOLTAGE	200 Vdc max.		120 Vdc max.		120 Vac max.		5 - 25 Vdc			
OUTPUT RATING	—		—		—		25 Vdc, 200mA dc			
OPERATING TIME	0.6 msec max. (including bounce)		0.7 msec max. (including bounce)		—		< 10 micro sec.			
OPERATING TEMPERATURE	-40°F [-40°C] to 158°F [70°C]						0°F [-18°C] to 150°F [66°C]			
RELEASE TIME	1.0 msec. max.		—		—		—			
ON TRIP POINT	—		—		—		150 Gauss maximum			
OFF TRIP POINT	—		—		—		40 Gauss minimum			
**POWER RATING (WATTS)	10.0 §		3.0 §§		10.0		5.0			
VOLTAGE DROP	2.6 V typical at 100 mA		NA		—		—			
RESISTANCE	0.1 Ω Initial (Max.)						—			
CURRENT CONSUMPTION	—		—		1 Amp at 86°F [30°C]   0.5 Amp at 140°F [60°C]		200 mA at 25 Vdc			
FREQUENCY	—		—		47 - 63 Hz		—			
CABLE MIN. BEND RADIUS	STATIC	0.630" [16mm]								
	DYNAMIC	Not Recommended								

**CAUTION: DO NOT OVER TIGHTEN SWITCH HARDWARE WHEN INSTALLING!**

**WARNING:** Do not exceed power rating (Watt = Voltage X Amperage). Permanent damage to sensor will occur.

\*QD = Quick Disconnect; Male coupler is located 6" [152mm] from sensor, Female coupler to flying lead distance is 197" [5m] also see Cable Shielding specification above

**REPLACEMENT OF QD SWITCHES MANUFACTURED BEFORE JULY 1, 1997:** It will be necessary to replace or rewire the female end coupler.



**Reed Switch Life Expectancy:** Up to 200,000,000 cycles (depending on load current, duty cycle and environmental conditions)

†Shielded from the female quick disconnect coupler to the flying leads. Shield should be terminated at flying lead end.

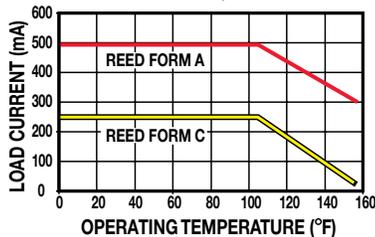
§ Maximum current 500mA (not to exceed 10VA) Refer to Temperature vs. Current graph and Voltage Derating graph

§§ Maximum current 250mA (not to exceed 3VA) Refer to Temperature vs. Current graph and Voltage Derating graph

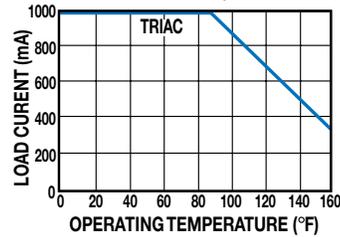
# SLS Rodless Screw Drive Actuator

## PERFORMANCE

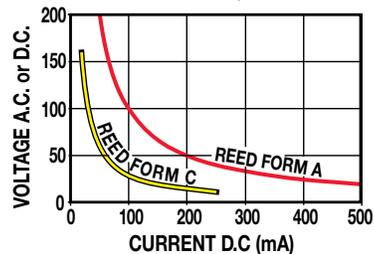
TEMP. vs CURRENT, DC REED



TEMP. vs CURRENT, AC REED

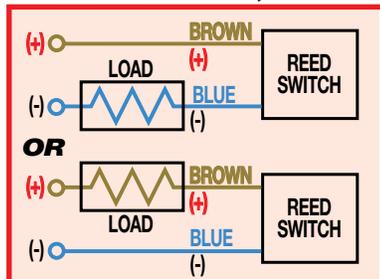


VOLTAGE DERATING, DC REED

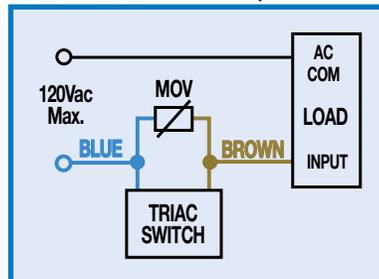


## WIRING DIAGRAMS

**R**T & **R**M DC REED, FORM A



**C**T & **C**M AC REED, TRIAC

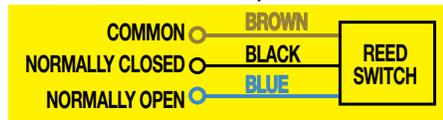


## INSTALLATION INFORMATION

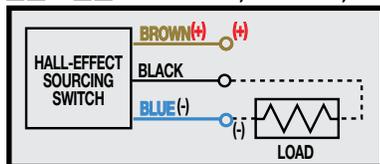


**⚠** THE NOTCHED FACE OF THE SWITCH INDICATES THE SENSING SURFACE AND MUST FACE TOWARD THE MAGNET.

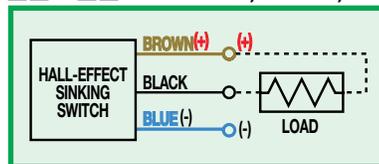
**B**T & **B**M DC REED, FORM C



**T**T & **T**M HALL-EFFECT, SOURCING, PNP



**K**T & **K**M HALL-EFFECT, SINKING, NPN



# COMPILE APPLICATION REQUIREMENTS

## APPLICATION DATA WORKSHEET

Fill in known data. Not all information is required for all applications

### ORIENTATION

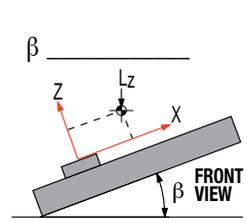
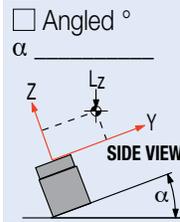
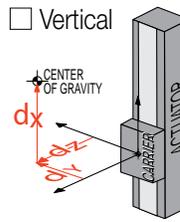
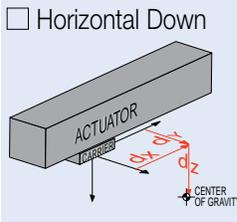
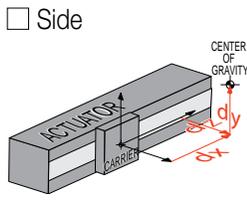
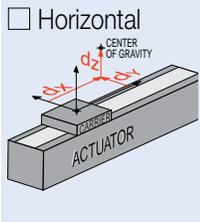
Horizontal

Side

Horizontal Down

Vertical

Angled  $^{\circ}$



Load attached to carrier OR  Load supported by other mechanism

### DISTANCE FROM CENTER OF CARRIER TO LOAD CENTER OF GRAVITY

$dx$  \_\_\_\_\_  
 $dy$  \_\_\_\_\_  
 $dz$  \_\_\_\_\_

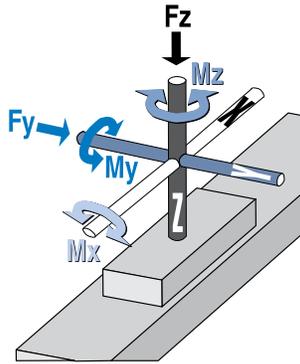
inch (U.S. Standard)

millimeter (Metric)

### STROKE LENGTH \_\_\_\_\_

inch (S I) (U.S. Standard)

millimeters (Metric)



### BENDING MOMENTS APPLIED TO CARRIER

in.-lbs. (U.S. Standard)

N-m (Metric)

$M_x$  \_\_\_\_\_  
 $M_y$  \_\_\_\_\_  
 $M_z$  \_\_\_\_\_

### PRECISION

Repeatability \_\_\_\_\_

inch

millimeters

**NOTE:** If load or force on carrier changes during cycle use the highest numbers for calculations

### THRUST REQUIRED

lbf. (U.S. Standard)

N (Metric)

$F_z$  \_\_\_\_\_  
 $F_y$  \_\_\_\_\_

### OPERATING ENVIRONMENT

Temperature, Contamination, etc.

### LOAD \_\_\_\_\_

lb. (U.S. Standard)

kg. (Metric)

### MOVE PROFILE

Move Distance \_\_\_\_\_

inch

millimeters

Dwell Time After Move \_\_\_\_\_

Max. Speed \_\_\_\_\_

in/sec

mm/sec

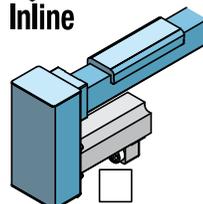
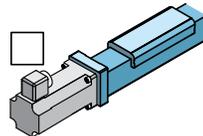
### MOVE TIME \_\_\_\_\_

sec

### NO. OF CYCLES \_\_\_\_\_

per minute

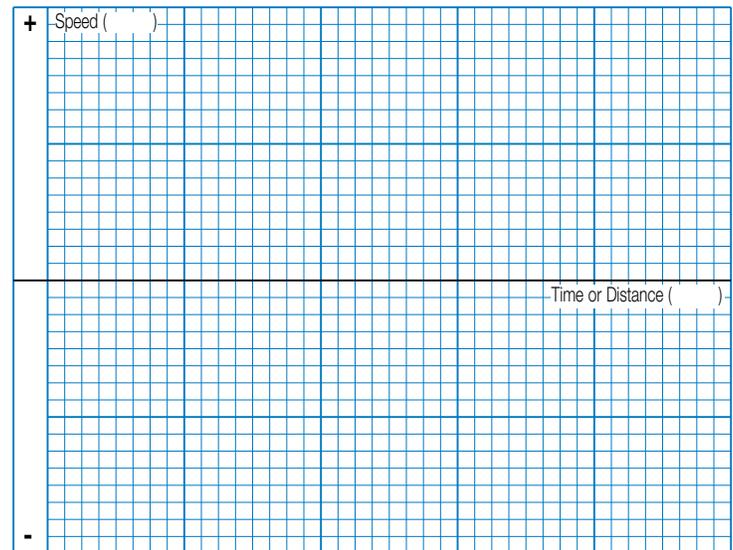
per hour



**Inline**

**Reverse Parallel**

### MOTION PROFILE



Graph your most demanding cycle, including accel/decel, velocity and dwell times. You may also want to indicate load variations and I/O changes during the cycle. Label axes with proper scale and units.



**USE THE TOLOMATIC SIZING AND SELECTION SOFTWARE AVAILABLE ON-LINE AT [www.tolomatic.com](http://www.tolomatic.com) OR... CALL TOLOMATIC 1-800-328-2174** with the above information. We will provide any assistance needed to determine the proper MX actuator for the job.

**FAX 1-763-478-8080**

### CONTACT INFORMATION

Name, Phone, Email  
 Co. Name, Etc.

\_\_\_\_\_  
 \_\_\_\_\_  
 \_\_\_\_\_

# SELECTION GUIDELINES

The process of selecting a load bearing actuator for a given application can be complex. It is highly recommended that you contact Tolomatic or a Tolomatic Distributor for assistance in selecting the best actuator for your application. The following overview of the selection guidelines are for educational purposes only.

## 1 COMPARE LOAD TO MAXIMUM LOAD CAPACITIES

Calculate the application load (combination of load mass and forces applied to the carrier) and application bending moments (sum of all moments  $M_x$ ,  $M_y$ , and  $M_z$  applied to the carrier). Be sure to evaluate the magnitude of dynamic inertia moments. When a rigidly attached load mass is accelerated or decelerated, its inertia induces bending moments on the carrier. Careful attention to how the load is decelerated at the end of the stroke is required for extended actuator performance and application safety. If either load or any of your moments exceed figures indicated in the Moment and Load Capacity table (pg. SLS\_8) for the actuator consider:

- 1) Higher capacity bearing style

- 2) A different actuator style (B3S, MXE, etc.)
- 3) Auxiliary carrier
- 4) External guide system

## 2 CALCULATE LOAD FACTOR LF

For loads with a center of gravity offset from the carrier account for both applied (static) and dynamic loads. The load factor ( $L_F$ ) must not exceed the value of 1.

$$L_F = \frac{M_x}{M_{x_{max}}} + \frac{M_y}{M_{y_{max}}} + \frac{M_z}{M_{z_{max}}} + \frac{F_y}{F_{y_{max}}} + \frac{F_z}{F_{z_{max}}} \leq 1$$

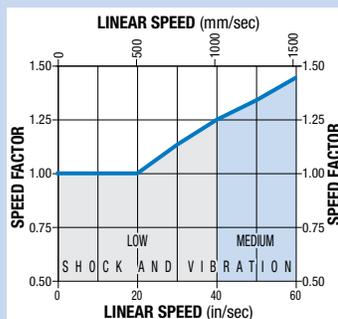
If  $L_F$  does exceed the value of 1, consider the four choices listed in step #2.

## 3 ESTABLISH YOUR MOTION PROFILE AND CALCULATE ACCELERATION RATE

Using the application stroke length and maximum carrier velocity (or time to complete the linear motion), establish the motion profile. Select either triangular (accel-decel) or trapezoidal (accel-constant speed-decel) profile. Now calculate the maximum acceleration and de-

### SPEED FACTOR

FOR APPLICATIONS WITH HIGH SPEED OR SIGNIFICANT SHOCK AND VIBRATION: Calculated values of loads and bending moments must be increased by speed factor from the graph below to obtain full rated life of profiled rail bearing system.



celeration rates of the move. Speed should not exceed critical speed value as shown in graph (page SLS\_4-5) for the screw/nut combination chosen. Also, do not exceed safe rates of dynamic inertia moments determined in step #3.

## 4 SELECT THE LEAD SCREW

Based on the application requirements for accuracy, backlash, quiet operation, life, etc. select the appropriate lead screw type (Acme screw with a solid nut or ball screw with a standard or anti-backlash nut) and the pitch (lead). For additional information on screw selection, consult "Which Screw? Picking the Right Technology" (#9900-4644) available at [www.tolomatic.com](http://www.tolomatic.com).

## 5 SELECT MOTOR (GEARHEAD IF NECESSARY) AND DRIVE

To help select a motor and drive, use the sizing equations located in the Engineering Resources section [ENGR] to calculate the application thrust and torque requirements. Refer to Motor sections [MRV] & [MRS] to determine the motor and drive.

## 6 DETERMINE T-NUTS/MOUNTING PLATE REQUIREMENTS

- Consult the Support Recommendations graph for the model selected (page SLS\_7)
- Cross reference the application load and maximum distance between supports
- Select the appropriate number of T-nuts, and mounting plates if required for motor and adapter clearance.

## 7 CONSIDER OPTIONS

- Choose metric or inch (US Conventional) load mounting.
- Switches - Reed, Solid State PNP or NPN, all available normally open or normally closed



# SLS Rodless Screw Drive Actuator

## ORDERING



### BASE MODEL SPECIFICATIONS

**SLS 10 SN02 SK25 LMI**

#### MODEL TYPE

**SLS** SLS Series US Conventional Screw Drive  
**MLS** MLS Series Metric Screw Drive

#### TUBE BORE DIAMETER

**10** 1-inch (25 mm) bore

#### NUT/SCREW CONFIGURATION

##### INCH (US Conventional) MODELS

SOLID NUT / PITCH (turn/in)	SERIES
<b>SN01</b>	SLS10
<b>SN02</b>	SLS10
<b>SNA02</b>	SLS10
<b>SN05</b>	SLS10

BALL NUT / PITCH (turn/in)	SERIES
<b>BN08</b>	SLS10
<b>BNL08</b>	SLS10

##### METRIC MODELS

SOLID NUT / LEAD (mm/turn)	SERIES
<b>SN12</b>	MLS10
<b>SN25</b>	MLS10

BALL NUT / LEAD (mm/turn)	SERIES
<b>BN08</b>	MLS10
<b>BNL08</b>	MLS10

#### STROKE LENGTH

**SK** Stroke, then enter desired stroke length in decimal inches

### OPTIONS SPECIFICATIONS

**DC18 KT2 TN4 MP2**

#### MOTOR MOUNTING / REDUCTIONS

*(must choose one)*

**LMI** In-Line mounting  
**\*\*LNX** Extended shaft - old style (see note)

**\*\*For replacement actuators with extended motor shafts purchased prior to 6/24/02 use LMX**

#### AUXILIARY CARRIER

**DC\_** Auxiliary Carrier, then center-to-center spacing desired in decimal inches. (Center-to-Center spacing will add to overall dead length and will not subtract from the stroke length)



**"YOUR MOTOR HERE" MADE-TO-ORDER MOTOR MOUNTS. 15 DAYS.**

• Select a high-performance Tolomatic electric actuator and we'll provide a motor-specific interface for your motor. With our online database, you can select from over 60 motor manufacturers and hundreds of models.

Visit [www.tolomatic.com/ymh](http://www.tolomatic.com/ymh) to find your motor/actuator match!

#### SWITCHES

**RM\_** Reed Switch (Form A) with 5-meter lead/QD (*quick-disconnect*), & quantity  
**RT\_** Reed Switch (Form A) with 5-meter lead, and quantity desired  
**BM\_** Reed Switch (Form C) with 5-meter lead/QD, and quantity desired  
**BT\_** Reed Switch (Form C) with 5-meter lead, and quantity desired  
**KM\_** Hall-effect Sinking Switch with 5-meter lead/QD, and quantity desired  
**KT\_** Hall-effect Sinking Switch with 5-meter lead, and quantity desired  
**TM\_** Hall-effect Sourcing Switch with 5-meter lead/QD, and quantity desired  
**TT\_** Hall-effect Sourcing Switch with 5-meter lead, and quantity desired  
**CM\_** TRIAC Switch with 5-meter lead/QD, and quantity desired  
**CT\_** TRIAC Switch with 5-meter lead, and quantity desired

#### T-NUT OPTION

**TN\_** Additional T-nuts and quantity

#### MOUNTING PLATES

**MP\_** Mounting Plates plus quantity desired

#### FOOD GRADE LUBRICATION

**LUB** Grease, Food/Drug

FIELD RETROFIT KITS		
ITEM	SLS10	MLS10
1/4" Mounting Plates	0610-9010	0610-9010
1/2" Mounting Plates	0610-9045	0610-9045

**⚠ Not all codes listed are compatible with all options.**

**Use the Sizing Software to determine available options and accessories based on your application requirements.**

**📄 NOTE: MRB & MRV motors are discontinued contact Tolomatic for information on YMH (Your Motor Here)**

