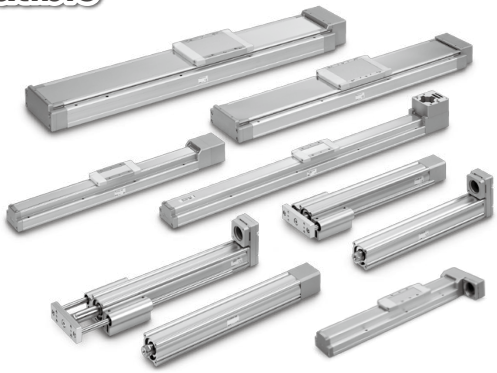
Your motor and driver can be used together!

RoHS

Manufacturers of compatible motors: 15 companies

Mitsubishi Electric Corporation	YASKAWA Electric Corporation
SANYO DENKI CO., LTD.	OMRON Corporation
Panasonic Corporation	FANUC CORPORATION
NIDEC SANKYO CORPORATION	KEYENCE CORPORATION
FUJI ELECTRIC CO., LTD.	ORIENTAL MOTOR Co., Ltd.
FASTECH Co., Ltd.	Rockwell Automation, Inc. (Allen-Bradley)
Beckhoff Automation GmbH	Siemens AG
Delta Electronics, Inc.	



Slider Type *LEF Series*

Ball Screw Drive/*LEFS Series*

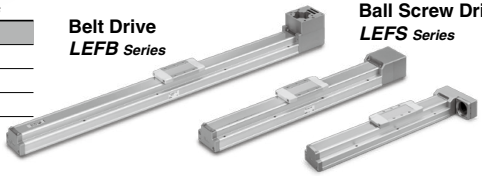
Size	Stroke
25	50 to 800
32	50 to 1000
40	150 to 1200

Belt Drive/*LEFB Series*

Size	Stroke
25	300 to 2000
32	300 to 2500
40	300 to 3000

Belt Drive
LEFB Series

Ball Screw Drive
LEFS Series

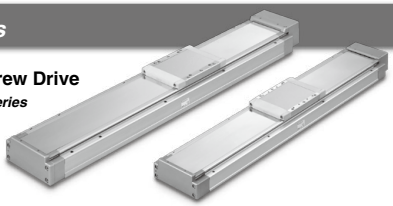


High Rigidity Slider Type *LEJ Series*

Ball Screw Drive/*LEJS Series*

Size	Stroke
40	200 to 1200
63	300 to 1500

Ball Screw Drive
LEJS Series



Rod Type *LEY Series*

Size	Stroke
25	30 to 400
32	30 to 500
63	100 to 800

Guide Rod Type *LEYG Series*

Size	Stroke
25	30 to 300
32	

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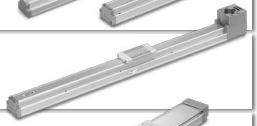
Compatible Motors by Manufacturer (100 W/200 W/400 W equivalent)

Manufacturer	Series	Type *1	Pulse input	CC-Link	SSCNETIII	SSCNETIII/H
Mitsubishi Electric Corporation	MELSERVO-JN	HF-KN	●			
	MELSERVO-J3	HF-KP	●	●	●	
	MELSERVO-J4	HG-KR	●			●
YASKAWA Electric Corporation	Σ-V	SGMJV	●			
SANYO DENKI CO., LTD.	SANMOTION R	R2	●			
OMRON Corporation	Sysmac G5	R88M-K	●			
Panasonic Corporation	MINAS-A4	MSMD	●			
	MINAS-A5	MSMD/MHMD	●			
FANUC CORPORATION	βis	β	●			
NIDEC SANKYO CORPORATION	S-FLAG	MA/MH/MM	●			
KEYENCE CORPORATION	SV	SV-M/SV-B	●			
FUJI ELECTRIC CO., LTD.	ALPHA5	GYS/GYB	●			
	FALDIC-α	GYS	●			
ORIENTAL MOTOR Co., Ltd.	AR	AR	●	●		
	AZ	AZ	●			
FASTECH Co., Ltd.	Ezi-SERVO	EzM	●			
Rockwell Automation, Inc. (Allen-Bradley)	MP-/VP-	MP/VP				
	TL	TLY-A				
Beckhoff Automation GmbH	AM	AM30/AM31				
	AM	AM80/AM81				
Siemens AG	1FK7	1FK7				
Delta Electronics, Inc.	ASDA-A2	ECMA	●			

*1 Motors should be applicable to the mounting dimensions and compatible motor types. Select a motor after checking the specifications of each model.
Additionally, when considering a motor other than those shown above, select a motor within the range of the specifications after checking the mounting dimensions.

Series Variations

Series	Size 25	32	40	63	Page
Slider Type Ball Screw Drive ***LEFS Series*** 	100 W	200 W	400 W		784
Slider Type Belt Drive ***LEFB Series*** 	100 W	200 W	400 W		805
High Rigidity Slider Type Ball Screw Drive ***LEJS Series*** 			100 W	200 W	824
Rod Type ***LEY Series*** 	100 W	200 W		400 W	848
Guide Rod Type ***LEYG Series*** 	100 W	200 W			864

The values in ● shows the equivalent motor capacity.

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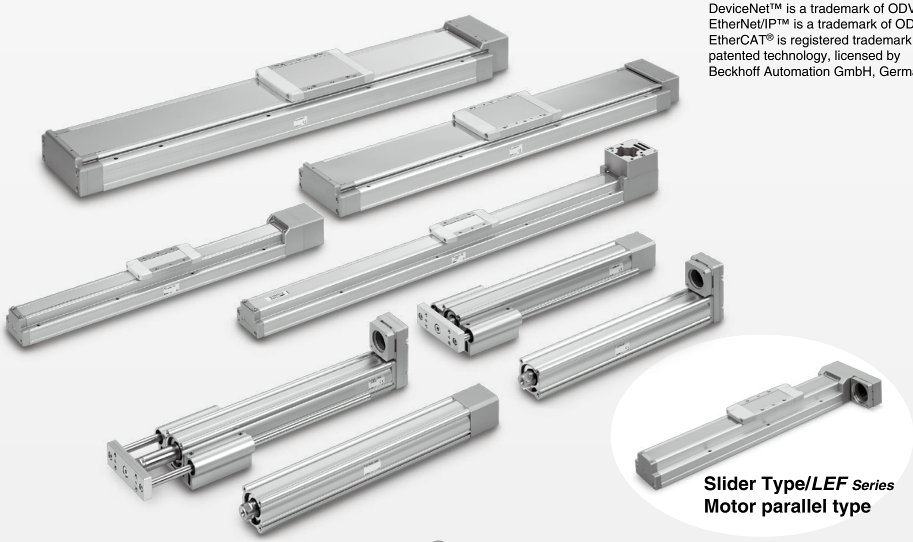
Compatible interfaces *2									
	MECHATROLINK II	MECHATROLINK III	DeviceNet™	EtherNet/IP™	EtherCAT®	PROFIBUS®	PROFINET®	SX bus	E-SX bus
	●	●	●						
					●				
	●				●				
	●								
								●	●
								●	
	●		●						
				●					
				●					
					●				
					●				
						●	●		
					●				

*2 For details about compatible interfaces, refer to each manufacturer's catalog.

Trademark
DeviceNet™ is a trademark of ODVA.
EtherNet/IP™ is a trademark of ODVA.
EtherCAT® is registered trademark and patented technology, licensed by Beckhoff Automation GmbH, Germany.



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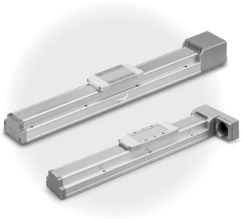
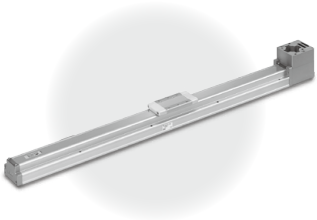
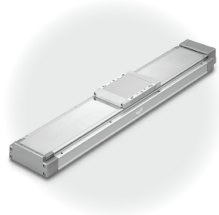
Motorless Type Electric Actuators







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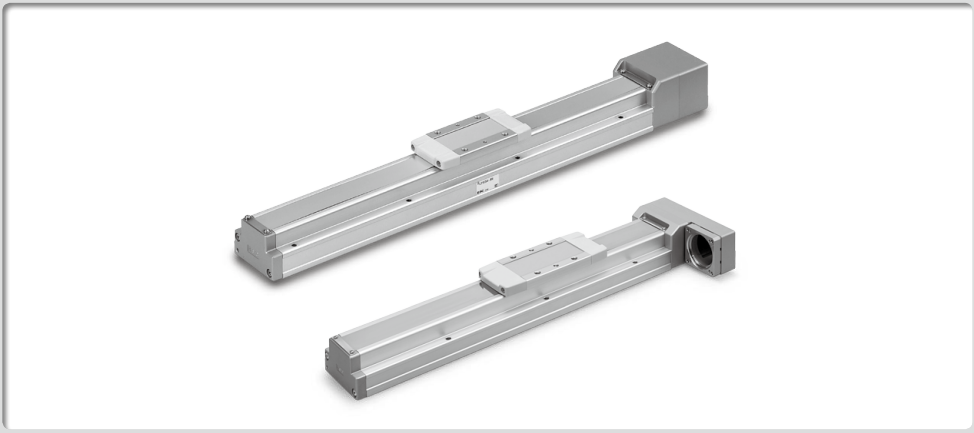
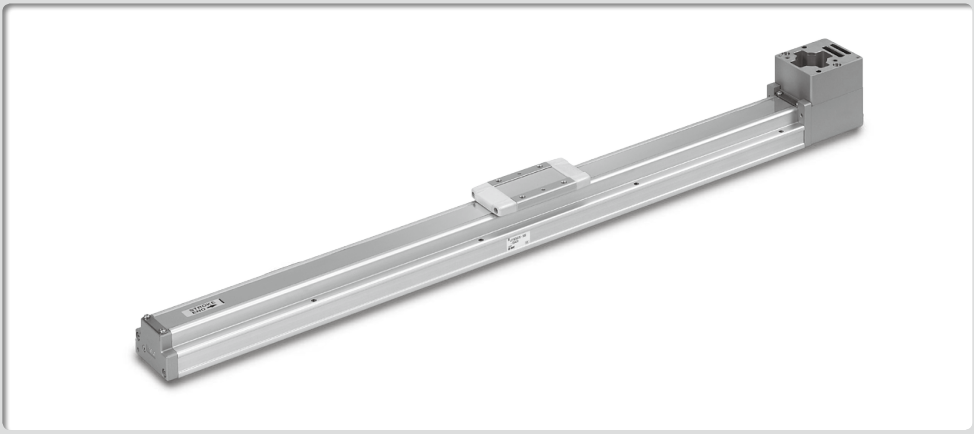
Slider Type

Ball Screw Drive *LEFS Series*



Belt Drive *LEFB Series*



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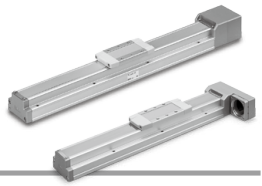
Model Selection



LEFS Series ▶ Page 792

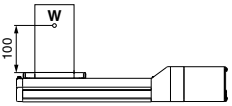
Selection Procedure

Step 1 Check the work load–speed. → **Step 2** Check the cycle time. → **Step 3** Check the allowable moment.

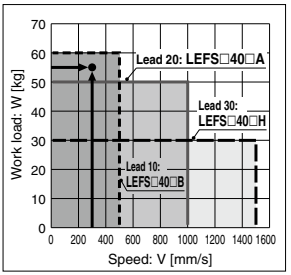
Selection Example

Operating conditions

- Workpiece mass: 55 [kg]
- Workpiece mounting condition:



- Speed: 300 [mm/s]
- Acceleration/Deceleration: 3000 [mm/s^2]
- Stroke: 200 [mm]
- Mounting position: Horizontal upward
- Incremental encoder
- Settling time



<Speed–Work Load Graph> (LEFS40)

Step 1 Check the work load–speed. <Speed–Work Load Graph>

Select a model based on the workpiece mass and speed which are within the range of the actuator body specifications with reference to the "Speed–Work Load Graph (Guide)" on page 785.

Selection example) The **LEFS□40□B-200** is temporarily selected based on the graph shown on the right side.

∗ Refer to the selection method of motor manufacturers for regeneration resistance.

Step 2 Check the cycle time.

Calculate **the cycle time** using the following calculation method.

Cycle time:

T can be found from the following equation.

$$T = T1 + T2 + T3 + T4 \text{ [s]}$$

- T1: Acceleration time and T3: Deceleration time can be obtained by the following equation.

$$T1 = V/a1 \text{ [s]} \qquad T3 = V/a2 \text{ [s]}$$

- T2: Constant speed time can be found from the following equation.

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} \text{ [s]}$$

- T4: Settling time varies depending on the motor type and load. The value below is recommended.

$$T4 = 0.05 \text{ [s]}$$

∗ The conditions for the settling time vary depending on the motor or driver to be used.

Calculation example)
T1 to T4 can be calculated as follows.

$T1 = V/a1 = 300/3000 = 0.1$ [s],

$T3 = V/a2 = 300/3000 = 0.1$ [s]

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} = \frac{200 - 0.5 \cdot 300 \cdot (0.1 + 0.1)}{300} = 0.57 \text{ [s]}$$

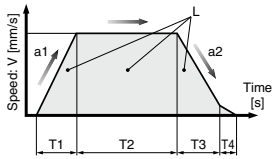
$T4 = 0.05$ [s]

Therefore, **the cycle time** can be obtained as follows.

$T = T1 + T2 + T3 + T4$

$= 0.1 + 0.57 + 0.1 + 0.05$

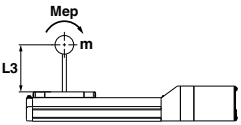
$= \mathbf{0.82}$ **[s]**

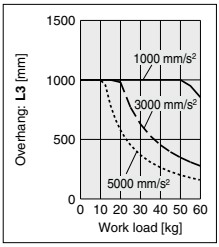


L : Stroke [mm]
··· (Operating condition)
V : Speed [mm/s]
··· (Operating condition)
a1: Acceleration [mm/s^2]
··· (Operating condition)
a2: Deceleration [mm/s^2]
··· (Operating condition)

T1: Acceleration time [s]
Time until reaching the set speed
T2: Constant speed time [s]
Time while the actuator is operating at a constant speed
T3: Deceleration time [s]
Time from the beginning of the constant speed operation to stop
T4: Settling time [s]
Time until positioning is completed

Step 3 Check the guide moment.





Based on the above calculation result, the LEFS□40□B-200 is selected.

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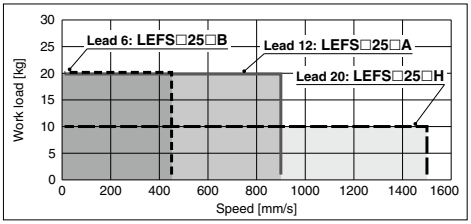
Speed–Work Load Graph (Guide)

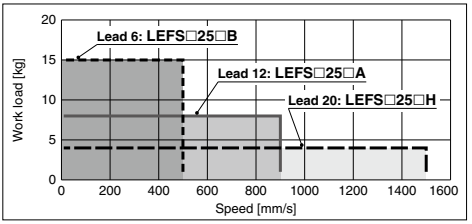
* The values shown below are allowable values of the actuator body. Do not use the actuator so that it exceeds these specification ranges.
* The allowable speed is restricted depending on the stroke. Select it by referring to the "Allowable Stroke Speed" below.

LEFS□25/Ball Screw Drive

Horizontal

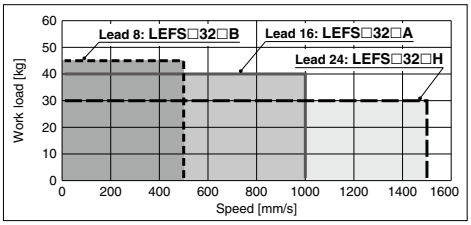


Vertical

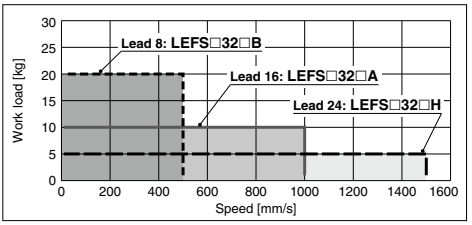


LEFS□32/Ball Screw Drive

Horizontal

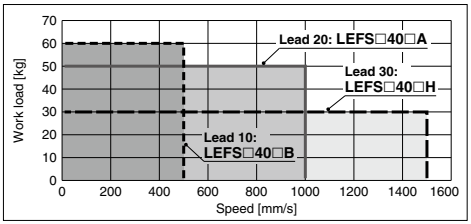


Vertical

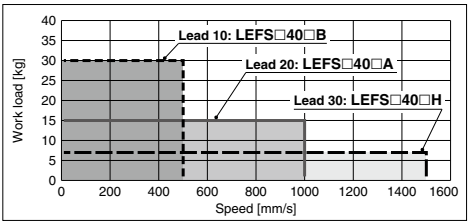


LEFS□40/Ball Screw Drive

Horizontal



Vertical



Allowable Stroke Speed

[mm/s]

Model	AC servo motor	Lead		Stroke [mm]											
		Symbol	[mm]	Up to 100	Up to 200	Up to 300	Up to 400	Up to 500	Up to 600	Up to 700	Up to 800	Up to 900	Up to 1000	Up to 1100	Up to 1200
LEFS25	100 W equivalent	H	20	1500				1200	900	700	550	—	—	—	—
		A	12	900				720	540	420	330	—	—	—	—
		B	6	450				360	270	210	160	—	—	—	—
		(Motor rotation speed)		(4500 rpm)				(3650 rpm)	(2700 rpm)	(2100 rpm)	(1650 rpm)	—	—	—	—
LEFS32	200 W equivalent	H	24	1500					1200	930	750	610	510	—	—
		A	16	1000					800	620	500	410	340	—	—
		B	8	500					400	310	250	200	170	—	—
		(Motor rotation speed)		(3750 rpm)					(3000 rpm)	(2325 rpm)	(1875 rpm)	(1537 rpm)	(1275 rpm)	—	—
LEFS40	400 W equivalent	H	30	—	1500					1410	1140	930	780	500	500
		A	20	—	1000					940	760	620	520	440	380
		B	10	—	500					470	380	310	260	220	190
		(Motor rotation speed)		—	(3000 rpm)					(2820 rpm)	(2280 rpm)	(1860 rpm)	(1560 rpm)	(1320 rpm)	(1140 rpm)

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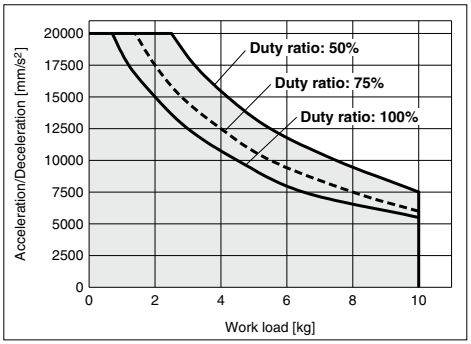
Work Load–Acceleration/Deceleration Graph (Guide)

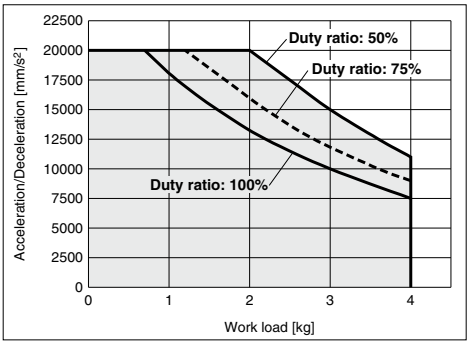
LEFS□25□H/Ball Screw Drive

Horizontal



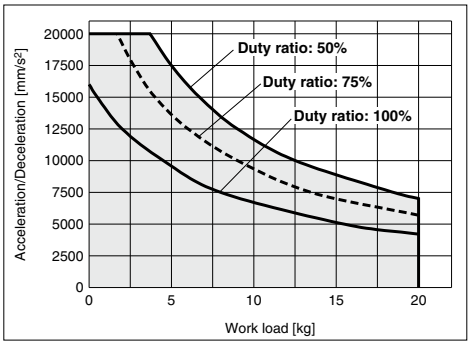
LEFS□25□H/Ball Screw Drive

Vertical



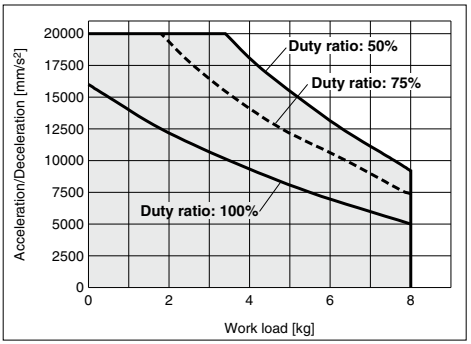
LEFS□25□A/Ball Screw Drive

Horizontal



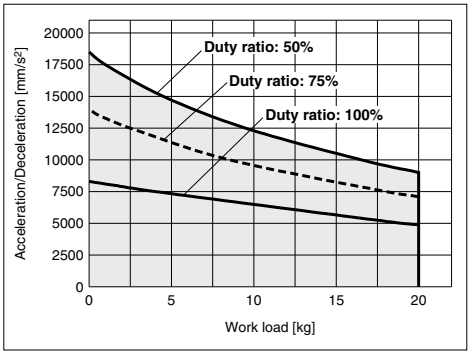
LEFS□25□A/Ball Screw Drive

Vertical



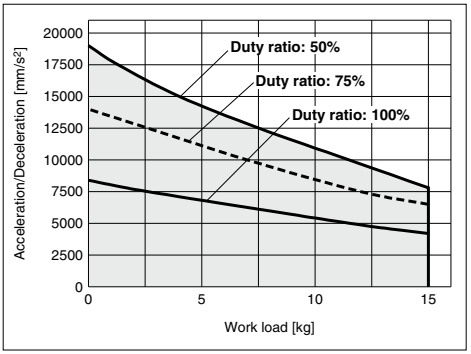
LEFS□25□B/Ball Screw Drive

Horizontal



LEFS□25□B/Ball Screw Drive

Vertical



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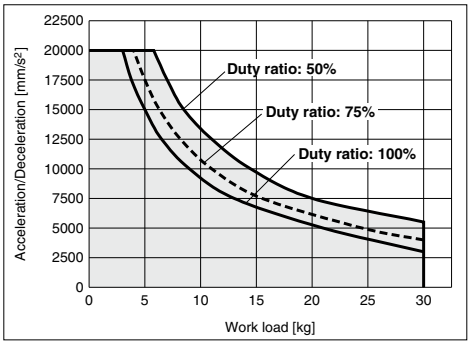
Work Load–Acceleration/Deceleration Graph (Guide)

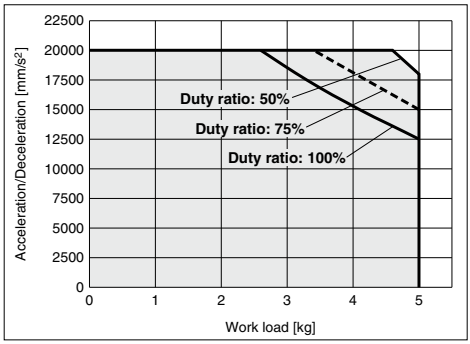
LEFS□32□H/Ball Screw Drive

Horizontal



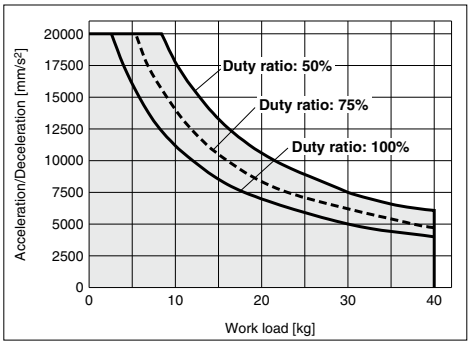
LEFS□32□H/Ball Screw Drive

Vertical



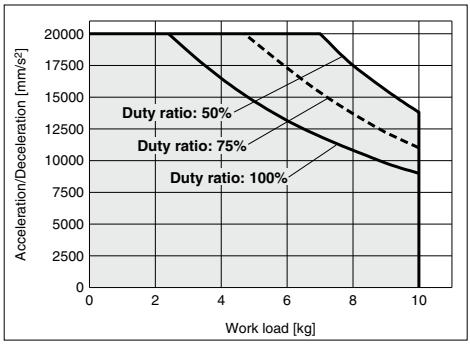
LEFS□32□A/Ball Screw Drive

Horizontal



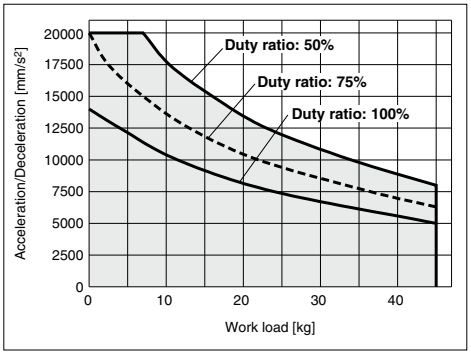
LEFS□32□A/Ball Screw Drive

Vertical



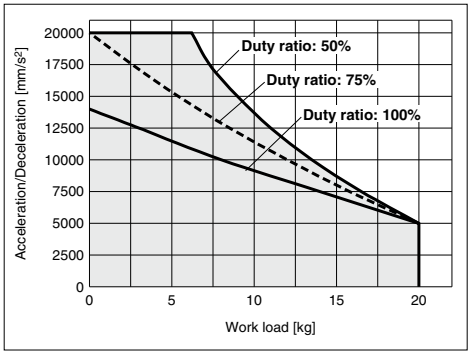
LEFS□32□B/Ball Screw Drive

Horizontal



LEFS□32□B/Ball Screw Drive

Vertical



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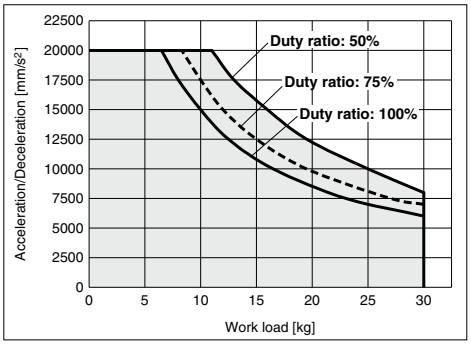
Work Load–Acceleration/Deceleration Graph (Guide)

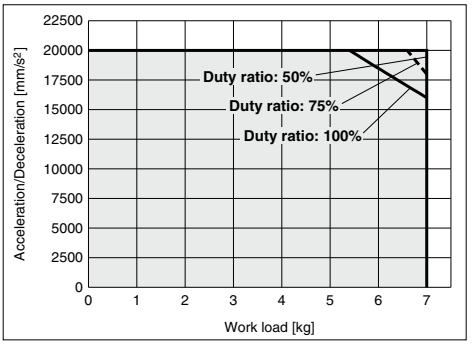
LEFS□40□H/Ball Screw Drive

Horizontal



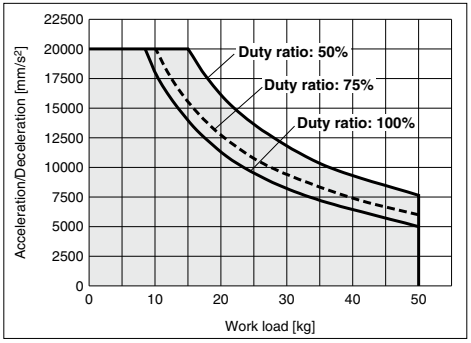
LEFS□40□H/Ball Screw Drive

Vertical



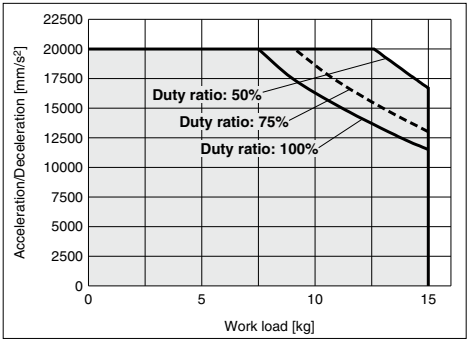
LEFS□40□A/Ball Screw Drive

Horizontal



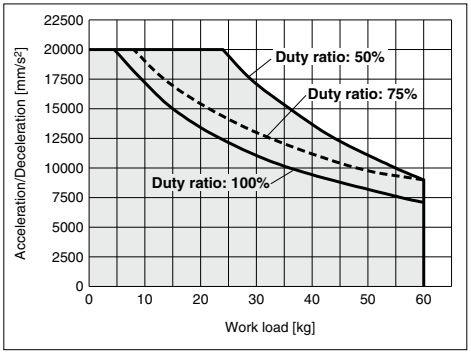
LEFS□40□A/Ball Screw Drive

Vertical



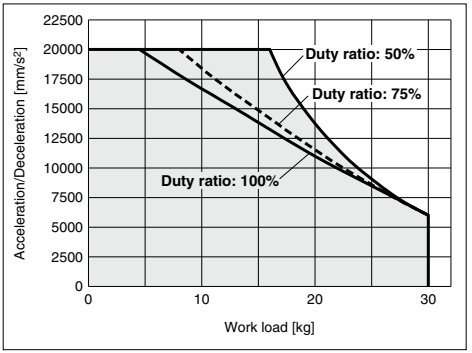
LEFS□40□B/Ball Screw Drive

Horizontal



LEFS□40□B/Ball Screw Drive

Vertical



These graphs are examples of when the standard motor is mounted.
Determine the duty ratio after taking into account the load factor of the motor or driver to be used.

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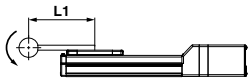
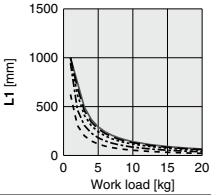
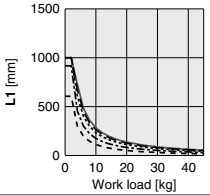
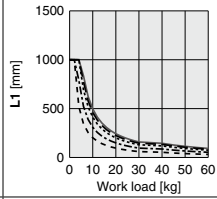
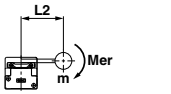
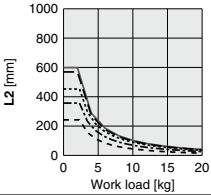
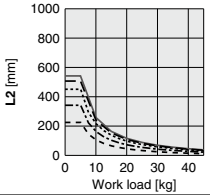
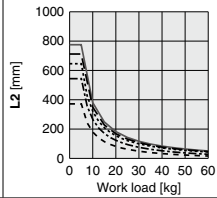
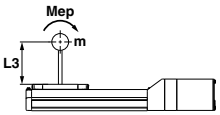
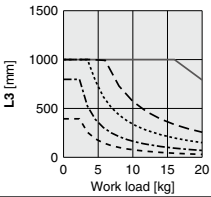
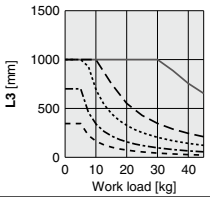
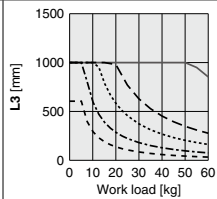
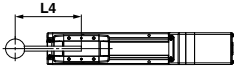
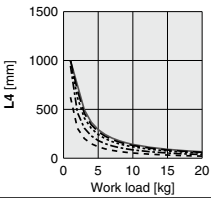
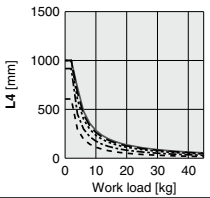
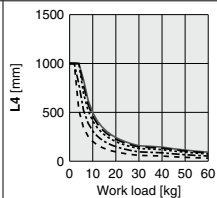
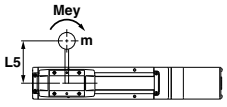
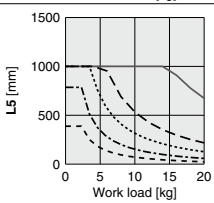
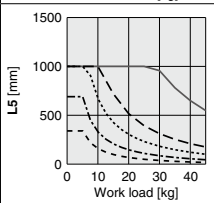
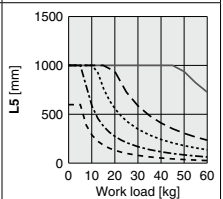
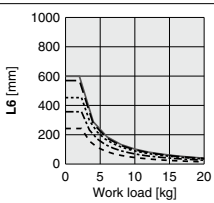
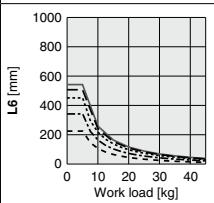
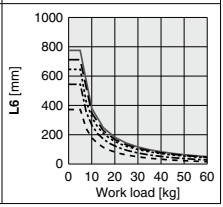
Dynamic Allowable Moment

* This graph shows the amount of allowable overhang (guide unit) when the center of gravity of the workpiece overhangs in one direction. When selecting the overhang, refer to "Calculation of Guide Load Factor" or the Electric Actuator Selection Software for confirmation, http://www.smcworld.com

Acceleration/Deceleration ——1000 mm/s² – – –3000 mm/s² ·····5000 mm/s² –·–·–10000 mm/s² - - - - 20000 mm/s²

Orientation	Load overhanging direction **m** : Work load [kg] **Me**: Dynamic allowable moment [N·m] **L** : Overhang to the work load center of gravity [mm]		Model LEFS25□	Model LEFS32□	Model LEFS40□
Horizontal/Bottom		X			
		Y			
		Z			
Wall		X			
		Y			
		Z			

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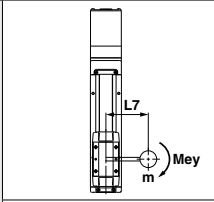
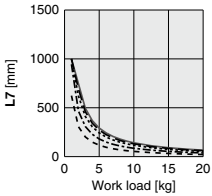
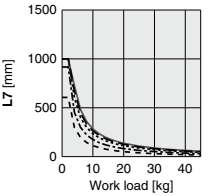
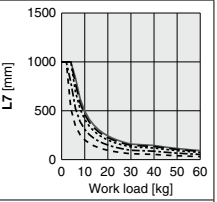
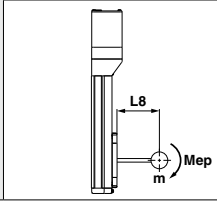
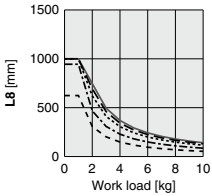
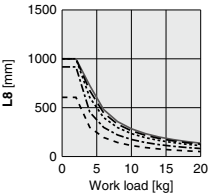
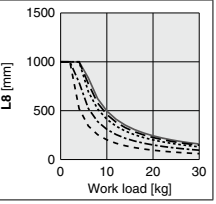
Dynamic Allowable Moment

* This graph shows the amount of allowable overhang (guide unit) when the center of gravity of the workpiece overhangs in one direction. When selecting the overhang, refer to "Calculation of Guide Load Factor" or the Electric Actuator Selection Software for confirmation, http://www.smcworld.com

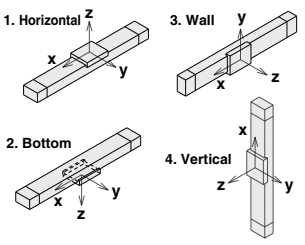
Acceleration/Deceleration ——1000 mm/s² – – –3000 mm/s² ·····5000 mm/s² –·–·–10000 mm/s² - - - -20000 mm/s²

Orientation	Load overhanging direction **m** : Work load [kg] **Me**: Dynamic allowable moment [N·m] **L** : Overhang to the work load center of gravity [mm]		Model: LEFS25□	Model: LEFS32□	Model: LEFS40□
Vertical		Y			
		Z			

Calculation of Guide Load Factor

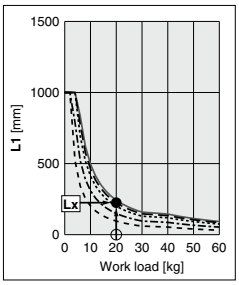
1. Decide operating conditions.
   Model: LEFS
   Size: 25/32/40
   Mounting orientation: Horizontal/Bottom/Wall/Vertical
   Acceleration [mm/s²]: **a**
   Work load [kg]: **m**
   Work load center position [mm]: **Xc/Yc/Zc**
2. Select the target graph with reference to the model, size and mounting orientation.
3. Based on the acceleration and work load, obtain the overhang [mm]: **Lx/Ly/Lz** from the graph.
4. Calculate the load factor for each direction.
   α**x = Xc/Lx**, α**y = Yc/Ly**, α**z = Zc/Lz**
5. Confirm the total of α**x**, α**y** and α**z** is 1 or less.
   α**x + **α**y + **α**z** $\leq$ **1**
   When 1 is exceeded, consider a reduction of acceleration and work load, or a change of the work load center position and series.

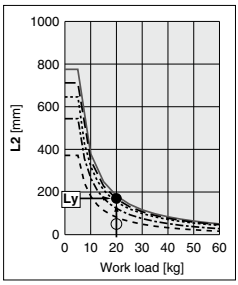
Mounting Orientation



Example

1. Operating conditions
   Model: LEFS40
   Size: 40
   Mounting orientation: Horizontal
   Acceleration [mm/s²]: 3000
   Work load [kg]: 20
   Work load center position [mm]: **Xc = 0**, **Yc = 50**, **Zc = 200**
2. Select the graphs for horizontal of the LEFS40 on page 789.
3. **Lx = 250 mm**, **Ly = 180 mm**, **Lz = 1000 mm**
4. The load factor for each direction can be obtained as follows.
   α**x = 0/250 = 0**
   α**y = 50/180 = 0.27**
   α**z = 200/1000 = 0.2**
5. α**x + **α**y + **α**z = 0.47** $\leq$ **1**





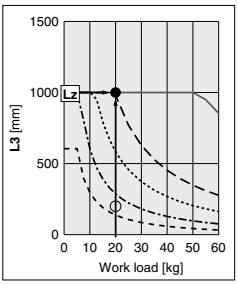


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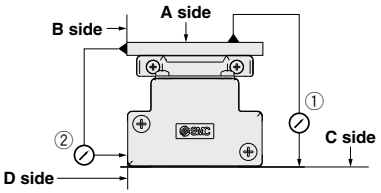
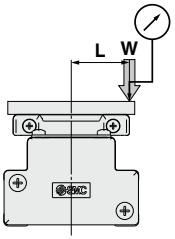
Table Accuracy (Reference Value)

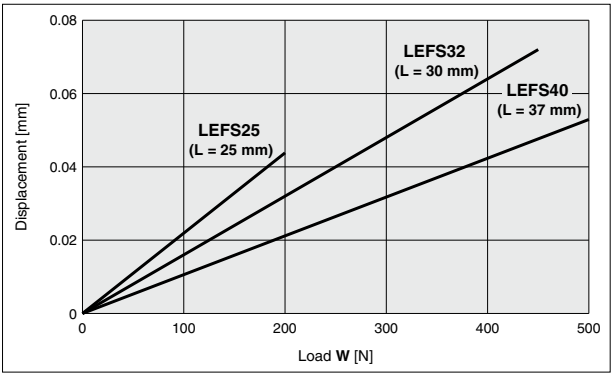


Model	Traveling parallelism [mm] (Every 300 mm)	
	① C side traveling parallelism to A side	② D side traveling parallelism to B side
LEFS25	0.05	0.03
LEFS32	0.05	0.03
LEFS40	0.05	0.03

Note) Traveling parallelism does not include the mounting surface accuracy.

Table Displacement (Reference Value)

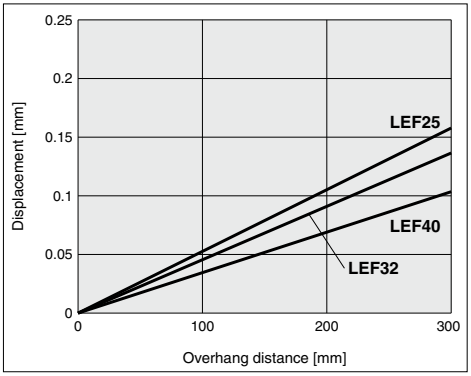




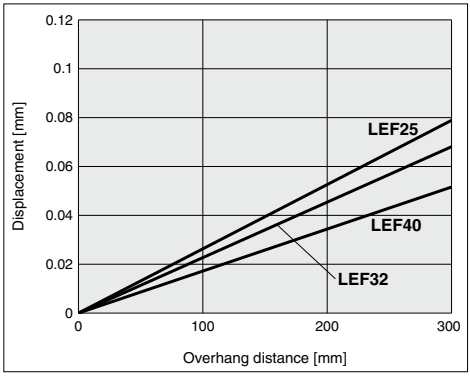
Note 1) This displacement is measured when a 15 mm aluminum plate is mounted and fixed on the table.
Note 2) Check the clearance and play of the guide separately.

Overhang Displacement Due to Table Clearance (Reference Value)

Basic Type



High Precision Type



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Motorless Type

Electric Actuator/Slider Type
Ball Screw Drive
LEFS Series LEFS25, 32, 40

RoHS

How to Order

LEFS H 25 R NZ A – 100 C N K

❶ ❷ ❸ ❹ ❺ ❻ ❼ ❽ ❾

❶ Accuracy

Nil	Basic type
H	High precision type

❷ Size

25
32
40

❸ Motor mounting position

Nil	In-line
R	Right side parallel
L	Left side parallel

❹ Motor type

Symbol	Type
NZ	Mounting type Z
NY	Mounting type Y
NX	Mounting type X
NW	Mounting type W
NV	Mounting type V
NU	Mounting type U
NT	Mounting type T
NM1	Mounting type M1
NM2	Mounting type M2

❺ Lead [mm]

Symbol	LEFS25	LEFS32	LEFS40
H	20	24	30
A	12	16	20
B	6	8	10

❻ Stroke [mm]

50	50
to	to
1200	1200

∗ Refer to the applicable stroke table.

❼ Auto switch mounting bracket

Nil	None
C	With 1 pc. (Included)

∗ If 2 or more are required, please order them separately. (Part no.: LEF-D-2-1 For details, refer to page 112-1.)
∗ Order auto switches separately. (For details, refer to pages 112-2 and 112-3.)

❽ Grease application (Seal band part)

Nil	With
N	Without (Roller specification)

❾ Positioning pin hole

Nil	Housing B bottom∗	Housing B bottom
K	Body bottom 2 locations	Body bottom

∗ Refer to the body mounting example on page 822 for the mounting method.

Applicable Stroke Table

●: Standard

Model \ Stroke [mm]	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1100	1200
LEFS25	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	—	—	—	—	—	—
LEFS32	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	—	—
LEFS40	—	—	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●

∗ Please consult with SMC for non-standard strokes as they are produced as special orders.

Compatible Motors

Applicable motor model			Size/Motor type															
			25					32/40										
Manufacturer	Series	Type	NZ Mounting type Z	NY Mounting type Y	NX Mounting type X	NM1 Mounting type M1	NM2 Mounting type M2	NZ Mounting type Z	NY Mounting type Y	NX Mounting type X	NW Mounting type W	NV Mounting type V	NU Mounting type U	NT Mounting type T	NM1 Mounting type M1	NM2 Mounting type M2
Mitsubishi Electric Corporation	MELSERVO-JN	HF-KN	●	—	—	—	—	●	—	—	—	—	—	—	—	—
	MELSERVO-J3	HF-KP	●	—	—	—	—	●	—	—	—	—	—	—	—	—
	MELSERVO-J4	HG-KR	●	—	—	—	—	●	—	—	—	—	—	—	—	—
YASKAWA Electric Corporation	Σ-V	SGMJV	●	—	—	—	—	●	—	—	—	—	—	—	—	—
SANYO DENKI CO., LTD.	SANMOTION R	R2	●	—	—	—	—	●	—	—	—	—	—	—	—	—
OMRON Corporation	Sysmac G5	R88M-K	●	—	—	—	—	—	●	—	—	—	—	—	—	—
Panasonic Corporation	MINAS-A4	MSMD	—	●	—	—	—	—	●	—	—	—	—	—	—	—
	MINAS-A5	MSMD/MHMD	—	●	—	—	—	—	●	—	—	—	—	—	—	—
FANUC CORPORATION	βis	β	●	—	—	—	—	● (β1 only)	—	—	●	—	—	—	—	—
NIDEC SANKYO CORPORATION	S-FLAG	MA/MH/MM	●	—	—	—	—	●	—	—	—	—	—	—	—	—
KEYENCE CORPORATION	SV	SV-M/SV-B	●	—	—	—	—	●	—	—	—	—	—	—	—	—
FUJI ELECTRIC CO., LTD.	ALPHA5	GYS/GYB	●	—	—	—	—	●	—	—	—	—	—	—	—	—
	FALDIC-α	GYS	●	—	—	—	—	●	—	—	—	—	—	—	—	—
ORIENTAL MOTOR Co., Ltd.	AR/AZ	AR/AZ (46 only)	—	—	—	—	●	—	—	—	—	—	—	—	—	—
	AR/AZ	AR/AZ	—	—	—	—	—	—	—	—	—	—	—	—	—	●∗2
FASTECH Co., Ltd.	Ezi-SERVO	EzM	—	—	—	●	—	—	—	—	—	—	—	—	●∗2	—
Rockwell Automation, Inc. (Allen-Bradley)	MP-/VP-	MP/VP	—	—	—	—	—	—	—	●∗1	—	—	—	—	—	—
	TL	TLY-A	●	—	—	—	—	—	—	—	—	—	—	●	—	—
Beckhoff Automation GmbH	AM	AM30	●	—	—	—	—	—	—	—	—	●∗1	—	—	—	—
	AM	AM31	●	—	—	—	—	—	—	—	—	—	●∗2	—	—	—
	AM	AM80/AM81	●	—	—	—	—	—	—	●∗1	—	—	—	—	—	—
Siemens AG	1FK7	1FK7	—	—	●	—	—	—	—	●∗1	—	—	—	—	—	—
Delta Electronics, Inc.	ASDA-A2	ECMA	●	—	—	—	—	●	—	—	—	—	—	—	—	—

∗1 Motor mounting position: In-line only
∗2 Only size 32 is available when the motor mounting position is right (or left) side parallel.

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Specifications Note 2)

- Values in this specification table are the allowable values of the actuator body with the standard motor mounted.
- Do not use the actuator so that it exceeds these values.

	Model			LEFS25			LEFS32			LEFS40		
Actuator specifications	Stroke [mm] Note 1)			50 to 800			50 to 1000			150 to 1200		
	Work load [kg]		Horizontal	10	20	20	30	40	45	30	50	60
			Vertical	4	8	15	5	10	20	7	15	30
	Speed [mm/s]	Stroke range	Up to 400	1500	900	450	1500	1000	500	1500	1000	500
			401 to 500	1200	720	360	1500	1000	500	1500	1000	500
			501 to 600	900	540	270	1200	800	400	1500	1000	500
			601 to 700	700	420	210	930	620	310	1410	940	470
			701 to 800	550	330	160	750	500	250	1140	760	380
			801 to 900	—	—	—	610	410	200	930	620	310
			901 to 1000	—	—	—	510	340	170	780	520	260
			1001 to 1100	—	—	—	—	—	—	500	440	220
			1101 to 1200	—	—	—	—	—	—	500	380	190
	Pushing return to origin speed [mm/s]			30 or less								
	Positioning repeatability [mm]		Basic type	±0.02								
			High precision type	±0.01								
	Lost motion Note 3) [mm]		Basic type	0.1 or less								
			High precision type	0.05 or less								
	Ball screw specifications		Thread size [mm]	ø10			ø12			ø15		
			Lead [mm]	20	12	6	24	16	8	30	20	10
			Shaft length [mm]	Stroke + 150			Stroke + 185			Stroke + 235		
	Max. acceleration/deceleration [mm/s²]			20000 Note 4)								
	Impact/Vibration resistance [m/s²] Note 6)			50/20								
	Actuation type			Ball screw (LEFS□), Ball screw + Belt (LEFS□$^{R}_{L}$)								
	Guide type			Linear guide								
	Operating temperature range [°C]			5 to 40								
	Operating humidity range [%RH]			90 or less (No condensation)								
Other specifications	Actuation unit weight [kg]			0.2			0.3			0.55		
	Other inertia [kg·cm²]			0.02 (LEFS25) 0.02 (LEFS25$^{R}_{L}$)			0.08 (LEFS32) 0.06 (LEFS32$^{R}_{L}$)			0.08 (LEFS40) 0.17 (LEFS40$^{R}_{L}$)		
	Friction coefficient			0.05								
Note 5)	Mechanical efficiency			0.8								
Reference motor specifications	Motor shape			□40			□60					
	Motor type			AC servo motor (100 V/200 V)								
	Rated output capacity [W]			100			200			400		
	Rated torque [N·m]			0.32			0.64			1.3		
	Rated rotation [rpm]			3000								

Note 1) Please consult with SMC for non-standard strokes as they are produced as special orders.
Note 2) Do not allow collisions at either end of the table traveling distance at a speed exceeding "pushing return to origin speed."
Additionally, when running the positioning operation, do not set within 2 mm of both ends.
Note 3) A reference value for correcting an error in reciprocal operation.
Note 4) Maximum acceleration/deceleration changes according to the work load.
Refer to the "Work Load–Acceleration/Deceleration Graph (Guide)" for ball screw drive on pages 786 to 788.
Note 5) Each value is a guide. Use such value to select a motor capacity.
Note 6) Impact resistance: No malfunction occurred when the actuator was tested with a drop tester in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the actuator in the initial state.)
Vibration resistance: No malfunction occurred in a test ranging between 45 to 2000 Hz. Test was performed in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the actuator in the initial state.)

Weight

Model	LEFS25															
Stroke [mm]	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
Product weight [kg]	1.50	1.70	1.80	2.00	2.10	2.25	2.40	2.55	2.70	2.80	2.90	3.10	3.35	3.50	3.65	3.80

Model	LEFS32																				
Stroke [mm]	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
Product weight [kg]	2.40	2.60	2.80	3.00	3.20	3.40	3.60	3.80	4.00	4.20	4.40	4.60	4.80	5.00	5.20	5.40	5.60	5.80	6.00	6.20

Model	LEFS40																				
Stroke [mm]	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1100	1200
Product weight [kg]	4.60	4.80	5.20	5.35	5.70	5.95	6.30	6.50	6.80	6.95	7.40	7.60	8.00	8.15	8.50	8.75	9.10	9.30	9.76	10.32

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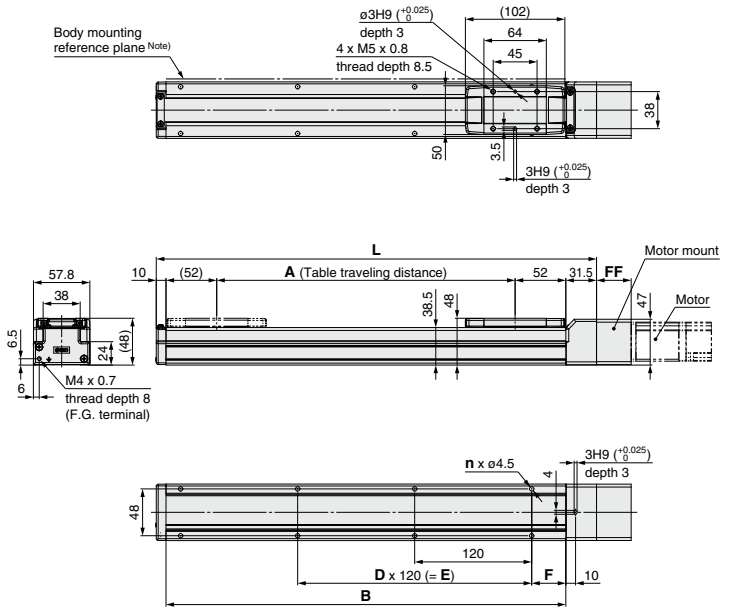
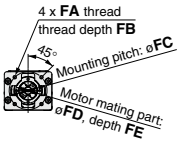
Dimensions: Ball Screw Drive

Refer to the "Motor Mounting" on page 800 for details about motor mounting and included parts.

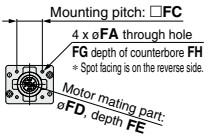
LEFS25



Motor type: NZ, NY, NX



Motor type: NM1, NM2



Note) When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height 5 mm)

Dimensions [mm]

Stroke	L	A	B	n	D	E	F
50	201.5	56	160	4	—	—	20
100	251.5	106	210	4	—	—	35
150	301.5	156	260	4	—	—	35
200	351.5	206	310	6	2	240	35
250	401.5	256	360	6	2	240	35
300	451.5	306	410	8	3	360	35
350	501.5	356	460	8	3	360	35
400	551.5	406	510	8	3	360	35
450	601.5	456	560	10	4	480	35
500	651.5	506	610	10	4	480	35
550	701.5	556	660	12	5	600	35
600	751.5	606	710	12	5	600	35
650	801.5	656	760	12	5	600	35
700	851.5	706	810	14	6	720	35
750	901.5	756	860	14	6	720	35
800	951.5	806	910	16	7	840	35

Motor Mounting Dimensions [mm]

Motor type	FA	FB	FC	FD	FE	FF	FG	FH
NZ/NX	M4 x 0.7	8	46	30	3.5	35.5	—	—
NY	M3 x 0.5	8	45	30	3.5	35.5	—	—
NM1	3.4	—	31	22∗	2.5∗	24	6.5	13.5
NM2	3.4	—	31	22∗	2.5∗	33.1	6.5	22.6

∗ Dimensions after mounting a ring spacer (Refer to page 800.)

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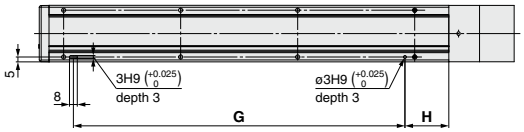
Refer to the "Motor Mounting" on page 800 for details about motor mounting and included parts.

Dimensions: Ball Screw Drive

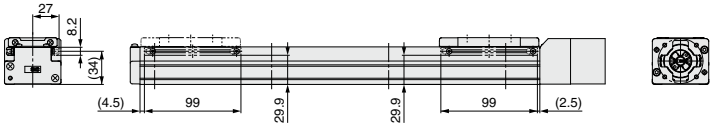
LEFS25

Positioning pin hole Note) **(Option): Body bottom**



Note) When using the body bottom positioning pin holes, do not simultaneously use the housing B bottom pin hole.

With auto switch (Option)



Dimensions [mm]

Stroke	G	H
50	100	30
100	100	45
150	100	45
200	220	45
250	220	45
300	340	45
350	340	45
400	340	45
450	460	45
500	460	45
550	580	45
600	580	45
650	580	45
700	700	45
750	700	45
800	820	45

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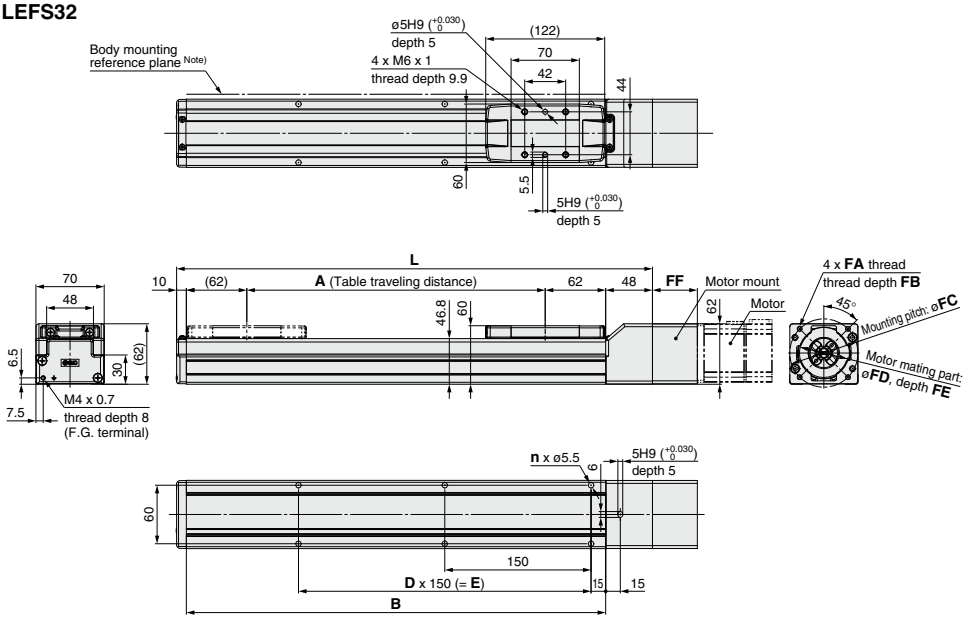
Refer to the "Motor Mounting" on page 800 for details about motor mounting and included parts.

Dimensions: Ball Screw Drive

LEFS32



Note) When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height 5 mm)

Dimensions [mm]

Stroke	L	A	B	n	D	E
50	238	56	180	4	—	—
100	288	106	230	4	—	—
150	338	156	280	4	—	—
200	388	206	330	6	2	300
250	438	256	380	6	2	300
300	488	306	430	6	2	300
350	538	356	480	8	3	450
400	588	406	530	8	3	450
450	638	456	580	8	3	450
500	688	506	630	10	4	600
550	738	556	680	10	4	600
600	788	606	730	10	4	600
650	838	656	780	12	5	750
700	888	706	830	12	5	750
750	938	756	880	12	5	750
800	988	806	930	14	6	900
850	1038	856	980	14	6	900
900	1088	906	1030	14	6	900
950	1138	956	1080	16	7	1050
1000	1188	1006	1130	16	7	1050

Motor Mounting Dimensions [mm]

Motor type	FA	FB	FC	FD	FE	FF
NZ/NT	M5 x 0.8	9	70	50	5	46
NY	M4 x 0.7	8	70	50	5	46
NX	M5 x 0.8	9	63	40*	4.5*	49.7
NW/NU	M5 x 0.8	9	70	50	5	47.5
NV	M4 x 0.7	8	63	40*	4.5*	49.7
NM1	M4 x 0.7	8	□47.14	38.1*	4.5*	21
NM2	M4 x 0.7	8	□50	36*	4.5*	40.1

* Dimensions after mounting a ring spacer (Refer to page 800.)

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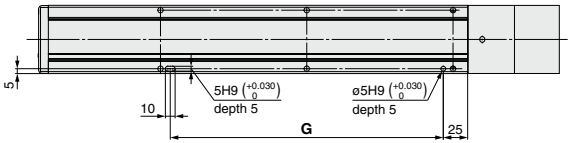
Refer to the "Motor Mounting" on page 800 for details about motor mounting and included parts.

Dimensions: Ball Screw Drive

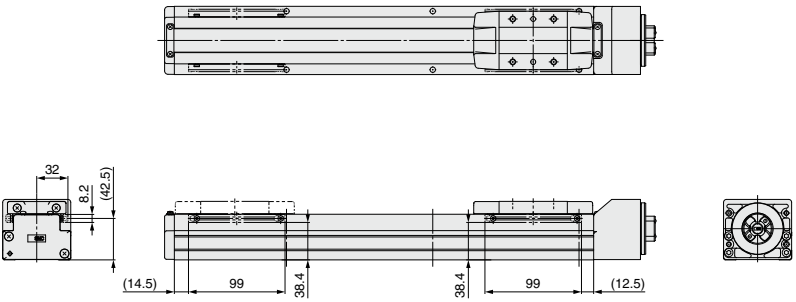
LEFS32

Positioning pin hole Note) **(Option): Body bottom**



Note) When using the body bottom positioning pin holes, do not simultaneously use the housing B bottom pin hole.

With auto switch (Option)



Dimensions [mm]

Stroke	G
50	130
100	130
150	130
200	280
250	280
300	280
350	430
400	430
450	430
500	580
550	580
600	580
650	730
700	730
750	730
800	880
850	880
900	880
950	1030
1000	1030

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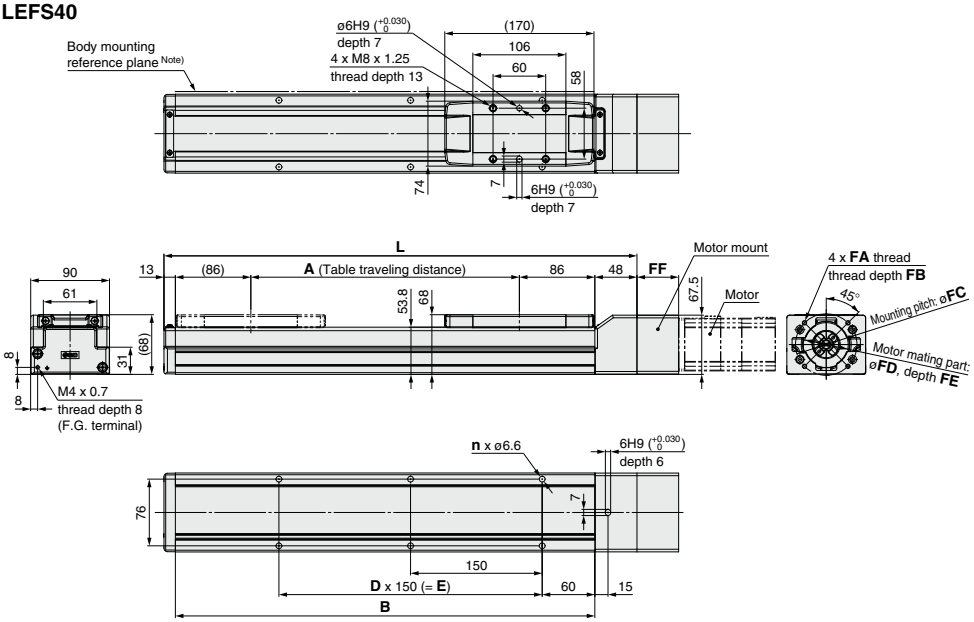
Dimensions: Ball Screw Drive

Refer to the "Motor Mounting" on page 800 for details about motor mounting and included parts.

LEFS40



Note) When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height 5 mm)

Dimensions

[mm]

Stroke	L	A	B	n	D	E
150	389	156	328	4	—	150
200	439	206	378	6	2	300
250	489	256	428	6	2	300
300	539	306	478	6	2	300
350	589	356	528	8	3	450
400	639	406	578	8	3	450
450	689	456	628	8	3	450
500	739	506	678	10	4	600
550	789	556	728	10	4	600
600	839	606	778	10	4	600
650	889	656	828	12	5	750
700	939	706	878	12	5	750
750	989	756	928	12	5	750
800	1039	806	978	14	6	900
850	1089	856	1028	14	6	900
900	1139	906	1078	14	6	900
950	1189	956	1128	16	7	1050
1000	1239	1006	1178	16	7	1050
1100	1339	1106	1278	18	8	1200
1200	1439	1206	1378	18	8	1200

Motor Mounting Dimensions

[mm]

Motor type	FA	FB	FC	FD	FE	FF
NZ/NT	M5 x 0.8	9	70	50	5	47.5
NY	M4 x 0.7	8	70	50	5	47.5
NX	M5 x 0.8	9	63	40*	4.5*	51
NW/NU	M5 x 0.8	9	70	50	5	48.8
NV	M4 x 0.7	8	63	40*	4.5*	51
NM1	M4 x 0.7	8	□47.14	38.1*	4.5*	22
NM2	M4 x 0.7	8	□50	36*	4.5*	41.4

* Dimensions after mounting a ring spacer (Refer to page 800.)

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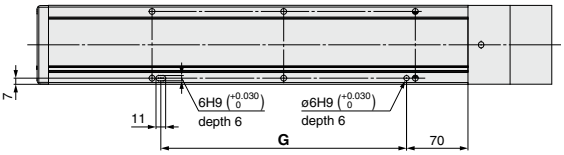
Refer to the "Motor Mounting" on page 800 for details about motor mounting and included parts.

Dimensions: Ball Screw Drive

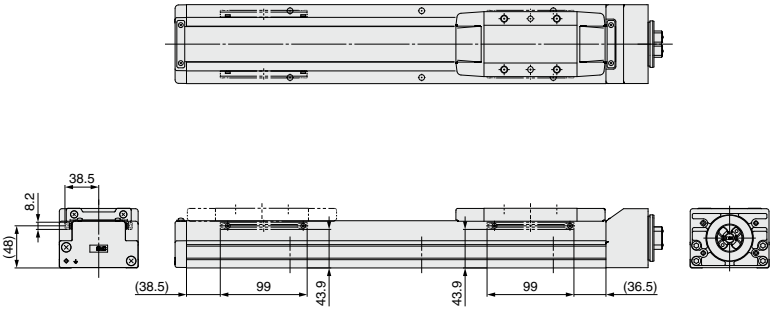
LEFS40

Positioning pin hole Note) **(Option): Body bottom**



Note) When using the body bottom positioning pin holes, do not simultaneously use the housing B bottom pin hole.

With auto switch (Option)



Dimensions [mm]

Stroke	G
150	130
200	280
250	280
300	280
350	430
400	430
450	430
500	580
550	580
600	580
650	730
700	730
750	730
800	880
850	880
900	880
950	1030
1000	1030
1100	1180
1200	1180

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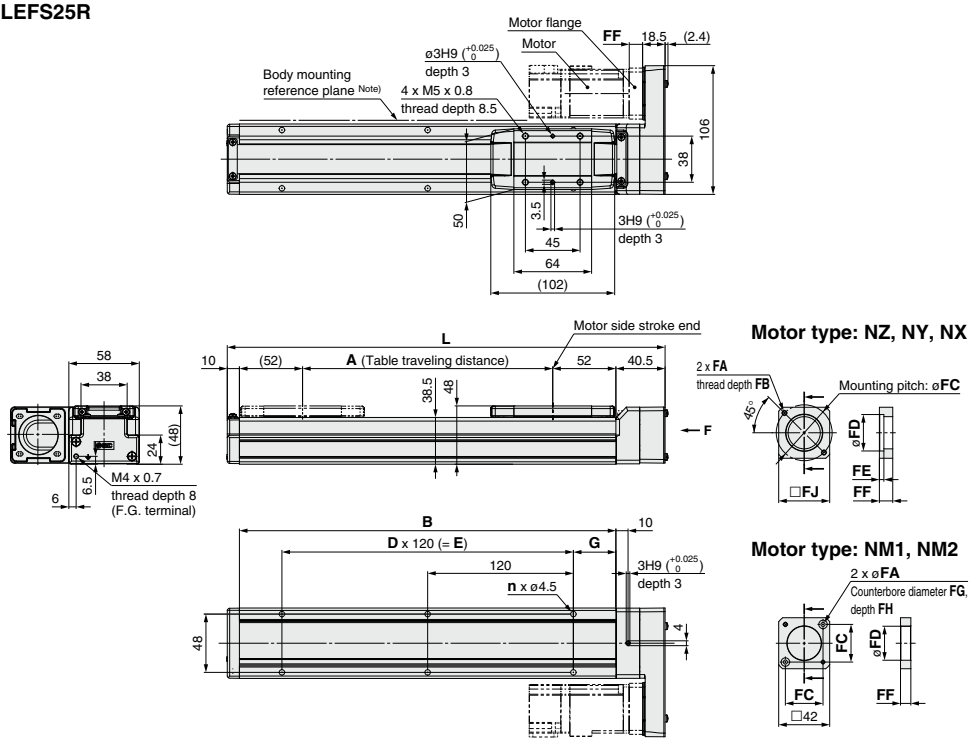
Refer to the "Motor Mounting" on page 801 for details about motor mounting and included parts.

Dimensions: Ball Screw Drive

LEFS25R



Note) When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height 5 mm)

Dimensions [mm]

Stroke	L	A	B	n	D	E	G
50	210.5	56	160	4	—	—	20
100	260.5	106	210	4	—	—	35
150	310.5	156	260	4	—	—	35
200	360.5	206	310	6	2	240	35
250	410.5	256	360	6	2	240	35
300	460.5	306	410	8	3	360	35
350	510.5	356	460	8	3	360	35
400	560.5	406	510	8	3	360	35
450	610.5	456	560	10	4	480	35
500	660.5	506	610	10	4	480	35
550	710.5	556	660	12	5	600	35
600	760.5	606	710	12	5	600	35
650	810.5	656	760	12	5	600	35
700	860.5	706	810	14	6	720	35
750	910.5	756	860	14	6	720	35
800	960.5	806	910	16	7	840	35

Motor Mounting Dimensions [mm]

Motor type	FA	FB	FC	FD	FE	FF	FG	FH	FJ
NZ	M4 x 0.7	7.5	46	30	3.7	11	—	—	42
NY	M3 x 0.5	5.5	45	30	5	11	—	—	38
NX	M4 x 0.7	7	46	30	3.7	8	—	—	42
NM1/NM2	ø3.4	—	31	28	—	8.5	7	3.5	—

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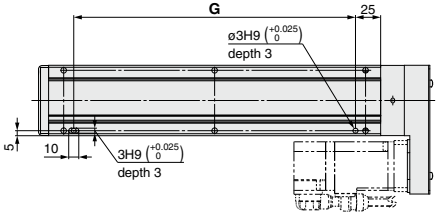
Refer to the "Motor Mounting" on page 801 for details about motor mounting and included parts.

Dimensions: Ball Screw Drive

LEFS25R

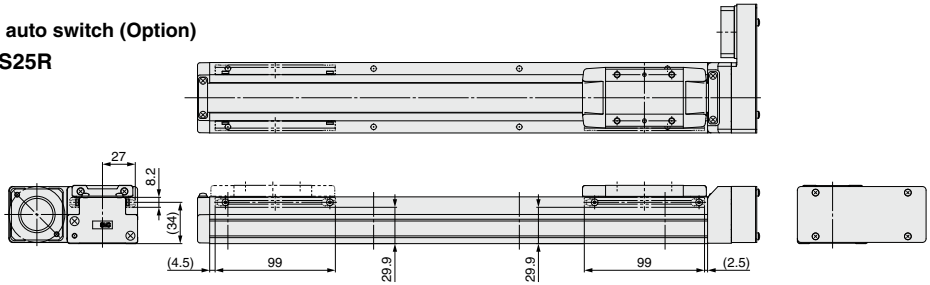
Positioning pin hole Note) **(Option): Body bottom**



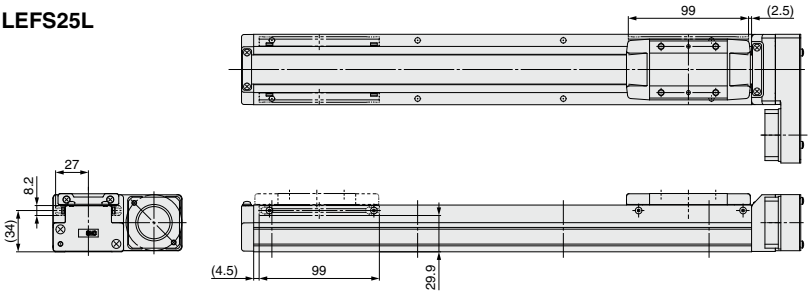
Note) When using the body bottom positioning pin holes, do not simultaneously use the housing B bottom pin hole.

With auto switch (Option)

LEFS25R



LEFS25L



Dimensions [mm]

Stroke	G	H
50	100	30
100	100	45
150	100	45
200	220	45
250	220	45
300	340	45
350	340	45
400	340	45
450	460	45
500	460	45
550	580	45
600	580	45
650	580	45
700	700	45
750	700	45
800	820	45

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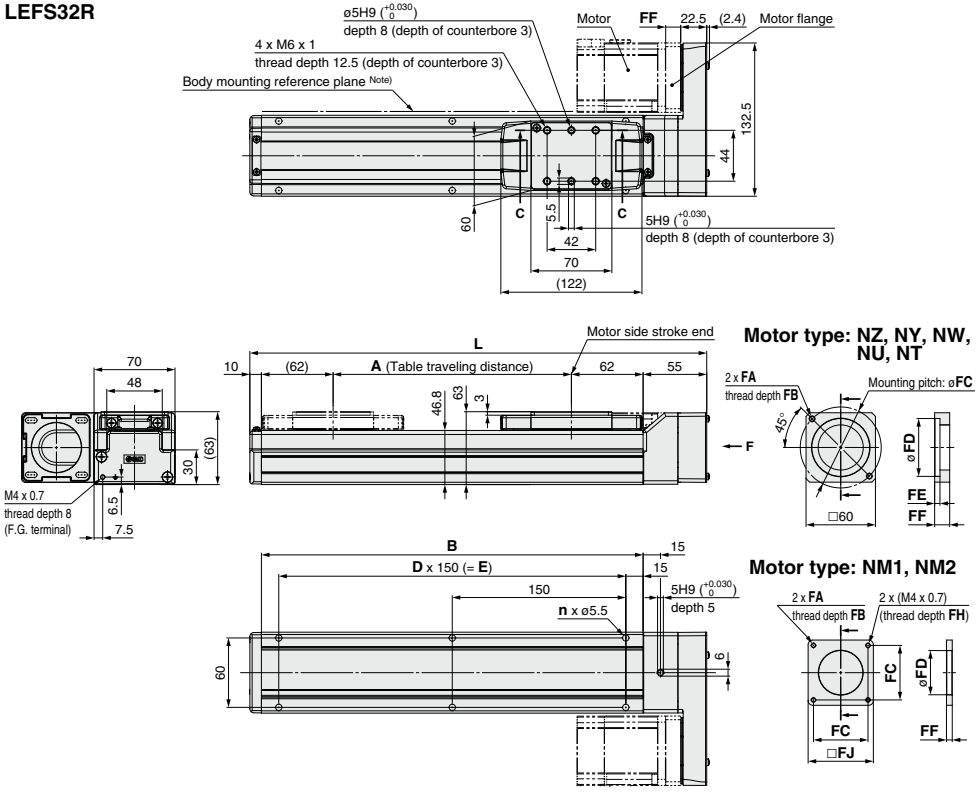
Dimensions: Ball Screw Drive

Refer to the "Motor Mounting" on page 801 for details about motor mounting and included parts.

LEFS32R



Note) When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height 5 mm)

Dimensions [mm]

Stroke	L	A	B	n	D	E
50	245	56	180	4	—	—
100	295	106	230	4	—	—
150	345	156	280	4	—	—
200	395	206	330	6	2	300
250	445	256	380	6	2	300
300	495	306	430	6	2	300
350	545	356	480	8	3	450
400	595	406	530	8	3	450
450	645	456	580	8	3	450
500	695	506	630	10	4	600
550	745	556	680	10	4	600
600	795	606	730	10	4	600
650	845	656	780	12	5	750
700	895	706	830	12	5	750
750	945	756	880	12	5	750
800	995	806	930	14	6	900
850	1045	856	980	14	6	900
900	1095	906	1030	14	6	900
950	1145	956	1080	16	7	1050
1000	1195	1006	1130	16	7	1050

Motor Mounting Dimensions [mm]

Motor type	FA	FB	FC	FD	FE	FF	FJ	FH
NZ/NW	M5 x 0.8	8.5	70	50	4.6	13	—	—
NY	M4 x 0.7	8	70	50	4.6	13	—	—
NU	M5 x 0.8	8.5	70	50	4.6	10.6	—	—
NT	M5 x 0.8	8.5	70	50	4.6	17	—	—
NM1	M4 x 0.7	5	47.14	38.2	—	5	56.4	5
NM2	M4 x 0.7	8	50	38.2	—	11.5	60	7

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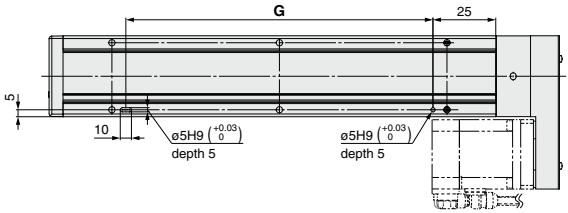
Refer to the "Motor Mounting" on page 801 for details about motor mounting and included parts.

Dimensions: Ball Screw Drive

LEFS32R

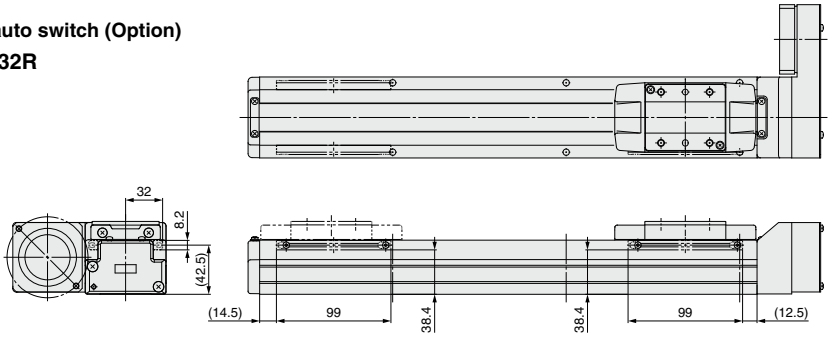
Positioning pin hole Note) **(Option): Body bottom**



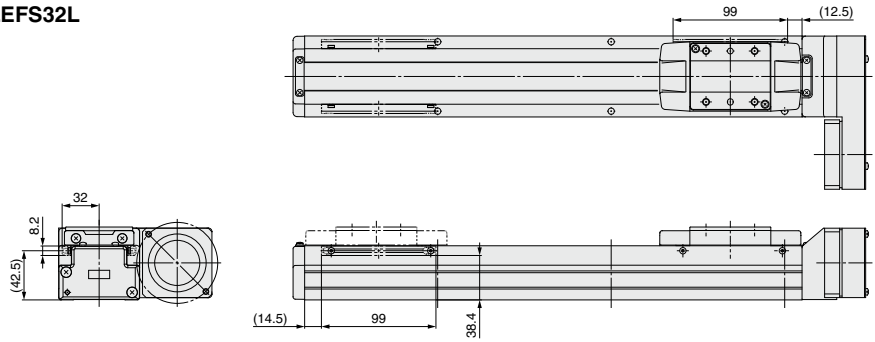
Note) When using the body bottom positioning pin holes, do not simultaneously use the housing B bottom pin hole.

With auto switch (Option)

LEFS32R



LEFS32L



Dimensions [mm]

Stroke	G
50	130
100	130
150	130
200	280
250	280
300	280
350	430
400	430
450	430
500	580

Dimensions [mm]

Stroke	G
550	580
600	580
650	730
700	730
750	730
800	880
850	880
900	880
950	1030
1000	1030

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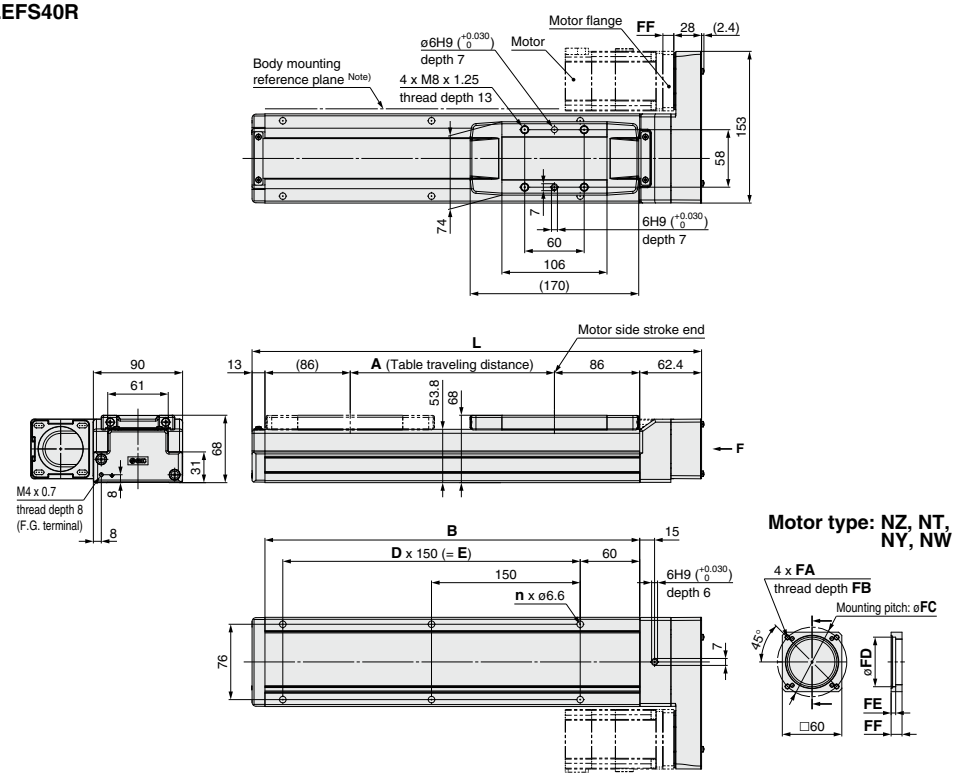
Dimensions: Ball Screw Drive

Refer to the "Motor Mounting" on page 801 for details about motor mounting and included parts.

LEFS40R



Note) When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height 5 mm)

Dimensions [mm]

Stroke	L	A	B	n	D	E
150	403.4	156	328	4	—	150
200	453.4	206	378	6	2	300
250	503.4	256	428	6	2	300
300	553.4	306	478	6	2	300
350	603.4	356	528	8	3	450
400	653.4	406	578	8	3	450
450	703.4	456	628	8	3	450
500	753.4	506	678	10	4	600
550	803.4	556	728	10	4	600
600	853.4	606	778	10	4	600
650	903.4	656	828	12	5	750
700	953.4	706	878	12	5	750
750	1003.4	756	928	12	5	750
800	1053.4	806	978	14	6	900
850	1103.4	856	1028	14	6	900
900	1153.4	906	1078	14	6	900
950	1203.4	956	1128	16	7	1050
1000	1253.4	1006	1178	16	7	1050
1100	1353.4	1106	1278	18	8	1200
1200	1453.4	1206	1378	18	8	1200

Motor Mounting Dimensions [mm]

Motor type	FA	FB	FC	FD	FE	FF
NZ/NW	M5 x 0.8	8.5	70	50	4.6	11
NY	M4 x 0.7	8	70	50	4.6	11
NT	M5 x 0.8	8.5	70	50	4.6	14.5

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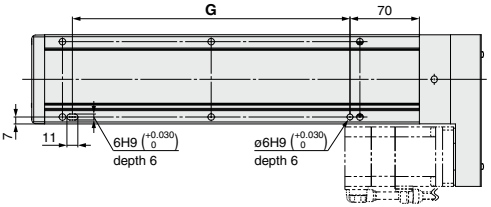
Refer to the "Motor Mounting" on page 801 for details about motor mounting and included parts.

Dimensions: Ball Screw Drive

LEFS40R

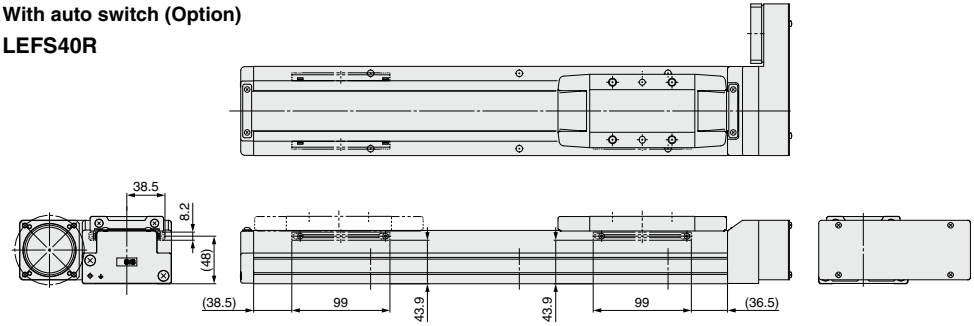
Positioning pin hole Note) **(Option): Body bottom**



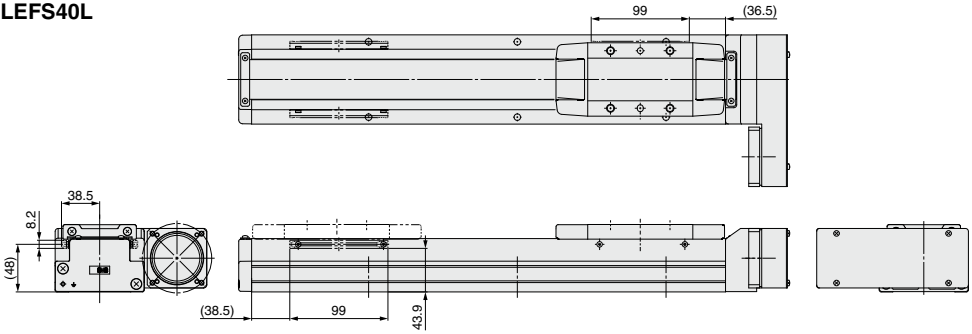
Note) When using the body bottom positioning pin holes, do not simultaneously use the housing B bottom pin hole.

With auto switch (Option)

LEFS40R



LEFS40L



Dimensions [mm]

Stroke	G
150	130
200	280
250	280
300	280
350	430
400	430
450	430
500	580
550	580
600	580

Dimensions [mm]

Stroke	G
650	730
700	730
750	730
800	880
850	880
900	880
950	1030
1000	1030
1100	1180
1200	1180

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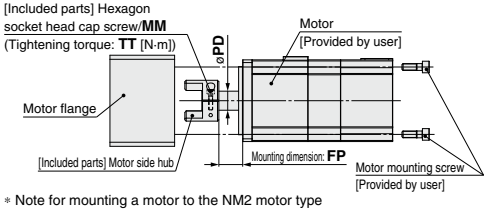
- When mounting a hub, remove the oil content, dust, or dirt sticking to the shaft and hub inside diameter.
- This product does not include the motor and motor mounting screws. (Provided by user) For the shaft-end shape of the motor, prepare the round type.
- Take loose prevention measures for the motor mounting screws.

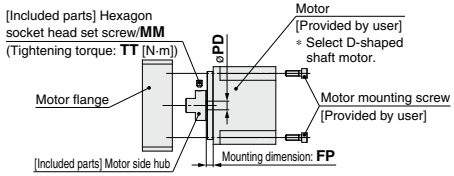
Motor Mounting: In-line

Motor type: NZ, NY, NX, NW, NV, NU, NT, NM2

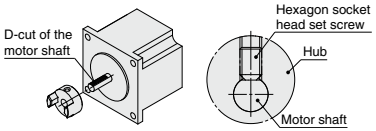


∗ Note for mounting a motor to the NM2 motor type
Motor mounting screws for the LEFS25 are fixed starting from the motor flange side. (Opposite of the drawing)

Motor type: NM1



∗ Note for mounting a hub to the NM1 motor type
When mounting the hub to the motor, make sure to position the set screw vertical to the D-cut surface of the motor shaft. (Refer to the figure shown below.)
∗ Motor mounting screws for the LEFS25 are fixed starting from the motor flange side. (Opposite of the drawing)



Size: 25 **Hub Mounting Dimensions** [mm]

Motor type	MM	TT	PD	FP
NZ	M2.5 x 10	1.00	8	12.4
NY	M2.5 x 10	1.00	8	12.4
NX	M2.5 x 10	1.00	8	6.9
NM1	M3 x 4	0.63	5	11.9
NM2	M2.5 x 10	1.00	6	10

Size: 32 **Hub Mounting Dimensions** [mm]

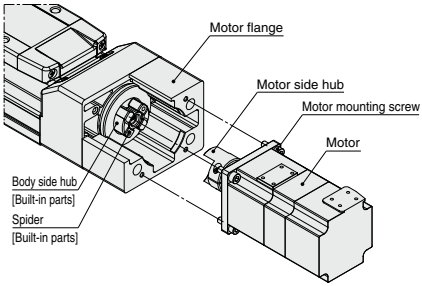
Motor type	MM	TT	PD	FP
NZ	M3 x 12	1.5	14	17.5
NY	M4 x 12	2.5	11	17.5
NX	M4 x 12	2.5	9	5.2
NW	M4 x 12	2.5	9	13
NV	M4 x 12	2.5	9	5.2
NU	M4 x 12	2.5	11	13
NT	M3 x 12	1.5	12	17.5
NM1	M4 x 5	1.5	6.35	5.4
NM2	M4 x 12	2.5	10	12

Size: 40 **Hub Mounting Dimensions** [mm]

Motor type	MM	TT	PD	FP
NZ	M3 x 12	1.5	14	17.5
NY	M3 x 12	1.5	14	17.5
NX	M4 x 12	2.5	9	5.2
NW	M4 x 12	2.5	9	13
NV	M4 x 12	2.5	9	5.2
NU	M4 x 12	2.5	11	13
NT	M3 x 12	1.5	12	17.5
NM1	M4 x 5	1.5	6.35	5.1
NM2	M4 x 12	2.5	10	12

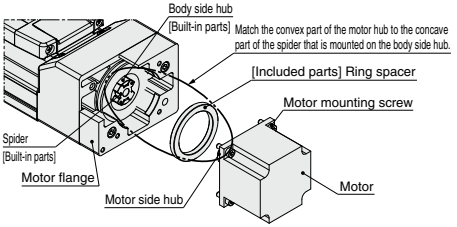
Motor Mounting Diagram

Motor type: NZ, NY, NW, NU, NT



Mounting procedure
1) Fix the motor (provided by user) and the "motor hub" with the "MM hexagon socket head cap screw."
2) Check the "motor hub position", and then insert it. (Refer to the mounting diagram.)
3) Fix the motor and the "motor flange" with the motor mounting screws (provided by user).

Motor type: NX, NV, NM1, NM2



Mounting procedure
1) Fix the motor (provided by user) and the "motor hub" with the "MM hexagon socket head cap screw (Motor type: NX, NM2)" or "MM hexagon socket head set screw (Motor type: NM1)."
2) Check the "motor hub position", and then insert it. (Refer to the mounting diagram.)
3) Mount the "ring spacer" to the motor.
4) Fix the motor and the "motor flange" with the motor mounting screws (provided by user).
∗ For the LEFS25
4) Remove the "motor flange", which has been temporarily mounted, from the housing B, and secure the motor to the "motor flange" using the motor mounting screws (that are to be prepared by user).
5) Tighten the "motor flange" to the "housing B" using motor flange fixing screws (included parts).

Included Parts List

Size: 25

Description	Quantity				
	Motor type				
	NZ	NY	NX	NM1	NM2
Motor side hub	1	1	1	1	1
Hexagon socket head cap screw/set screw (for hub fixing)∗	1	1	1	1	1
Hexagon socket head cap screw (for motor flange fixing)∗	—	—	—	2	2
Ring spacer	—	—	—	1	1

∗ For screw sizes, refer to the hub mounting dimensions.

Size: 32, 40

Description	Quantity								
	Motor type								
	NZ	NY	NX	NW	NV	NU	NT	NM1	NM2
Motor side hub	1	1	1	1	1	1	1	1	1
Hexagon socket head cap screw/set screw (for hub fixing)∗	1	1	1	1	1	1	1	1	1
Ring spacer	—	—	1	—	1	—	—	1	1

∗ For screw sizes, refer to the hub mounting dimensions.

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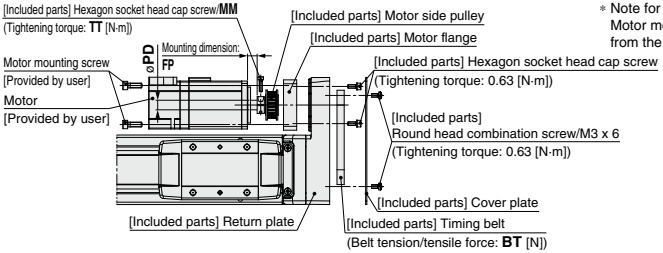
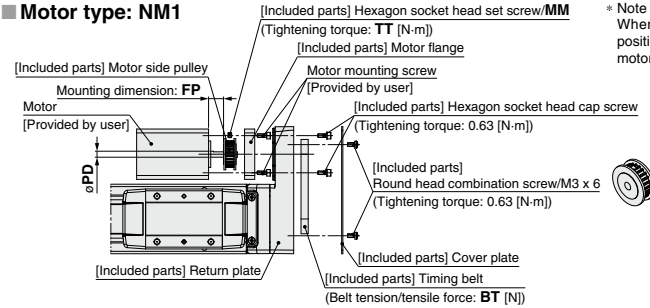
Motor Mounting: Motor Parallel

Motor type: NZ, NY, NX, NW, NU, NT, NM2

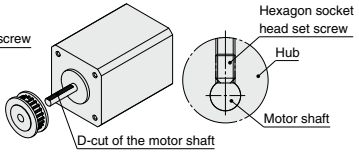


∗ Note for mounting a motor to the NM2 motor type
Motor mounting screws for the LEFS25 are fixed starting from the motor flange side. (Opposite of the drawing)

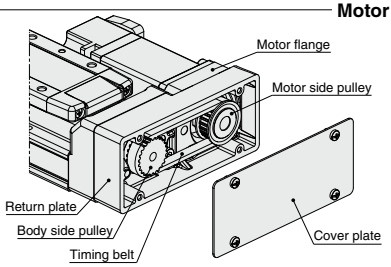
Motor type: NM1



∗ Note for mounting a pulley to the NM1 motor type
When mounting the hub to the motor, make sure to position the set screw vertical to the D-cut surface of the motor shaft. (Refer to the figure shown below.)



Motor Mounting Diagram



Mounting procedure

1) Fix the motor (provided by user) and the “motor side pulley” with the MM hexagon socket head cap screw. For motor type “NM1”, fix them with the MM hexagon socket head set screw.
2) Fix the motor and the “motor flange” with the motor mounting screws (provided by user).
3) Put the “timing belt” on the “motor side pulley” and “body side pulley”, and then fix it temporarily with the “hexagon socket head cap screws (2 x M3 x 8).” (Refer to the left diagram.)
4) Apply the belt tension and tighten the timing belt with the “hexagon socket head cap screws (2 x M3 x 8).”
5) Fix the “return plate” with the “round head combination screws (4 x M3 x 6).”

Size: 25 Hub Mounting Dimensions [mm]

Motor type	MM	TT	PD	FP	BT
NZ/NY	M2.5 x 10	1.00	8	8	19.6
NX	M2.5 x 10	1.00	8	5	19.6
NM1	M3 x 4	0.63	5	12.5	19.6
NM2	M2.5 x 10	1.00	6	5.5	19.6

Size: 32 Hub Mounting Dimensions [mm]

Motor type	MM	TT	PD	FP	BT
NZ	M3 x 12	1.50	14	6.6	49
NY	M3 x 12	1.50	11	6.6	49
NW	M4 x 12	2.50	9	6.6	49
NU	M3 x 12	1.50	11	4.2	49
NT	M3 x 12	1.50	12	10.6	49
NM1	M3 x 4	0.63	6.35	10.6	49
NM2	M3 x 12	1.50	10	5.1	49

Size: 40 Hub Mounting Dimensions [mm]

Motor type	MM	TT	PD	FP	BT
NZ/NY	M4 x 12	2.5	14	4.5	98.1
NW	M4 x 12	2.5	9	4.5	98.1
NT	M4 x 12	2.5	12	8	98.1

Included Parts List

Size: 25

Description	Quantity
Motor flange	1
Motor side pulley	1
Cover plate	1
Timing belt	1
Hexagon socket head cap screw/set screw (for pulley fixing)∗	1
Hexagon socket head cap screw M3 x 8 (for motor flange fixing)	2
Round head combination screw M3 x 6	4

∗ For screw sizes, refer to the hub mounting dimensions.

Size: 32, 40

Description	Quantity	
	32	40
Motor flange	1	1
Motor side pulley	1	1
Cover plate	1	1
Timing belt	1	1
Hexagon socket head cap screw/set screw (for pulley fixing)∗	1	1
Hexagon socket head cap screw M4 x 12 (for motor flange fixing)	2	4
Round head combination screw M3 x 6	4	4

∗ For screw sizes, refer to the hub mounting dimensions.

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LEFS Series
Motor Mounting Parts

Motor Flange Option

After purchasing the product, the motor can be changed to the motor types shown below by replacing with this option. (Except NM1)
Use the following part numbers to select a compatible motor flange option and place an order.

How to Order

LEF S – MF 25 ❶ ❷ – NZ ❸

Ball screw drive

❶ Size

25	For LEF□25
32	For LEF□32
40	For LEF□40

❷ Motor mounting position

Nil	In-line
P	(Right side/Left side) parallel

❸ Motor type

Symbol	Type	Symbol	Type
NZ	Mounting type Z	**NV**	Mounting type V
NY	Mounting type Y	**NU**	Mounting type U
NX	Mounting type X	**NT**	Mounting type T
NW	Mounting type W	**NM2**	Mounting type M2

∗ Select only NZ, NY, NX or NM2 for the LEFS-MF25.

Compatible Motors

Applicable motor model			Size/Motor type											
			25				32/40							
Manufacturer	Series	Type	NZ Mounting type Z	NY Mounting type Y	NX Mounting type X	NM2 Mounting type M2	NZ Mounting type Z	NY Mounting type Y	NX Mounting type X	NW Mounting type W	NV Mounting type V	NU Mounting type U	NT Mounting type T	NM2 Mounting type M2
Mitsubishi Electric Corporation	MELSERVO-JN	HF-KN	●	—	—	—	●	—	—	—	—	—	—	—
	MELSERVO-J3	KF-KP	●	—	—	—	●	—	—	—	—	—	—	—
	MELSERVO-J4	HG-KR	●	—	—	—	●	—	—	—	—	—	—	—
YASKAWA Electric Corporation	Σ-V	SGMJV	●	—	—	—	●	—	—	—	—	—	—	—
SANYO DENKI CO., LTD.	SANMOTION R	R2	●	—	—	—	●	—	—	—	—	—	—	—
OMRON Corporation	Sysmac G5	R88M-K	●	—	—	—	—	●	—	—	—	—	—	—
Panasonic Corporation	MINAS-A4	MSMD	—	●	—	—	—	●	—	—	—	—	—	—
	MINAS-A5	MSMD/MHMD	—	●	—	—	—	●	—	—	—	—	—	—
FANUC CORPORATION	βis	β	●	—	—	—	● (β1 only)	—	—	●	—	—	—	—
NIDEC SANKYO CORPORATION	S-FLAG	MA/MH/MM	●	—	—	—	●	—	—	—	—	—	—	—
KEYENCE CORPORATION	SV	SV-M/SV-B	●	—	—	—	●	—	—	—	—	—	—	—
FUJI ELECTRIC CO., LTD.	ALPHA5	GYS/GYB	●	—	—	—	●	—	—	—	—	—	—	—
	FALDIC-α	GYS	●	—	—	—	●	—	—	—	—	—	—	—
ORIENTAL MOTOR Co., Ltd.	AR/AZ	AR/AZ (46 only)	—	—	—	●	—	—	—	—	—	—	—	—
	AR/AZ	AR/AZ	—	—	—	—	—	—	—	—	—	—	—	●∗2
Rockwell Automation, Inc. (Allen-Bradley)	MP-/VP-	MP/VP	—	—	—	—	—	—	●∗1	—	—	—	—	—
	TL	TLY-A	●	—	—	—	—	—	—	—	—	—	●	—
Beckhoff Automation GmbH	AM	AM30	●	—	—	—	—	—	—	—	●∗1	—	—	—
	AM	AM31	●	—	—	—	—	—	—	—	—	●∗2	—	—
	AM	AM80/AM81	●	—	—	—	—	—	●∗1	—	—	—	—	—
Siemens AG	1FK7	1FK7	—	—	●	—	—	—	●∗1	—	—	—	—	—
Delta Electronics, Inc.	ASDA-A2	ECMA	●	—	—	—	●	—	—	—	—	—	—	—

Note) When the LEF□□□NM1□-□ is purchased, it is not possible to change to other motor types.

∗1 Motor mounting position: In-line only
∗2 Only size 32 is available when the motor mounting position is right (or left) side parallel.

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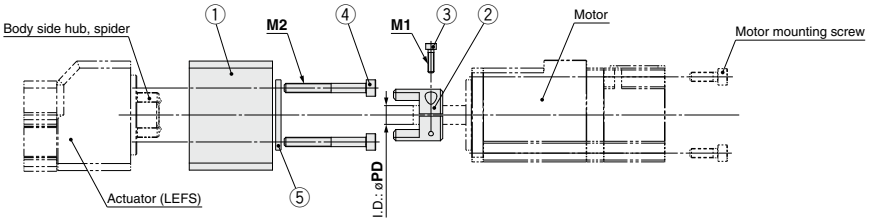
Dimensions: Motor Flange Option

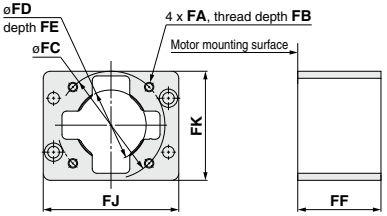
Motor mounting position: In-line



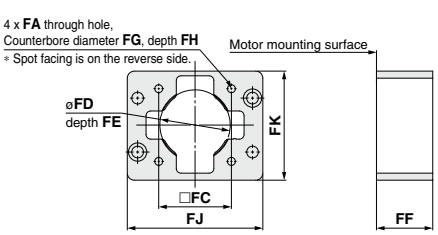
Component Parts

No.	Description	Quantity
1	**Motor flange**	1
2	**Hub (Motor side)**	1
3	**Hexagon socket head cap screw (for hub fixing)**	1
4	**Hexagon socket head cap screw (for motor flange mounting)**	2
5	**Ring spacer (Only for NX, NV and NM2 of size 32, 40)**	1

Motor flange details



For NM2



Dimensions

[mm]

Size	Motor type	FA	FB	FC	FD	FE	FF	FG	FH	FJ	FK	M1	M2	PD
25	**NZ/NX**	M4 x 0.7	8	46	30	3.5	35.5	—	—	57.8	46.5	M2.5 x 10	M4 x 35	8
	NY	M3 x 0.5	8	45	30	3.5	35.5	—	—	57.8	46.5	M2.5 x 10	M4 x 35	8
	NM2	ø3.4	—	31	22∗	2.5∗	33.1	6.5	22.6	57.8	46.5	M2.5 x 10	M4 x 18	6
32	**NZ**	M5 x 0.8	9	70	50	5	46	—	—	69.8	61.4	M3 x 12	M5 x 40	14
	NY	M4 x 0.7	8	70	50	5	46	—	—	69.8	61.4	M4 x 12	M5 x 40	11
	NX	M5 x 0.8	9	63	50	5	49.7	—	—	69.8	61.4	M4 x 12	M5 x 40	9
	NW	M5 x 0.8	9	70	50	5	47.5	—	—	69.8	61.4	M4 x 12	M5 x 40	9
	NV	M4 x 0.7	8	63	50	5	49.7	—	—	69.8	61.4	M4 x 12	M5 x 40	9
	NU	M5 x 0.8	9	70	50	5	47.5	—	—	69.8	61.4	M4 x 12	M5 x 40	11
	NT	M5 x 0.8	9	70	50	5	46	—	—	69.8	61.4	M3 x 12	M5 x 40	12
	NM2	M4 x 0.7	8	50	36∗	4.5∗	40.1	—	—	69.8	61.4	M4 x 12	M5 x 25	10
40	**NZ**	M5 x 0.8	9	70	50	5	47.5	—	—	89.8	66.9	M3 x 12	M5 x 40	14
	NY	M4 x 0.7	8	70	50	5	47.5	—	—	89.8	66.9	M3 x 12	M5 x 40	14
	NX	M5 x 0.8	9	63	50	5	51	—	—	89.8	66.9	M4 x 12	M5 x 40	9
	NW	M5 x 0.8	9	70	50	5	48.8	—	—	89.8	66.9	M4 x 12	M5 x 40	9
	NV	M4 x 0.7	8	63	50	5	51	—	—	89.8	66.9	M4 x 12	M5 x 40	9
	NU	M5 x 0.8	9	70	50	5	48.8	—	—	89.8	66.9	M4 x 12	M5 x 40	11
	NT	M5 x 0.8	9	70	50	5	47.5	—	—	89.8	66.9	M3 x 12	M5 x 40	12
	NM2	M4 x 0.7	8	50	36∗	4.5∗	41.4	—	—	89.8	66.9	M4 x 12	M5 x 25	10

∗ Dimensions after mounting a ring spacer

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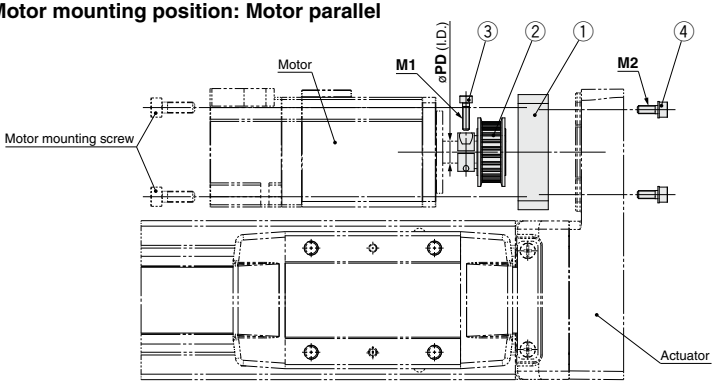
Dimensions: Motor Flange Option

Motor mounting position: Motor parallel

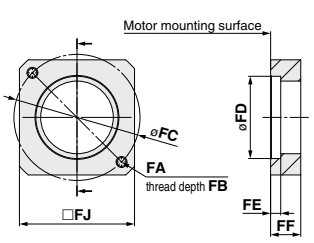


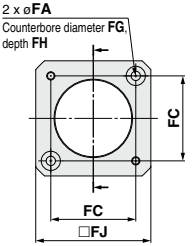
Component Parts

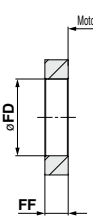
No.	Description	Quantity Size	
		25, 32	40
1	Motor flange	1	1
2	Motor pulley	1	1
3	Hexagon socket head cap screw (for pulley fixing)	1	1
4	Hexagon socket head cap screw (for motor flange mounting)	2	4

Motor flange details

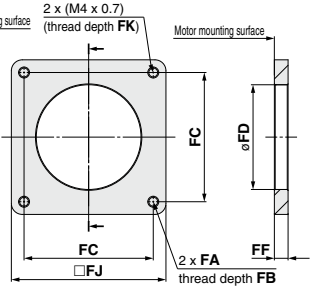
Size 25: NM2







Size 32: NM2



Dimensions

[mm]

Size	Motor type	FA	FB	FC	FD	FE	FF	FG	FH	FJ	FK	M1	M2	PD
25	NZ	2 x M4 x 0.7	7.5	46	30	3.7	11	—	—	42	—	M2.5 x 10	M3 x 8	8
	NY	2 x M3 x 0.5	5.5	45	30	5	11	—	—	38	—	M2.5 x 10	M3 x 8	8
	NX	2 x M4 x 0.7	7	46	30	3.7	8	—	—	42	—	M2.5 x 10	M3 x 8	8
	NM2	ø3.4	—	31	28	—	8.5	7	3.5	42	—	M2.5 x 10	M3 x 8	6
32	NZ	2 x M5 x 0.8	8.5	70	50	4.6	13	—	—	60	—	M3 x 12	M4 x 12	14
	NY	2 x M4 x 0.7	8	70	50	4.6	13	—	—	60	—	M3 x 12	M4 x 12	11
	NW	2 x M5 x 0.8	8.5	70	50	4.6	13	—	—	60	—	M4 x 12	M4 x 12	9
	NU	2 x M5 x 0.8	8.5	70	50	4.6	10.6	—	—	60	—	M3 x 12	M4 x 12	11
	NT	2 x M5 x 0.8	8.5	70	50	4.6	17	—	—	60	—	M3 x 12	M4 x 12	12
	NM2	M4 x 0.7	8	50	38.2	—	11.5	—	—	60	7	M3 x 12	M4 x 12	10
40	NZ	4 x M5 x 0.8	8.5	70	50	4.6	11	—	—	60	—	M4 x 12	M4 x 12	14
	NY	4 x M4 x 0.7	8	70	50	4.6	11	—	—	60	—	M4 x 12	M4 x 12	14
	NW	4 x M5 x 0.8	8.5	70	50	4.6	11	—	—	60	—	M4 x 12	M4 x 12	9
	NT	4 x M5 x 0.8	8.5	70	50	4.6	14.5	—	—	60	—	M4 x 12	M4 x 12	12

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Model Selection

LEFB Series ▶ Page 810

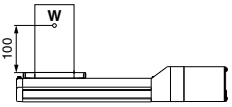
Selection Procedure

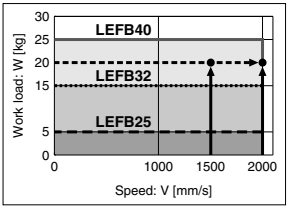
Step 1 Check the work load–speed. → **Step 2** Check the cycle time. → **Step 3** Check the allowable moment.

Selection Example

Operating conditions

- Workpiece mass: 20 [kg]
- Speed: 1500 [mm/s]
- Acceleration/Deceleration: 3000 [mm/s²]
- Stroke: 2000 [mm]
- Mounting position: Horizontal upward
- Workpiece mounting condition:





<Speed–Work Load Graph> (LEFB40)

Step 1 Check the work load–speed. <Speed–Work Load Graph>

Select a model based on the workpiece mass and speed which are within the range of the actuator body specifications with reference to the "Speed–Work Load Graph (Guide)" on page 806.

Selection example) The **LEFB40□S-2000** is temporarily selected based on the graph shown on the right side.

∗ Refer to the selection method of motor manufacturers for regeneration resistance.

Step 2 Check the cycle time.

Calculate **the cycle time** using the following calculation method.

Cycle time:

T can be found from the following equation.

$$T = T1 + T2 + T3 + T4 \text{ [s]}$$

- T1: Acceleration time and T3: Deceleration time can be obtained by the following equation.

$$T1 = V/a1 \text{ [s]} \qquad T3 = V/a2 \text{ [s]}$$

- T2: Constant speed time can be found from the following equation.

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} \text{ [s]}$$

- T4: Settling time varies depending on the motor type and load. The value below is recommended.

$$T4 = 0.05 \text{ [s]}$$

∗ The conditions for the settling time vary depending on the motor or driver to be used.

Calculation example)
T1 to T4 can be calculated as follows.

$T1 = V/a1 = 1500/3000 = 0.5$ [s],

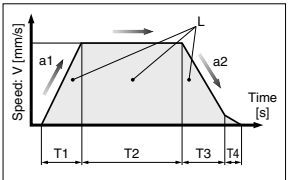
$T3 = V/a2 = 1500/3000 = 0.5$ [s]

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} = \frac{2000 - 0.5 \cdot 1500 \cdot (0.5 + 0.5)}{1500} = 0.83 \text{ [s]}$$

$T4 = 0.05$ [s]

Therefore, **the cycle time** can be obtained as follows.

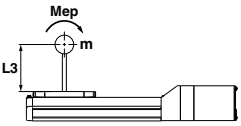
$T = T1 + T2 + T3 + T4 = 0.5 + 0.83 + 0.5 + 0.05 = \mathbf{1.88}$ **[s]**

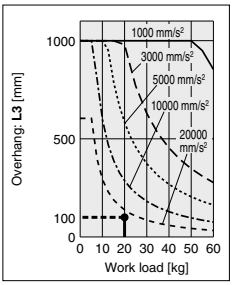


L : Stroke [mm]
··· (Operating condition)
V : Speed [mm/s]
··· (Operating condition)
a1: Acceleration [mm/s²]
··· (Operating condition)
a2: Deceleration [mm/s²]
··· (Operating condition)

T1: Acceleration time [s]
Time until reaching the set speed
T2: Constant speed time [s]
Time while the actuator is operating at a constant speed
T3: Deceleration time [s]
Time from the beginning of the constant speed operation to stop
T4: Settling time [s]
Time until positioning is completed

Step 3 Check the guide moment.





Based on the above calculation result, the LEFB40□S-2000 is selected.

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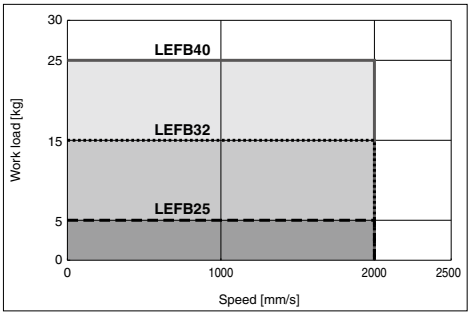
∗ The values shown below are allowable values of the actuator body.
Do not use the actuator so that it exceeds these specification ranges.

Speed–Work Load Graph (Guide)

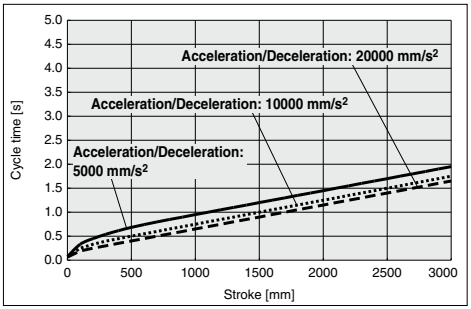
LEFB□/Belt Drive



Cycle Time Graph (Guide)

LEFB□/Belt Drive

LEFB25/32/40

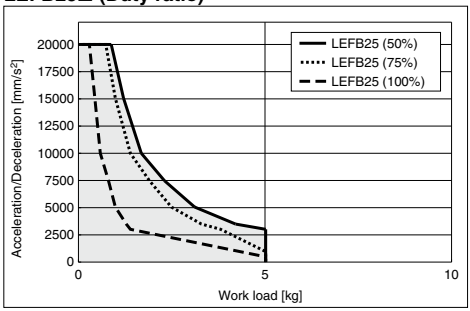


∗ Cycle time is for when maximum speed.
∗ Maximum stroke: LEFB25: 2000 mm
LEFB32: 2500 mm
LEFB40: 3000 mm

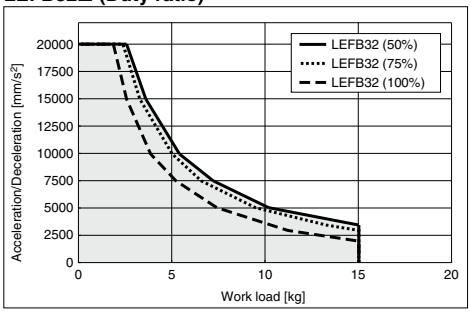
Work Load–Acceleration/Deceleration Graph (Guide)

LEFB□/Belt Drive

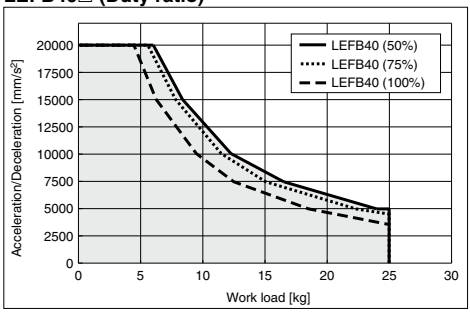
LEFB25□ (Duty ratio)



LEFB32□ (Duty ratio)



LEFB40□ (Duty ratio)



These graphs are examples of when the standard motor is mounted.
Determine the duty ratio after taking into account the load factor of the motor or driver to be used.

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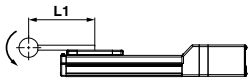
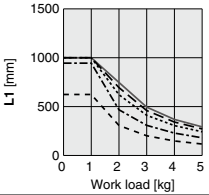
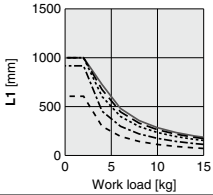
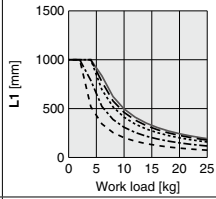
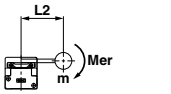
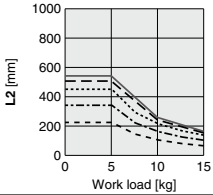
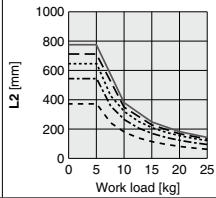
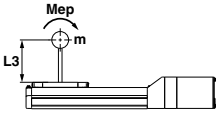
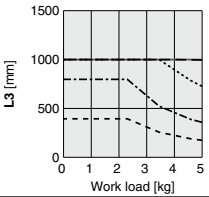
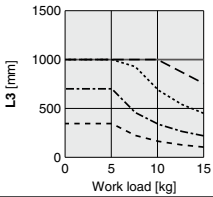
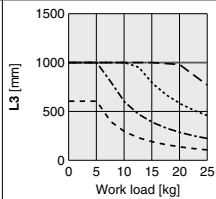
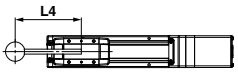
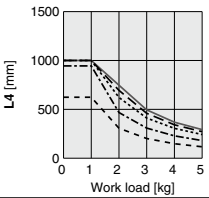
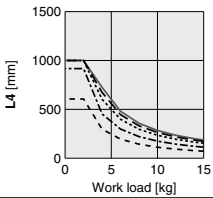
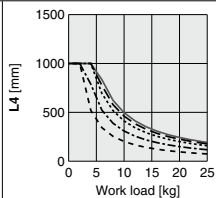
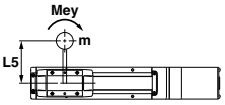
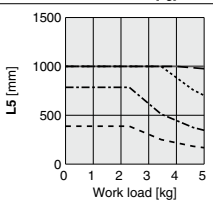
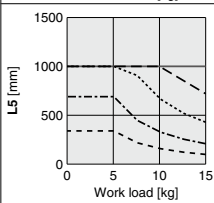
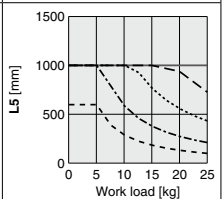
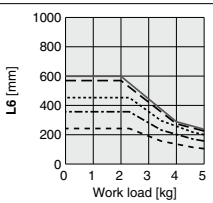
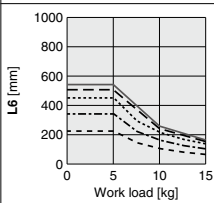
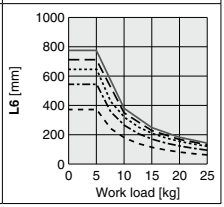
Dynamic Allowable Moment

* This graph shows the amount of allowable overhang (guide unit) when the center of gravity of the workpiece overhangs in one direction. When selecting the overhang, refer to "Calculation of Guide Load Factor" or the Electric Actuator Selection Software for confirmation, http://www.smcworld.com

Acceleration/Deceleration ——1000 mm/s² — — —3000 mm/s² ·····5000 mm/s² —·—·—10000 mm/s² - - - - 20000 mm/s²

Orientation	Load overhanging direction **m** : Work load [kg] **Me**: Dynamic allowable moment [N·m] **L** : Overhang to the work load center of gravity [mm]		Model LEFB25□	Model LEFB32□	Model LEFB40□
Horizontal/Bottom		X			
		Y			
		Z			
Wall		X			
		Y			
		Z			

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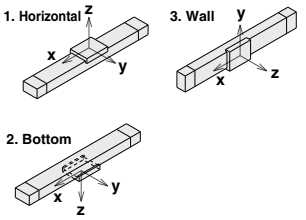
Calculation of Guide Load Factor

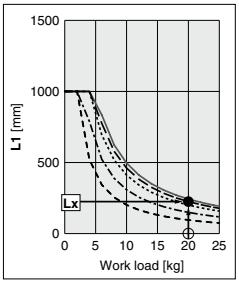
1. Decide operating conditions.
   Model: LEFB
   Size: 25/32/40
   Mounting orientation: Horizontal/Bottom/Wall
   Acceleration [mm/s²]: **a**
   Work load [kg]: **m**
   Work load center position [mm]: **Xc/Yc/Zc**
2. Select the target graph with reference to the model, size and mounting orientation.
3. Based on the acceleration and work load, obtain the overhang [mm]: **Lx/Ly/Lz** from the graph.
4. Calculate the load factor for each direction.
   α**x = Xc/Lx**, α**y = Yc/Ly**, α**z = Zc/Lz**
5. Confirm the total of α**x**, α**y** and α**z** is 1 or less.
   α**x + αy + αz ≤ 1**
   When 1 is exceeded, consider a reduction of acceleration and work load, or a change of the work load center position and series.

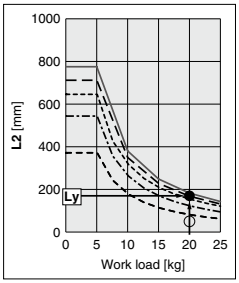
Mounting Orientation



Example

1. Operating conditions
   Model: LEFB40
   Size: 40
   Mounting orientation: Horizontal
   Acceleration [mm/s²]: 3000
   Work load [kg]: 20
   Work load center position [mm]: **Xc = 0**, **Yc = 50**, **Zc = 200**
2. Select the graphs for horizontal of the LEFB40 on page 807.
3. **Lx = 250 mm**, **Ly = 180 mm**, **Lz = 1000 mm**
4. The load factor for each direction can be obtained as follows.
   α**x = 0/250 = 0**
   α**y = 50/180 = 0.27**
   α**z = 200/1000 = 0.2**
5. α**x + αy + αz = 0.47 ≤ 1**





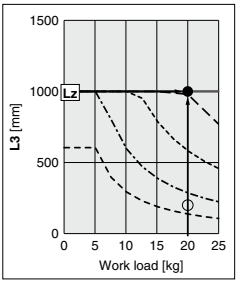


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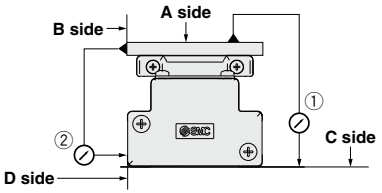
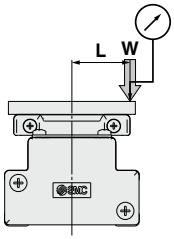
Table Accuracy (Reference Value)

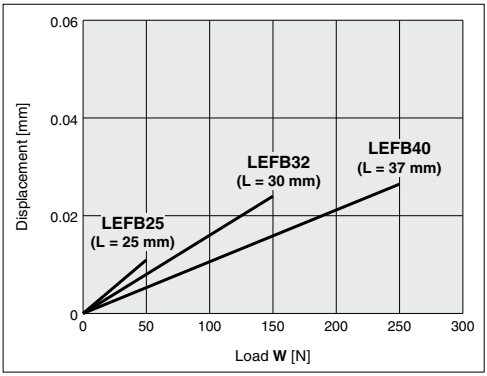


Model	Traveling parallelism [mm] (Every 300 mm)	
	① C side traveling parallelism to A side	② D side traveling parallelism to B side
LEFB25	0.05	0.03
LEFB32	0.05	0.03
LEFB40	0.05	0.03

Note) Traveling parallelism does not include the mounting surface accuracy.

Table Displacement (Reference Value)

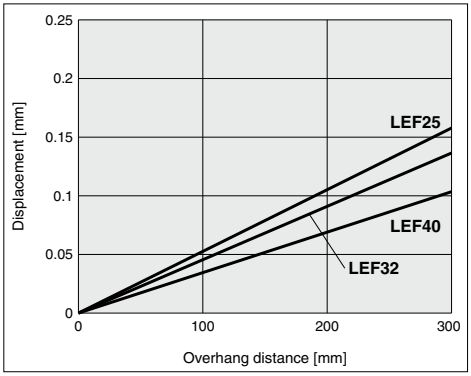




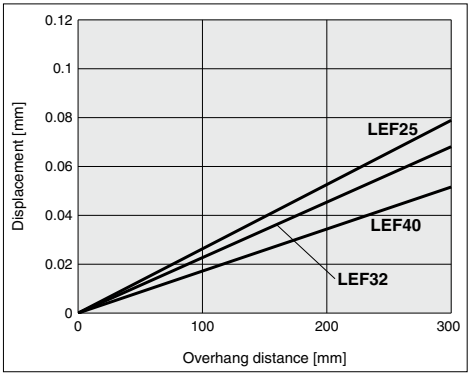
Note 1) This displacement is measured when a 15 mm aluminum plate is mounted and fixed on the table.
Note 2) Check the clearance and play of the guide separately.

Overhang Displacement Due to Table Clearance (Reference Value)

Basic Type



High Precision Type



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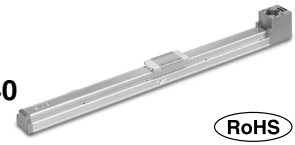
Motorless Type

Electric Actuator/Slider Type
Belt Drive

LEFB Series LEFB25, 32, 40



RoHS

How to Order

LEFB 25 ❶ NZ ❷ S ❸ – 300 ❹ C ❺ K ❻ ❼

❶ Size

25
32
40

❷ Motor mounting position

Nil	Top mounting
U	Bottom mounting

❸ Motor type

Symbol	Type
NZ	Mounting type Z
NY	Mounting type Y
NX	Mounting type X
NW	Mounting type W
NV	Mounting type V
NU	Mounting type U
NT	Mounting type T
NM1	Mounting type M1
NM2	Mounting type M2

❹ Equivalent lead [mm]

S	54

❺ Stroke [mm]

300	300
to	to
3000	3000

∗ Refer to the applicable stroke table.

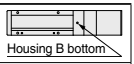
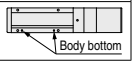
❻ Auto switch mounting bracket

Nil	None
C	With 1 pc. (Included)

∗ If 2 or more are required, please order them separately. (Part no.: LEF-D-2-1 For details, refer to page 112-1.)

∗ Order auto switches separately. (For details, refer to pages 112-2 and 112-3.)

❼ Positioning pin hole

Nil	Housing B bottom∗	
K	Body bottom 2 locations	

∗ Refer to the body mounting example on page 822 for the mounting method.

Applicable Stroke Table

●: Standard/○: Produced upon receipt of order

	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2500	3000
LEFB25	●	●	●	●	●	●	●	●	○	●	○	○	●	○	○	○	○	●	—	—
LEFB32	●	●	●	●	●	●	●	●	○	●	○	○	●	○	○	○	○	●	●	—
LEFB40	●	●	●	●	●	●	●	●	○	●	○	○	●	○	○	○	○	●	●	●

∗ Please consult with SMC as all non-standard and non-made-to-order strokes are produced as special orders.

Compatible Motors

Applicable motor model			Size/Motor type													
			25					32/40								
Manufacturer	Series	Type	NZ Mounting type Z	NY Mounting type Y	NX Mounting type X	NM1 Mounting type M1	NM2 Mounting type M2	NZ Mounting type Z	NY Mounting type Y	NX Mounting type X	NW Mounting type W	NV Mounting type V	NU Mounting type U	NT Mounting type T	NM1 Mounting type M1	NM2 Mounting type M2
Mitsubishi Electric Corporation	MELSERVO-JN	HF-KN	●	—	—	—	—	●	—	—	—	—	—	—	—	—
	MELSERVO-J3	HF-KP	●	—	—	—	—	●	—	—	—	—	—	—	—	—
	MELSERVO-J4	HG-KR	●	—	—	—	—	●	—	—	—	—	—	—	—	—
YASKAWA Electric Corporation	Σ-V	SGMJV	●	—	—	—	—	●	—	—	—	—	—	—	—	—
SANYO DENKI CO., LTD.	SANMOTION R	R2	●	—	—	—	—	●	—	—	—	—	—	—	—	—
OMRON Corporation	Sysmac G5	R88M-K	●	—	—	—	—	—	●	—	—	—	—	—	—	—
Panasonic Corporation	MINAS-A4	MSMD	—	●	—	—	—	—	●	—	—	—	—	—	—	—
	MINAS-A5	MSMD/MHMD	—	●	—	—	—	—	●	—	—	—	—	—	—	—
FANUC CORPORATION	βis	β	●	—	—	—	—	● (β1 only)	—	—	●	—	—	—	—	—
NIDEC SANKYO CORPORATION	S-FLAG	MA/MH/MM	●	—	—	—	—	●	—	—	—	—	—	—	—	—
KEYENCE CORPORATION	SV	SV-M/SV-B	●	—	—	—	—	●	—	—	—	—	—	—	—	—
FUJI ELECTRIC CO., LTD.	ALPHA5	GYS/GYB	●	—	—	—	—	●	—	—	—	—	—	—	—	—
	FALDIC-α	GYS	●	—	—	—	—	●	—	—	—	—	—	—	—	—
ORIENTAL MOTOR Co., Ltd.	AR/AZ	AR/AZ (46 only)	—	—	—	—	●	—	—	—	—	—	—	—	—	—
	AR/AZ	AR/AZ	—	—	—	—	—	—	—	—	—	—	—	—	—	●
FASTECH Co., Ltd.	Ezi-SERVO	EzM	—	—	—	●	—	—	—	—	—	—	—	—	●	—
Rockwell Automation, Inc. (Allen-Bradley)	MP-/VP-	MP/VP	—	—	—	—	—	—	—	●	—	—	—	—	—	—
	TL	TLY-A	●	—	—	—	—	—	—	—	—	—	—	●	—	—
Beckhoff Automation GmbH	AM	AM30	●	—	—	—	—	—	—	—	—	●	—	—	—	—
	AM	AM31	●	—	—	—	—	—	—	—	—	—	●	—	—	—
	AM	AM80/AM81	●	—	—	—	—	—	—	●	—	—	—	—	—	—
Siemens AG	1FK7	1FK7	—	—	●	—	—	—	—	●	—	—	—	—	—	—
Delta Electronics, Inc.	ASDA-A2	ECMA	●	—	—	—	—	●	—	—	—	—	—	—	—	—

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Specifications Note 2)

- Values in this specification table are the allowable values of the actuator body with the standard motor mounted.
- Do not use the actuator so that it exceeds these values.

	Model		LEFB25	LEFB32	LEFB40
Actuator specifications	Stroke [mm] Note 1)		300, 400, 500 600, 700, 800 900, 1000, (1100) 1200, (1300, 1400) 1500, (1600, 1700) (1800, 1900), 2000	300, 400, 500 600, 700, 800 900, 1000, (1100) 1200, (1300, 1400) 1500, (1600, 1700) (1800, 1900), 2000 2500	300, 400, 500 600, 700, 800 900, 1000, (1100) 1200, (1300, 1400) 1500, (1600, 1700) (1800, 1900), 2000 2500, 3000
	Work load [kg]	Horizontal	5	15	25
	Speed [mm/s]		2000		
	Pushing return to origin speed [mm/s]		30 or less		
	Positioning repeatability [mm]		±0.06		
	Lost motion [mm] Note 3)		0.1 or less		
	Equivalent lead [mm]		54		
	Max. acceleration/deceleration [mm/s²]		20000 Note 4)		
	Impact/Vibration resistance [m/s²]		50/20		
	Actuation type		Belt		
	Guide type		Linear guide		
	Operating temperature range [°C]		5 to 40		
	Operating humidity range [%RH]		90 or less (No condensation)		
Other specifications Note 5)	Actuation unit weight [kg]		0.2	0.3	0.55
	Other inertia [kg·cm²]		0.1	0.2	0.25
	Friction coefficient		0.05		
	Mechanical efficiency		0.8		
Reference motor specifications	Motor shape		□40	□60	
	Motor type		AC servo motor (100 V/200 V)		
	Rated output capacity [W]		100	200	400
	Rated torque [N·m]		0.32	0.64	1.3
	Rated rotation [rpm]		3000		

Note 1) Please consult with SMC as all non-standard and non-made-to-order strokes are produced as special orders.
Note 2) Do not allow collisions at either end of the table traveling distance at a speed exceeding "pushing return to origin speed."
Additionally, when running the positioning operation, do not set within 3 mm of both ends.
Note 3) A reference value for correcting an error in reciprocal operation.
Note 4) Maximum acceleration/deceleration changes according to the work load.
Refer to the "Work Load–Acceleration/Deceleration Graph (Guide)" for belt drive on page 806.
Note 5) Each value is a guide. Use such value to select a motor capacity.

Weight

Model	LEFB25																	
Stroke [mm]	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000
Product weight [kg]	2.5	2.75	3	3.25	3.5	3.75	4	4.25	4.5	4.75	5	5.25	5.5	5.75	6	6.25	6.5	6.75

Model	LEFB32																		
Stroke [mm]	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2500
Product weight [kg]	4.00	4.35	4.70	5.05	5.40	5.75	6.10	6.45	6.80	7.15	7.50	7.85	8.20	8.55	8.90	9.25	9.60	9.95	11.70

Model	LEFB40																			
Stroke [mm]	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2500	3000
Product weight [kg]	5.72	6.17	6.62	7.07	7.52	7.97	8.42	8.87	9.32	9.77	10.22	10.67	11.12	11.57	12.02	12.47	12.92	13.32	15.62	17.87

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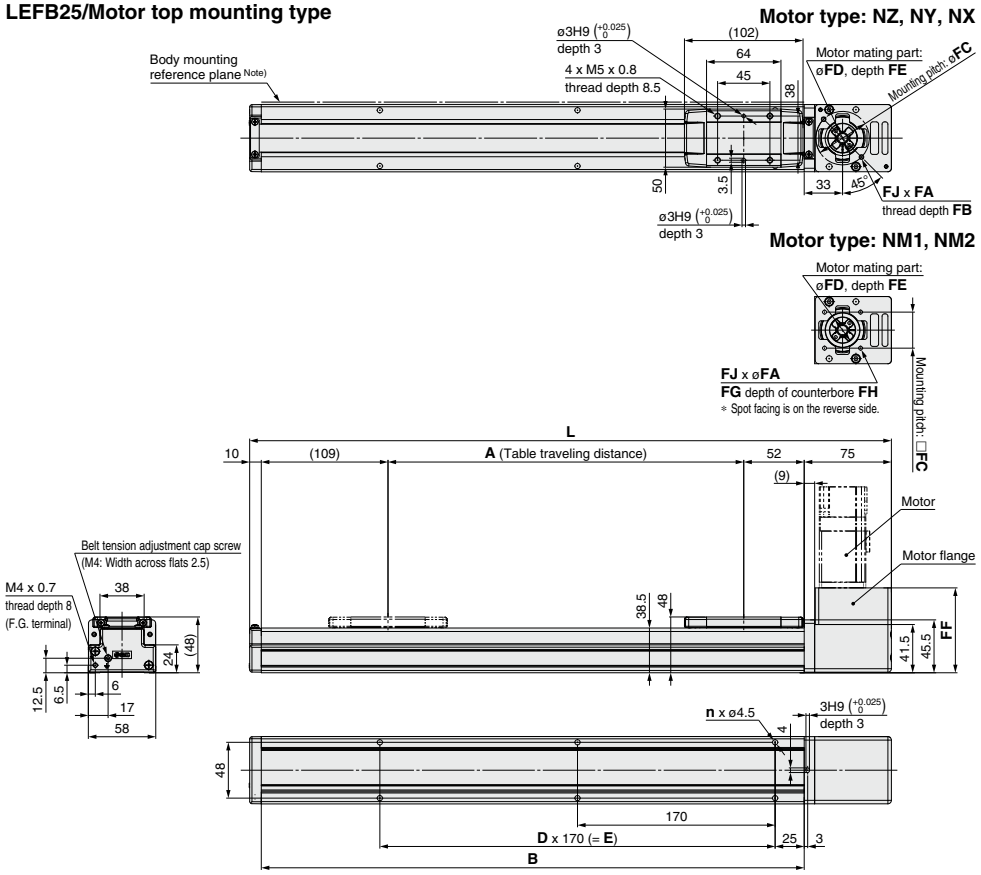
Dimensions: Belt Drive

Refer to the "Motor Mounting" on page 818 for details about motor mounting and included parts.

LEFB25/Motor top mounting type



Note) When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height 5 mm)

Dimensions

[mm]

Stroke	L	A	B	n	D	E
300	552	306	467	6	2	340
400	652	406	567	8	3	510
500	752	506	667	8	3	510
600	852	606	767	10	4	680
700	952	706	867	10	4	680
800	1052	806	967	12	5	850
900	1152	906	1067	14	6	1020
1000	1252	1006	1167	14	6	1020
1100	1352	1106	1267	16	7	1190
1200	1452	1206	1367	16	7	1190
1300	1552	1306	1467	18	8	1360
1400	1652	1406	1567	20	9	1530
1500	1752	1506	1667	20	9	1530
1600	1852	1606	1767	22	10	1700
1700	1952	1706	1867	22	10	1700
1800	2052	1806	1967	24	11	1870
1900	2152	1906	2067	24	11	1870
2000	2252	2006	2167	26	12	2040

Motor Mounting Dimensions

[mm]

Motor type	FA	FB	FC	FD	FE	FF	FG	FH	FJ
NZ	M4 x 0.7	8	46	30	3.5	73	—	—	2
NY	M3 x 0.5	8	45	30	3.5	73	—	—	4
NX	M4 x 0.7	8	46	30	3.5	73	—	—	2
NM1/NM2	3.4	—	31	22∗	2.5∗	73	6	21	4

∗ Dimensions after mounting a ring spacer (Refer to page 818.)

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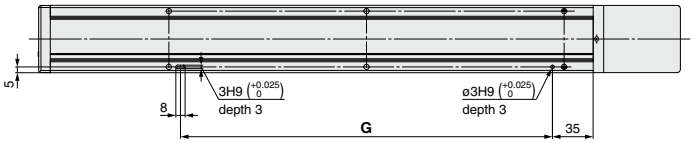
Refer to the "Motor Mounting" on page 818 for details about motor mounting and included parts.

Dimensions: Belt Drive

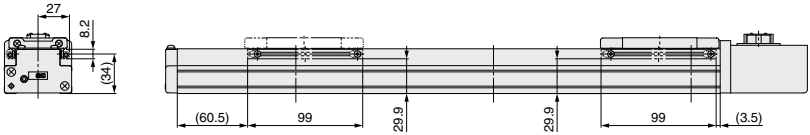
LEFB25/Motor top mounting type

Positioning pin hole Note) **(Option): Body bottom**



Note) When using the body bottom positioning pin holes, do not simultaneously use the housing B bottom pin hole.

With auto switch (Option)



Dimensions [mm]

Stroke	G
300	320
400	490
500	490
600	660
700	660
800	830
900	1000
1000	1000
1100	1170
1200	1170
1300	1340
1400	1510
1500	1510
1600	1680
1700	1680
1800	1850
1900	1850
2000	2020

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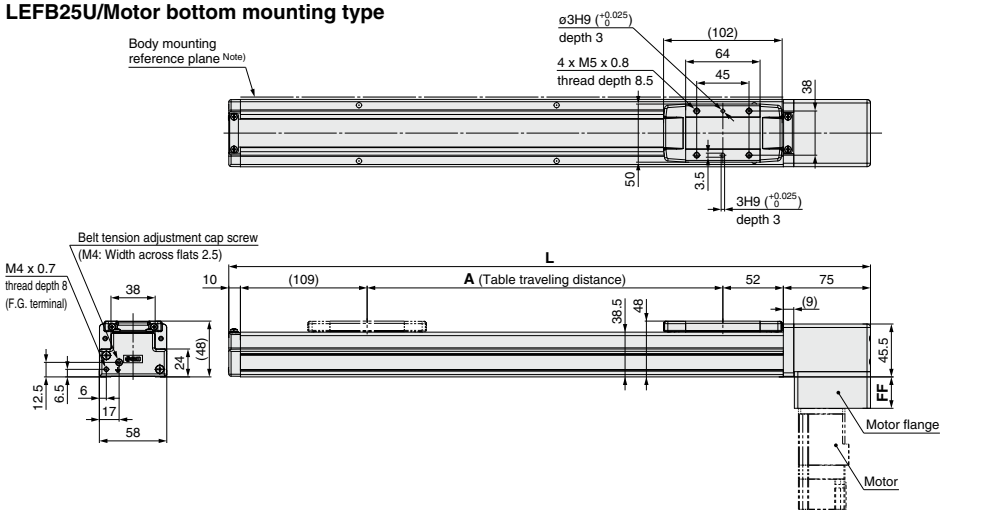
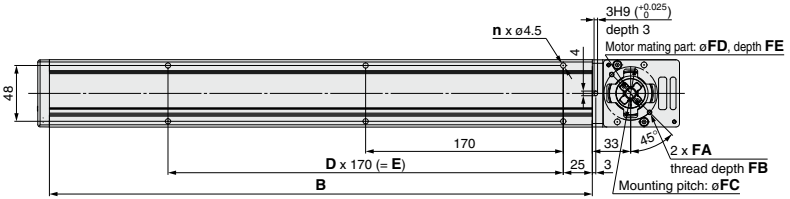
Dimensions: Belt Drive

Refer to the "Motor Mounting" on page 818 for details about motor mounting and included parts.

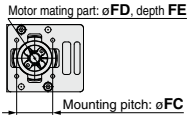
LEFB25U/Motor bottom mounting type



Motor type: NZ, NY, NX



Motor type: NM1, NM2



Dimensions [mm]

Stroke	L	A	B	n	D	E
300	552	306	467	6	2	340
400	652	406	567	8	3	510
500	752	506	667	8	3	510
600	852	606	767	10	4	680
700	952	706	867	10	4	680
800	1052	806	967	12	5	850
900	1152	906	1067	14	6	1020
1000	1252	1006	1167	14	6	1020
1100	1352	1106	1267	16	7	1190
1200	1452	1206	1367	16	7	1190
1300	1552	1306	1467	18	8	1360
1400	1652	1406	1567	20	9	1530
1500	1752	1506	1667	20	9	1530
1600	1852	1606	1767	22	10	1700
1700	1952	1706	1867	22	10	1700
1800	2052	1806	1967	24	11	1870
1900	2152	1906	2067	24	11	1870
2000	2252	2006	2167	26	12	2040

Note) When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height 5 mm)

Motor Mounting Dimensions [mm]

Motor type	FA	FB	FC	FD	FE	FF	FG	FH	FJ
NZ	M4 x 0.7	8	46	30	3.5	27	—	—	2
NY	M3 x 0.5	8	45	30	3.5	27	—	—	4
NX	M4 x 0.7	8	46	30	3.5	27	—	—	2
NM1/NM2	3.4	—	31	22*	2.5*	27	6	21	4

* Dimensions after mounting a ring spacer (Refer to page 818.)

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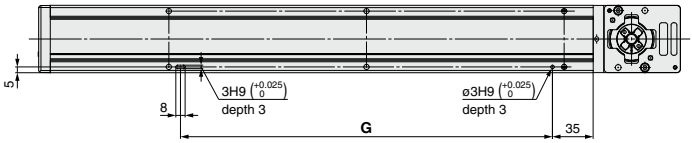
Refer to the "Motor Mounting" on page 818 for details about motor mounting and included parts.

Dimensions: Belt Drive

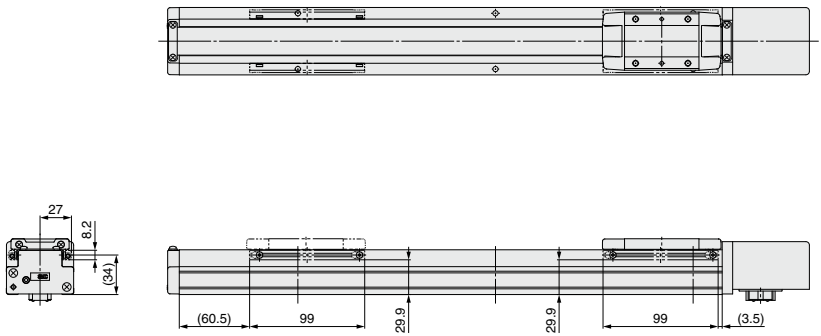
LEFB25U/Motor bottom mounting type

Positioning pin hole Note) **(Option): Body bottom**



Note) When using the body bottom positioning pin holes, do not simultaneously use the housing B bottom pin hole.

With auto switch (Option)



Dimensions [mm]

Stroke	G
300	320
400	490
500	490
600	660
700	660
800	830
900	1000
1000	1000
1100	1170
1200	1170
1300	1340
1400	1510
1500	1510
1600	1680
1700	1680
1800	1850
1900	1850
2000	2020

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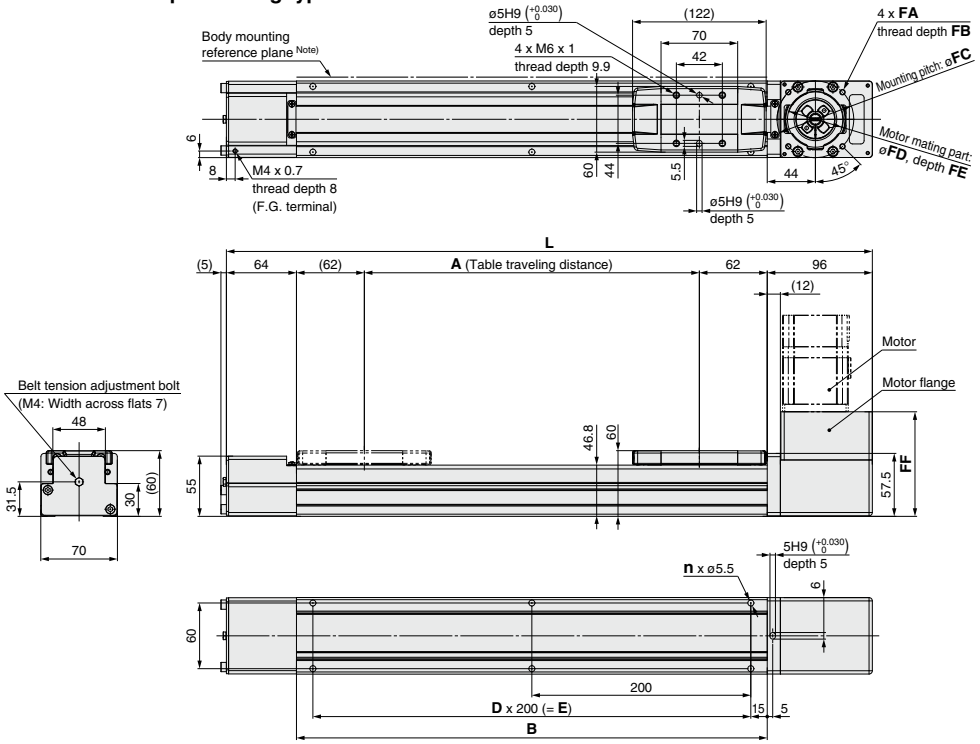
Refer to the "Motor Mounting" on page 818 for details about motor mounting and included parts.

Dimensions: Belt Drive

LEFB32/Motor top mounting type



Note) When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height 5 mm)

Dimensions

[mm]

Stroke	L	A	B	n	D	E
300	590	306	430	6	2	400
400	690	406	530	6	2	400
500	790	506	630	8	3	600
600	890	606	730	8	3	600
700	990	706	830	10	4	800
800	1090	806	930	10	4	800
900	1190	906	1030	12	5	1000
1000	1290	1006	1130	12	5	1000
1100	1390	1106	1230	14	6	1200
1200	1490	1206	1330	14	6	1200
1300	1590	1306	1430	16	7	1400
1400	1690	1406	1530	16	7	1400
1500	1790	1506	1630	18	8	1600
1600	1890	1606	1730	18	8	1600
1700	1990	1706	1830	20	9	1800
1800	2090	1806	1930	20	9	1800
1900	2190	1906	2030	22	10	2000
2000	2290	2006	2130	22	10	2000
2500	2790	2506	2630	28	13	2600

Motor Mounting Dimensions

[mm]

Motor type	FA	FB	FC	FD	FE	FF
NZ	M5 x 0.8	9	70	50	4	95.5
NY	M4 x 0.7	8	70	50	4	95.5
NX	M5 x 0.8	9	63	40*	4.5*	99.2
NW	M5 x 0.8	9	70	50	5	96.5
NV	M4 x 0.7	8	63	40*	4.5*	99.2
NU	M5 x 0.8	9	70	50	5	96.5
NT	M5 x 0.8	9	70	50	4	95.5
NM1	M4 x 0.7	8	□47.14	38.1*	4.5*	82.5
NM2	M4 x 0.7	8	□50	36*	4.5*	90.0

* Dimensions after mounting a ring spacer (Refer to page 818.)

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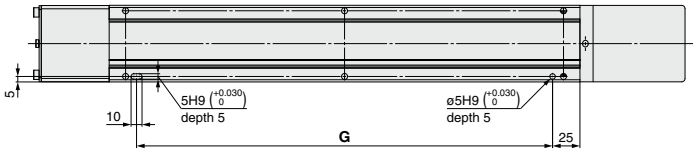
Refer to the "Motor Mounting" on page 818 for details about motor mounting and included parts.

Dimensions: Belt Drive

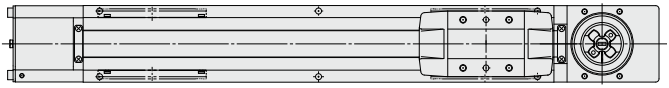
LEFB32/Motor top mounting type

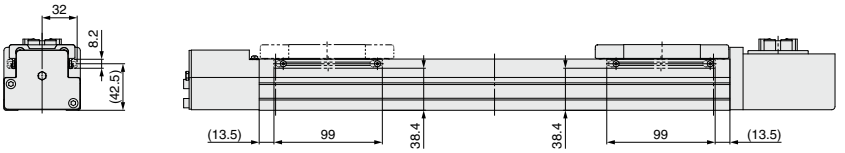
Positioning pin hole Note) **(Option): Body bottom**



Note) When using the body bottom positioning pin holes, do not simultaneously use the housing B bottom pin hole.

With auto switch (Option)





Dimensions [mm]

Stroke	G
300	380
400	380
500	580
600	580
700	780
800	780
900	980
1000	980
1100	1180
1200	1180
1300	1380
1400	1380
1500	1580
1600	1580
1700	1780
1800	1780
1900	1980
2000	1980
2500	2580

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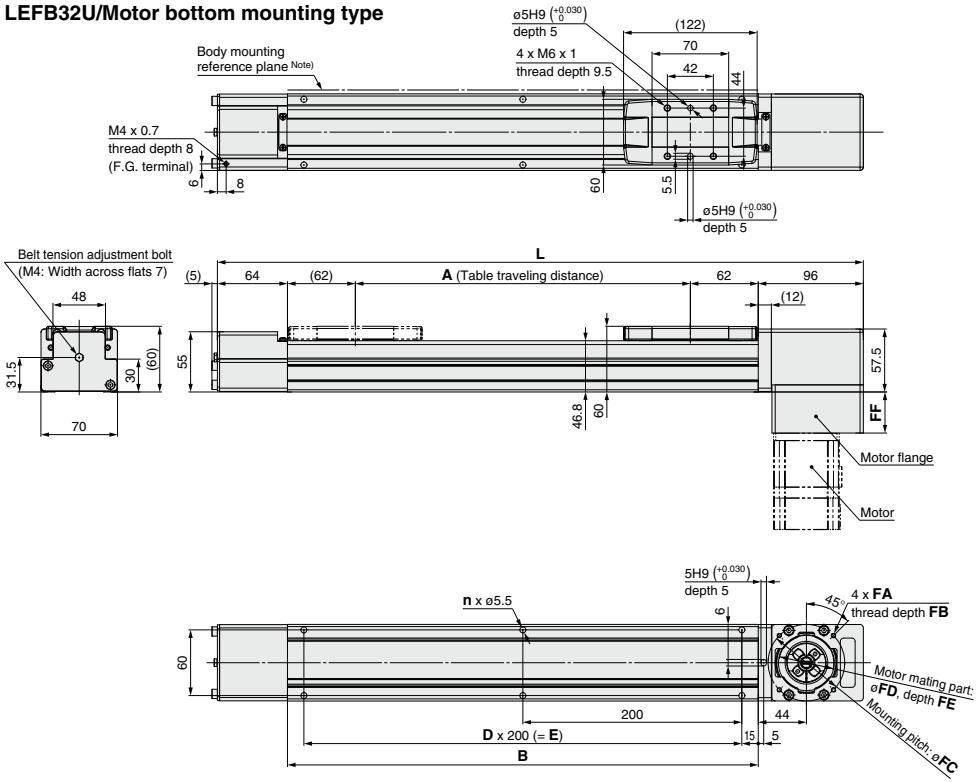
Refer to the "Motor Mounting" on page 818 for details about motor mounting and included parts.

Dimensions: Belt Drive

LEFB32U/Motor bottom mounting type



Note) When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height 5 mm)

Dimensions

[mm]

Stroke	L	A	B	n	D	E
300	590	306	430	6	2	400
400	690	406	530	6	2	400
500	790	506	630	8	3	600
600	890	606	730	8	3	600
700	990	706	830	10	4	800
800	1090	806	930	10	4	800
900	1190	906	1030	12	5	1000
1000	1290	1006	1130	12	5	1000
1100	1390	1106	1230	14	6	1200
1200	1490	1206	1330	14	6	1200
1300	1590	1306	1430	16	7	1400
1400	1690	1406	1530	16	7	1400
1500	1790	1506	1630	18	8	1600
1600	1890	1606	1730	18	8	1600
1700	1990	1706	1830	20	9	1800
1800	2090	1806	1930	20	9	1800
1900	2190	1906	2030	22	10	2000
2000	2290	2006	2130	22	10	2000
2500	2790	2506	2630	28	13	2600

Motor Mounting Dimensions

[mm]

Motor type	FA	FB	FC	FD	FE	FF
NZ	M5 x 0.8	9	70	50	4	37.5
NY	M4 x 0.7	8	70	50	4	37.5
NX	M5 x 0.8	9	63	40*	4.5*	41.2
NW	M5 x 0.8	9	70	50	5	38.5
NV	M4 x 0.7	8	63	40*	4.5*	41.2
NU	M5 x 0.8	9	70	50	5	38.5
NT	M5 x 0.8	9	70	50	4	37.5
NM1	M4 x 0.7	8	□47.14	38.1*	4.5*	24.5
NM2	M4 x 0.7	8	□50	36*	4.5*	32

* Dimensions after mounting a ring spacer (Refer to page 818.)

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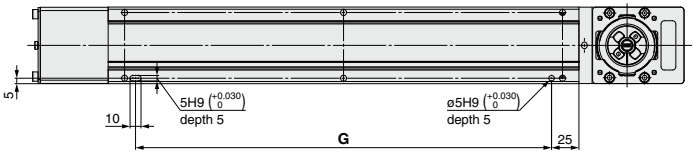
Refer to the "Motor Mounting" on page 818 for details about motor mounting and included parts.

Dimensions: Belt Drive

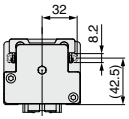
LEFB32U/Motor bottom mounting type

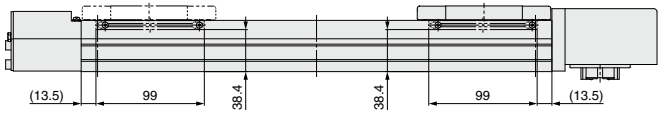
Positioning pin hole Note) **(Option): Body bottom**



Note) When using the body bottom positioning pin holes, do not simultaneously use the housing B bottom pin hole.

With auto switch (Option)





Dimensions [mm]

Stroke	G
300	380
400	380
500	580
600	580
700	780
800	780
900	980
1000	980
1100	1180
1200	1180
1300	1380
1400	1380
1500	1580
1600	1580
1700	1780
1800	1780
1900	1980
2000	1980
2500	2580

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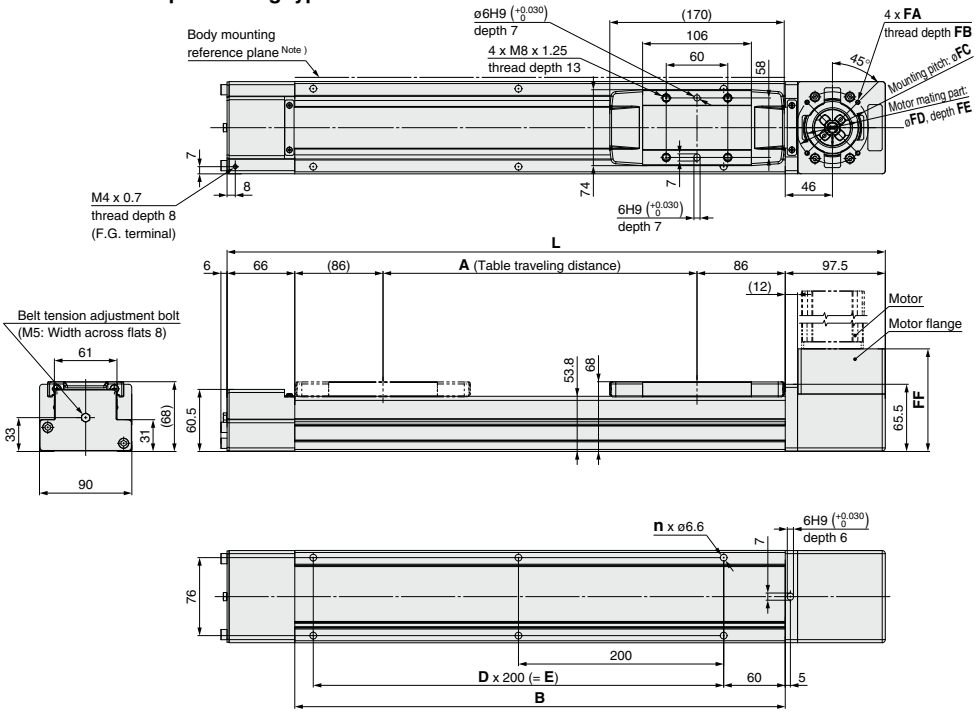
Refer to the "Motor Mounting" on page 818 for details about motor mounting and included parts.

Dimensions: Belt Drive

LEFB40/Motor top mounting type



Note) When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height 5 mm)

Dimensions

[mm]

Stroke	L	A	B	n	D	E
300	641.5	306	478	6	2	400
400	741.5	406	578	6	2	400
500	841.5	506	678	8	3	600
600	941.5	606	778	8	3	600
700	1041.5	706	878	10	4	800
800	1141.5	806	978	10	4	800
900	1241.5	906	1078	12	5	1000
1000	1341.5	1006	1178	12	5	1000
1100	1441.5	1106	1278	14	6	1200
1200	1541.5	1206	1378	14	6	1200
1300	1641.5	1306	1478	16	7	1400
1400	1741.5	1406	1578	16	7	1400
1500	1841.5	1506	1678	18	8	1600
1600	1941.5	1606	1778	18	8	1600
1700	2041.5	1706	1878	20	9	1800
1800	2141.5	1806	1978	20	9	1800
1900	2241.5	1906	2078	22	10	2000
2000	2341.5	2006	2178	22	10	2000
2500	2841.5	2506	2678	28	13	2600
3000	3341.5	3006	3178	32	15	3000

Motor Mounting Dimensions

[mm]

Motor type	FA	FB	FC	FD	FE	FF
NZ	M5 x 0.8	9	70	50	4	100
NY	M4 x 0.7	8	70	50	4	100
NX	M5 x 0.8	9	63	40*	4.5*	103.2
NW	M5 x 0.8	9	70	50	5	101
NV	M4 x 0.7	8	63	40	4.5*	103.2
NU	M5 x 0.8	9	70	50	5	101
NT	M5 x 0.8	9	70	50	4	100
NM1	M4 x 0.7	8	□47.14	38.1*	4.5*	87
NM2	M4 x 0.7	8	□50	36*	4.5*	94

* Dimensions after mounting a ring spacer (Refer to page 818.)

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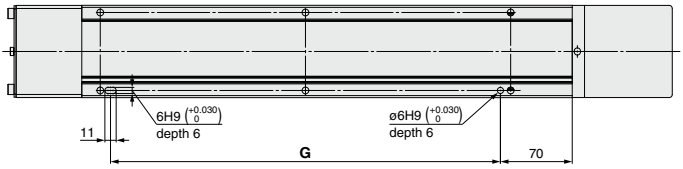
Refer to the "Motor Mounting" on page 818 for details about motor mounting and included parts.

Dimensions: Belt Drive

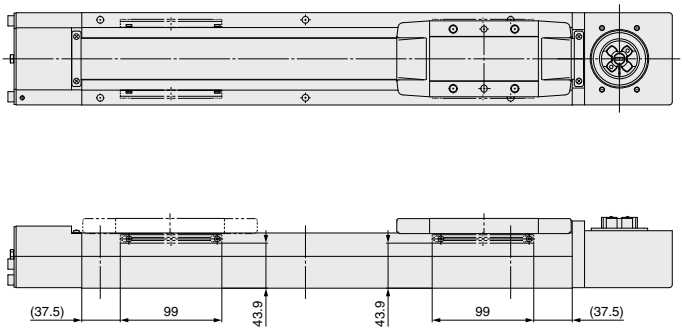
LEFB40/Motor top mounting type

Positioning pin hole Note) **(Option): Body bottom**



Note) When using the body bottom positioning pin holes, do not simultaneously use the housing B bottom pin hole.

With auto switch (Option)



Dimensions [mm]

Stroke	G
300	380
400	380
500	580
600	580
700	780
800	780
900	980
1000	980
1100	1180
1200	1180
1300	1380
1400	1380
1500	1580
1600	1580
1700	1780
1800	1780
1900	1980
2000	1980
2500	2580
3000	2980

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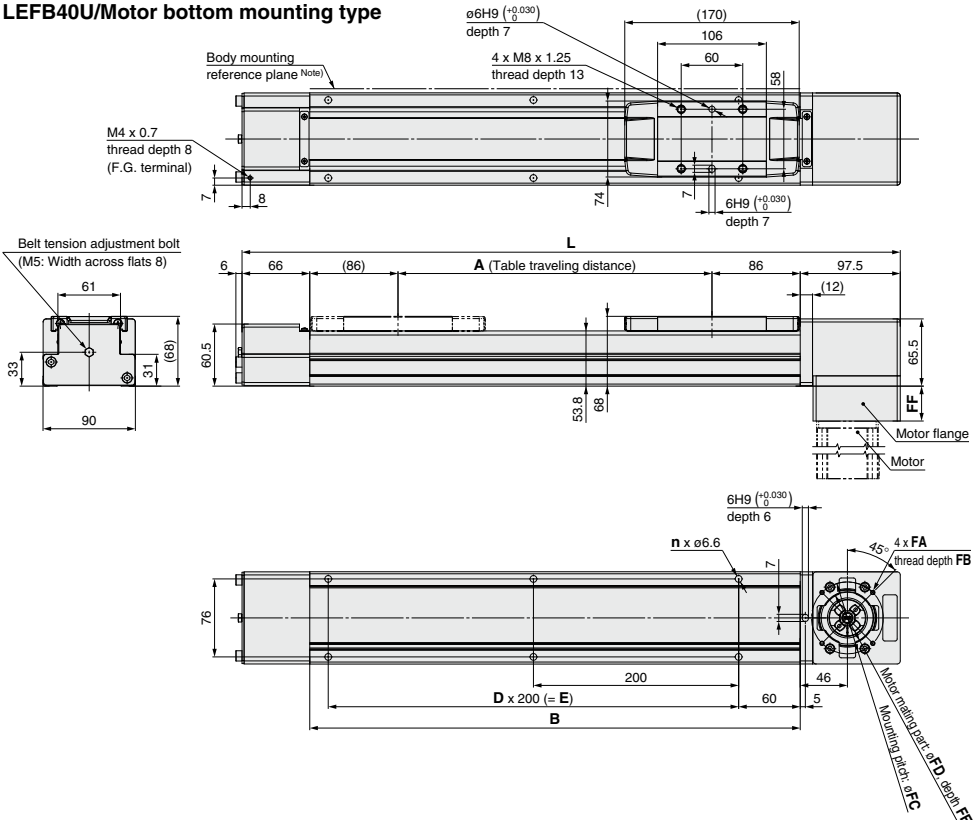
Refer to the "Motor Mounting" on page 818 for details about motor mounting and included parts.

Dimensions: Belt Drive

LEFB40U/Motor bottom mounting type



Dimensions [mm]

Stroke	L	A	B	n	D	E
300	641.5	306	478	6	2	400
400	741.5	406	578	6	2	400
500	841.5	506	678	8	3	600
600	941.5	606	778	8	3	600
700	1041.5	706	878	10	4	800
800	1141.5	806	978	10	4	800
900	1241.5	906	1078	12	5	1000
1000	1341.5	1006	1178	12	5	1000
1100	1441.5	1106	1278	14	6	1200
1200	1541.5	1206	1378	14	6	1200
1300	1641.5	1306	1478	16	7	1400
1400	1741.5	1406	1578	16	7	1400
1500	1841.5	1506	1678	18	8	1600
1600	1941.5	1606	1778	18	8	1600
1700	2041.5	1706	1878	20	9	1800
1800	2141.5	1806	1978	20	9	1800
1900	2241.5	1906	2078	22	10	2000
2000	2341.5	2006	2178	22	10	2000
2500	2841.5	2506	2678	28	13	2600
3000	3341.5	3006	3178	32	15	3000

Note) When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height 5 mm)

Motor Mounting Dimensions [mm]

Motor type	FA	FB	FC	FD	FE	FF
NZ	M5 x 0.8	9	70	50	4	34
NY	M4 x 0.7	8	70	50	4	34
NX	M5 x 0.8	9	63	40*	4.5*	37.2
NW	M5 x 0.8	9	70	50	5	35
NV	M4 x 0.7	8	63	40*	4.5*	37.2
NU	M5 x 0.8	9	70	50	5	35
NT	M5 x 0.8	9	70	50	4	34
NM1	M4 x 0.7	8	□47.14	38.1*	4.5*	21
NM2	M4 x 0.7	8	□50	36*	4.5*	28

* Dimensions after mounting a ring spacer (Refer to page 818.)

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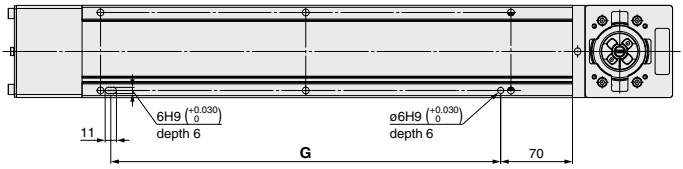
Refer to the "Motor Mounting" on page 818 for details about motor mounting and included parts.

Dimensions: Belt Drive

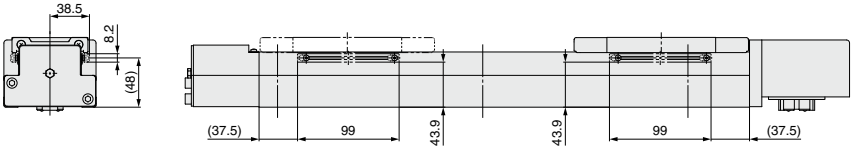
LEFB40U/Motor bottom mounting type

Positioning pin hole Note) **(Option): Body bottom**



Note) When using the body bottom positioning pin holes, do not simultaneously use the housing B bottom pin hole.

With auto switch (Option)



Dimensions [mm]

Stroke	G
300	380
400	380
500	580
600	580
700	780
800	780
900	980
1000	980
1100	1180
1200	1180
1300	1380
1400	1380
1500	1580
1600	1580
1700	1780
1800	1780
1900	1980
2000	1980
2500	2580
3000	2980

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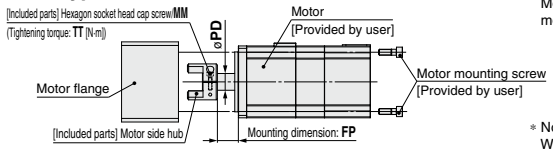
Motor Mounting

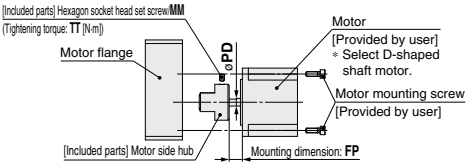
- When mounting a hub, remove the oil content, dust, or dirt sticking to the shaft and hub inside diameter.
- This product does not include the motor and motor mounting screws. (Provided by user)
  For the shaft-end shape of the motor, prepare the round type.
- Take loose prevention measures for the motor mounting screws.

Motor type: NZ, NY, NX, NW, NV, NU, NT, NM2

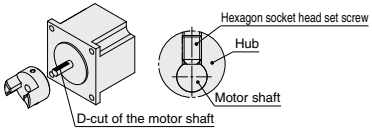


∗ Note for mounting a motor to the NM2 motor type
Motor mounting screws for the LEFS25 are fixed starting from the motor flange side. (Opposite of the drawing)

Motor type: NM1



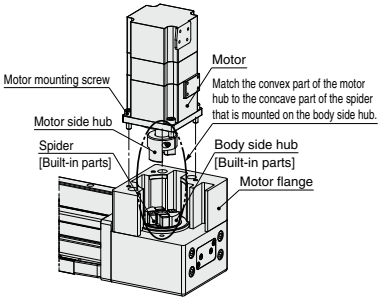
∗ Note for mounting a hub to the NM1 motor type
When mounting the hub to the motor, make sure to position the set screw vertical to the D-cut surface of the motor shaft. (Refer to the figure shown below)
∗ Motor mounting screws for the LEFB25 are fixed starting from the motor flange side. (Opposite of the drawing)



Motor Mounting Diagram

Motor type: NZ, NY, NW, NU, NT

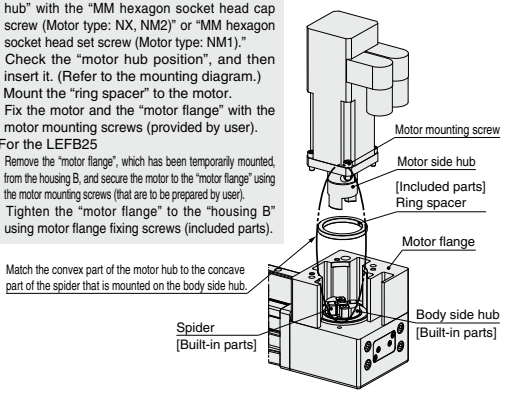
Mounting procedure
1) Fix the motor (provided by user) and the motor hub with the "MM hexagon socket head cap screw."
2) Check the "motor hub position", and then insert it. (Refer to the mounting diagram.)
3) Fix the motor and the "motor flange" with the motor mounting screws (provided by user).



Motor type: NX, NV, NM1, NM2

Mounting procedure
1) Fix the motor (provided by user) and the "motor hub" with the "MM hexagon socket head cap screw (Motor type: NX, NM2)" or "MM hexagon socket head set screw (Motor type: NM1)."
2) Check the "motor hub position", and then insert it. (Refer to the mounting diagram.)
3) Mount the "ring spacer" to the motor.
4) Fix the motor and the "motor flange" with the motor mounting screws (provided by user).

∗ For the LEFB25
4) Remove the "motor flange", which has been temporarily mounted, from the housing B, and secure the motor to the "motor flange" using the motor mounting screws (that are to be prepared by user).
5) Tighten the "motor flange" to the "housing B" using motor flange fixing screws (included parts).



Size: 25 Hub Mounting Dimensions [mm]

Motor type	MM	TT	PD	FP
NZ	M2.5 x 10	1.00	8	11
NY	M2.5 x 10	1.00	8	11
NX	M2.5 x 10	1.00	8	5.5
NM1	M3 x 4	0.63	5	11
NM2	M2.5 x 10	1.00	6	11

Size: 32 Hub Mounting Dimensions [mm]

Motor type	MM	TT	PD	FP
NZ	M3 x 12	1.5	14	17.5
NY	M4 x 12	2.5	11	17.5
NX	M4 x 12	2.5	9	5.2
NW	M4 x 12	2.5	9	12.5
NV	M4 x 12	2.5	9	5.2
NU	M4 x 12	2.5	11	12.5
NT	M3 x 12	1.5	12	17.5
NM1	M4 x 5	1.5	6.35	4.5
NM2	M4 x 12	2.5	10	12

Size: 40 Hub Mounting Dimensions [mm]

Motor type	MM	TT	PD	FP
NZ	M3 x 12	1.5	14	17.5
NY	M3 x 12	1.5	14	17.5
NX	M4 x 12	2.5	9	5.2
NW	M4 x 12	2.5	9	13
NV	M4 x 12	2.5	9	5.2
NU	M4 x 12	2.5	11	13
NT	M3 x 12	1.5	12	17.5
NM1	M4 x 5	1.5	6.35	5
NM2	M4 x 12	2.5	10	12

Included Parts List

Size: 25

Description	Quantity				
	Motor type				
	NZ	NY	NX	NM1	NM2
Motor side hub	1	1	1	1	1
Hexagon socket head cap screw/set screw (for hub fixing)∗	1	1	1	1	1
Hexagon socket head cap screw (for motor flange fixing)∗	—	—	—	2	2
Ring spacer	—	—	—	1	1

∗ For screw sizes, refer to the hub mounting dimensions.

Size: 32, 40

Description	Quantity								
	Motor type								
	NZ	NY	NX	NW	NV	NU	NT	NM1	NM2
Motor side hub	1	1	1	1	1	1	1	1	1
Hexagon socket head cap screw/set screw (for hub fixing)∗	1	1	1	1	1	1	1	1	1
Ring spacer	—	—	1	—	1	—	—	1	1

∗ For screw sizes, refer to the hub mounting dimensions.

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LEFB Series
Motor Mounting Parts

Motor Flange Option

After purchasing the product, the motor can be changed to the motor types shown below by replacing with this option. (Except NM1)
Use the following part numbers to select a compatible motor flange option and place an order.

How to Order

LEF B – MF 25 – NZ

B: Belt drive

❶ Size

25	For LEF□25
32	For LEF□32
40	For LEF□40

❷ Motor type

Symbol	Type	Symbol	Type
NZ	Mounting type Z	**NV**	Mounting type V
NY	Mounting type Y	**NU**	Mounting type U
NX	Mounting type X	**NT**	Mounting type T
NW	Mounting type W	**NM2**	Mounting type M2

∗ Select only NZ, NY, NX or NM2 for the LEFB-MF25.

Compatible Motors

Applicable motor model			Size/Motor type											
			25				32/40							
Manufacturer	Series	Type	NZ Mounting type Z	NY Mounting type Y	NX Mounting type X	NM2 Mounting type M2	NZ Mounting type Z	NY Mounting type Y	NX Mounting type X	NW Mounting type W	NV Mounting type V	NU Mounting type U	NT Mounting type T	NM2 Mounting type M2
Mitsubishi Electric Corporation	MELSERVO-JN	HF-KN	●	—	—	—	●	—	—	—	—	—	—	—
	MELSERVO-J3	HF-KP	●	—	—	—	●	—	—	—	—	—	—	—
	MELSERVO-J4	HG-KR	●	—	—	—	●	—	—	—	—	—	—	—
YASKAWA Electric Corporation	Σ-V	SGMJV	●	—	—	—	●	—	—	—	—	—	—	—
SANYO DENKI CO., LTD.	SANMOTION R	R2	●	—	—	—	●	—	—	—	—	—	—	—
OMRON Corporation	Sysmac G5	R88M-K	●	—	—	—	—	●	—	—	—	—	—	—
Panasonic Corporation	MINAS-A4	MSMD	—	●	—	—	—	●	—	—	—	—	—	—
	MINAS-A5	MSMD/MHMD	—	●	—	—	—	●	—	—	—	—	—	—
FANUC CORPORATION	βis	β	●	—	—	—	● (β1 only)	—	—	●	—	—	—	—
NIDEC SANKYO CORPORATION	S-FLAG	MA/MH/MM	●	—	—	—	●	—	—	—	—	—	—	—
KEYENCE CORPORATION	SV	SV-M/SV-B	●	—	—	—	●	—	—	—	—	—	—	—
FUJI ELECTRIC CO., LTD.	ALPHA5	GYS/GYB	●	—	—	—	●	—	—	—	—	—	—	—
	FALDIC-α	GYS	●	—	—	—	●	—	—	—	—	—	—	—
ORIENTAL MOTOR Co., Ltd.	AR/AZ	AR/AZ (46 only)	—	—	—	●	—	—	—	—	—	—	—	—
	AR/AZ	AR/AZ	—	—	—	—	—	—	—	—	—	—	—	●
Rockwell Automation, Inc. (Allen-Bradley)	MP-/VP-	MP/VP	—	—	—	—	—	—	●	—	—	—	—	—
	TL	TLY-A	●	—	—	—	—	—	—	—	—	—	●	—
Beckhoff Automation GmbH	AM	AM30	●	—	—	—	—	—	—	—	●	—	—	—
	AM	AM31	●	—	—	—	—	—	—	—	—	●	—	—
	AM	AM80/AM81	●	—	—	—	—	—	●	—	—	—	—	—
Siemens AG	1FK7	1FK7	—	—	●	—	—	—	●	—	—	—	—	—
Delta Electronics, Inc.	ASDA-A2	ECMA	●	—	—	—	●	—	—	—	—	—	—	—

Note) When the LEF□25NM1□-□ is purchased, it is not possible to change to other motor types.

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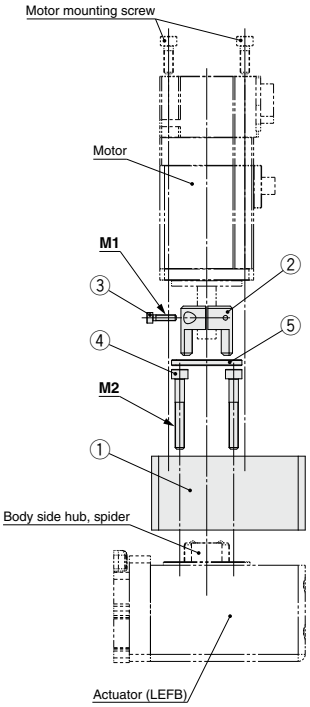
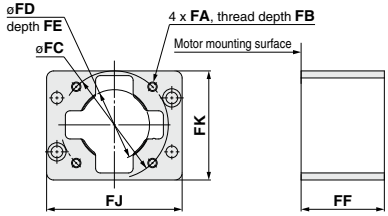
Dimensions: Motor Flange Option



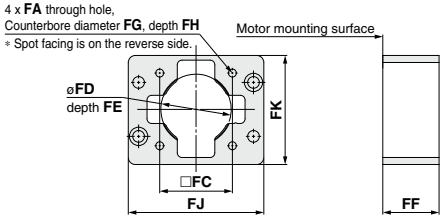
Component Parts

No.	Description	Quantity
1	**Motor flange**	1
2	**Hub (Motor side)**	1
3	**Hexagon socket head cap screw (for hub fixing)**	1
4	**Hexagon socket head cap screw (for motor flange mounting)**	2
5	**Ring spacer (Only for NX, NV and NM2 of size 32, 40)**	1

Motor flange details



For NM2



Dimensions

[mm]

Size	Motor type	FA	FB	FC	FD	FE	FF	FG	FH	FJ	FK	M1	M2	PD
25	**NZ/NX**	M4 x 0.7	8	46	30	3.5	31.5	—	—	57.8	65.5	M2.5 x 10	M4 x 30	8
	NY	M3 x 0.5	8	45	30	3.5	31.5	—	—	57.8	65.5	M2.5 x 10	M4 x 30	8
	NM2	ø3.4	—	31	22*	2.5*	31.5	6	21	57.8	65.5	M2.5 x 10	M4 x 30	6
32	**NZ**	M5 x 0.8	9	70	50	4	44	—	—	69.8	83.5	M3 x 12	M5 x 45	14
	NY	M4 x 0.7	8	70	50	4	44	—	—	69.8	83.5	M4 x 12	M5 x 45	11
	NX	M5 x 0.8	9	63	50	5	47.7	—	—	69.8	83.5	M4 x 12	M5 x 45	9
	NW	M5 x 0.8	9	70	50	5	45	—	—	69.8	83.5	M4 x 12	M5 x 45	9
	NV	M4 x 0.7	8	63	50	5	47.7	—	—	69.8	83.5	M4 x 12	M5 x 45	9
	NU	M5 x 0.8	9	70	50	5	45	—	—	69.8	83.5	M4 x 12	M5 x 45	11
	NT	M5 x 0.8	9	70	50	4	44	—	—	69.8	83.5	M3 x 12	M5 x 45	12
	NM2	M4 x 0.7	8	50	36*	4.5*	38.5	—	—	69.8	83.5	M4 x 12	M5 x 25	10
40	**NZ**	M5 x 0.8	9	70	50	4	44	—	—	89.8	85	M3 x 12	M5 x 45	14
	NY	M4 x 0.7	8	70	50	4	44	—	—	89.8	85	M3 x 12	M5 x 45	14
	NX	M5 x 0.8	9	63	50	5	47.2	—	—	89.8	85	M4 x 12	M5 x 45	9
	NW	M5 x 0.8	9	70	50	5	45	—	—	89.8	85	M4 x 12	M5 x 45	9
	NV	M4 x 0.7	8	63	50	5	47.2	—	—	89.8	85	M4 x 12	M5 x 45	9
	NU	M5 x 0.8	9	70	50	5	45	—	—	89.8	85	M4 x 12	M5 x 45	11
	NT	M5 x 0.8	9	70	50	4	44	—	—	89.8	85	M3 x 12	M5 x 45	12
	NM2	M4 x 0.7	8	50	36*	4.5*	38	—	—	89.8	85	M4 x 12	M5 x 25	10

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LEF Series
Electric Actuator
Specific Product Precautions 1

Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions and pages 3 to 8 for Electric Actuator Precautions.

Design

⚠Caution

1. Do not apply a load in excess of the specification limits.

Select a suitable actuator by work load and allowable moment. If the product is used outside of the specification limits, the eccentric load applied to the guide will be excessive and have adverse effects such as creating play on the guide, degrading accuracy and shortening the life of the product.

2. Do not use the product in applications where excessive external force or impact force is applied to it.

This can cause a failure.

Selection

⚠Warning

1. Do not increase the speed in excess of the specification limits.

Select a suitable actuator by the relationship of the allowable work load and speed, and the allowable speed of each stroke. If the product is used outside of the specification limits, it will have adverse effects such as creating noise, degrading accuracy and shortening the life of the product.

2. Do not use the product in applications where excessive external force or impact force is applied to it.

This can cause a failure.

3. When the product repeatedly cycles with partial strokes (see the table below), operate it at a full stroke at least once every dozens of cycles.

Otherwise, lubrication can run out.

Model	Partial stroke
LEF□25	65 mm or less
LEF□32	70 mm or less
LEF□40	105 mm or less

4. When external force is applied to the table, it is necessary to add external force to the work load as the total carried load for the sizing.

When a cable duct or flexible moving tube is attached to the actuator, the sliding resistance of the table increases and may lead to operational failure of the product.

5. Depending on the shape of the motor to be mounted, some of the product's interior parts (hub, spider, etc.) may be visible from the motor mounting surface. If this is undesirable, please contact your nearest sales office for details on options such as covers.

Handling

⚠Caution

1. Do not allow the table to hit the end of stroke.

When the driver parameters, origin or programs are set incorrectly, the table may collide against the stroke end of the actuator during operation. Check these points before use.
If the table collides against the stroke end of the actuator, the guide, ball screw, belt or internal stopper can be broken. This may lead to abnormal operation.

Handle the actuator with care when it is used in the vertical direction as the workpiece will fall freely from its own weight.

2. The actual speed of this actuator is affected by the work load and stroke.

Check the specifications with reference to the model selection section of the catalog.

3. Do not apply a load, impact or resistance in addition to the transferred load during return to origin.

4. Do not dent, scratch or cause other damage to the body and table mounting surfaces.

This may cause unevenness in the mounting surface, play in the guide or an increase in the sliding resistance.

5. Do not apply strong impact or an excessive moment while mounting a workpiece.

If an external force over the allowable moment is applied, it may cause play in the guide or an increase in the sliding resistance.

6. Keep the flatness of mounting surface should be within 0.1 mm/500 mm.

Unevenness of a workpiece or base mounted on the body of the product may cause play in the guide and an increase in the sliding resistance.

7. Do not hit the table with the workpiece in the positioning operation and positioning range.

8. Grease is applied to the dust seal band for sliding. When wiping off the grease to remove foreign matter etc., be sure to apply it again.

9. For bottom mounting, the dust seal band may be deflected.

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LEF Series
Electric Actuator
Specific Product Precautions 2

Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions and pages 3 to 8 for Electric Actuator Precautions.

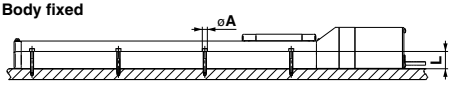
Handling

⚠Caution

10. When mounting the product, use screws with adequate length and tighten them with adequate torque.

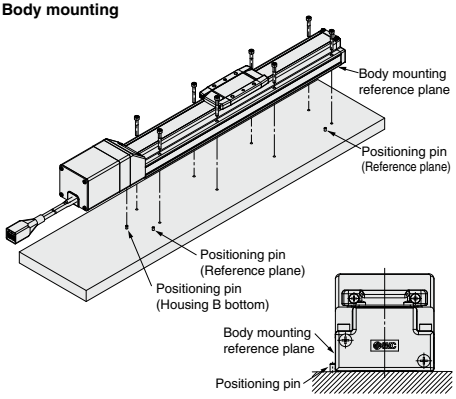
Tightening the screws with a higher torque than recommended may cause a malfunction, whilst the tightening with a lower torque can cause the displacement of the mounting position or in extreme conditions the actuator could become detached from its mounting position.

Body fixed



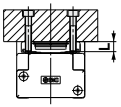
Model	Screw size	Max. tightening torque [N·m]	ø**A** [mm]	**L** [mm]
LEF□25	M4	1.5	4.5	24
LEF□32	M5	3.0	5.5	30
LEF□40	M6	5.2	6.6	31

Body mounting



The traveling parallelism is the reference plane for the body mounting reference plane. If the traveling parallelism for a table is required, set the reference plane against parallel pins etc.

Workpiece fixed



Model	Screw size	Max. tightening torque [N·m]	**L** (Max. screw-in depth) [mm]
LEF□25	M5 x 0.8	3.0	8
LEF□32	M6 x 1	5.2	9
LEF□40	M8 x 1.25	12.5	13

To prevent the workpiece retaining screws from touching the body, use screws that are 0.5 mm or shorter than the maximum screw-in depth. If long screws are used, they can touch the body and cause a malfunction.

11. Do not operate by fixing the table and moving the actuator body.

12. The belt drive actuator cannot be used vertically for applications.

13. Check the specifications for the minimum speed of each actuator.

Otherwise, unexpected malfunctions, such as knocking, may occur.

14. In the case of the belt drive actuator, vibration may occur during operation at speeds within the actuator specifications, this could be caused by the operating conditions. Change the speed setting to a speed that does not cause vibration.

Maintenance

⚠Warning

Maintenance frequency

Perform maintenance according to the table below.

Frequency	Appearance check	Internal check
Inspection before daily operation	○	—
Inspection every 6 months/1000 km/ 5 million cycles*	○	○

* Select whichever comes first.

- **Items for visual appearance check**
  1. Loose set screws, Abnormal dirt
  2. Check of flaw and cable joint
  3. Vibration, Noise
- **Items for internal check**
  1. Lubricant condition on moving parts.
  2. Loose or mechanical play in fixed parts or fixing screws.

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High Rigidity Slider Type

Ball Screw Drive *LEJS Series*

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Motorless Type

Electric Actuator/High Rigidity Slider Type

Ball Screw Drive/*LEJS Series*

Model Selection

LEJS Series ▶Page 834

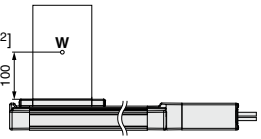
Selection Procedure

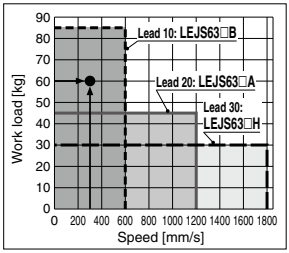
Step 1 Check the speed–work load. → **Step 2** Check the cycle time. → **Step 3** Check the allowable moment.

Selection Example

Operating conditions

- Work load: 60 [kg]
- Speed: 300 [mm/s]
- Acceleration/Deceleration: 3000 [mm/s^2]
- Stroke: 300 [mm]
- Mounting orientation: Horizontal
- External force: 10 [N]
- Workpiece mounting condition:





<Speed–Work Load Graph> (LEJS63)

Step 1 Check the speed–work load.

Select a model based on the workpiece mass and speed which are within the range of the actuator body specifications with reference to the "Speed–Work Load Graph (Guide)" on page 825.

Selection example) The **LEJS63□B-300** is temporarily selected based on the graph shown on the right side.

∗ Refer to the selection method of motor manufacturers for regeneration resistance.

Step 2 Check the cycle time.

Refer to method 1 for a rough estimate, and method 2 for a more precise value.

Method 1: Check the cycle time graph. (Page 826)

The graph is based on the maximum speed of each size.

Method 2: Calculation

Cycle time T can be found from the following equation.

$$T = T1 + T2 + T3 + T4 \text{ [s]}$$

- T1 and T3 can be obtained by the following equation.

$$T1 = V/a1 \text{ [s]} \qquad T3 = V/a2 \text{ [s]}$$

The acceleration and deceleration values have upper limits depending on the workpiece mass and the duty ratio.
Confirm that they do not exceed the upper limit, by referring to the "Work load–Acceleration/Deceleration Graph (Guide)" on pages 827 and 828.
For the ball screw type, there is an upper limit of the speed depending on the stroke. Confirm that it does not exceed the upper limit, by referring to the specifications on page 835.

- T2 can be found from the following equation.

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} \text{ [s]}$$

- T4 varies depending on the motor type and load. The value below is recommended.

$$T4 = 0.05 \text{ [s]}$$

∗ The conditions for the settling time vary depending on the motor or driver to be used.

Calculation example)
T1 to T4 can be calculated as follows.

$T1 = V/a1 = 300/3000 = 0.1$ [s],

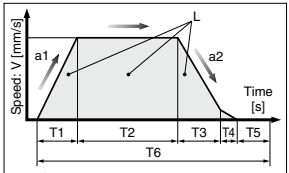
$T3 = V/a2 = 300/3000 = 0.1$ [s]

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} = \frac{300 - 0.5 \cdot 300 \cdot (0.1 + 0.1)}{300} = 0.90 \text{ [s]}$$

$T4 = 0.05$ [s]

Therefore, **the cycle time** can be obtained as follows.

$T = T1 + T2 + T3 + T4$
$= 0.1 + 0.90 + 0.1 + 0.05$
$= \mathbf{1.15}$ **[s]**



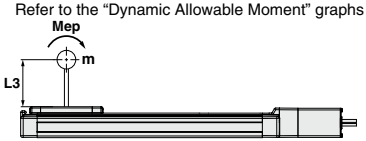
L : Stroke [mm]
V : Speed [mm/s]
a1: Acceleration [mm/s^2]
a2: Deceleration [mm/s^2]

T1: Acceleration time [s]
Time until reaching the set speed
T2: Constant speed time [s]
Time while the actuator is operating at a constant speed
T3: Deceleration time [s]
Time from the beginning of the constant speed operation to stop
T4: Settling time [s]
Time until positioning is completed
T5: Resting time [s]
Time the product is not running
T6: Total time [s]
Total time from T1 to T5

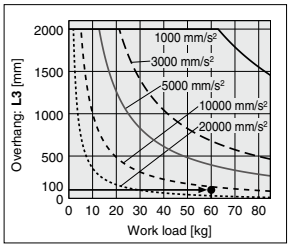
Duty ratio: Ratio of T to T6
T ÷ T6 x 100

Step 3 Check the allowable moment.

Refer to the "Dynamic Allowable Moment" graphs on pages 829 and 830.



Selection example) Select the **LEJS63□B-300** from the graph on the right side.
Confirm that the external force is within the allowable external force (20 [N]).
(The external force is the resistance due to cable duct, flexible trunking or air tubing.)



<Dynamic Allowable Moment> (LEJS63)

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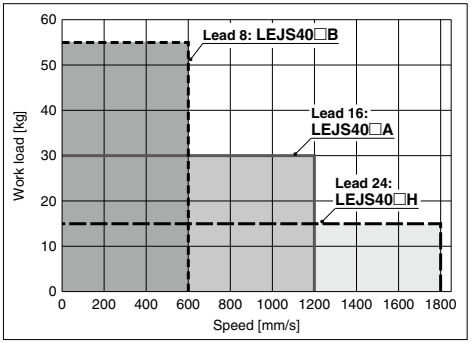
Speed–Work Load Graph (Guide)

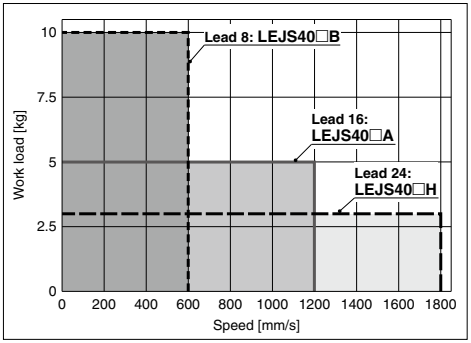
* The values shown below are allowable values of the actuator body. Do not use the actuator so that it exceeds these specification ranges.
* The allowable speed is restricted depending on the stroke. Select it by referring to the "Allowable Stroke Speed."

LEJS40/Ball Screw Drive

Horizontal

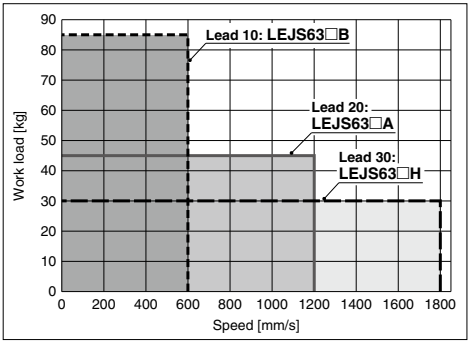


Vertical

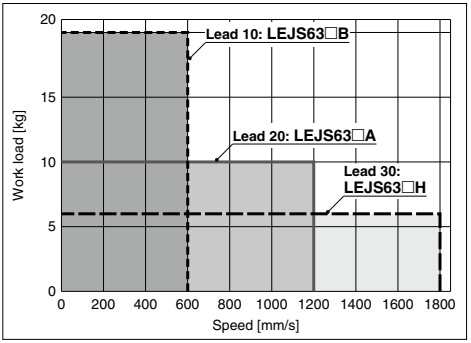


LEJS63/Ball Screw Drive

Horizontal



Vertical



Allowable Stroke Speed

[mm/s]

Model	Motor	Lead		Stroke [mm]														
		Symbol	[mm]	Up to 200	Up to 300	Up to 400	Up to 500	Up to 600	Up to 700	Up to 800	Up to 900	Up to 1000	Up to 1100	Up to 1200	Up to 1300	Up to 1400	Up to 1500
LEJS40	100 W equivalent	H	24	1800				1580	1170	910	720	580	480	410	—	—	—
		A	16	1200				1050	780	600	480	390	320	270	—	—	—
		B	8	600				520	390	300	240	190	160	130	—	—	—
		(Motor rotation speed)		(4500 rpm)				(3938 rpm)	(2925 rpm)	(2250 rpm)	(1800 rpm)	(1463 rpm)	(1200 rpm)	(1013 rpm)	—	—	—
LEJS63	200 W equivalent	H	30	—	1800					1390	1110	900	750	630	540	470	410
		A	20	—	1200					930	740	600	500	420	360	310	270
		B	10	—	600					460	370	300	250	210	180	150	130
		(Motor rotation speed)		—	(3600 rpm)					(2790 rpm)	(2220 rpm)	(1800 rpm)	(1500 rpm)	(1260 rpm)	(1080 rpm)	(930 rpm)	(810 rpm)

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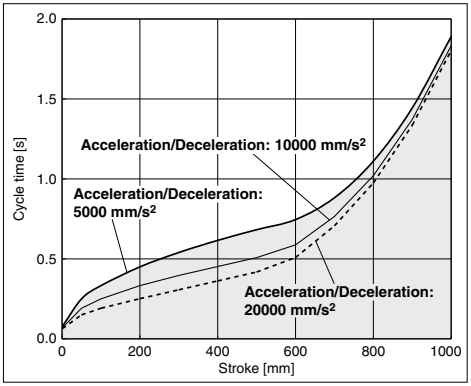
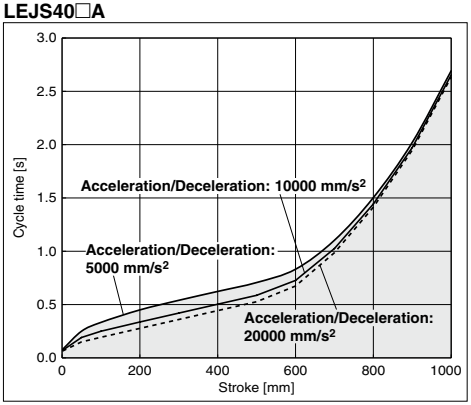
Cycle Time Graph (Guide)

LEJS40/Ball Screw Drive

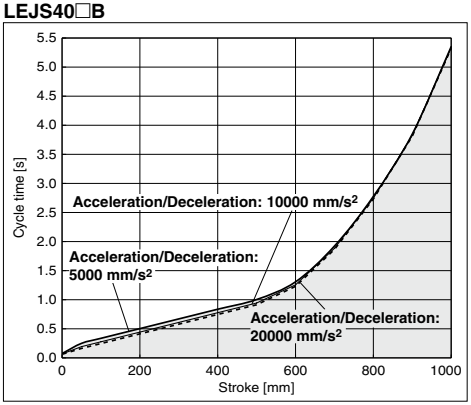
LEJS40□H



LEJS40□A

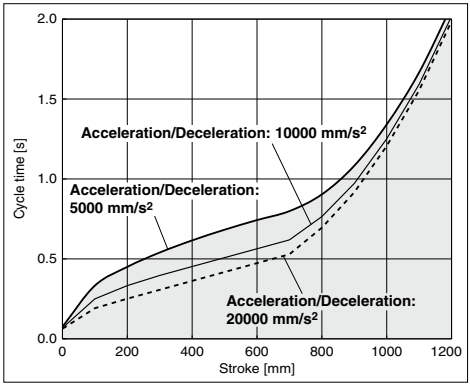


LEJS40□B

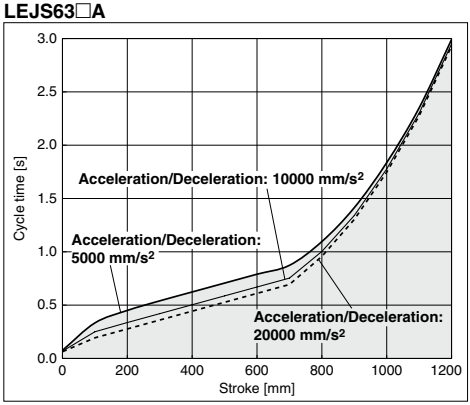


LEJS63/Ball Screw Drive

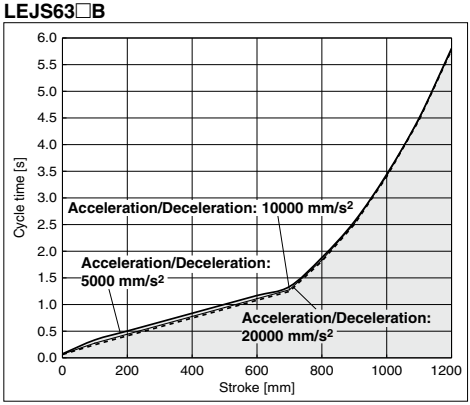
LEJS63□H



LEJS63□A



LEJS63□B



∗ These graphs show the cycle time for each acceleration/deceleration.
∗ These graphs show the cycle time for each stroke at the maximum speed.

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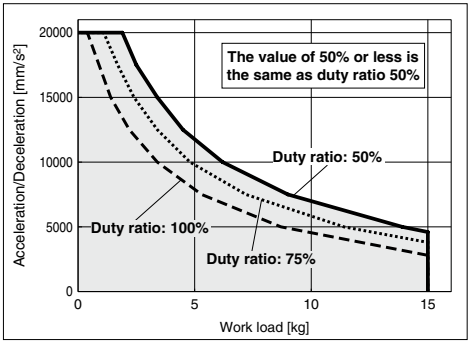
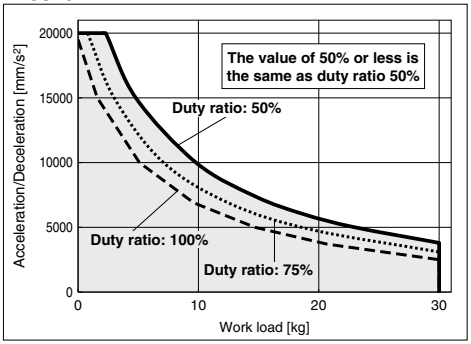
Work Load–Acceleration/Deceleration Graph (Guide)

LEJS40/Ball Screw Drive: Horizontal

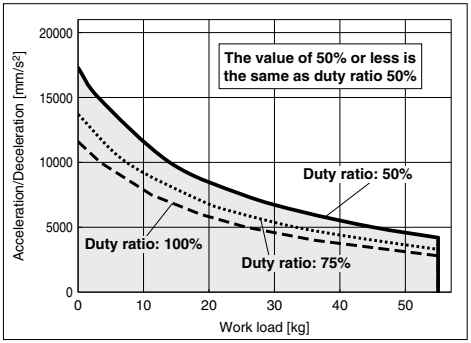
LEJS40□H



LEJS40□A

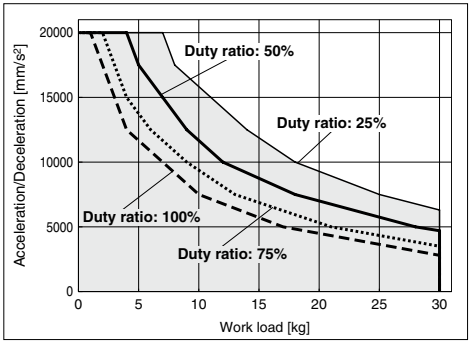


LEJS40□B

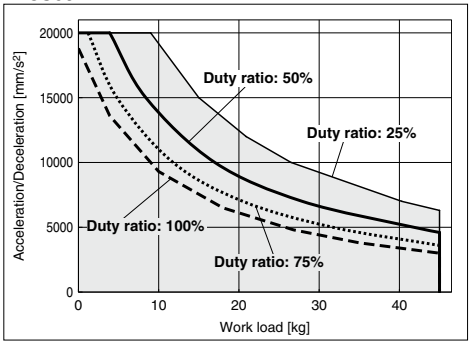


LEJS63/Ball Screw Drive: Horizontal

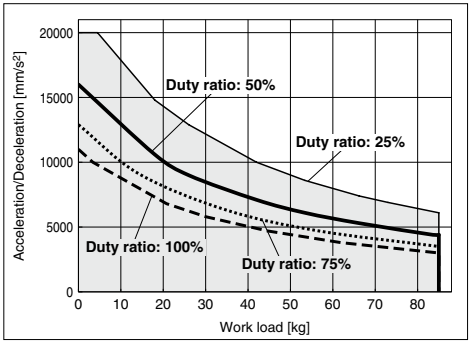
LEJS63□H



LEJS63□A



LEJS63□B



These graphs are examples of when the standard motor is mounted.
Determine the duty ratio after taking into account the load factor of the motor or driver to be used.

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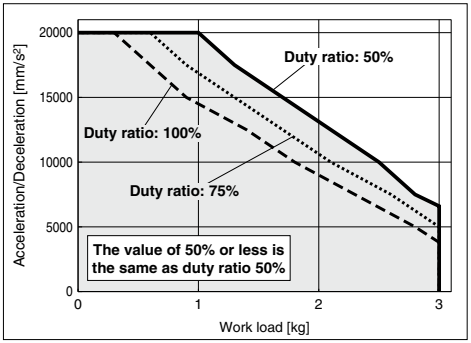
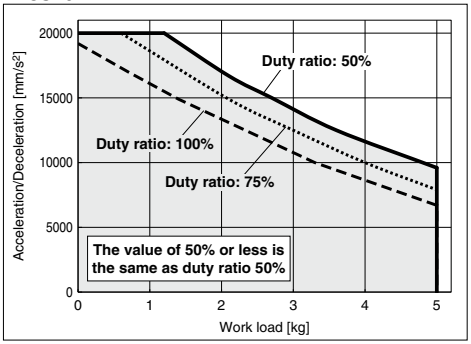
Work Load–Acceleration/Deceleration Graph (Guide)

LEJS40/Ball Screw Drive: Vertical

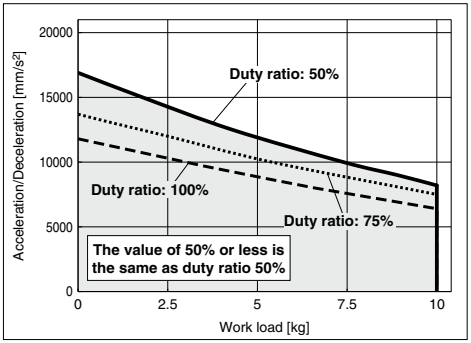
LEJS40□H



LEJS40□A

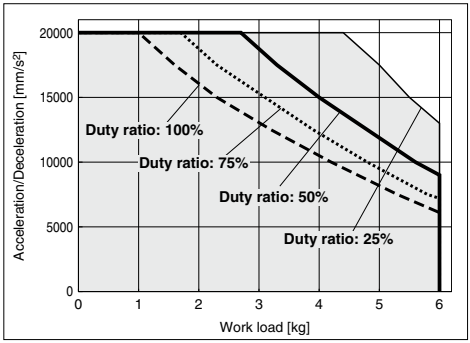


LEJS40□B

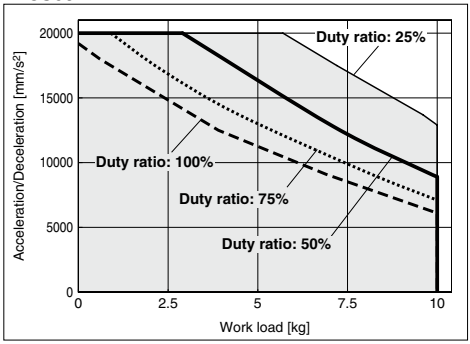


LEJS63/Ball Screw Drive: Vertical

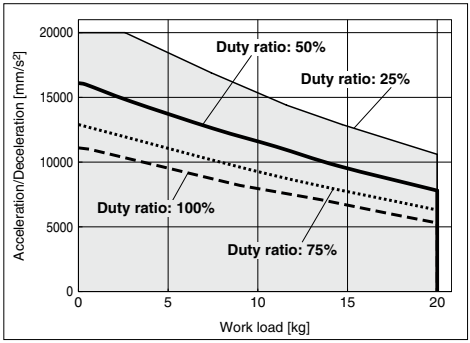
LEJS63□H



LEJS63□A



LEJS63□B



These graphs are examples of when the standard motor is mounted.
Determine the duty ratio after taking into account the load factor of the motor or driver to be used.

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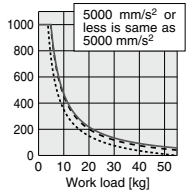
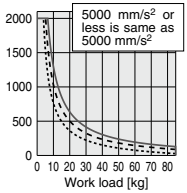
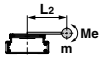
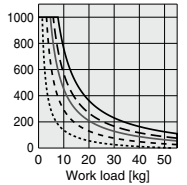
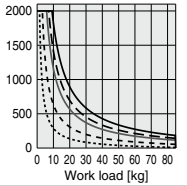
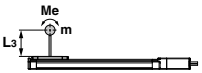
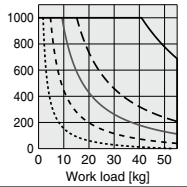
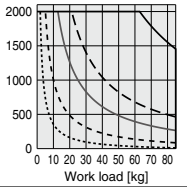
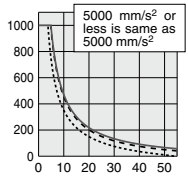
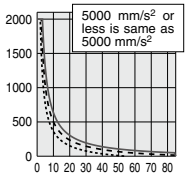
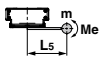
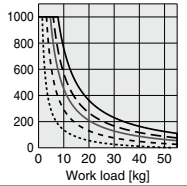
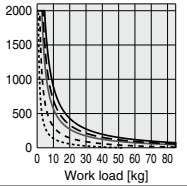
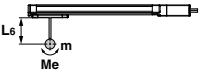
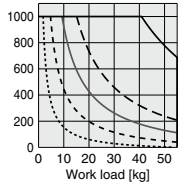
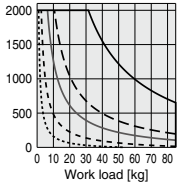
Dynamic Allowable Moment

* This graph shows the amount of allowable overhang (guide unit) when the center of gravity of the workpiece overhangs in one direction. When selecting the overhang, refer to "Calculation of Guide Load Factor" or the Electric Actuator Selection Software for confirmation, http://www.smcworld.com

Acceleration/Deceleration —— 1000 mm/s² - - - 3000 mm/s² —— 5000 mm/s² - - - - 10000 mm/s² ·····20000 mm/s²

Orientation	Load overhanging direction **m** : Work load [kg] **Me**: Dynamic allowable moment [N·m] **L** : Overhang to the work load center of gravity [mm]		Model LEJS40	Model LEJS63
Horizontal		X		
		Y		
		Z		
Bottom		X		
		Y		
		Z		

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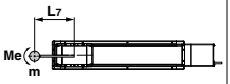
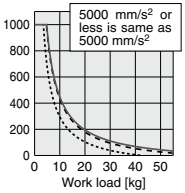
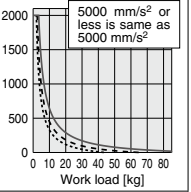
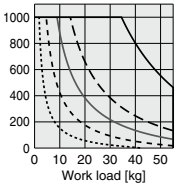
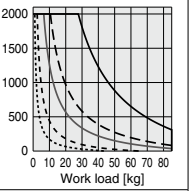
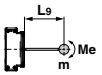
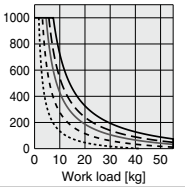
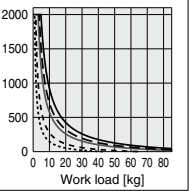
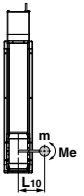
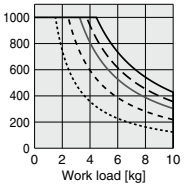
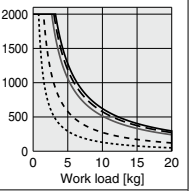
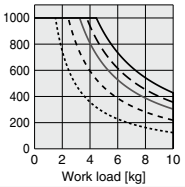
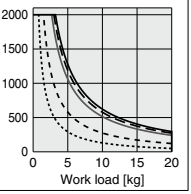
Dynamic Allowable Moment

* This graph shows the amount of allowable overhang (guide unit) when the center of gravity of the workpiece overhangs in one direction. When selecting the overhang, refer to "Calculation of Guide Load Factor" or the Electric Actuator Selection Software for confirmation, http://www.smcworld.com

Acceleration/Deceleration —— 1000 mm/s² - - - 3000 mm/s² —— 5000 mm/s² - - - - 10000 mm/s² ·····20000 mm/s²

Orientation	Load overhanging direction **m** : Work load [kg] **Me:** Dynamic allowable moment [N·m] **L** : Overhang to the work load center of gravity [mm]		Model LEJS40	Model LEJS63
Wall		X		
		Y		
		Z		
Vertical		Y		
		Z		

SMC
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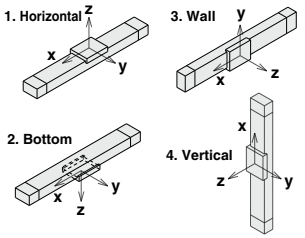
Calculation of Guide Load Factor

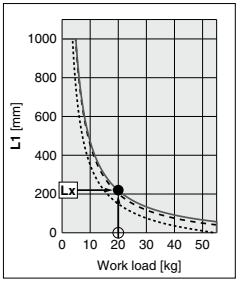
1. Decide operating conditions.
   Model: LEJS
   Size: 40/63
   Mounting orientation: Horizontal/Bottom/Wall/Vertical
   Acceleration [mm/s²]: **a**
   Work load [kg]: **m**
   Work load center position [mm]: **Xc/Yc/Zc**
2. Select the target graph with reference to the model, size and mounting orientation.
3. Based on the acceleration and work load, obtain the overhang [mm]: **Lx/Ly/Lz** from the graph.
4. Calculate the load factor for each direction.
   α**x = Xc/Lx**, α**y = Yc/Ly**, α**z = Zc/Lz**
5. Confirm the total of α**x**, α**y** and α**z** is 1 or less.
   α**x + αy + αz ≤ 1**
   When 1 is exceeded, consider a reduction of acceleration and work load, or a change of the work load center position and series.

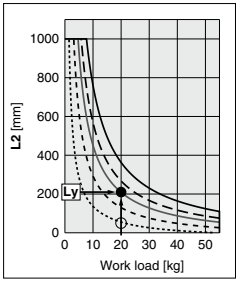
Mounting Orientation



Example

1. Operating conditions
   Model: LEJS
   Size: 40
   Mounting orientation: Horizontal
   Acceleration [mm/s²]: 5000
   Work load [kg]: 20
   Work load center position [mm]: **Xc = 0**, **Yc = 50**, **Zc = 200**
2. Select the graph on page 829, top and left side first row.
3. **Lx = 220 mm**, **Ly = 210 mm**, **Lz = 430 mm**
4. The load factor for each direction can be obtained as follows.
   α**x = 0/220 = 0**
   α**y = 50/210 = 0.24**
   α**z = 200/430 = 0.47**
5. α**x + αy + αz = 0.71 ≤ 1**





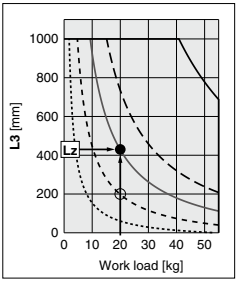


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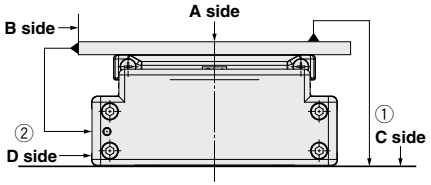
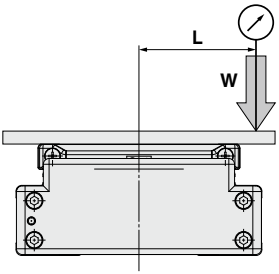
Table Accuracy (Reference Value)

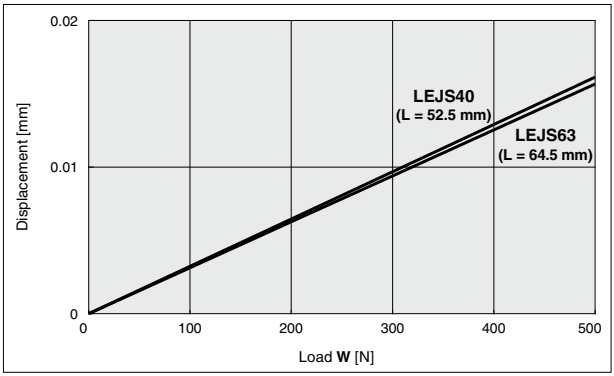


Model	Traveling parallelism [mm] (Every 300 mm)	
	① C side traveling parallelism to A side	② D side traveling parallelism to B side
LEJS40	0.05	0.03
LEJS63	0.05	0.03

Note) Traveling parallelism does not include the mounting surface accuracy.

Table Displacement (Reference Value)





Note) This displacement is measured when a 15 mm aluminum plate is mounted and fixed on the table. (Table clearance is included.)

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Motorless Type

Electric Actuator/High Rigidity Slider Type
Ball Screw Drive
LEJS Series LEJS40, 63

RoHS

How to Order

LEJS H 40 NZ A – 500

❶ ❷ ❸ ❹ ❺

❶ Accuracy

Nil	Basic type
H	High precision type

❷ Size

40
63

❸ Motor type

Symbol	Type
NZ	Mounting type Z
NY	Mounting type Y
NX	Mounting type X
NW*	Mounting type W
NV*	Mounting type V
NU*	Mounting type U
NT*	Mounting type T

* Size 63 only

❹ Lead [mm]

Symbol	LEJS40	LEJS63
H	24	30
A	16	20
B	8	10

❺ Stroke [mm]

200
to
1500

* For details, refer to the table below.

Applicable Stroke Table ●: Standard

Model \ Stroke [mm]	200	300	400	500	600	700	800	900	1000	1200	1500
LEJS40	●	●	●	●	●	●	●	●	●	●	—
LEJS63	—	●	●	●	●	●	●	●	●	●	●

* Please consult with SMC for non-standard strokes as they are produced as special orders.

For auto switches, refer to pages 841 to 843.

Compatible Motors

Applicable motor model			Size/Motor type									
			40			63						
Manufacturer	Series	Type	NZ Mounting type Z	NY Mounting type Y	NX Mounting type X	NZ Mounting type Z	NY Mounting type Y	NX Mounting type X	NW Mounting type W	NV Mounting type V	NU Mounting type U	NT Mounting type T
Mitsubishi Electric Corporation	MELSERVO-JN	HF-KN	●	—	—	●	—	—	—	—	—	—
	MELSERVO-J3	KF-KP	●	—	—	●	—	—	—	—	—	—
	MELSERVO-J4	HG-KR	●	—	—	●	—	—	—	—	—	—
YASKAWA Electric Corporation	Σ-V	SGMJV	●	—	—	●	—	—	—	—	—	—
SANYO DENKI CO., LTD.	SANMOTION R	R2	●	—	—	●	—	—	—	—	—	—
OMRON Corporation	Sysmac G5	R88M-K	●	—	—	—	●	—	—	—	—	—
Panasonic Corporation	MINAS-A4	MSMD	—	●	—	—	●	—	—	—	—	—
	MINAS-A5	MSMD/MHMD	—	●	—	—	●	—	—	—	—	—
FANUC CORPORATION	βis	β	●	—	—	● (β1 only)	—	—	●	—	—	—
NIDEC SANKYO CORPORATION	S-FLAG	MA/MH/MM	●	—	—	●	—	—	—	—	—	—
KEYENCE CORPORATION	SV	SV-M/SV-B	●	—	—	●	—	—	—	—	—	—
FUJI ELECTRIC CO., LTD.	ALPHA5	GYS/GYB	●	—	—	●	—	—	—	—	—	—
	FALDIC-α	GYS	●	—	—	●	—	—	—	—	—	—
Rockwell Automation, Inc. (Allen-Bradley)	MP-/VP-	MP/VP	—	—	—	—	—	●	—	—	—	—
	TL	TLY-A	●	—	—	—	—	—	—	—	—	●
Beckhoff Automation GmbH	AM	AM30	●	—	—	—	—	—	—	●	—	—
	AM	AM31	●	—	—	—	—	—	—	—	●	—
	AM	AM80/AM81	●	—	—	—	—	●	—	—	—	—
Siemens AG	1FK7	1FK7	—	—	●	—	—	●	—	—	—	—
Delta Electronics, Inc.	ASDA-A2	ECMA	●	—	—	●	—	—	—	—	—	—

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Specifications

- Values in this specification table are the allowable values of the actuator body with the standard motor mounted.
- Do not use the actuator so that it exceeds these values.

	Model			LEJS40			LEJS63		
Actuator specifications	Stroke [mm] Note 1)			200, 300, 400, 500, 600, 700, 800 900, 1000, 1200			300, 400, 500, 600, 700, 800, 900 1000, 1200, 1500		
	Work load [kg] Note 2)		Horizontal	15	30	55	30	45	85
			Vertical	3	5	10	6	10	20
	Speed [mm/s] Note 3)	Stroke range	Up to 500	1800	1200	600	1800	1200	600
			501 to 600	1580	1050	520			
			601 to 700	1170	780	390			
			701 to 800	910	600	300	1390	930	460
			801 to 900	720	480	240	1110	740	370
			901 to 1000	580	390	190	900	600	300
			1001 to 1100	480	320	160	750	500	250
			1101 to 1200	410	270	130	630	420	210
			1201 to 1300	—	—	—	540	360	180
			1301 to 1400	—	—	—	470	310	150
			1401 to 1500	—	—	—	410	270	130
	Max. acceleration/deceleration [mm/s²]			20000					
	Positioning repeatability [mm]		Basic type	±0.02					
			High precision type	±0.01					
	Lost motion [mm] Note 4)		Basic type	0.1 or less					
			High precision type	0.05 or less					
	Ball screw specifications		Thread size [mm]	ø12			ø15		
			Lead [mm]	24	16	8	30	20	10
			Shaft length [mm]	Stroke + 118.5			Stroke + 126.5		
	Impact/Vibration resistance [m/s²] Note 5)			50/20					
	Actuation type			Ball screw					
	Guide type			Linear guide					
	Operating temperature range [°C]			5 to 40					
	Operating humidity range [%RH]			90 or less (No condensation)					
Other specifications Note 6)	Actuation unit weight [kg]			0.86			1.37		
	Other inertia [kg·cm²]			0.031			0.129		
	Friction coefficient			0.05					
	Mechanical efficiency			0.8					
Reference motor specifications	Motor shape			□40			□60		
	Motor type			AC servo motor (100 V/200 V)					
	Rated output capacity [W]			100			200		
	Rated torque [N·m]			0.32			0.64		
	Rated rotation [rpm]			3000			3000		

Note 1) Please consult with SMC for non-standard strokes as they are produced as special orders.
Note 2) Check the "Speed–Work Load Graph (Guide)" on page 825.
Note 3) The allowable speed changes according to the stroke.
Note 4) A reference value for correcting an error in reciprocal operation.
Note 5) Impact resistance: No malfunction occurred when the actuator was tested with a drop tester in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the actuator in the initial state.)
Vibration resistance: No malfunction occurred in a test ranging between 45 to 2000 Hz. Test was performed in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the actuator in the initial state.)
Note 6) Each value is a guide. Use such value to select a motor capacity.
Note 7) Sensor magnet position is located in the table center.
For detailed dimensions, refer to the "Auto Switch Mounting Position."
Note 8) Do not allow collisions at either end of the table traveling distance.
Additionally, when running the positioning operation, do not set within 2 mm of both ends.
Note 9) Please consult with SMC for the manufacture of intermediate strokes.
(LEJS40/Manufacturable stroke range: 200 to 1200 mm, LEJS63/Manufacturable stroke range: 300 to 1500 mm)

Weight

Model	LEJS40									
Stroke [mm]	200	300	400	500	600	700	800	900	1000	1200
Product weight [kg]	5.0	5.8	6.5	7.3	8.1	8.8	9.6	10.4	11.1	12.7

Model	LEJS63									
Stroke [mm]	300	400	500	600	700	800	900	1000	1200	1500
Product weight [kg]	10.4	11.7	12.9	14.2	15.4	16.7	17.9	19.1	21.6	25.4

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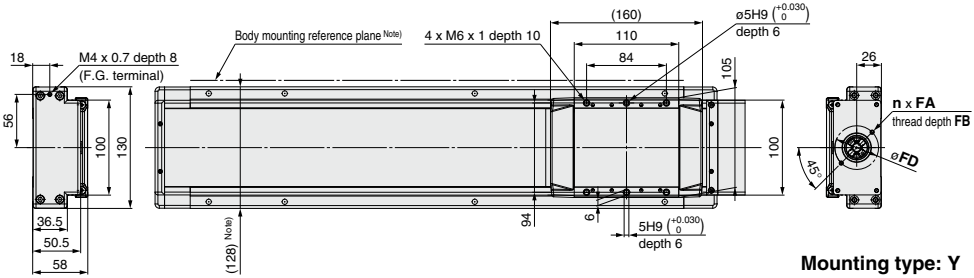
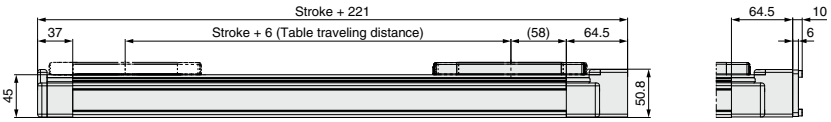
Refer to the "Motor Mounting" on page 838 for details about motor mounting and included parts.

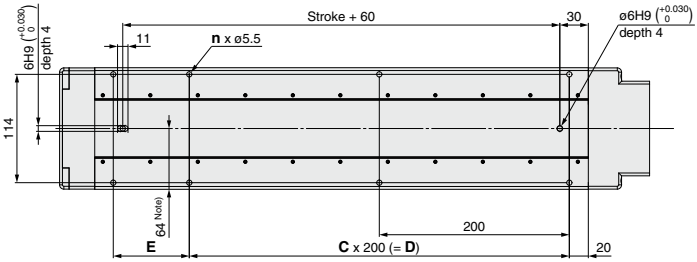
Dimensions: Ball Screw Drive

LEJS40



Mounting type: Y
LEJS40NY□-□





Note) When mounting the actuator using the body mounting reference plane, use a pin. Set the height of the pin to be 5 mm or more because of round chamfering. (Recommended height 6 mm)

Dimensions [mm]

Model	n	C	D	E
LEJS40N□□-200	6	1	200	80
LEJS40N□□-300	6	1	200	180
LEJS40N□□-400	8	2	400	80
LEJS40N□□-500	8	2	400	180
LEJS40N□□-600	10	3	600	80
LEJS40N□□-700	10	3	600	180
LEJS40N□□-800	12	4	800	80
LEJS40N□□-900	12	4	800	180
LEJS40N□□-1000	14	5	1000	80
LEJS40N□□-1200	16	6	1200	80

Motor Mounting Dimensions [mm]

Motor type	n	FA	FB	FD
NZ/Mounting type Z	2	M4 x 0.7	7	46
NY/Mounting type Y	4	M3 x 0.5	6	45
NX/Mounting type X	2	M4 x 0.7	7	46

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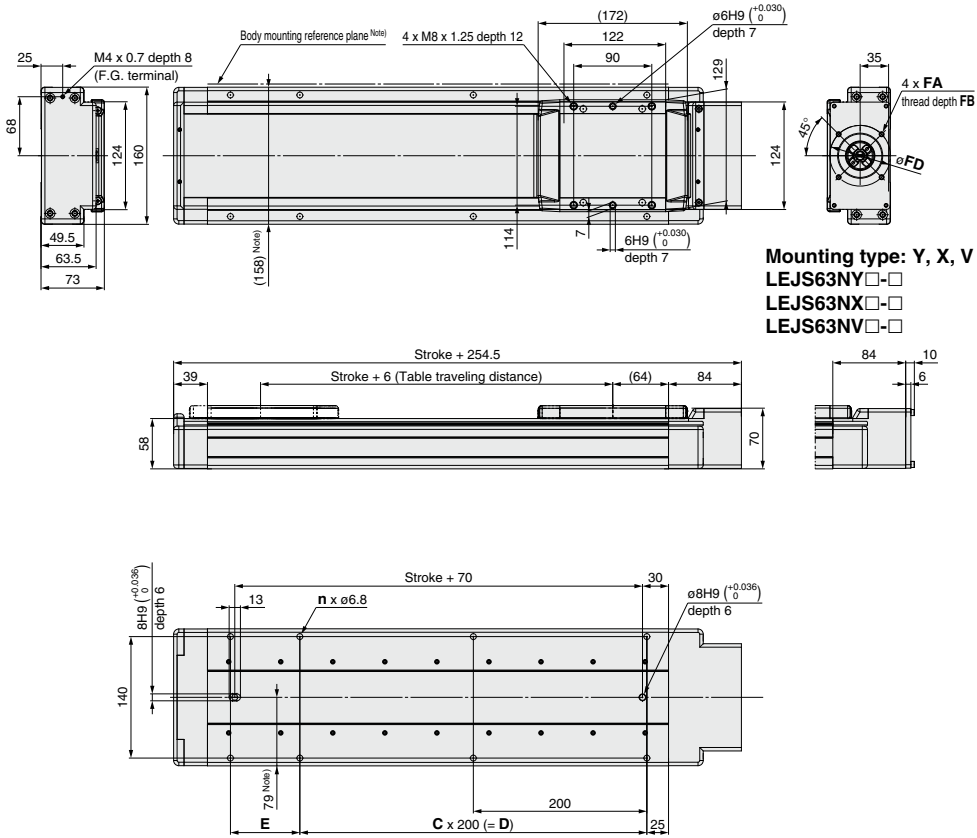
Refer to the "Motor Mounting" on page 838 for details about motor mounting and included parts.

Dimensions: Ball Screw Drive

LEJS63



Note) When mounting the actuator using the body mounting reference plane, use a pin. Set the height of the pin to be 5 mm or more because of round chamfering. (Recommended height 6 mm)

Dimensions [mm]

Model	n	C	D	E
LEJS63N□□-300	6	1	200	180
LEJS63N□□-400	8	2	400	80
LEJS63N□□-500	8	2	400	180
LEJS63N□□-600	10	3	600	80
LEJS63N□□-700	10	3	600	180
LEJS63N□□-800	12	4	800	80
LEJS63N□□-900	12	4	800	180
LEJS63N□□-1000	14	5	1000	80
LEJS63N□□-1200	16	6	1200	80
LEJS63N□□-1500	18	7	1400	180

Motor Mounting Dimensions [mm]

Motor type	FA	FB	FD
NZ/Mounting type Z	M5 x 0.8	7	70
NY/Mounting type Y	M4 x 0.7	6	70
NX/Mounting type X	M5 x 0.8	6	63
NW/Mounting type W	M5 x 0.8	7	70
NV/Mounting type V	M4 x 0.7	6	63
NU/Mounting type U	M5 x 0.8	7	70
NT/Mounting type T	M5 x 0.8	7	70

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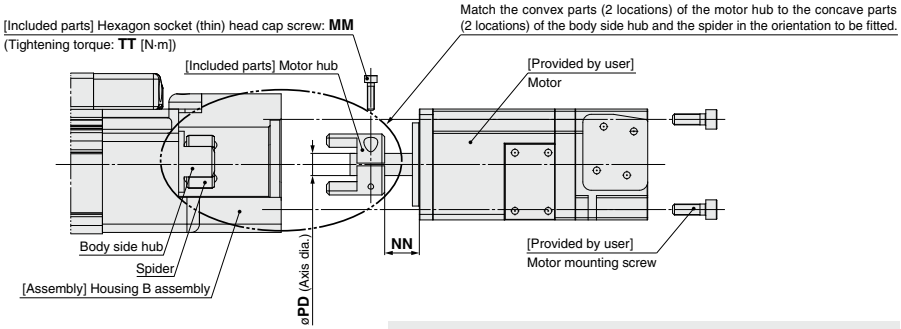
Motor Mounting

- When mounting a hub, remove the oil content, dust, or dirt sticking to the shaft and hub inside diameter.
- This product does not include the motor and motor mounting screws. (Provided by user)
  For the shaft-end shape of the motor, prepare the round type.
- Take loose prevention measures for the motor mounting screws.



Mounting procedure

1) Fix the motor (provided by user) and the "motor hub" with the "MM hexagon socket head cap screw."
2) Check the "motor hub position", and then insert it.
3) Fix the motor and the "housing B assembly" with the motor mounting screws (provided by user).

Dimensions

[mm]

Size	Motor type	MM	TT	NN	PD
40	**NZ/Mounting type Z**	M2.5 x 10	0.65	12.5	8
	NY/Mounting type Y	M2.5 x 10	0.65	12.5	8
	NX/Mounting type X	M2.5 x 10	0.65	7	8
63	**NZ/Mounting type Z**	M3 x 12	1.5	18	14
	NY/Mounting type Y	M4 x 12	2.7	18	11
	NX/Mounting type X	M4 x 12	2.7	8	9
	NW/Mounting type W	M4 x 12	2.7	12	9
	NV/Mounting type V	M4 x 12	2.7	8	9
	NU/Mounting type U	M4 x 12	2.7	12	11
	NT/Mounting type T	M3 x 12	1.5	18	12

Included Parts List

Size: 40

Description	Quantity	Note
Motor hub	1	—
Hexagon socket head cap screw (for hub fixing)	1	M2.5 x 10: Motor type "NZ", "NY", "NX"

Size: 63

Description	Quantity	Note
Motor hub	1	—
Hexagon socket head cap screw (for hub fixing)	1	M3 x 12: Motor type "NZ", "NT"
Hexagon socket thin head cap screw (for hub fixing)		M4 x 12: Motor type "NY", "NX", "NW", "NV", "NU"

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LEJS Series
Motor Mounting Parts

Motor Flange Option

As the motor type “NZ” is selected for the model and this option is mounted, the motor types that can be used are shown below.

How to Order

LEJ – MF 63 D – NY

❶ ❷

❶ Size

40	For LEJ40
63	For LEJ63

❷ Motor type

Symbol	Type
NY	Mounting type Y
NX	Mounting type X
NW	Mounting type W
NV	Mounting type V
NU	Mounting type U
NT	Mounting type T

∗ Component parts vary depending on the motor type. Refer to “Component Parts” on page 840.

Compatible Motors

Applicable motor model			Size/Motor type									
			40			63						
Manufacturer	Series	Type	NZ Mounting type Z	NY Mounting type Y	NX Mounting type X	NZ Mounting type Z	NY Mounting type Y	NX Mounting type X	NW Mounting type W	NV Mounting type V	NU Mounting type U	NT Mounting type T
Mitsubishi Electric Corporation	MELSERVO-JN	HF-KN	●	—	—	●	—	—	—	—	—	—
	MELSERVO-J3	KF-KP	●	—	—	●	—	—	—	—	—	—
	MELSERVO-J4	HG-KR	●	—	—	●	—	—	—	—	—	—
YASKAWA Electric Corporation	Σ-V	SGMJV	●	—	—	●	—	—	—	—	—	—
SANYO DENKI CO., LTD.	SANMOTION R	R2	●	—	—	●	—	—	—	—	—	—
OMRON Corporation	Sysmac G5	R88M-K	●	—	—	—	●	—	—	—	—	—
Panasonic Corporation	MINAS-A4	MSMD	—	●	—	—	●	—	—	—	—	—
	MINAS-A5	MSMD/MHMD	—	●	—	—	●	—	—	—	—	—
FANUC CORPORATION	βis	β	●	—	—	● (β1 only)	—	—	●	—	—	—
NIDEC SANKYO CORPORATION	S-FLAG	MA/MH/MM	●	—	—	●	—	—	—	—	—	—
KEYENCE CORPORATION	SV	SV-M/SV-B	●	—	—	●	—	—	—	—	—	—
FUJI ELECTRIC CO., LTD.	ALPHA5	GYS/GYB	●	—	—	●	—	—	—	—	—	—
	FALDIC-α	GYS	●	—	—	●	—	—	—	—	—	—
Rockwell Automation, Inc. (Allen-Bradley)	MP-/VP-	MP/VP	—	—	—	—	—	●	—	—	—	—
	TL	TLY-A	●	—	—	—	—	—	—	—	—	●
Beckhoff Automation GmbH	AM	AM30	●	—	—	—	—	—	—	●	—	—
	AM	AM31	●	—	—	—	—	—	—	—	●	—
	AM	AM80/AM81	●	—	—	—	—	●	—	—	—	—
Siemens AG	1FK7	1FK7	—	—	●	—	—	●	—	—	—	—
Delta Electronics, Inc.	ASDA-A2	ECMA	●	—	—	●	—	—	—	—	—	—

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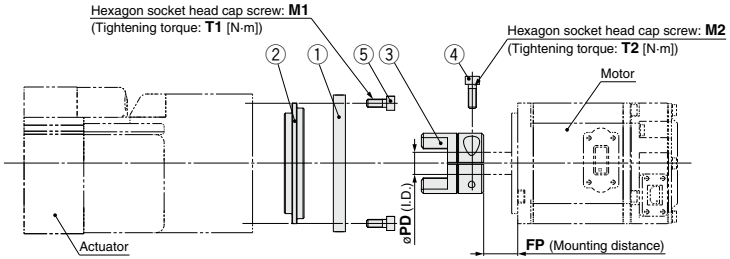
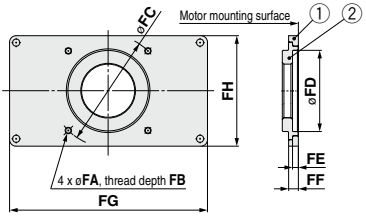
Dimensions: Motor Flange Option



Motor plate details



Dimensions [mm]

Size	Motor type	FA	FB	FC	FD	FE	FF	FG	FH	M1	T1	M2	T2	PD	FP
40	NY	M3 x 0.5	6	45	30	3.5	6	99	49	M4 x 12	2.7	M2.5 x 10	0.65	8	12.5
	NX	—	—	—	—	—	—	—	—	—	—	M2.5 x 10	0.65	8	7
63	NY	M4 x 0.7	6	70	50	3.5	6	123	68	M4 x 12	2.7	M4 x 12	2.7	11	18
	NX	M5 x 0.8	6	63	40	3.5	6	123	68	M4 x 12	2.7	M4 x 12	2.7	9	8
	NW	—	—	—	—	—	—	—	—	—	—	M4 x 12	2.7	9	12
	NV	M4 x 0.7	6	63	40	3.5	6	123	68	M4 x 12	2.7	M4 x 12	2.7	9	8
	NU	—	—	—	—	—	—	—	—	—	—	M4 x 12	2.7	11	12
	NT	—	—	—	—	—	—	—	—	—	—	M3 x 12	1.5	12	18

Component Parts

Size: 40

No.	Description	Quantity	
		Motor type	
		NY	NX
1	Motor plate	1	—
2	Ring	1	—
3	Hub (Motor side)	1	1
4	Hexagon socket thin head cap screw	1	1
5	Hexagon socket head cap screw	4	—

Size: 63

No.	Description	Quantity					
		Motor type					
		NY	NX	NW	NV	NU	NT
1	Motor plate	1	1	—	1	—	—
2	Ring	1	1	—	1	—	—
3	Hub (Motor side)	1	1	1	1	1	1
4	Hexagon socket thin head cap screw	1	1	1	1	1	1
5	Hexagon socket head cap screw	4	4	—	4	—	—

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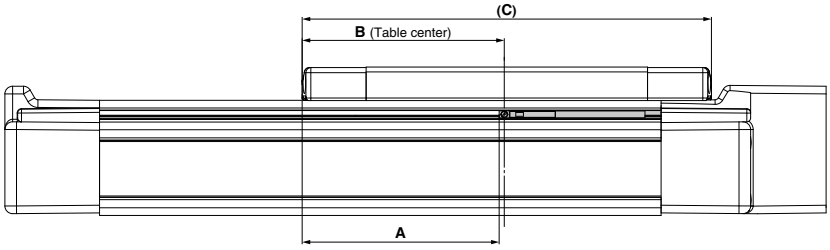
Auto Switch Mounting

Auto Switch Mounting Position



[mm]

Model	Size	A	B	C	Operating range
LEJS	40	77	80	160	5.5
	63	83	86	172	7.0

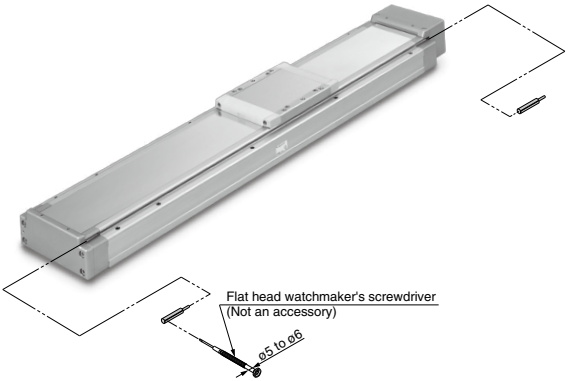
Note) Since the operating range is provided as a guideline including hysteresis, it cannot be guaranteed (assuming approximately ±30% dispersion). It may change substantially depending on the ambient environment.

Auto Switch Mounting

When mounting the auto switches, they should be inserted into the actuator's auto switch mounting groove as shown in the drawing below. After setting in the mounting position, use a flat head watchmaker's screwdriver to tighten the auto switch mounting screw that is included.

Auto Switch Mounting Screw Tightening Torque [N·m]

Auto switch model	Tightening torque
D-M9□(V) **D-M9□W(V)**	0.10 to 0.15



Note) When tightening the auto switch mounting screw (included with auto switch), use a watchmaker's screwdriver with a handle diameter of about 5 to 6 mm.

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Solid State Auto Switch
Direct Mounting Type
D-M9N(V)/D-M9P(V)/D-M9B(V)

RoHS

Refer to SMC website for the details of the products conforming to the international standards.

Grommet

- **2-wire load current is reduced (2.5 to 40 mA).**
- **Using flexible cable as standard spec.**

⚠Caution

Precautions

Fix the auto switch with the existing screw installed on the auto switch body. The auto switch may be damaged if a screw other than the one supplied is used.

Auto Switch Specifications

PLC: Programmable Logic Controller

D-M9□, D-M9□V (With indicator light)						
Auto switch model	D-M9N	D-M9NV	D-M9P	D-M9PV	D-M9B	D-M9BV
Electrical entry direction	In-line	Perpendicular	In-line	Perpendicular	In-line	Perpendicular
Wiring type	3-wire				2-wire	
Output type	NPN		PNP		—	
Applicable load	IC circuit, Relay, PLC				24 VDC relay, PLC	
Power supply voltage	5, 12, 24 VDC (4.5 to 28 V)				—	
Current consumption	10 mA or less				—	
Load voltage	28 VDC or less		—		24 VDC (10 to 28 VDC)	
Load current	40 mA or less				2.5 to 40 mA	
Internal voltage drop	0.8 V or less at 10 mA (2 V or less at 40 mA)				4 V or less	
Leakage current	100 μA or less at 24 VDC				0.8 mA or less	
Indicator light	Red LED illuminates when turned ON.					
Standard	CE marking, RoHS					

Oilproof Heavy-duty Lead Wire Specifications

Auto switch model		D-M9N(V)	D-M9P(V)	D-M9B(V)
Sheath	Outside diameter [mm]	2.6		
Insulator	Number of cores	3 cores (Brown/Blue/Black)		2 cores (Brown/Blue)
	Outside diameter [mm]	0.88		
Conductor	Effective area [mm²]	0.15		
	Strand diameter [mm]	0.05		
Minimum bending radius [mm] (Reference values)		17		

Note 1) Refer to Best Pneumatics No. 2-1 for solid state auto switch common specifications.
Note 2) Refer to Best Pneumatics No. 2-1 for lead wire lengths.

Weight

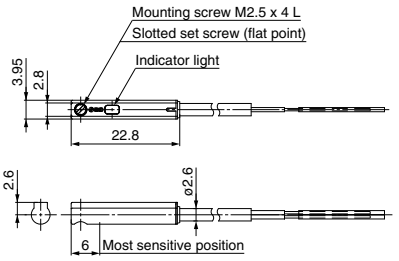
(g)

Auto switch model		D-M9N(V)	D-M9P(V)	D-M9B(V)
Lead wire length	0.5 m (**Nil**)	8		7
	1 m (**M**)	14		13
	3 m (**L**)	41		38
	5 m (**Z**)	68		63

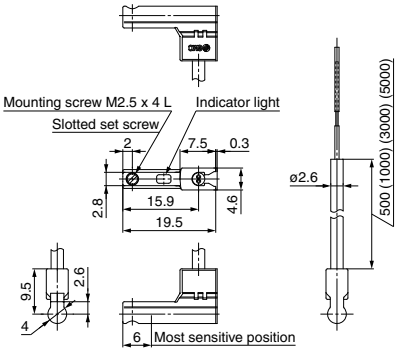
Dimensions

(mm)

D-M9□



D-M9□V



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2-Color Indicator Solid State Auto Switch Direct Mounting Type
D-M9NW(V)/D-M9PW(V)/D-M9BW(V)

RoHS

Refer to SMC website for the details of the products conforming to the international standards.

Grommet

- **2-wire load current is reduced (2.5 to 40 mA).**
- **Using flexible cable as standard spec.**
- **The proper operating range can be determined by the color of the light. (Red → Green ← Red)**

⚠Caution

Precautions

Fix the auto switch with the existing screw installed on the auto switch body. The auto switch may be damaged if a screw other than the one supplied is used.

Auto Switch Specifications

PLC: Programmable Logic Controller

D-M9□W, D-M9□WV (With indicator light)						
Auto switch model	D-M9NW	D-M9NWV	D-M9PW	D-M9PWV	D-M9BW	D-M9BWV
Electrical entry direction	In-line	Perpendicular	In-line	Perpendicular	In-line	Perpendicular
Wiring type	3-wire				2-wire	
Output type	NPN		PNP		—	
Applicable load	IC circuit, Relay, PLC				24 VDC relay, PLC	
Power supply voltage	5, 12, 24 VDC (4.5 to 28 V)				—	
Current consumption	10 mA or less				—	
Load voltage	28 VDC or less		—		24 VDC (10 to 28 VDC)	
Load current	40 mA or less				2.5 to 40 mA	
Internal voltage drop	0.8 V or less at 10 mA (2 V or less at 40 mA)				4 V or less	
Leakage current	100 μA or less at 24 VDC				0.8 mA or less	
Indicator light	Operating range ····· Red LED illuminates. Proper operating range ····· Green LED illuminates.					
Standard	CE marking, RoHS					

Oilproof Flexible Heavy-duty Lead Wire Specifications

Auto switch model		D-M9NW(V)	D-M9PW(V)	D-M9BW(V)
Sheath	Outside diameter [mm]	2.6		
Insulator	Number of cores	3 cores (Brown/Blue/Black)		2 cores (Brown/Blue)
	Outside diameter [mm]	0.88		
Conductor	Effective area [mm²]	0.15		
	Strand diameter [mm]	0.05		
Minimum bending radius [mm] (Reference values)		17		

Note 1) Refer to Best Pneumatics No. 2-1 for solid state auto switch common specifications.
Note 2) Refer to Best Pneumatics No. 2-1 for lead wire lengths.

Weight

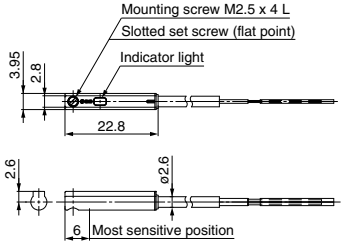
(g)

Auto switch model		D-M9NW(V)	D-M9PW(V)	D-M9BW(V)
Lead wire length	0.5 m (**Nil**)	8		7
	1 m (**M**)	14		13
	3 m (**L**)	41		38
	5 m (**Z**)	68		63

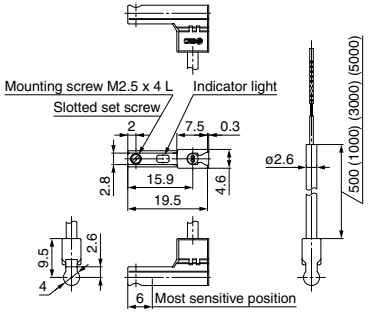
Dimensions

(mm)

D-M9□W



D-M9□WV



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LEJS Series
Electric Actuator
Specific Product Precautions 1

Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions and pages 3 to 8 for Electric Actuator Precautions.

Design

⚠Caution

1. Do not apply a load in excess of the specification limits.

Select a suitable actuator by work load and allowable moment. If the product is used outside of the specification limits, the eccentric load applied to the guide will be excessive and have adverse effects such as creating play on the guide, degrading accuracy and shortening the life of the product.

2. Do not use the product in applications where excessive external force or impact force is applied to it.

The product can be damaged.

The components including the motor are manufactured to precise tolerances. So that even a slight deformation may cause a malfunction or seizure.

Selection

⚠Warning

1. Do not increase the speed in excess of the specification limits.

Select a suitable actuator by the relationship of the allowable work load and speed, and the allowable speed of each stroke. If the product is used outside of the specification limits, it will have adverse effects such as creating noise, degrading accuracy and shortening the life of the product.

2. When the product repeatedly cycles with partial strokes (100 mm or less), lubrication can run out. Operate it at a full stroke at least once a day or every a thousand cycles.

3. When external force is applied to the table, it is necessary to add external force to the work load as the total carried load for the sizing.

When a cable duct or flexible moving tube is attached to the actuator, the sliding resistance of the table increases and may lead to operational failure of the product.

4. Depending on the shape of the motor to be mounted, some of the product's interior parts (hub, spider, etc.) may be visible from the motor mounting surface. If this is undesirable, please contact your nearest sales office for details on options such as covers.

Handling

⚠Caution

1. Do not allow the table to hit the end of stroke.

When the driver parameters, origin or programs are set incorrectly, the table may collide against the stroke end of the actuator during operation. Check these points before use.

If the table collides against the stroke end of the actuator, the guide, ball screw, belt or internal stopper can be broken. This may lead to abnormal operation.

Handle the actuator with care when it is used in the vertical direction as the workpiece will fall freely from its own weight.

2. The actual speed of this actuator is affected by the work load and stroke.

Check the specifications with reference to the model selection section of the catalog.

3. Do not apply a load, impact or resistance in addition to the transferred load during return to origin.

4. Do not dent, scratch or cause other damage to the body and table mounting surfaces.

This may cause unevenness in the mounting surface, play in the guide or an increase in the sliding resistance.

5. Do not apply strong impact or an excessive moment while mounting the product or a workpiece.

If an external force over the allowable moment is applied, it may cause play in the guide or an increase in the sliding resistance.

6. Keep the flatness of mounting surface should be within 0.1 mm/500 mm.

Unevenness of a workpiece or base mounted on the body of the product may cause play in the guide and an increase in the sliding resistance.

In the case of overhang mounting (including cantilever), use a support plate or support guide to avoid deflection of the actuator body.

7. When mounting the actuator, use all mounting holes.

If all mounting holes are not used, it influences the specifications, e.g., the amount of displacement of the table increases.

8. Do not hit the table with the workpiece in the positioning operation and positioning range.

9. Do not apply external force to the dust seal band.

Particularly during the transportation

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LEJS Series
Electric Actuator
Specific Product Precautions 2

Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions and pages 3 to 8 for Electric Actuator Precautions.

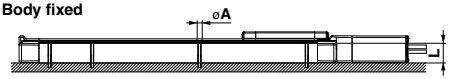
Handling

⚠Caution

10. When mounting the product, use screws with adequate length and tighten them with adequate torque.

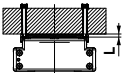
Tightening the screws with a higher torque than recommended may cause a malfunction, whilst the tightening with a lower torque can cause the displacement of the mounting position or in extreme conditions the actuator could become detached from its mounting position.

Body fixed



Model	Screw size	Max. tightening torque [N·m]	ø**A** [mm]	**L** [mm]
LEJS40	M5	3.0	5.5	36.5
LEJS63	M6	5.2	6.8	49.5

Workpiece fixed

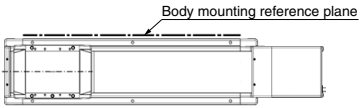


Model	Screw size	Max. tightening torque [N·m]	**L** (Max. screw-in depth) [mm]
LEJS40	M6 x 1	5.2	10
LEJS63	M8 x 1.25	12.5	12

To prevent the workpiece retaining screws from touching the body, use screws that are 0.5 mm or shorter than the maximum screw-in depth. If long screws are used, they can touch the body and cause a malfunction.

11. Do not operate by fixing the table and moving the actuator body.

12. When mounting the actuator using the body mounting reference plane, use a pin. Set the height of the pin to be 5 mm or more because of round chamfering. (Recommended height 6 mm)



Maintenance

⚠Warning

Maintenance frequency

Perform maintenance according to the table below.

Frequency	Appearance check	Internal check
Inspection before daily operation	○	—
Inspection every 6 months/1000 km/5 million cycles*	○	○

* Select whichever comes first.

• Items for visual appearance check

1. Loose set screws, Abnormal dirt
2. Check of flaw and cable joint
3. Vibration, Noise

• Items for internal check

1. Lubricant condition on moving parts.
   * For lubrication, use lithium grease No. 2.
2. Loose or mechanical play in fixed parts or fixing screws.

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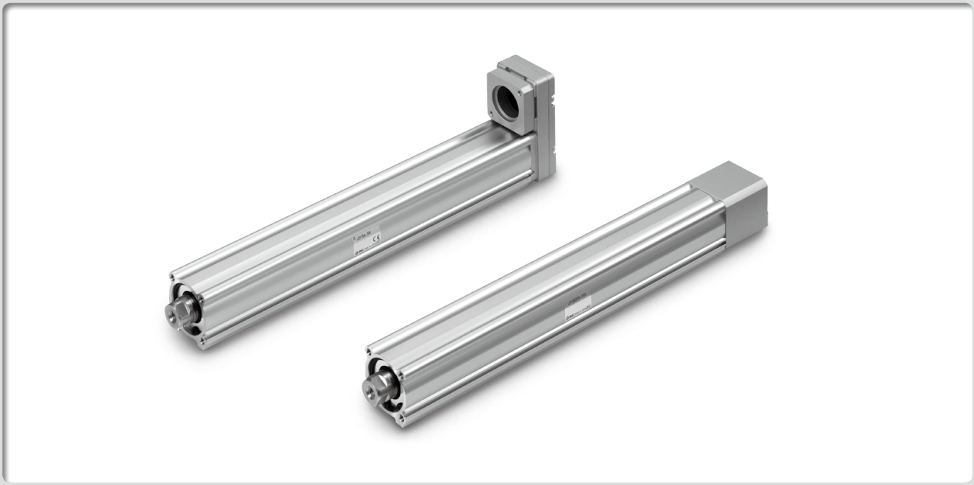
Rod Type *LEY Series*



Guide Rod Type *LEYG Series*

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Motorless Type

Electric Actuator/Rod Type

LEY Series

Model Selection

Size **25, 32, 63**

LEY Series ▶ Page 854

Selection Procedure

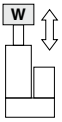
Positioning Control Selection Procedure

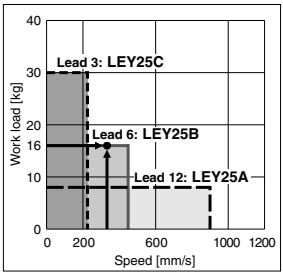
Step 1 Check the work load–speed. (Vertical transfer) → **Step 2** Check the cycle time.

Selection Example

Operating conditions

- Work load: 16 [kg]
- Speed: 300 [mm/s]
- Acceleration/Deceleration: 5000 [mm/s^2]
- Stroke: 300 [mm]
- Workpiece mounting condition: Vertical upward / downward transfer





<Speed–Vertical Work Load Graph> (LEY25)

Step 1 **Check the work load–speed. <Speed–Vertical Work Load Graph>**

Select a model based on the workpiece mass and speed which are within the range of the actuator body specifications with reference to the "Speed–Vertical Work Load Graph" on page 850.

Selection example) The **LEY25B** is temporarily selected based on the graph shown on the right side.

* It is necessary to mount a guide outside the actuator when used for horizontal transfer. When selecting the target model, refer to horizontal work load in the specifications on pages 855 and 856 and, for the precautions.

* Refer to the selection method of motor manufacturers for regeneration resistance.

Step 2 **Check the cycle time.**

Calculate the cycle time using the following calculation method.

- Cycle time T can be found from the following equation.

$$T = T1 + T2 + T3 + T4 \ [s]$$

- T1: Acceleration time and T3: Deceleration time can be obtained by the following equation.

$$T1 = V/a1 \ [s] \qquad T3 = V/a2 \ [s]$$

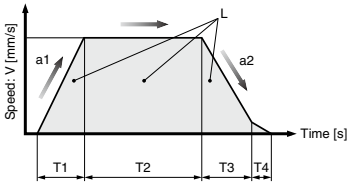
- T2: Constant speed time can be found from the following equation.

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} \ [s]$$

- T4: Settling time varies depending on the motor type and load. The value below is recommended.

$$T4 = 0.05 \ [s]$$

* The conditions for the settling time vary depending on the motor or driver to be used.



L : Stroke [mm] ····· (Operating condition)
V : Speed [mm/s] ····· (Operating condition)
a1: Acceleration [mm/s^2] ··· (Operating condition)
a2: Deceleration [mm/s^2] ··· (Operating condition)

T1: Acceleration time [s] ··· Time until reaching the set speed
T2: Constant speed time [s] ··· Time while the actuator is operating at a constant speed
T3: Deceleration time [s] ··· Time from the beginning of the constant speed operation to stop
T4: Settling time [s] ··· Time until positioning is completed

Calculation example)
T1 to T4 can be calculated as follows.

$T1 = V/a1 = 300/5000 = 0.06$ [s], $T3 = V/a2 = 300/5000 = 0.06$ [s]

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} = \frac{300 - 0.5 \cdot 300 \cdot (0.06 + 0.06)}{300} = 0.94 \ [s]$$

$T4 = 0.05$ [s]

Therefore, the cycle time can be obtained as follows.
$T = T1 + T2 + T3 + T4 = 0.06 + 0.94 + 0.06 + 0.05 =$ **1.11 [s]**

Based on the above calculation result, the LEY25B-300 is selected.

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Selection Procedure

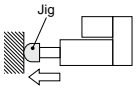
Pushing Control Selection Procedure

Step 1 Check the force. → **Step 2** Check the lateral load on the rod end.

Selection Example

Operating conditions

- Mounting condition: Horizontal (pushing)
- Speed: 100 [mm/s]
- Jig weight: 0.5 [kg]
- Stroke: 300 [mm]
- Force: 255 [N]



Step 1 **Check the force. <Force Conversion Graph>**

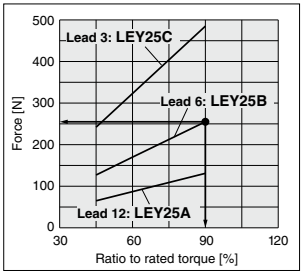
Select the target model based on the "Ratio to rated torque" and force with reference to the "Force Conversion Graph."

Selection example)

Based on the graph shown on the right side,

- Ratio to rated torque: 30 [%]
- Force: 255 [N]

Therefore, the **LEY25B** is temporarily selected.



<Force Conversion Graph>
(LEY25)

Step 2 **Check the lateral load on the rod end.**
<Graph of Allowable Lateral Load on the Rod End>

Confirm the allowable lateral load on the rod end of the actuator: LEY25B, which has been selected temporarily with reference to the "Graph of Allowable Lateral Load on the Rod End."

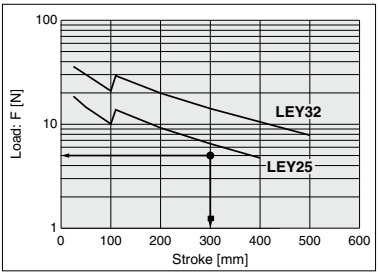
Selection example)

Based on the graph shown on the right side,

- Jig weight: 0.5 [kg] ≈ 5 [N]
- Product stroke: 300 [mm]

Therefore, the lateral load on the rod end is in the allowable range.

Based on the above calculation result, the LEY25B-300 is selected.



<Graph of Allowable Lateral Load on the Rod End>

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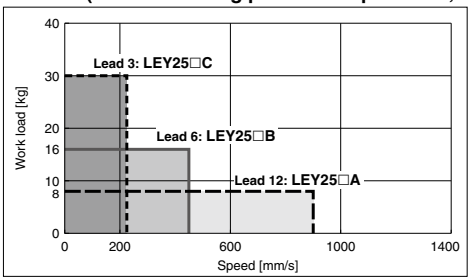
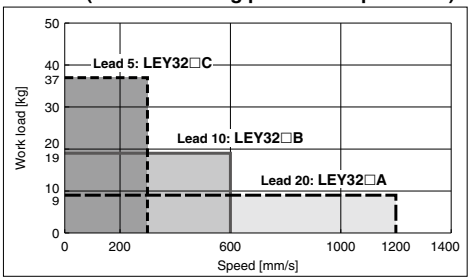
Speed–Vertical Work Load Graph

* The values shown below are allowable values of the actuator body. Do not use the actuator so that it exceeds these specification ranges.
* The allowable speed is restricted depending on the stroke. Select it by referring to the "Allowable Stroke Speed."

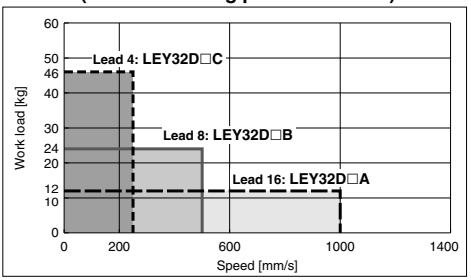
LEY25□ (Motor mounting position: Top/Parallel, In-line)



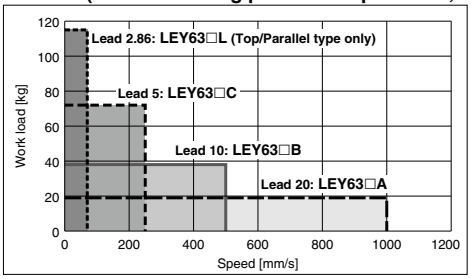
LEY32□ (Motor mounting position: Top/Parallel)



LEY32D (Motor mounting position: In-line)



LEY63□ (Motor mounting position: Top/Parallel, In-line)



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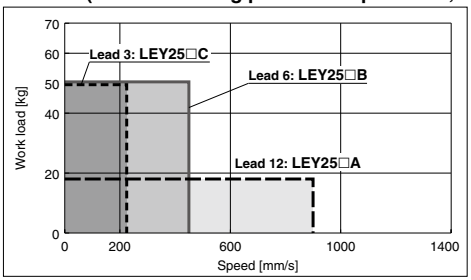
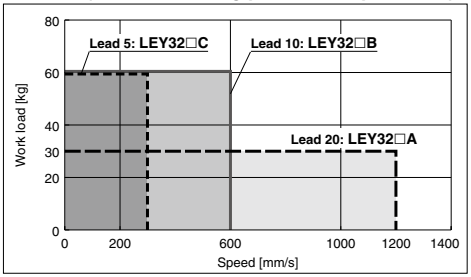
Speed–Horizontal Work Load Graph

* The values shown below are allowable values of the actuator body. Do not use the actuator so that it exceeds these specification ranges.
* The allowable speed is restricted depending on the stroke. Select it by referring to the "Allowable Stroke Speed."

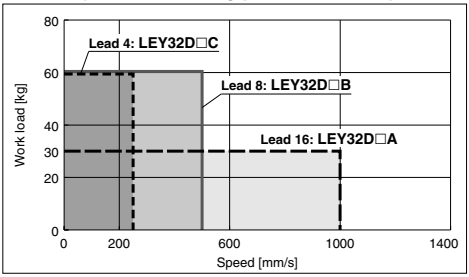
LEY25□ (Motor mounting position: Top/Parallel, In-line)



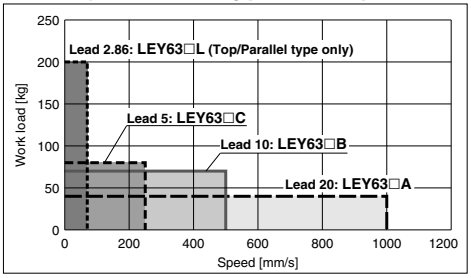
LEY32□ (Motor mounting position: Top/Parallel)



LEY32D (Motor mounting position: In-line)



LEY63□ (Motor mounting position: Top/Parallel, In-line)



Allowable Stroke Speed

[mm/s]

Model	Motor	Lead		Stroke [mm]							
		Symbol	[mm]	Up to 100	Up to 200	Up to 300	Up to 400	Up to 500	Up to 600	Up to 700	Up to 800
LEY25□ (Motor mounting position: Top/Parallel, In-line)	100 W equivalent	**A**	12	900			600	—	—	—	—
		B	6	450			300	—	—	—	—
		C	3	225			150	—	—	—	—
		(Motor rotation speed)		(4500 rpm)			(3000 rpm)	—	—	—	—
LEY32□ (Motor mounting position: Top/Parallel)	200 W equivalent	**A**	20	1200				800	—	—	—
		B	10	600				400	—	—	—
		C	5	300				200	—	—	—
		(Motor rotation speed)		(3600 rpm)				(2400 rpm)	—	—	—
LEY32D (Motor mounting position: In-line)	200 W equivalent	**A**	16	1000				640	—	—	—
		B	8	500				320	—	—	—
		C	4	250				160	—	—	—
		(Motor rotation speed)		(3750 rpm)				(2400 rpm)	—	—	—
LEY63□	400 W equivalent	**A**	20	1000					800	600	500
		B	10	500					400	300	250
		C	5	250					200	150	125
		(Motor rotation speed)		(3000 rpm)					(2400 rpm)	(1800 rpm)	(1500 rpm)
		L	2.86*	70							
		(Motor rotation speed)		(1470 rpm)							

* Equivalent lead which includes the screw lead 5 and the pulley ratio 4:7

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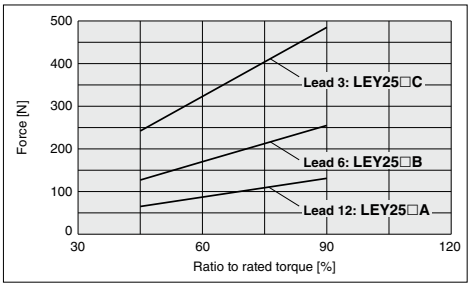
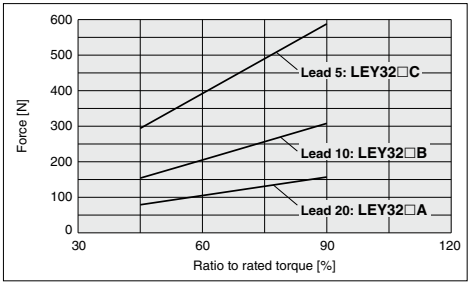
Force Conversion Graph (Guide)

∗ These graphs show an example of when the standard motor is mounted. Calculate the force based on used motor and driver.

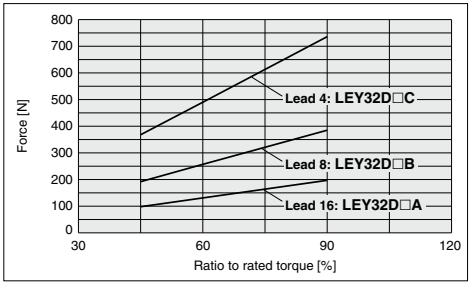
LEY25□ (Motor mounting position: Top/Parallel, In-line)



LEY32□ (Motor mounting position: Top/Parallel)

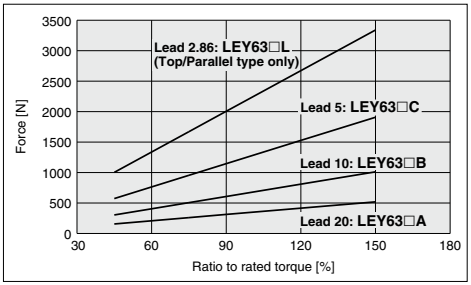


LEY32D□ (Motor mounting position: In-line)

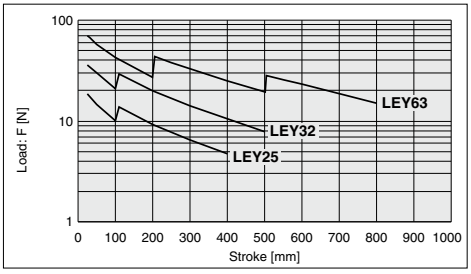


∗ When using the force control or speed control, set the maximum value to be no more than 90% of the rated torque.

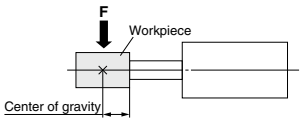
LEY63□ (Motor mounting position: Top/Parallel, In-line)



Graph of Allowable Lateral Load on the Rod End (Guide)



[Stroke] = [Product stroke] + [Distance from the rod end to the center of gravity of the workpiece]



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Motorless Type

Electric Actuator/ Rod Type

LEY Series LEY25, 32, 63

RoHS

How to Order

LEY **H** **25** **□** **NZ** **B** – **500** **□** **□** **□**

❶ ❷ ❸ ❹ ❺ ❻ ❼ ❽ ❾

❶ Accuracy

Nil	Basic type
H	High precision type

❷ Size

25
32
63

❸ Motor mounting position

Nil	Top mounting
R	Right side parallel
L	Left side parallel
D	In-line

❹ Motor type

Symbol	Type
NZ	Mounting type Z
NY	Mounting type Y
NX	Mounting type X
NW	Mounting type W
NV	Mounting type V
NU	Mounting type U
NT	Mounting type T
NM1	Mounting type M1
NM2	Mounting type M2

❺ Lead [mm]

Symbol	LEY25	LEY32	LEY63
A	12	16 (20)	20
B	6	8 (10)	10
C	3	4 (5)	5
L	—	—	2.86*2

*1 The values shown in ( ) are the lead for top mounting, right/left side parallel types. Except motor type NM1. (Equivalent lead which includes the pulley ratio [1.25:1])

*2 Only available for top mounting and right/left side parallel types. (Equivalent lead which includes the pulley ratio [4:7])

❻ Stroke [mm]

30	30
to	to
800	800

* Refer to the applicable stroke table.

❼ Dust-tight/Water-jet-proof <Only available for LEY63>

Symbol	LEY25/32	LEY63
Nil	IP4x equivalent	IP5x equivalent (Dust-protected)
P	—	IP65 equivalent (Dust-tight/Water-jet-proof)/ With vent hole tap

* When using the dust-tight/water-jet-proof (IP65 equivalent), correctly mount the fitting and tubing to the vent hole tap, and then place the end of the tubing in an area not exposed to dust or water.
* The fitting and tubing should be provided separately by user. Select [Applicable tubing O.D.: ø4 or more, Connection thread: Rc1/8].
* Cannot be used in environments exposed to cutting oil etc. Take suitable protective measures.
* For details about enclosure, refer to "Enclosure" on pages 883 and 884.

❽ Rod end thread

Nil	Rod end female thread
M	Rod end male thread (1 rod end nut is included.)

❾ Mounting*1

Symbol	Type	Motor mounting position: Top/Parallel	Motor mounting position: In-line
Nil	Ends tapped/ Body bottom tapped *2	●	●
L	Foot	●	—
F	Rod flange*2	●*4	●
G	Head flange*2	●*5	—
D	Double clevis*3	●	—

*1 Mounting bracket is shipped together, (but not assembled).

*2 For horizontal cantilever mounting with the ends tapped, rod flange and head flange, use the actuator within the following stroke range.
· LEY25: 200 mm or less, LEY32: 100 mm or less, LEY63: 400 mm or less

*3 For mounting with the double clevis, use the actuator within the following stroke range.
· LEY25: 200 mm or less, LEY32: 200 mm or less

*4 If the stroke of the LEY25 is "30 mm or less", the rod flange may interfere with the motor.

*5 Head flange is not applicable to the in-line type and the LEY32/63.

Applicable Stroke Table

●: Standard

Model \ Stroke [mm]	30	50	100	150	200	250	300	350	400	450	500	600	700	800
LEY25	●	●	●	●	●	●	●	●	●	—	—	—	—	—
LEY32	●	●	●	●	●	●	●	●	●	●	●	—	—	—
LEY63	—	●	●	●	●	●	●	●	●	●	●	●	●	●

* Please consult with SMC for non-standard strokes as they are produced as special orders.

For auto switches, refer to pages 880 to 882.

Compatible Motors

Applicable motor model			Size/Motor type																						
			25					32										63							
Manufacturer	Series	Type	NZ Mounting type Z	NY Mounting type Y	NX Mounting type X	NM1 Mounting type M1	NM2 Mounting type M2	NZ Mounting type Z	NY Mounting type Y	NX Mounting type X	NW Mounting type W	NV Mounting type V	NU Mounting type U	NT Mounting type T	NM1 Mounting type M1	NM2 Mounting type M2	NZ Mounting type Z	NY Mounting type Y	NX Mounting type X	NW Mounting type W	NV Mounting type V	NU Mounting type U	NT Mounting type T
Mitsubishi Electric Corporation	MELSERVO-JN	HF-KN	●	—	—	—	—	●	—	—	—	—	—	—	—	—	●	—	—	—	—	—	—
	MELSERVO-J3	KF-KP	●	—	—	—	—	●	—	—	—	—	—	—	—	—	●	—	—	—	—	—	—
	MELSERVO-J4	HG-KR	●	—	—	—	—	●	—	—	—	—	—	—	—	—	●	—	—	—	—	—	—
YASKAWA Electric Corporation	Σ-V	SGMJV	●	—	—	—	—	●	—	—	—	—	—	—	—	—	●	—	—	—	—	—	—
SANYO DENKI CO., LTD.	SANMOTION R	R2	●	—	—	—	—	●	—	—	—	—	—	—	—	—	●	—	—	—	—	—	—
OMRON Corporation	Sysmac G5	R88M-K	●	—	—	—	—	—	●	—	—	—	—	—	—	—	—	●	—	—	—	—	—
Panasonic Corporation	MINAS-A4	MSMD	—	●	—	—	—	—	●	—	—	—	—	—	—	—	—	●	—	—	—	—	—
	MINAS-A5	MSMD/MHMD	—	●	—	—	—	—	●	—	—	—	—	—	—	—	—	●	—	—	—	—	—
FANUC CORPORATION	βis	β	●	—	—	—	—	● (β1 only)	—	—	●	—	—	—	—	—	● (β1 only)	—	—	●	—	—	—
NIDEC SANKYO CORPORATION	S-FLAG	MA/MH/MM	●	—	—	—	—	●	—	—	—	—	—	—	—	—	●	—	—	—	—	—	—
KEYENCE CORPORATION	SV	SV-M/SV-B	●	—	—	—	—	●	—	—	—	—	—	—	—	—	●	—	—	—	—	—	—
FUJI ELECTRIC CO., LTD.	ALPHA5	GYS/GYB	●	—	—	—	—	●	—	—	—	—	—	—	—	—	●	—	—	—	—	—	—
	FALDIC-α	GYS	●	—	—	—	—	●	—	—	—	—	—	—	—	—	●	—	—	—	—	—	—
ORIENTAL MOTOR Co., Ltd.	AR/AZ	AR/AZ (46 only)	—	—	—	—	●	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—
	AR/AZ	AR/AZ	—	—	—	—	—	—	—	—	—	—	—	—	—	●	—	—	—	—	—	—	—
FASTECH Co., Ltd.	Ezi-SERVO	EzM	—	—	—	●	—	—	—	—	—	—	—	—	●	—	—	—	—	—	—	—	—
Rockwell Automation, Inc. (Allen-Bradley)	MP-/VP-	MP/VP	—	—	—	—	—	—	—	●*	—	—	—	—	—	—	—	—	—	●*	—	—	—
	TL	TLY-A	●	—	—	—	—	—	—	—	—	—	●	—	—	—	—	—	—	—	—	—	●
Beckhoff Automation	AM	AM30	●	—	—	—	—	—	—	—	—	●*	—	—	—	—	—	—	—	—	●*	—	—
	AM	AM31	●	—	—	—	—	—	—	—	—	—	●	—	—	—	—	—	—	—	—	●*	—
GmbH	AM	AM80/AM81	●	—	—	—	—	—	—	●*	—	—	—	—	—	—	—	—	●*	—	—	—	—
Siemens AG	1FK7	1FK7	—	—	●	—	—	—	—	●*	—	—	—	—	—	—	—	—	●*	—	—	—	—
Delta Electronics, Inc.	ASDA-A2	ECMA	●	—	—	—	—	●	—	—	—	—	—	—	—	—	●	—	—	—	—	—	—

* Motor mounting position: In-line only

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Specifications

- Values in this specification table are the allowable values of the actuator body with the standard motor mounted.
- Do not use the actuator so that it exceeds these values.

	Model			LEY25 (Top/Parallel) LEY25D (In-line)			LEY32 (Top/Parallel)			LEY32D (In-line)		
Actuator specifications	Stroke [mm] Note 1)			30, 50, 100, 150, 200, 250 300, 350, 400			30, 50, 100, 150, 200, 250 300, 350, 400, 450, 500			30, 50, 100, 150, 200, 250 300, 350, 400, 450, 500		
	Work load [kg] Note 2)		Horizontal	18	50	50	30	60	60	30	60	60
			Vertical	8	16	30	9	19	37	12	24	46
	Force [N] Note 3) (Set value: Rated torque 45 to 90%)			65 to 131	127 to 255	242 to 485	79 to 157	154 to 308	294 to 588	98 to 197	192 to 385	368 to 736
	Max. speed [mm/s] Note 4)	Stroke range	Up to 300	900	450	225	1200	600	300	1000	500	250
			305 to 400	600	300	150						
			405 to 500	—	—	—	800	400	200	640	320	160
	Pushing speed [mm/s] Note 5)			35 or less			30 or less					
	Max. acceleration/deceleration [mm/s²]			5000								
	Positioning repeatability [mm]	Basic type		±0.02								
		High precision type		±0.01								
	Lost motion Note 6) [mm]	Basic type		0.1 or less								
		High precision type		0.05 or less								
	Ball screw specifications	Thread size [mm]		ø10			ø12					
		Lead [mm] (including pulley ratio)		12	6	3	16 (20)	8 (10)	4 (5)	16	8	4
		Shaft length [mm]		Stroke + 93.5			Stroke + 104.5					
	Impact/Vibration resistance [m/s²] Note 7)			50/20								
	Actuation type			Ball screw + Belt (Top/Parallel) Ball screw (In-line)			Ball screw + Belt [Pulley ratio 1.25:1]			Ball screw		
	Guide type			Sliding bushing (Piston rod)								
	Operating temperature range [°C]			5 to 40								
	Operating humidity range [%RH]			90 or less (No condensation)								
Other specifications Note 8)	Actuation unit weight [kg] (∗[ST]: Stroke)			0.15 + (0.69 x 10^{-3}) x [ST]: 100 st or less 0.16 + (0.69 x 10^{-3}) x [ST]: Over 100 st			0.24 + (1.40 x 10^{-3}) x [ST]: 100 st or less 0.28 + (1.40 x 10^{-3}) x [ST]: Over 100 st					
	Other inertia [kg·cm²]			0.012 (LEY25), 0.015 (LEY25D)			0.035 (LEY32), 0.061 (LEY32D)					
	Friction coefficient			0.05								
	Mechanical efficiency			0.8								
Reference motor spec.	Motor shape			□40			□60					
	Motor type			AC servo motor								
	Rated output capacity [W]			100			200					
	Rated torque [N·m]			0.32			0.64					
	Rated rotation [rpm]			3000								

Note 1) Please consult with SMC for non-standard strokes as they are produced as special orders.

Note 2) The maximum value of the horizontal work load. An external guide is necessary to support the load (Friction coefficient of guide: 0.1 or less). The actual work load changes according to the condition of the external guide. Confirm using actual device.

Note 3) The force setting range for the force control (Speed control mode, Torque control mode).
The force changes according to the set value. Set it with reference to the "Force Conversion Graph (Guide)" on page 852.

Note 4) The allowable speed changes according to the stroke.

Note 5) The allowable collision speed for collision with the workpiece.

Note 6) A reference value for correcting an error in reciprocal operation.

Note 7) Impact resistance: No malfunction occurred when the actuator was tested with a drop tester in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the actuator in the initial state.)
Vibration resistance: No malfunction occurred in a test ranging between 45 to 2000 Hz. Test was performed in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the actuator in the initial state.)

Note 8) Each value is a guide. Use such value to select a motor capacity.

Weight

Product Weight

Series	LEY25 (Motor mounting position: Top/Parallel)									LEY32 (Motor mounting position: Top/Parallel)										
Stroke [mm]	30	50	100	150	200	250	300	350	400	30	50	100	150	200	250	300	350	400	450	500
Product weight [kg]	0.8	0.9	1.1	1.3	1.5	1.7	1.8	2.0	2.2	1.4	1.5	1.8	2.3	2.6	2.9	3.1	3.4	3.7	4.0	4.3

Series	LEY25D (Motor mounting position: In-line)									LEY32D (Motor mounting position: In-line)										
Stroke [mm]	30	50	100	150	200	250	300	350	400	30	50	100	150	200	250	300	350	400	450	500
Product weight [kg]	0.8	0.9	1.1	1.3	1.5	1.7	1.9	2.0	2.2	1.4	1.6	1.8	2.3	2.6	2.9	3.2	3.4	3.7	4.0	4.3

Additional Weight

[kg]

Size		25	32
Rod end male thread	Male thread	0.03	0.03
	Nut	0.02	0.02
Foot (2 sets including mounting bolt)		0.08	0.14
Rod flange (including mounting bolt)		0.17	0.20
Head flange (including mounting bolt)			
Double clevis (including pin, retaining ring and mounting bolt)		0.16	0.22

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Specifications

- Values in this specification table are the allowable values of the actuator body with the standard motor mounted.
- Do not use the actuator so that it exceeds these values.

	Model			LEY63D (In-line)			LEY63 (Top/Parallel)			
Actuator specifications	Stroke [mm] Note 1)			50, 100, 150, 200, 250, 300, 350, 400, 450, 500, 600, 700, 800						
	Work load [kg]		Horizontal Note 2)	40	70	80	40	70	80	200
			Vertical	19	38	72	19	38	72	115
	Force [N] Note 3) (Set value: Rated torque 45 to 150%)			156 to 521	304 to 1012	573 to 1910	156 to 521	304 to 1012	573 to 1910	1003 to 3343
	Max. speed [mm/s] Note 4)	Stroke range	Up to 500	1000	500	250	1000	500	250	70
			505 to 600	800	400	200	800	400	200	
			605 to 700	600	300	150	600	300	150	
			705 to 800	500	250	125	500	250	125	
	Pushing speed [mm/s] Note 5)			30 or less						
	Max. acceleration/deceleration [mm/s²]			5000						3000
	Positioning repeatability [mm]		Basic type	±0.02						
			High precision type	±0.01						
	Lost motion Note 6) [mm]		Basic type	0.1 or less						
			High precision type	0.05 or less						
	Ball screw specifications		Thread size [mm]	ø20						
			Lead [mm]	20	10	5	20	10	5	5 (2.86)
			Shaft length [mm]	Stroke + 147						
	Impact/Vibration resistance [m/s²] Note 7)			50/20						
	Actuation type			Ball screw			Ball screw + Belt [Pulley ratio 1:1]			Ball screw + Belt [Pulley ratio 4:7]
	Guide type			Sliding bushing (Piston rod)						
	Operating temperature range [°C]			5 to 40						
	Operating humidity range [%RH]			90 or less (No condensation)						
Other specifications	Actuation unit weight [kg] (※[ST]: Stroke)			0.84 + (2.77 x 10⁻³) x [ST]: 200 st or less 0.94 + (2.77 x 10⁻³) x [ST]: Over 200 st, 500 st or less 1.03 + (2.77 x 10⁻³) x [ST]: Over 500 st						
	Other inertia [kg·cm²]			0.056 (LEY63D)			0.110			0.053
	Friction coefficient			0.05						
Note 8)	Mechanical efficiency			0.8						
Reference motor spec.	Motor shape			□60						
	Motor type			AC servo motor						
	Rated output capacity [W]			400						
	Rated torque [N·m]			1.27						
	Rated rotation [rpm]			3000						

Note 1) Please consult with SMC for non-standard strokes as they are produced as special orders.
Note 2) The maximum value of the horizontal work load. An external guide is necessary to support the load (Friction coefficient of guide: 0.1 or less). The actual work load changes according to the condition of the external guide. Confirm using actual device.
Note 3) The force setting range for the force control (Speed control mode, Torque control mode).
The force changes according to the set value. Set it with reference to the "Force Conversion Graph (Guide)" on page 852.
Note 4) The allowable speed changes according to the stroke.
Note 5) The allowable collision speed for collision with the workpiece.
Note 6) A reference value for correcting an error in reciprocal operation.
Note 7) Impact resistance: No malfunction occurred when the actuator was tested with a drop tester in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the actuator in the initial state.)
Vibration resistance: No malfunction occurred in a test ranging between 45 to 2000 Hz. Test was performed in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the actuator in the initial state.)
Note 8) Each value is a guide. Use such value to select a motor capacity.

Weight

Product Weight

Model	LEY63D (Motor mounting position: In-line)												
Stroke [mm]	50	100	150	200	250	300	350	400	450	500	600	700	800
Product weight [kg]	3.7	4.2	4.8	5.3	6.5	7.0	7.6	8.2	8.8	9.3	11.0	12.1	13.3

Model	LEY63 (Motor mounting position: Top/Parallel)												
Stroke [mm]	50	100	150	200	250	300	350	400	450	500	600	700	800
Product weight [kg]	3.5	4.0	4.7	5.2	6.4	6.9	7.5	8.0	8.6	9.1	10.8	12.0	13.1

Additional Weight

[kg]

Size		63
Rod end male thread	Male thread	0.12
	Nut	0.04
Rod flange (including mounting bolt)		0.51
Foot (2 sets including mounting bolt)		0.26
Double clevis (including pin, retaining ring and mounting bolt)		0.58

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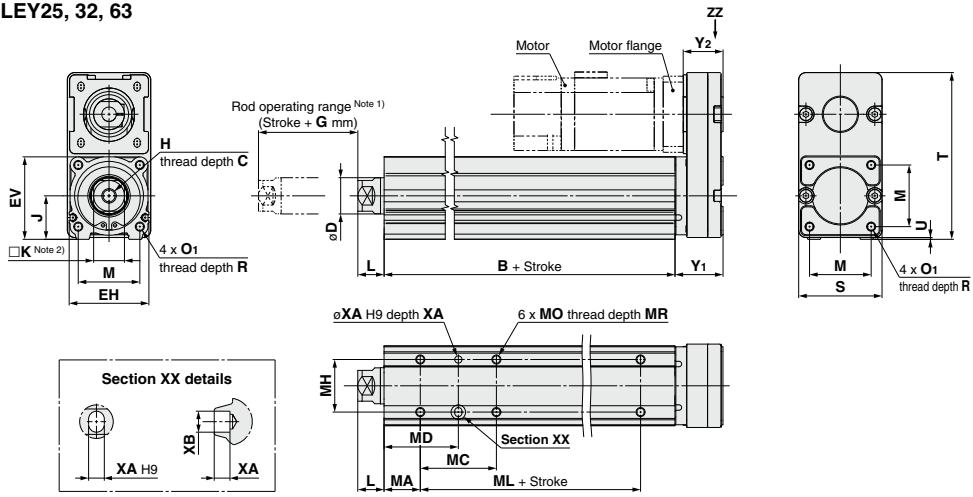
Refer to the "Motor Mounting" on pages 872 and 874 for details about motor mounting and included parts.

Dimensions: Motor Top/Parallel

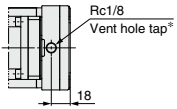
LEY25, 32, 63



Note 1) Do not allow collisions at either end of the rod operating range at a speed exceeding "pushing speed."
Additionally, when running the positioning operation, do not set within 2 mm of both ends for size 25, 32, and do not set within 4 mm of both ends for size 63.

Note 2) The direction of rod end width across flats (□K) differs depending on the products.

IP65 equivalent (Dust-tight/Water-jet-proof): LEY63□□□-□P (View ZZ)



* When using the dust-tight/water-jet-proof (IP65 equivalent), correctly mount the fitting and tubing to the vent hole tap, and then place the end of the tubing in an area not exposed to dust or water. The fitting and tubing should be provided separately by user.
Select [Applicable tubing O.D.: ø4 or more, Connection thread: Rc1/8].

Dimensions

[mm]

Size	Stroke range [mm]	B	C	D	EH	EV	H	J	K	L	M	O1	R	S	T	U	Y1	Y2	G
25	15 to 100	89.5	13	20	44	45.5	M8 x 1.25	24	17	12.5	34	M5 x 0.8	8	46	92	1	26.5	22	4
	105 to 400	114.5																	
32	20 to 100	96	13	25	51	56.5	M8 x 1.25	31	22	16.5	40	M6 x 1.0	10	60	118	1	34	27	4
	105 to 500	126																	
63	Up to 200	123	21	40	76	82	M16 x 2	44	36	33.4	60	M8 x 1.25	16	80	146	4	32.2	29	8
	205 to 500	158																	
	505 to 800	193																	

* The L measurement is when the unit is at the retracted stroke end position.

[mm]

Size	Stroke range [mm]	MA	MC	MD	MH	ML	MO	MR	XA	XB
25	15 to 39	20	24	32	29	50	M5 x 0.8	6.5	4	5
	40 to 100		42	41						
	101 to 124					75				
	125 to 200		59	49.5						
	201 to 400		76	58						
32	20 to 39	25	22	36	30	50	M6 x 1	8.5	5	6
	40 to 100		36	43						
	101 to 124					80				
	125 to 200		53	51.5						
	201 to 500		70	60						
63	50 to 70	38	24	50	44	65	M8 x 1.25	10	6	7
	75 to 120		45	60.5						
	125 to 200		58	67						
	205 to 500		86	81		100				
	505 to 800					135				

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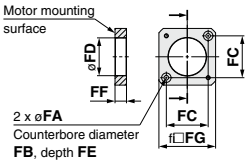
Dimensions: Motor Top/Parallel

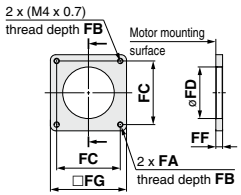
Refer to the "Motor Mounting" on pages 872 and 874 for details about motor mounting and included parts.

Motor flange dimensions

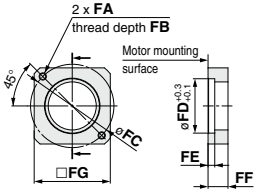
LEY25: NM1, NM2



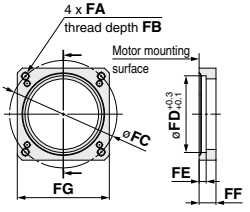
LEY32: NM1, NM2



LEY25: NZ, NY, NX
LEY32: NZ, NY, NW, NU, NT



LEY63: NZ, NY, NW, NT

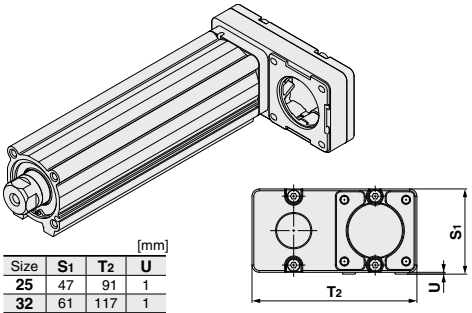


Dimensions

[mm]

Size	Motor type	FA	FB	FC	FD	FE	FF	FG
25	NZ	M4 x 0.7	7.5	46	30	3.7	11	42
	NY	M3 x 0.5	5.5	45	30	5	11	38
	NX	M4 x 0.7	7	46	30	3.7	8	42
	NM1, NM2	ø3.4	7	31	28	3.5	8.5	42
32	NZ, NW, NU	M5 x 0.8	8.5	70	50	4.6	13	60
	NY	M4 x 0.7	7	70	50	4.6	13	60
	NT	M5 x 0.8	8.5	70	50	4.6	17	60
	NM1	M4 x 0.7	(5)	47.1	38.2	—	5	56.4
	NM2	M4 x 0.7	8	50	38.2	—	11.5	60
63	NZ, NW	M5 x 0.8	8.5	70	50	4.6	11	60
	NY	M4 x 0.7	8	70	50	4.6	11	60
	NT	M5 x 0.8	8.5	70	50	4.6	14.5	60

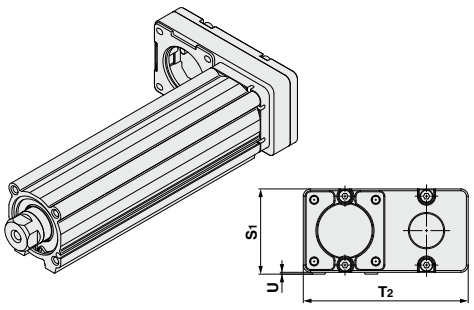
Motor left side parallel type: LEY32L
25
63



[mm]

Size	S_1	T_2	U
25	47	91	1
32	61	117	1
63	84	142	4

Motor right side parallel type: LEY32R
25
63



Note) When the motor is mounted on the left or right side in parallel, the groove for auto switch on the side to which the motor is mounted is hidden.

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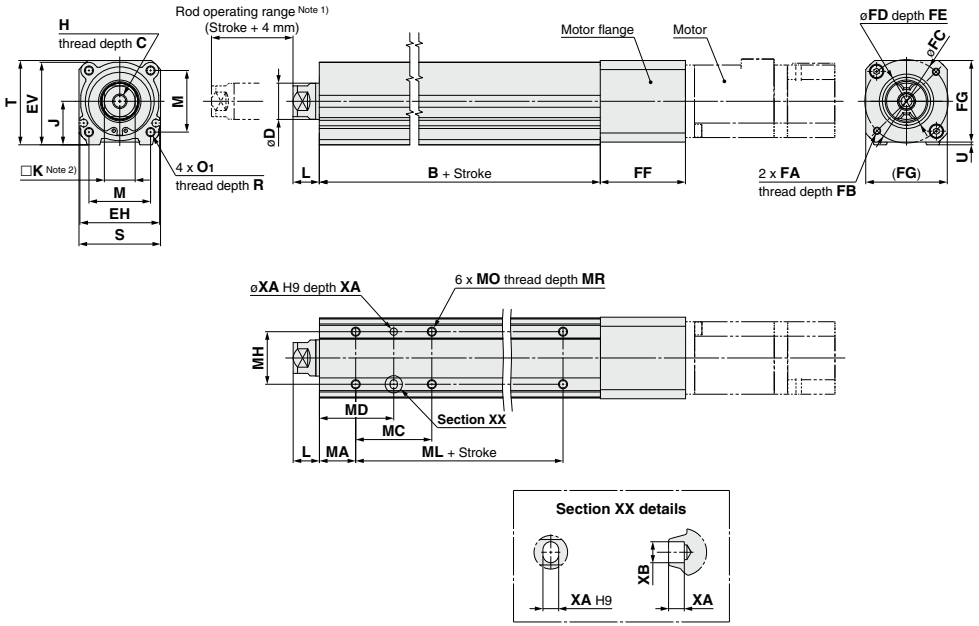
Refer to the "Motor Mounting" on page 873 for details about motor mounting and included parts.

Dimensions: In-line Motor

LEY25, 32



Note 1) Do not allow collisions at either end of the rod operating range at a speed exceeding "pushing speed."
Additionally, when running the positioning operation, do not set within 2 mm of both ends.
Note 2) The direction of rod end width across flats (□K) differs depending on the products.

Dimensions

[mm]

Size	Stroke range [mm]	B	C	D	EH	EV	H	J	K	L	M	O1	R	S	T	U
25	15 to 100	89.5	13	20	44	45.5	M8 x 1.25	24	17	12.5	34	M5 x 0.8	8	45	46.5	1.5
	105 to 400	114.5														
32	20 to 100	96	13	25	51	56.5	M8 x 1.25	31	22	16.5	40	M6 x 1.0	10	60	61	1
	105 to 500	126														

∗ The L measurement is when the unit is at the retracted stroke end position.

[mm]

Size	Stroke range [mm]	MA	MC	MD	MH	ML	MO	MR	XA	XB
25	15 to 35	20	24	32	29	50	M5 x 0.8	6.5	4	5
	40 to 100		42	41						
	105 to 120					75				
	125 to 200		59	49.5						
	205 to 400		76	58						
32	20 to 35	25	22	36	30	50	M6 x 1.0	8.5	5	6
	40 to 100		36	43						
	105 to 120					80				
	125 to 200		53	51.5						
	205 to 500		70	60						

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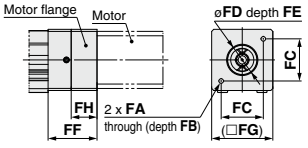
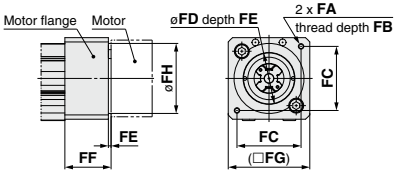
Refer to the "Motor Mounting" on page 873 for details about motor mounting and included parts.

Dimensions: In-line Motor

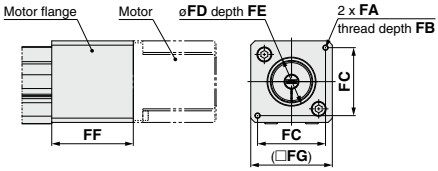
LEY25: NM1, NM2



LEY32: NM1



LEY32: NM2



Dimensions [mm]

Size	Motor type	FA	FB	FC	FD	FE	FF	FG	FH
25	NZ, NX	M4 x 0.7	7.5	46	30	3.7	47	45	—
	NY	M3 x 0.5	6	45	30	4.2	47	45	—
	NM1	ø3.4	17	31	22	2.5	36	45	19
	NM2	ø3.4	28	31	30	3.5	56	45	30
32	NZ, NW, NU, NT	M5 x 0.8	8.5	70	50	3.3	60	60	—
	NY	M4 x 0.7	8	70	50	3.3	60	60	—
	NX	M5 x 0.8	8.5	63	40	3.5	63	60	—
	NV	M4 x 0.7	8	63	40	3.5	63	60	—
	NM1	M4 x 0.7	8	47.14	38.1	2	34	60	51.5
	NM2	M4 x 0.7	8	50	36	3.3	60	60	—

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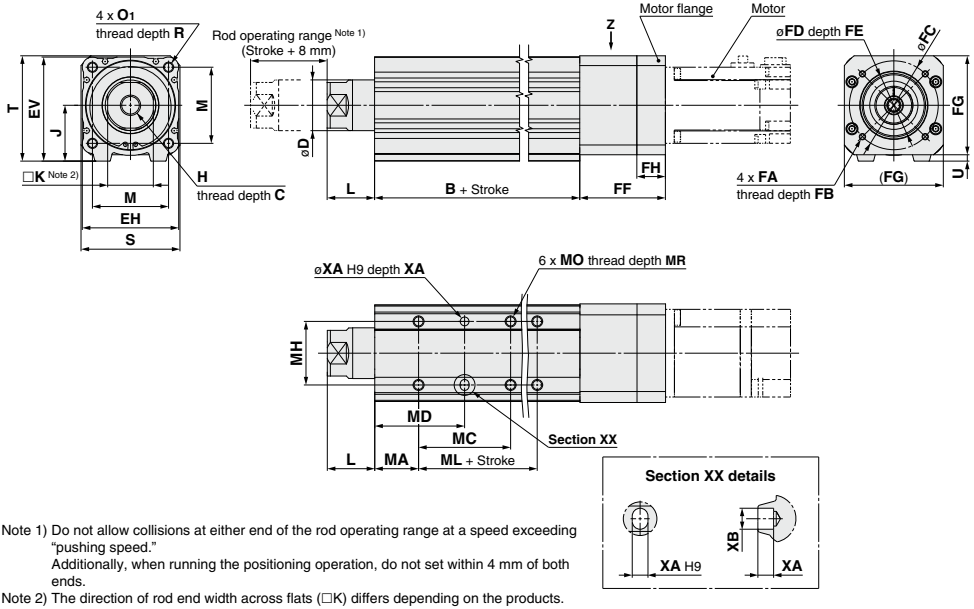
Refer to the "Motor Mounting" on page 875 for details about motor mounting and included parts.

Dimensions: In-line Motor

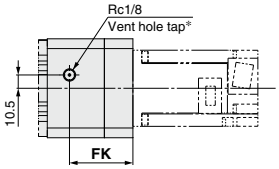
LEY63



Note 1) Do not allow collisions at either end of the rod operating range at a speed exceeding "pushing speed."
Additionally, when running the positioning operation, do not set within 4 mm of both ends.

Note 2) The direction of rod end width across flats (□K) differs depending on the products.

IP65 equivalent (Dust-tight/Water-jet-proof): LEY63DN□□-□P (View Z)



* When using the dust-tight/water-jet-proof (IP65 equivalent), correctly mount the fitting and tubing to the vent hole tap, and then place the end of the tubing in an area not exposed to dust or water. The fitting and tubing should be provided separately by user.
Select [Applicable tubing O.D.: ø4 or more, Connection thread: Rc1/8].

Dimensions

[mm]

Size	Stroke range [mm]	B	C	D	EH	EV	H	J	K	L	M	O1	R	S	T	U
63	50 to 200	123	21	40	76	82	M16 x 2	44	36	33.4	60	M8 x 1.25	16	78	83	5
	205 to 500	158														
	505 to 800	193														

* The L measurement is when the unit is at the retracted stroke end position.

[mm]

Size	Stroke range [mm]	MA	MC	MD	MH	ML	MO	MR	XA	XB
63	50 to 70	38	24	50	44	65	M8 x 1.25	10	6	7
	75 to 120		45	60.5						
	125 to 200		58	67						
	205 to 500		86	81		100				
	505 to 800					135				

Size	Motor type	FA	FB	FC	FD	FE	FF	FG	FH	FK
63	NZ, NW, NU, NT	M5 x 0.8	10	70	50	3.5	67.7	78	22.5	50
	NY	M4 x 0.7	8	70	50	3.5	67.7	78	22.5	50
	NX	M5 x 0.8	10	63	40	3.5	72.7	78	27.5	55
	NV	M4 x 0.7	10	63	40	3.5	72.7	78	27.5	55

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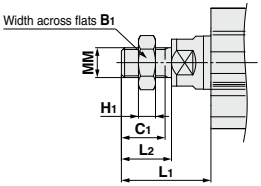
Dimensions

Rod end male thread: LEY 25/32/63 □□B-□□M (A / C)



∗ Refer to the **Web Catalog** or the "Electric Actuators" catalog (CAT.E102) for details about the rod end nut and mounting bracket.
Note) Refer to the precautions on pages 884 and 885 when mounting end brackets such as knuckle joint or workpieces.

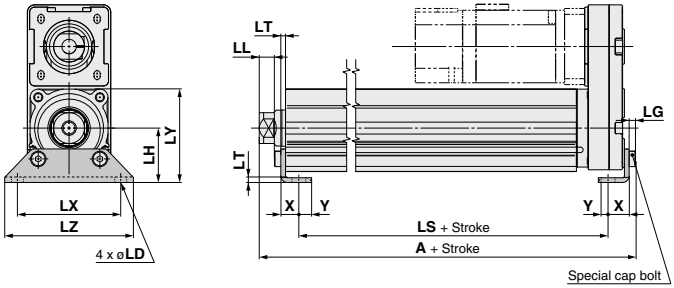
[mm]

Size	B1	C1	H1	L1	L2	MM
25	22	20.5	8	36	23.5	M14 x 1.5
32	22	20.5	8	40	23.5	M14 x 1.5
63	27	26	11	72.4	39	M18 x 1.5

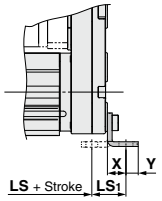
∗ The L1 measurement is when the unit is at the retracted stroke end position.

Foot: LEY 25/32/63 □□B-□□□L (A / C)

Included parts
· Foot
· Body mounting bolt



Outward mounting



Foot

[mm]

Size	Stroke range [mm]	A	LS	LS1	LL	LD	LG	LH	LT	LX	LY	LZ	X	Y
25	15 to 100	134.6	98.8	19.8	6.4	6.6	3.5	30	2.6	57	51.5	71	11.2	5.8
	105 to 400	159.6	123.8											
32	20 to 100	153.7	114	19.2	9.3	6.6	4	36	3.2	76	61.5	90	11.2	7
	105 to 500	183.7	144											
63	50 to 200	196.8	133.2	25.2	25.2	9	5	50	3.2	95	88	110	14.2	8
	205 to 500	231.8	168.2											
	505 to 800	266.8	203.2											

Material: Carbon steel (Chromated)
∗ The A and LL measurements are when the unit is at the retracted stroke end position.
Note) When the motor mounting is the right or left side parallel type, the head side foot should be mounted outward.

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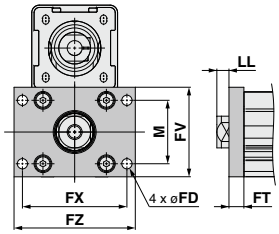
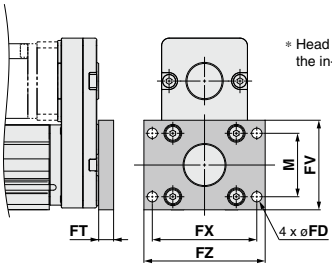
Dimensions

Rod flange: LEY32□□B-□□□F (25, 63: A, C)



Head flange: LEY25□□B-□□□G (A, C)



∗ Head flange is not applicable to the in-line type and the LEY32/63.

Included parts
· Flange
· Body mounting bolt

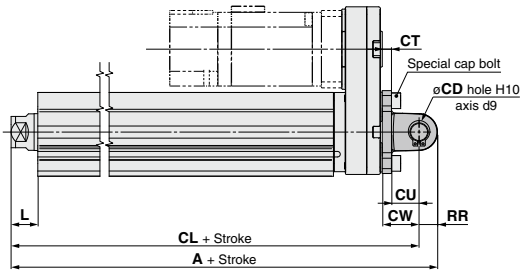
Rod/Head Flange

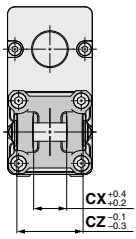
[mm]

Size	FD	FT	FV	FX	FZ	LL	M
25	5.5	8	48	56	65	4.5	34
32	5.5	8	54	62	72	8.5	40
63	9	9	80	92	108	24.4	60

Material: Carbon steel (Nickel plating)
∗ The LL measurement is when the unit is at the retracted stroke end position.

Double clevis: LEY32□□B-□□□D (25, 63: A, C)





Included parts
· Double clevis
· Body mounting bolt
· Clevis pin
· Retaining ring

∗ Refer to the **Web Catalog** or the "Electric Actuators" catalog (CAT.E102) for details about the rod end nut and mounting bracket.

Double Clevis

[mm]

Size	Stroke range [mm]	A	CL	CD	CT	CU	CW	CX	CZ	L	RR
25	15 to 100	158.5	148.5	10	5	14	20	18	36	12.5	10
	105 to 200	183.5	173.5								
32	20 to 100	178.5	168.5	10	6	14	22	18	36	16.5	10
	105 to 200	208.5	198.5								
63	50 to 200	232.6	218.6	14	8	22	30	22	44	33.4	14
	205 to 300	267.6	253.6								

Material: Cast iron (Coating)
∗ The A, CL and L measurements are when the unit is at the retracted stroke end position.

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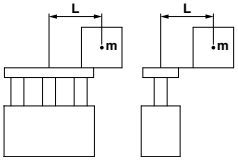
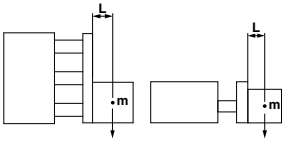
Model Selection

LEYG Series ▶ Page 868

Moment Load Graph

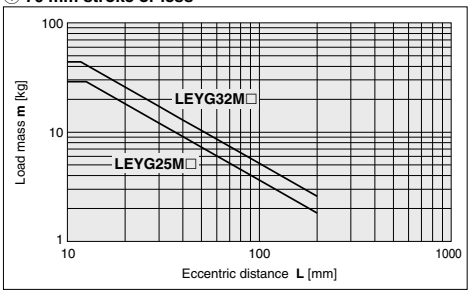
Selection Conditions

	Vertical	Horizontal	
Mounting orientation			
Max. speed [mm/s]	"Speed–Vertical Work Load Graph"	200 or less	Over 200
Graph (Sliding bearing type)	①, ②	⑤, ⑥*	⑦, ⑧
Graph (Ball bushing bearing type)	③, ④	⑨, ⑩	⑪, ⑫

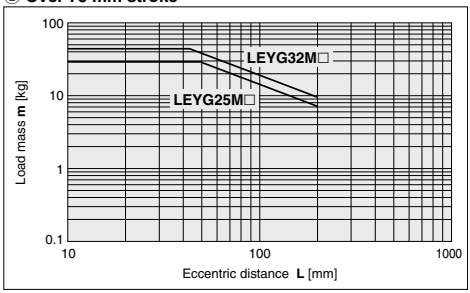
∗ For the sliding bearing type, the speed is restricted with a horizontal/moment load.

Vertical Mounting, Sliding Bearing

① 70 mm stroke or less



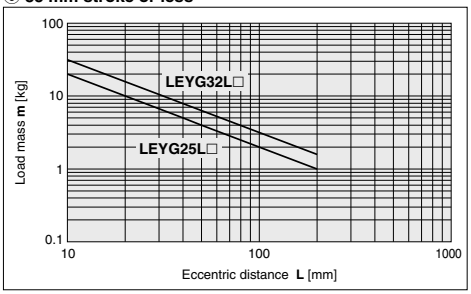
② Over 75 mm stroke



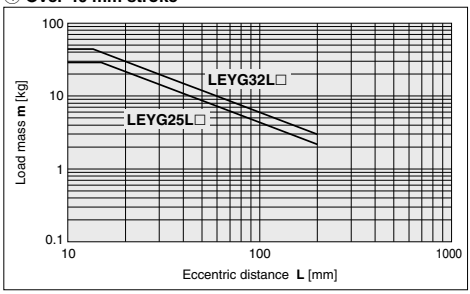
∗ The limit of vertical load mass varies depending on "lead" and "speed." Check the "Speed–Vertical Work Load Graph" on page 866.

Vertical Mounting, Ball Bushing Bearing

③ 35 mm stroke or less



④ Over 40 mm stroke



∗ The limit of vertical load mass varies depending on "lead" and "speed." Check the "Speed–Vertical Work Load Graph" on page 866.

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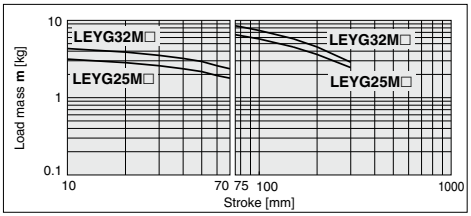
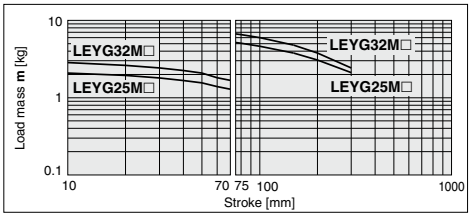
Moment Load Graph

Horizontal Mounting, Sliding Bearing

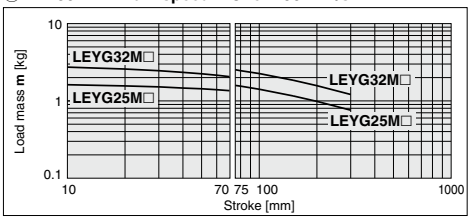
⑤ **L = 50 mm Max. speed = 200 mm/s or less**



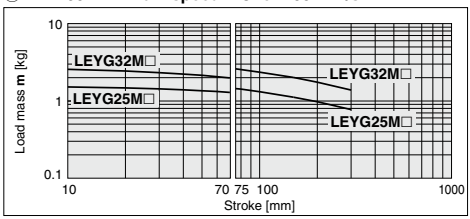
⑥ **L = 100 mm Max. speed = 200 mm/s or less**



⑦ **L = 50 mm Max. speed = Over 200 mm/s**

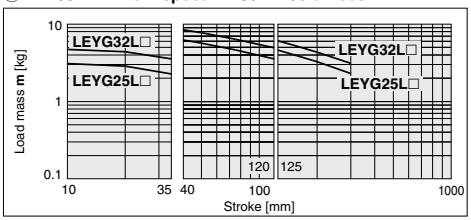


⑧ **L = 100 mm Max. speed = Over 200 mm/s**

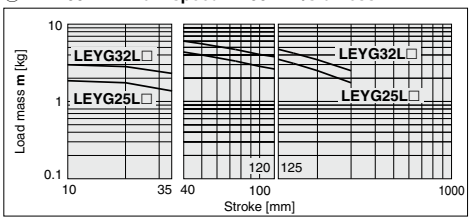


Horizontal Mounting, Ball Bushing Bearing

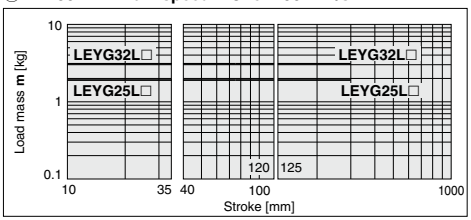
⑨ **L = 50 mm Max. speed = 200 mm/s or less**



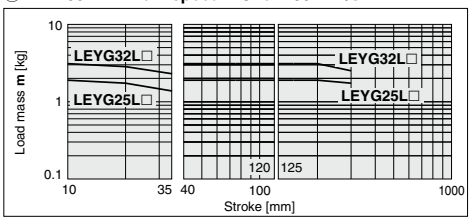
⑩ **L = 100 mm Max. speed = 200 mm/s or less**



⑪ **L = 50 mm Max. speed = Over 200 mm/s**

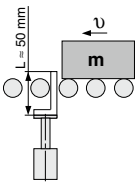


⑫ **L = 100 mm Max. speed = Over 200 mm/s**



Operating Range when Used as Stopper

LEYG□M (Sliding bearing)



⚠Caution

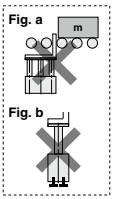
Handling Precautions

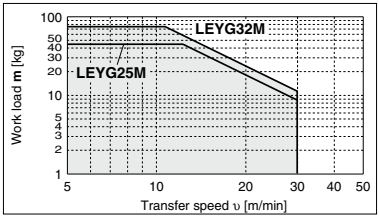
Note 1) When used as a stopper, select a model with 30 mm stroke or less.

Note 2) LEYG□L (ball bushing bearing) cannot be used as a stopper.

Note 3) Workpiece collision in series with guide rod cannot be permitted (**Fig. a**).

Note 4) The body should not be mounted on the end. It must be mounted on the top or bottom (**Fig. b**).





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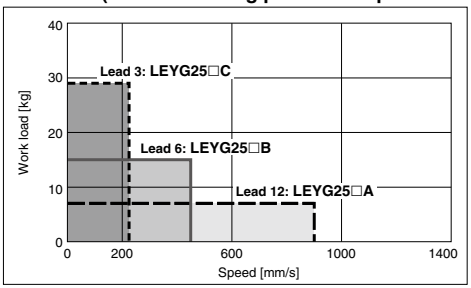
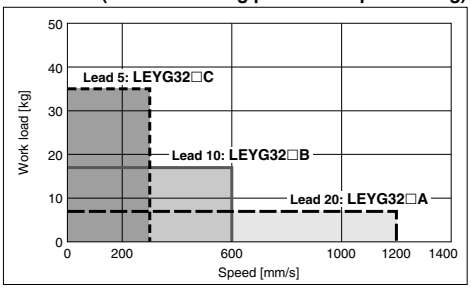
Speed–Vertical Work Load Graph

* These graphs show the work load when the external guide is used together. When using the LEYG alone, refer to pages 864 and 865.
* The values shown below are allowable values of the actuator body. Do not use the actuator so that it exceeds these specification ranges.

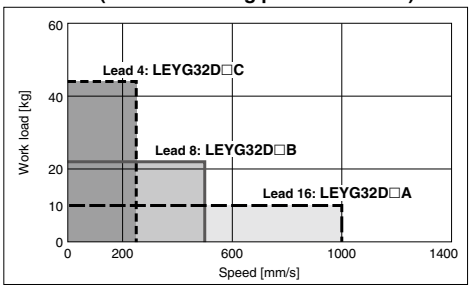
LEYG25□ (Motor mounting position: Top mounting/In-line)



LEYG32□ (Motor mounting position: Top mounting)



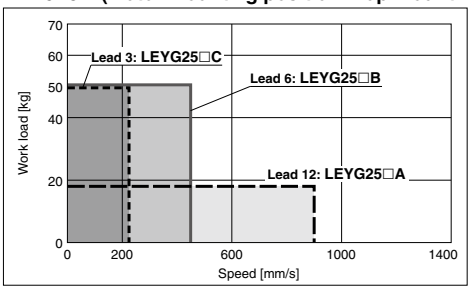
LEYG32D (Motor mounting position: In-line)



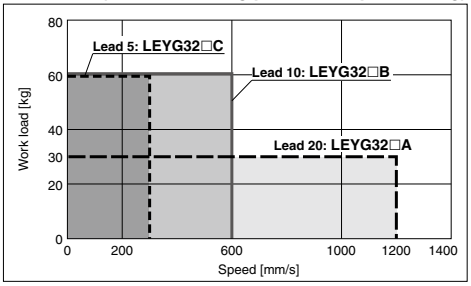
Speed–Horizontal Work Load Graph

* These graphs show the work load when the external guide is used together. When using the LEYG alone, refer to pages 864 and 865.

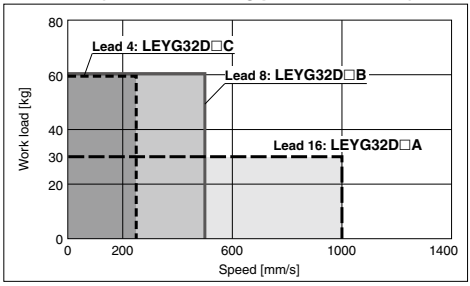
LEYG25□ (Motor mounting position: Top mounting/In-line)



LEYG32□ (Motor mounting position: Top mounting)



LEYG32D (Motor mounting position: In-line)



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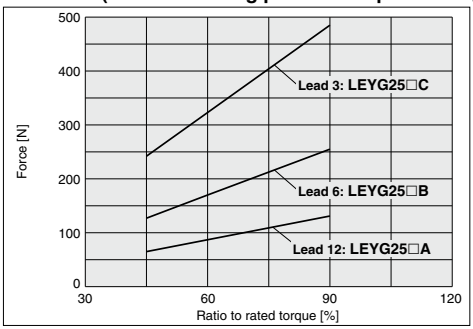
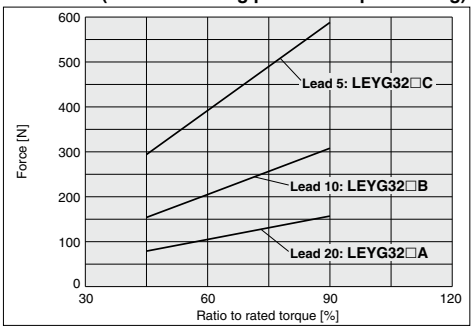
Force Conversion Graph

∗ These graphs show an example of when the standard motor is mounted. Calculate the force based on used motor and driver.

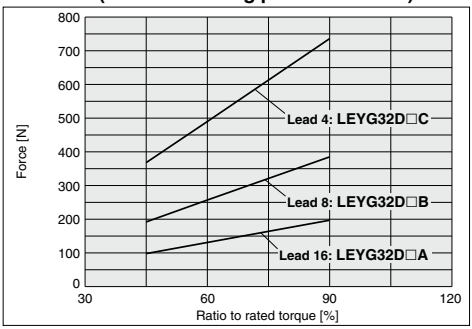
LEYG25□ (Motor mounting position: Top mounting/In-line)



LEYG32□ (Motor mounting position: Top mounting)



LEYG32D (Motor mounting position: In-line)



∗ When using the force control or speed control, set the maximum value to be no more than 90% of the rated torque.

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Motorless Type

Electric Actuator/ Guide Rod Type

LEYG Series LEYG25, 32

RoHS

How to Order

LEY H G 25 M □ NZ B – 200 □

❶ ❷ ❸ ❹ ❺ ❻ ❼ ❽

❶ Accuracy

Nil	Basic type
H	High precision type

❷ Size

25
32

❸ Bearing type

M	Sliding bearing
L	Ball bushing bearing

❹ Motor mounting position

Nil	Top mounting
D	In-line

❺ Motor type

Symbol	Type
NZ	Mounting type Z
NY	Mounting type Y
NX	Mounting type X
NW	Mounting type W
NV	Mounting type V
NU	Mounting type U
NT	Mounting type T
NM1	Mounting type M1
NM2	Mounting type M2

∗ Refer to the "Compatible Motors."

❻ Lead [mm]

Symbol	LEYG25	LEYG32∗
A	12	16 (20)
B	6	8 (10)
C	3	4 (5)

∗ The values shown in ( ) are the lead for size 32 top mounting type. Except motor type NM1. (Equivalent lead which includes the pulley ratio [1.25:1])

❼ Stroke [mm]

30	30
to	to
300	300

∗ Refer to the applicable stroke table.

❽ Guide option

Nil	Without option
F	With grease retaining function

∗ Only available for sliding bearing.

Applicable Stroke Table ●: Standard

Model \ Stroke [mm]	30	50	100	150	200	250	300
LEYG25	●	●	●	●	●	●	●
LEYG32	●	●	●	●	●	●	●

∗ Please consult with SMC for non-standard strokes as they are produced as special orders.

When using auto switch with the guide rod type LEYG series
- Insert the auto switch from the front side with rod (plate) sticking out.
- For the parts hidden behind the guide attachment (Rod stick out side), the auto switch cannot be fixed.
- Please consult with SMC when using auto switch on the rod stick out side, as it is produced as a special order.

For auto switches, refer to pages 880 to 882.

Compatible Motors

Applicable motor model			Size/Motor type													
			25					32								
Manufacturer	Series	Type	NZ Mounting type Z	NY Mounting type Y	NX Mounting type X	NM1 Mounting type M1	NM2 Mounting type M2	NZ Mounting type Z	NY Mounting type Y	NX Mounting type X	NW Mounting type W	NV Mounting type V	NU Mounting type U	NT Mounting type T	NM1 Mounting type M1	NM2 Mounting type M2
Mitsubishi Electric Corporation	MELSERVO-JN	HF-KN	●	—	—	—	—	●	—	—	—	—	—	—	—	—
	MELSERVO-J3	KF-KP	●	—	—	—	—	●	—	—	—	—	—	—	—	—
	MELSERVO-J4	HG-KR	●	—	—	—	—	●	—	—	—	—	—	—	—	—
YASKAWA Electric Corporation	Σ-V	SGMJV	●	—	—	—	—	●	—	—	—	—	—	—	—	—
SANYO DENKI CO., LTD.	SANMOTION R	R2	●	—	—	—	—	●	—	—	—	—	—	—	—	—
OMRON Corporation	Sysmac G5	R88M-K	●	—	—	—	—	—	●	—	—	—	—	—	—	—
Panasonic Corporation	MINAS-A4	MSMD	—	●	—	—	—	—	●	—	—	—	—	—	—	—
	MINAS-A5	MSMD/MHMD	—	●	—	—	—	—	●	—	—	—	—	—	—	—
FANUC CORPORATION	βis	β	●	—	—	—	—	●	—	—	●	—	—	—	—	—
NIDEC SANKYO CORPORATION	S-FLAG	MA/MH/MM	●	—	—	—	—	●	—	—	—	—	—	—	—	—
KEYENCE CORPORATION	SV	SV-M/SV-B	●	—	—	—	—	●	—	—	—	—	—	—	—	—
FUJI ELECTRIC CO., LTD.	ALPHA5	GYS/GYB	●	—	—	—	—	●	—	—	—	—	—	—	—	—
	FALDIC-α	GYS	●	—	—	—	—	●	—	—	—	—	—	—	—	—
ORIENTAL MOTOR Co., Ltd.	AR/AZ	AR/AZ (46 only)	—	—	—	—	●	—	—	—	—	—	—	—	—	—
	AR/AZ	AR/AZ	—	—	—	—	—	—	—	—	—	—	—	—	—	●
FASTECH Co., Ltd.	Ezi-SERVO	EzM	—	—	—	●	—	—	—	—	—	—	—	—	●	—
Rockwell Automation, Inc. (Allen-Bradley)	MP-/VP-	MP/VP	—	—	—	—	—	—	—	●∗	—	—	—	—	—	—
	TL	TLY-A	●	—	—	—	—	—	—	—	—	—	—	●	—	—
Beckhoff Automation GmbH	AM	AM30	●	—	—	—	—	—	—	—	—	●∗	—	—	—	—
	AM	AM31	●	—	—	—	—	—	—	—	—	—	●	—	—	—
	AM	AM80/AM81	●	—	—	—	—	—	—	●∗	—	—	—	—	—	—
Siemens AG	1FK7	1FK7	—	—	●	—	—	—	—	●∗	—	—	—	—	—	—
Delta Electronics, Inc.	ASDA-A2	ECMA	●	—	—	—	—	●	—	—	—	—	—	—	—	—

∗ Motor mounting position: In-line only

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Specifications

- Values in this specification table are the allowable values of the actuator body with the standard motor mounted.
- Do not use the actuator so that it exceeds these values.

Model			LEYG25$^{M}_{L}$ (Top mounting) LEYG25$^{M}_{L}$D (In-line)			LEYG32$^{M}_{L}$ (Top mounting)			LEYG32$^{M}_{L}$D (In-line)		
Actuator specifications	Stroke [mm] Note 1)		30, 50, 100, 150, 200, 250, 300			30, 50, 100, 150, 200, 250, 300			30, 50, 100, 150, 200, 250, 300		
	Work load [kg] Note 2)	Horizontal	18	50	50	30	60	60	30	60	60
		Vertical	7	15	29	7	17	35	10	22	44
	Force [N] Note 3) (Set value: Rated torque 30 to 90%)		65 to 131	127 to 255	242 to 485	79 to 157	154 to 308	294 to 588	98 to 197	192 to 385	368 to 736
	Max. speed [mm/s]		900	450	225	1200	600	300	1000	500	250
	Pushing speed [mm/s] Note 4)		35 or less			30 or less					
	Max. acceleration/deceleration [mm/s^2]		5000								
	Positioning repeatability [mm]	Basic type	±0.02								
		High precision type	±0.01								
	Lost motion Note 5) [mm]	Basic type	0.1 or less								
		High precision type	0.05 or less								
	Ball screw specifications	Thread size [mm]	ø10			ø12					
		Lead [mm] (including pulley ratio)	12	6	3	16 (20)	8 (10)	4 (5)	16	8	4
		Shaft length [mm]	Stroke + 93.5			Stroke + 104.5					
	Impact/Vibration resistance [m/s^2] Note 6)		50/20								
	Actuation type		Ball screw + Belt (LEY□) Ball screw (LEY□D)			Ball screw + Belt [Pulley ratio 1.25:1]			Ball screw		
	Guide type		Sliding bearing (LEYG□M), Ball bushing bearing (LEYG□L)								
	Operating temperature range [°C]		5 to 40								
	Operating humidity range [%RH]		90 or less (No condensation)								
Other specifications	Actuation unit weight [kg] (+[ST]: Stroke)	Sliding bearing LEYG□M	0.29 + (2.20 x 10^{-3}) x [ST]: 185 st or less 0.34 + (1.92 x 10^{-3}) x [ST]: Over 185 st			0.48 + (2.91 x 10^{-3}) x [ST]: 180 st or less 0.55 + (2.62 x 10^{-3}) x [ST]: Over 180 st					
		Ball bushing bearing LEYG□L	0.33 + (1.69 x 10^{-3}) x [ST]: 110 st or less 0.36 + (1.80 x 10^{-3}) x [ST]: Over 110 st			0.50 + (2.40 x 10^{-3}) x [ST]: 110 st or less 0.55 + (2.51 x 10^{-3}) x [ST]: Over 110 st					
	Other inertia [kg·cm^2]		0.012 (LEYG25) 0.015 (LEYG25D)			0.035 (LEYG32)			0.061 (LEYG32D)		
	Friction coefficient		0.05								
Note 7)	Mechanical efficiency		0.8								
Reference motor spec.	Motor shape		□40			□60					
	Motor type		AC servo motor								
	Rated output capacity [W]		100			200					
	Rated torque [N·m]		0.32			0.64					
	Rated rotation [rpm]		3000								

Note 1) Please consult with SMC for non-standard strokes as they are produced as special orders.

Note 2) The maximum value of the horizontal work load. An external guide is necessary to support the load (Friction coefficient of guide: 0.1 or less). The actual work load changes according to the condition of the external guide. Confirm using actual device.

Note 3) The force setting range for the force control (Speed control mode, Torque control mode).
The force changes according to the set value. Set it with reference to the "Force Conversion Graph" on page 867.

Note 4) The allowable collision speed for collision with the workpiece.

Note 5) A reference value for correcting an error in reciprocal operation.

Note 6) Impact resistance: No malfunction occurred when the actuator was tested with a drop tester in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the actuator in the initial state.)
Vibration resistance: No malfunction occurred in a test ranging between 45 to 2000 Hz. Test was performed in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the actuator in the initial state.)

Note 7) Each value is a guide. Use such value to select a motor capacity.

Weight

Product Weight

[kg]

Model	LEYG25$^{M}_{L}$ (Motor mounting position: Top mounting)							LEYG32$^{M}_{L}$ (Motor mounting position: Top mounting)						
Stroke [mm]	30	50	100	150	200	250	300	30	50	100	150	200	250	300
Sliding bearing LEYG□M	1.3	1.5	1.8	2.2	2.6	2.9	3.2	2.2	2.5	3.1	3.8	4.4	4.8	5.3
Ball bushing bearing LEYG□L	1.3	1.5	1.8	2.2	2.5	2.8	3.0	2.2	2.5	2.9	3.6	4.1	4.6	5.0

Model	LEYG25$^{M}_{L}$D (Motor mounting position: In-line)							LEYG32$^{M}_{L}$D (Motor mounting position: In-line)						
Stroke [mm]	30	50	100	150	200	250	300	30	50	100	150	200	250	300
Sliding bearing LEYG□M	1.3	1.5	1.8	2.3	2.6	2.9	3.2	2.3	2.5	3.1	3.8	4.4	4.9	5.3
Ball bushing bearing LEYG□L	1.3	1.6	1.8	2.2	2.5	2.8	3.0	2.3	2.5	2.9	3.7	4.1	4.6	5.0

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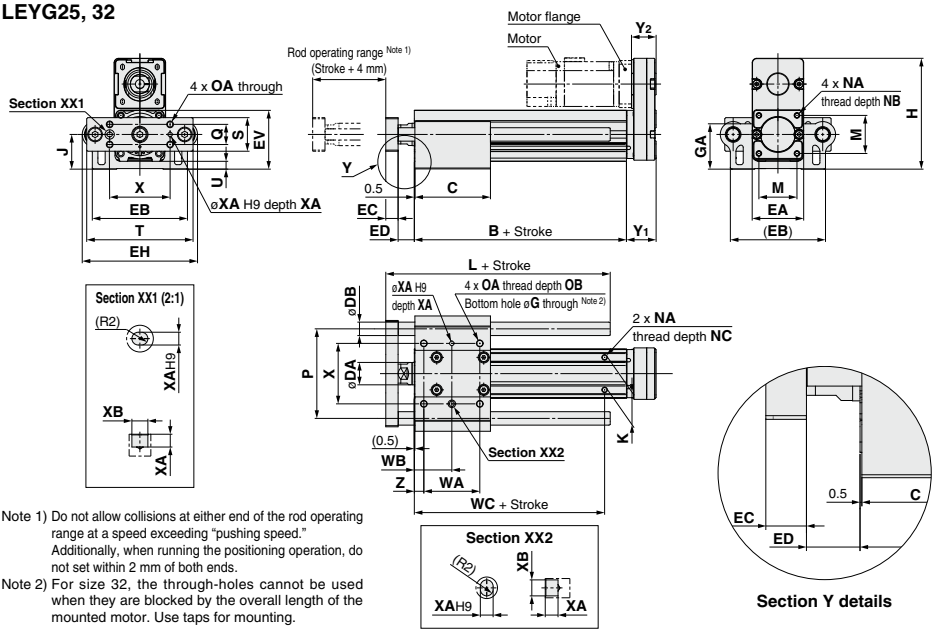
Dimensions: Motor Top Mounting

Refer to the "Motor Mounting" on page 872 for details about motor mounting and included parts.

LEYG25, 32



Section Y details

Note 1) Do not allow collisions at either end of the rod operating range at a speed exceeding "pushing speed." Additionally, when running the positioning operation, do not set within 2 mm of both ends.

Note 2) For size 32, the through-holes cannot be used when they are blocked by the overall length of the mounted motor. Use taps for mounting.

LEYG□L (Ball bushing bearing) [mm]

Size	Stroke range [mm]	L	DB
25	Up to 110	91	10
	115 to 190	115	
	195 to 300	133	
32	Up to 110	97.5	13
	115 to 190	116.5	
	195 to 300	134	

LEYG□M (Sliding bearing) [mm]

Size	Stroke range [mm]	L	DB
25	Up to 55	67.5	12
	60 to 185	100.5	
	190 to 300	138	
32	Up to 55	74	16
	60 to 185	107	
	190 to 300	144	

∗ Refer to page 872 for the dimensions of motor flange.

LEYG□M, LEYG□L Common [mm]

Size	Stroke range [mm]	B	C	DA	EA	EB	EH	EV	EC	ED	G	GA	H	J	K	M	NA	NB
25	Up to 35	89.5	50	20	46	85	103	52.3	11	12.5	5.4	40.3	98.8	30.8	29	34	M5 x 0.8	8
	40 to 100		67.5															
	105 to 120																	
	125 to 200	114.5	84.5															
	205 to 300		102															
32	Up to 35	96	55	25	60	101	123	63.8	12	16.5	5.4	50.3	125.3	38.3	30	40	M6 x 1.0	10
	40 to 100		68															
	105 to 120																	
	125 to 200	126	85															
	205 to 300		102															

Size	Stroke range [mm]	NC	OA	OB	P	Q	S	T	U	WA	WB	WC	X	XA	XB	Y_1	Y_2	Z
25	Up to 35	6.5	M6 x 1.0	12	80	18	30	95	6.8	35	26	70	54	4	5	26.5	22	8.5
	40 to 100									50	33.5							
	105 to 120																	
	125 to 200									70	43.5	95						
	205 to 300									85	51							
32	Up to 35	8.5	M6 x 1.0	12	95	28	40	117	7.3	40	28.5	75	64	5	6	34	27	8.5
	40 to 100									50	33.5							
	105 to 120																	
	125 to 200									70	43.5	105						
	205 to 300									85	51							

∗ The ED measurement is when the unit is at the retracted stroke end position.

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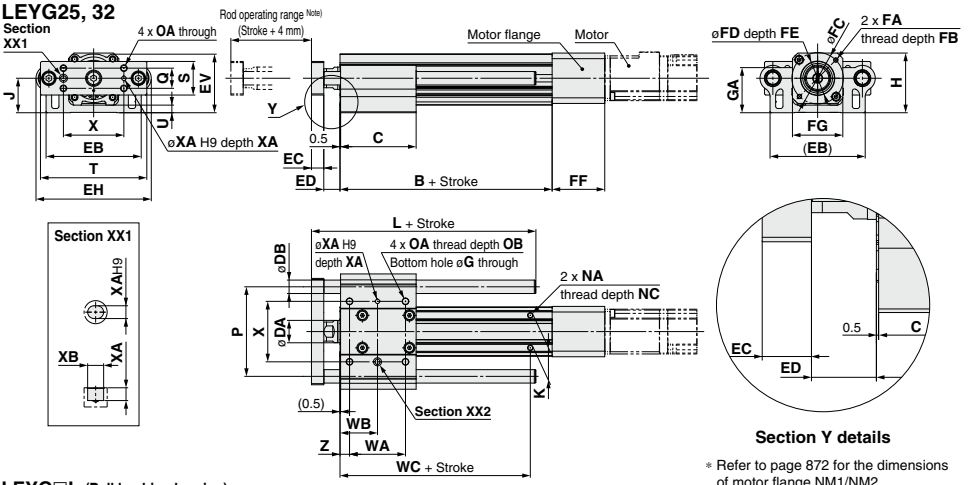
Refer to the "Motor Mounting" on page 873 for details about motor mounting and included parts.

Dimensions: In-line Motor

LEYG25, 32



∗ Refer to page 872 for the dimensions of motor flange NM1/NM2.

Note) Do not allow collisions at either end of the rod operating range at a speed exceeding "pushing speed." Additionally, when running the positioning operation, do not set within 2 mm of both ends.

LEYG□L (Ball bushing bearing) [mm]

Size	Stroke range [mm]	L	DB
25	Up to 114	91	10
	115 to 190	115	
	191 to 300	133	
32	Up to 114	97.5	13
	115 to 190	116.5	
	191 to 300	134	

LEYG□M (Sliding bearing) [mm]

Size	Stroke range [mm]	L	DB
25	Up to 55	67.5	12
	60 to 185	100.5	
	190 to 300	138	
32	Up to 55	74	16
	60 to 185	107	
	190 to 300	144	

Dimensions [mm]

Size	Motor type	FA	FB	FC	FD	FE	FF	FG	FH
25	NZ, NX	M4 x 0.7	7.5	46	30	3.7	47	45	—
	NY	M3 x 0.5	6	45	30	4.2	47	45	—
	NM1	ø3.4	17	31	22	2.5	36	45	19
	NM2	ø3.4	28	31	30	3.5	56	45	30
32	NZ, NW, NU, NT	M5 x 0.8	8.5	70	50	3.3	60	60	—
	NY	M4 x 0.7	8	70	50	3.3	60	60	—
	NX	M5 x 0.8	8.5	63	40	3.5	63	60	—
	NV	M4 x 0.7	8	63	40	3.5	63	60	—
	NM1	M4 x 0.7	8	47.14	38.1	2	34	60	51.5
	NM2	M4 x 0.7	8	50	36	3.3	60	60	—

LEYG□M, LEYG□L Common [mm]

Size	Stroke range [mm]	B	C	DA	EB	EH	EV	EC	ED	G	GA	H	J	K	NA
25	Up to 35	89.5	50	20	85	103	52.3	11	12.5	5.4	40.3	53.3	30.8	29	M5 x 0.8
	40 to 100		67.5												
	105 to 120														
	125 to 200	114.5	84.5												
	205 to 300		102												
32	Up to 35	96	55	25	101	123	63.8	12	16.5	5.4	50.3	68.3	38.3	30	M6 x 1.0
	40 to 100		68												
	105 to 120														
	125 to 200	126	85												
	205 to 300		102												

Size	Stroke range [mm]	NC	OA	OB	P	Q	S	T	U	WA	WB	WC	X	XA	XB	Z
25	Up to 35	6.5	M6 x 1.0	12	80	18	30	95	6.8	35	26	70	54	4	5	8.5
	40 to 100									50	33.5					
	105 to 120											95				
	125 to 200									70	43.5					
	205 to 300									85	51					
32	Up to 35	8.5	M6 x 1.0	12	95	28	40	117	7.3	40	28.5	75	64	5	6	8.5
	40 to 100									50	33.5					
	105 to 120											105				
	125 to 200									70	43.5					
	205 to 300									85	51					

∗ The ED measurement is when the unit is at the retracted stroke end position.

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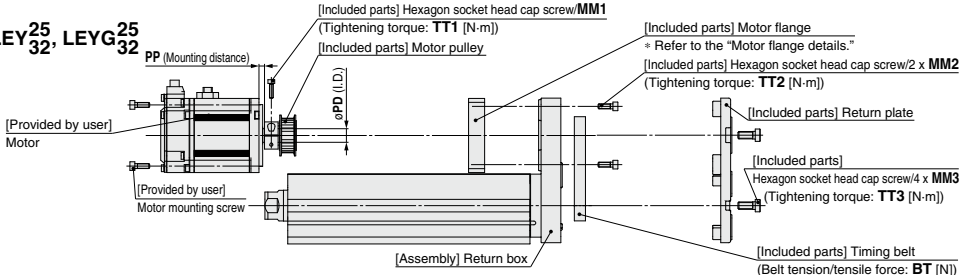
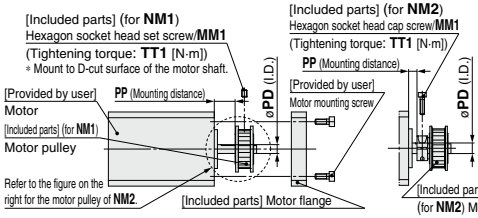
- The motor and motor mounting screws should be provided by user.
- Motor shaft type should be cylindrical for the NZ, NY, NW, NM2 motor types, and D-cut type for the NM1 motor type.
- When mounting a pulley, remove the oil content, dust, or dirt sticking to the shaft and pulley inside diameter.
- Take loose prevention measures for the motor mounting screws and hexagon socket head set screws.

Motor Mounting: Top/Parallel

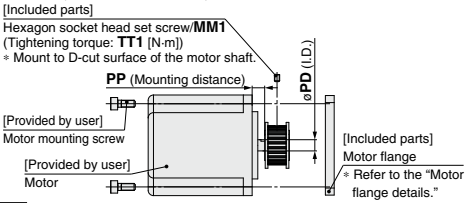
LEY$^{25}_{32}$, LEYG$^{25}_{32}$



LEY25, LEYG25: NM1, NM2

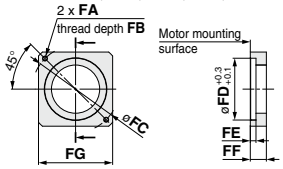


LEY32, LEYG32: NM1, NM2

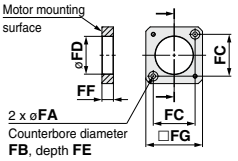


Motor flange details

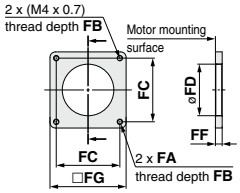
LEY25: NZ, NY, NX
LEY32: NZ, NY, NW, NU, NT



LEY25: NM1, NM2



LEY32: NM1, NM2



Dimensions

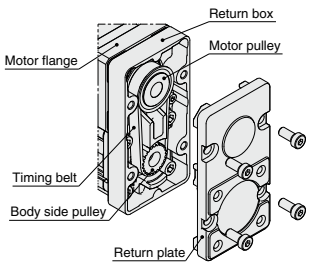
[mm]

Size	Motor type	MM1	TT1	MM2	TT2	MM3	TT3	PD	PP	BT	FA	FB	FC	FD	FE	FF	FG
25	NZ	M2.5 x 10	1.0	M3 x 8	0.63	M4 x 10	1.5	8	7.5	19	M4 x 0.7	7.5	46	30	3.7	11	42
	NY	M2.5 x 10	1.0	M3 x 8	0.63	M4 x 10	1.5	8	7.5	19	M3 x 0.5	5.5	45	30	5	11	38
	NX	M2.5 x 10	1.0	M3 x 8	0.63	M4 x 10	1.5	8	4.5	19	M4 x 0.7	7.5	46	30	3.7	11	42
	NM1	M3 x 5	0.63	M3 x 8	0.63	M4 x 10	1.5	5	11.8	19	ø3.4	7.0	31	28	3.5	8.5	42
	NM2	M2.5 x 10	1.0	M3 x 8	0.63	M4 x 10	1.5	6	48	19	ø3.4	7.0	31	28	3.5	8.5	42
32	NZ	M3 x 12	1.5	M4 x 12	1.5	M6 x 14	5.2	14	4.5	30	M5 x 0.8	8.5	70	50	4.6	13	60
	NY	M3 x 12	1.5	M4 x 12	1.5	M6 x 14	5.2	11	4.5	30	M4 x 0.7	7	70	50	4.6	13	60
	NW	M4 x 12	3.6	M4 x 12	1.5	M6 x 14	5.2	9	4.5	30	M5 x 0.8	8.5	70	50	4.6	13	60
	NU	M3 x 12	1.5	M4 x 12	1.5	M6 x 14	5.2	11	4.5	30	M5 x 0.8	8.5	70	50	4.6	13	60
	NT	M3 x 12	1.5	M4 x 12	1.5	M6 x 14	5.2	12	8.5	30	M5 x 0.8	8.5	70	50	4.6	17	60
	NM1	M3 x 5	0.63	M4 x 12	1.5	M6 x 14	5.2	6.35	8	30	M4 x 0.7	(5)	47.1	38.2	—	5	56.4
	NM2	M3 x 12	1.5	M4 x 12	1.5	M6 x 14	5.2	10	12	30	M4 x 0.7	8	50	38.2	—	11.5	60

Motor Mounting Diagram

Mounting procedure

1) Fix the motor (provided by user) and the "motor pulley" with the "MM1 hexagon socket head cap screw or hexagon socket head set screw."
2) Fix the motor and the "motor flange" with the motor mounting screws (provided by user).
3) Put the "timing belt" on the "motor pulley" and "body side pulley", and then fix it temporarily with the "MM2 hexagon socket head cap screws." (Refer to the mounting diagram.)
4) Apply the belt tension and tighten the timing belt with the "MM2 hexagon socket head cap screws." (The reference level is the elimination of the belt deflection.)
5) Fix the "return plate" with the "MM3 hexagon socket head cap screws."



Included Parts List

Size: 25, 32

Description	Quantity	
	Motor type	
	NZ, NY, NW, NT, NM2	NM1
Motor flange	1	1
Motor pulley	1	1
Return plate	1	1
Timing belt	1	1
Hexagon socket head cap screw (for return plate mounting)	4	4
Hexagon socket head cap screw (for motor flange mounting)	2	2
Hexagon socket head cap screw (for pulley fixing)	1	—
Hexagon socket head set screw (for pulley fixing)	—	1

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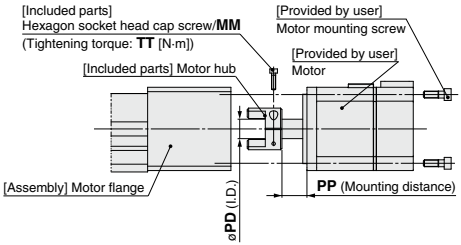
- The motor and motor mounting screws should be provided by user.
- Motor shaft type should be cylindrical for the NZ, NY, NX, NW, NM2 motor types, and D-cut type for the NM1 motor type.
- When mounting a hub, remove the oil content, dust, or dirt sticking to the shaft and hub inside diameter.
- Take loose prevention measures for the motor mounting screws and hexagon socket head set screws.

Motor Mounting: In-line

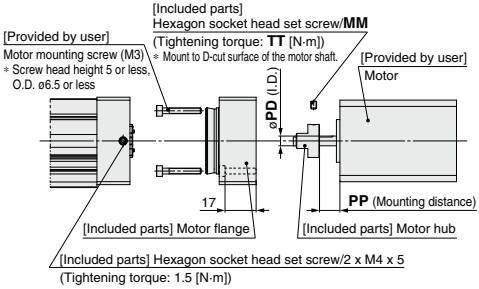
LEY$^{25}_{32}$D, LEYG$^{25}_{32}$□D



Mounting procedure

1) Fix the motor (provided by user) and the "motor hub" with the "MM hexagon socket head cap screw."
2) Check the "motor hub" position, and then insert it. (Refer to the mounting diagram.)
3) Fix the motor and the "motor flange" with the motor mounting screws (provided by user).

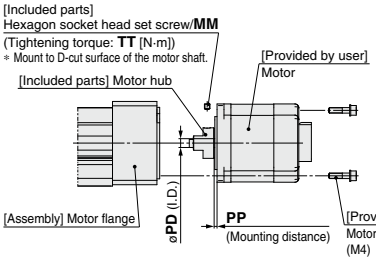
LEY25D, LEYG25□D: NM1



Mounting procedure

1) Fix the motor (provided by user) and the "motor hub" with the M3 x 4 hexagon socket head set screw.
2) Fix the motor and the "motor flange" with the motor mounting screws (provided by user).
3) Check the "motor hub position", and then insert it. (Refer to the mounting diagram.)
4) Fix the "motor flange" with the "M4 x 5 hexagon socket head set screws."

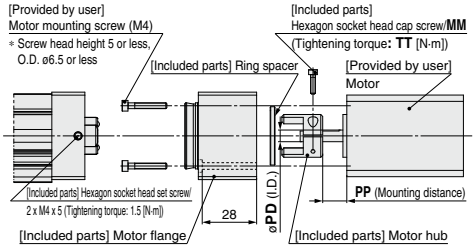
LEY32D, LEYG32□D: NM1



Mounting procedure

1) Fix the motor (provided by user) and the motor hub with the "MM hexagon socket head set screw."
2) Check the "motor hub" position, and then insert it. (Refer to the mounting diagram.)
3) Fix the motor and the "motor block" with the motor mounting screws (provided by user).

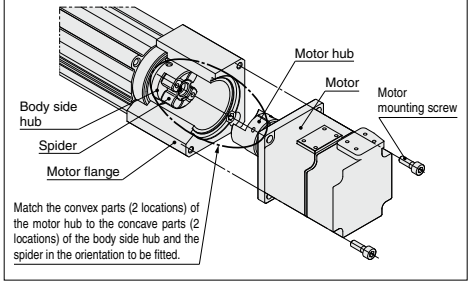
LEY25D, LEYG25□D: NM2



Mounting procedure

1) Insert the "ring spacer" into the motor (provided by user).
2) Fix the motor (provided by user) and the "motor hub" with the M2.5 x 10 hexagon socket head cap screw.
3) Fix the motor and the "motor flange" with the motor mounting screws (provided by user).
4) Check the "motor hub" position, and then insert it. (Refer to the mounting diagram.)
5) Fix the "motor flange" with the "M4 x 5 hexagon socket head set screws."

Motor Mounting Diagram



Dimensions

[mm]

Size	Motor type	MM	TT	PD	PP
25	NZ	M2.5 x 10	1.0	8	12.5
	NY	M2.5 x 10	1.0	8	12.5
	NX	M2.5 x 10	1.0	8	7
	NM1	M3 x 5	0.63	5	10.5
	NM2	M2.5 x 10	1.0	6	12.4
32	NZ	M3 x 12	1.5	14	18
	NY	M4 x 12	3.6	11	18
	NX	M4 x 12	3.6	9	5
	NW	M4 x 12	3.6	9	12
	NV	M4 x 12	3.6	9	5
	NU	M4 x 12	3.6	11	12
	NT	M3 x 12	1.5	12	18
	NM1	M4 x 5	1.5	6.35	2.1
	NM2	M4 x 12	3.6	10	3

Included Parts List

Size: 25

Description	Quantity: Motor type NZ, NY, NX	NM1	NM2
Motor hub	1	1	1
Hexagon socket head cap screw (for hub fixing)	1	—	1
Motor flange	—	1	1
Hexagon socket head set screw (for hub fixing)	—	1	—
Hexagon socket head set screw (for motor flange fixing)		2	2
Ring spacer	—	—	1

Size: 32

Description	Quantity: Motor type NZ, NY, NX, NW, NV, NU, NT, NM2	NM1
Motor hub	1	1
Hexagon socket head cap screw (for hub fixing)	1	—
Hexagon socket head set screw (for hub fixing)	—	1

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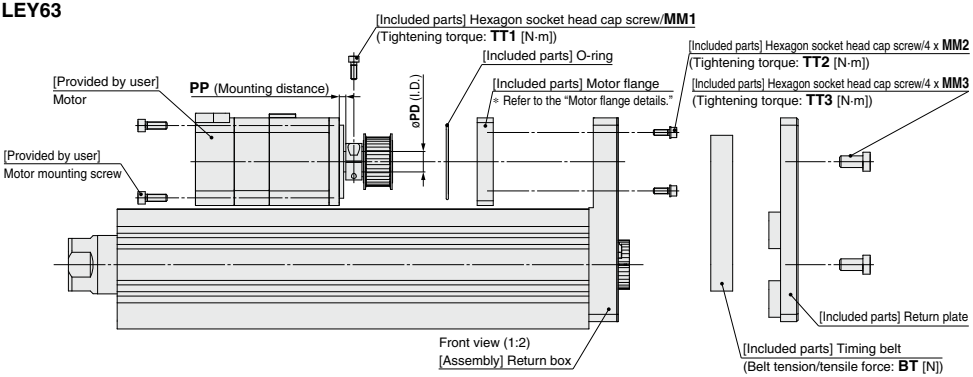
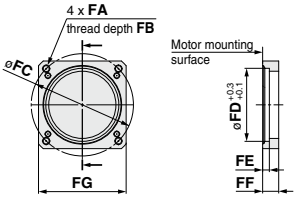
Motor Mounting: Top/Parallel

LEY63

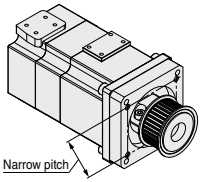


Motor flange details

LEY63: NZ, NY, NW, NT



⚠ **Be careful about the motor flange mounting direction.**



Dimensions

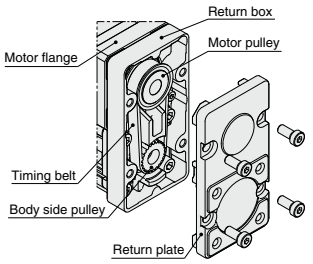
[mm]

Motor type	MM1	TT1	MM2	TT2	MM3	TT3	PD	PP	BT	FA	FB	FC	FD	FE	FF	FG
NZ	M4 x 12	3.6	M4 x 12	2.7	M8 x 16	12.5	14	4.5	98	M5 x 0.8	8.5	70	50	4.6	11	60
NY	M4 x 12	3.6	M4 x 12	2.7	M8 x 16	12.5	14	4.5	98	M4 x 0.7	8	70	50	4.6	11	60
NW	M4 x 12	3.6	M4 x 12	2.7	M8 x 16	12.5	9	4.5	98	M5 x 0.8	8.5	70	50	4.6	11	60
NT	M4 x 12	3.6	M4 x 12	2.7	M8 x 16	12.5	12	8	98	M5 x 0.8	8.5	70	50	4.6	14.5	60

Motor Mounting Diagram

Mounting procedure

1) Fix the motor (provided by user) and the "motor pulley" with the "MM1 hexagon socket head cap screw."
2) Fix the motor and the "motor flange" with the motor mounting screws (provided by user).
3) Put the "timing belt" on the "motor pulley" and "body side pulley", and then fix it temporarily with the "MM2 hexagon socket head cap screws." (Refer to the mounting diagram.)
4) Apply the belt tension and tighten the timing belt with the "MM2 hexagon socket head cap screws." (The reference level is the elimination of the belt deflection.)
5) Fix the "return plate" with the "MM3 hexagon socket head cap screws."



Included Parts List

Size: 63

Description	Quantity Motor type **NZ, NY, NW, NT**
Motor flange	1
Motor pulley	1
Return plate	1
Timing belt	1
Hexagon socket head cap screw (for return plate mounting)	4
Hexagon socket head cap screw (for motor flange mounting)	4
Hexagon socket head cap screw (for pulley fixing)	1
O-ring	1

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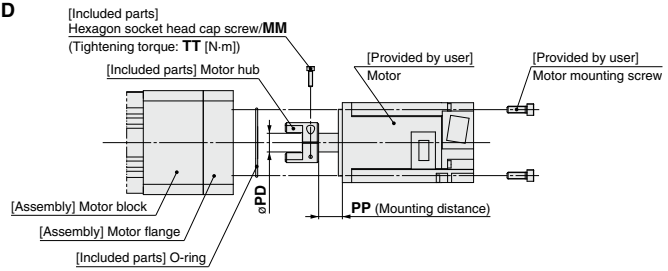
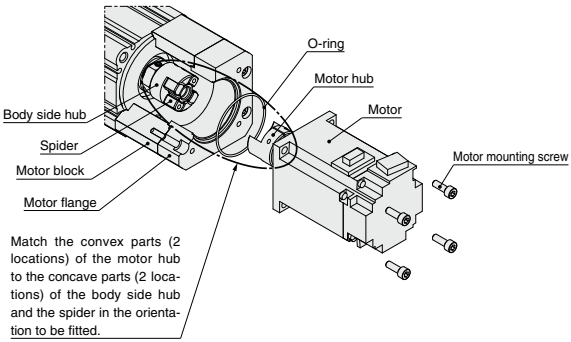
Motor Mounting: In-line

- The motor and motor mounting screws should be provided by user.
- For the shaft-end shape of the motor, prepare the round type.
- When mounting a hub, remove the oil content, dust, or dirt sticking to the shaft and hub inside diameter.
- Take loose prevention measures for the motor mounting screws.

LEY63D



Motor Mounting Diagram



Mounting procedure

1) Fix the motor (provided by user) and the "motor hub" with the "MM hexagon socket head cap screw."
2) Put the "O-ring" on the mating part of the motor, and check the "motor hub position" and then insert it. (Refer to the mounting diagram.)
3) Fix the motor and the "motor flange" with the motor mounting screws (provided by user).

Dimensions

[mm]

Size	Motor type	MM	TT	PD	PP
63	NZ	M3 x 12	1.5	14	17.7
	NY				
	NX	M4 x 12	3.6	9	6.7
	NW				11.7
	NV	M4 x 12	3.6	9	6.7
	NU	M4 x 12	3.6	11	11.7
	NT	M3 x 12	1.5	12	17.7

Included Parts List

Size: 63

Description	Quantity
	Motor type
	NZ, NY, NX, NW, NV, NU, NT
Motor hub	1
Hexagon socket head cap screw (for hub fixing)	1
O-ring	1

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LEY Series
Motor Mounting Parts

Motor Flange Option

After purchasing the product, the motor can be changed to the motor types shown below by replacing with this option. (Except NM1)
Use the following part numbers to select a compatible motor flange option and place an order.

How to Order

LEY – MF 25 ☐ – NZ

❶ ❷ ❸

❶ Size

25	For LEY25/LEY25
32	For LEY32/LEY32
63	For LEY63

❷ Motor mounting position

P	Top/Parallel
PL∗	Top/Parallel (Lead L)
D	In-line

∗ Size 63 only

❸ Motor type

Symbol	Type	Symbol	Type
NZ	Mounting type Z	**NV**	Mounting type V
NY	Mounting type Y	**NU**	Mounting type U
NX	Mounting type X	**NT**	Mounting type T
NW	Mounting type W	**NM2**	Mounting type M2

∗ Refer to the "Compatible Motors."

Compatible Motors

Applicable motor model			Size/Motor type											
			25				32/63							
Manufacturer	Series	Type	NZ Mounting type Z	NY Mounting type Y	NX Mounting type X	NX2 Mounting type M2	NZ Mounting type Z	NY Mounting type Y	NX Mounting type X	NW Mounting type W	NV Mounting type V	NU Mounting type U	NT Mounting type T	NM2 Mounting type M2
Mitsubishi Electric Corporation	MELSERVO-JN	HF-KN	●	—	—	—	●	—	—	—	—	—	—	—
	MELSERVO-J3	HF-KP	●	—	—	—	●	—	—	—	—	—	—	—
	MELSERVO-J4	HG-KR	●	—	—	—	●	—	—	—	—	—	—	—
YASKAWA Electric Corporation	Σ-V	SGMJV	●	—	—	—	●	—	—	—	—	—	—	—
SANYO DENKI CO., LTD.	SANMOTION R	R2	●	—	—	—	●	—	—	—	—	—	—	—
OMRON Corporation	Sysmac G5	R88M-K	●	—	—	—	—	●	—	—	—	—	—	—
Panasonic Corporation	MINAS-A4	MSMD	—	●	—	—	—	●	—	—	—	—	—	—
	MINAS-A5	MSMD/MHMD	—	●	—	—	—	●	—	—	—	—	—	—
FANUC CORPORATION	βis	β	●	—	—	—	● (β1 only)	—	—	●	—	—	—	—
NIDEC SANKYO CORPORATION	S-FLAG	MA/MH/MM	●	—	—	—	●	—	—	—	—	—	—	—
KEYENCE CORPORATION	SV	SV-M/SV-B	●	—	—	—	●	—	—	—	—	—	—	—
FUJI ELECTRIC CO., LTD.	ALPHA5	GYS/GYB	●	—	—	—	●	—	—	—	—	—	—	—
	FALDIC-α	GYS	●	—	—	—	●	—	—	—	—	—	—	—
ORIENTAL MOTOR Co., Ltd.	AR/AZ	AR/AZ (46 only)	—	—	—	●	—	—	—	—	—	—	—	—
	AR/AZ	AR/AZ	—	—	—	—	—	—	—	—	—	—	—	●∗3
Rockwell Automation, Inc. (Allen-Bradley)	MP-/VP-	MP/VP	—	—	—	—	—	—	●∗1	—	—	—	—	—
	TL	TLY-A	●	—	—	—	—	—	—	—	—	—	●	—
Beckhoff Automation GmbH	AM	AM30	●	—	—	—	—	—	—	—	●∗1	—	—	—
	AM	AM31	●	—	—	—	—	—	—	—	—	●∗2	—	—
	AM	AM80/AM81	●	—	—	—	—	—	●∗1	—	—	—	—	—
Siemens AG	1FK7	1FK7	—	—	●	—	—	—	●∗1	—	—	—	—	—
Delta Electronics, Inc.	ASDA-A2	ECMA	●	—	—	—	●	—	—	—	—	—	—	—

Note) When the LEY☐$^{25}_{32}$☐NM1☐-☐ or LEY☐G$^{25}_{32}$☐☐NM1☐-☐ is purchased, it is not possible to change to other motor types.

∗1 Motor mounting position: In-line only
∗2 Only in-line type is available for size 63.
∗3 Except size 63

SMC
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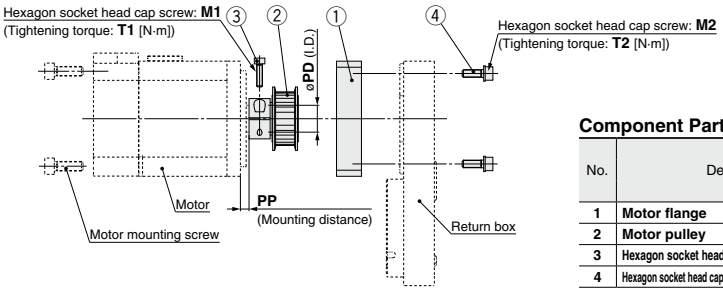
Dimensions: Motor Flange Option

Motor mounting position: Top/Parallel

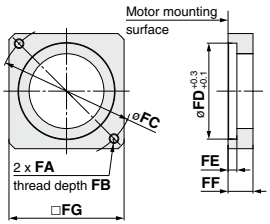


Component Parts

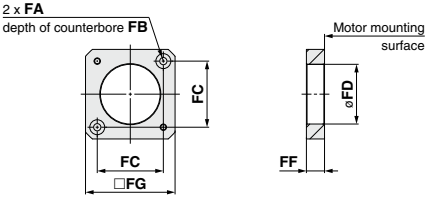
No.	Description	Quantity	
		Size	
		25, 32	63
1	**Motor flange**	1	1
2	**Motor pulley**	1	1
3	**Hexagon socket head cap screw (for pulley fixing)**	1	1
4	**Hexagon socket head cap screw (for motor flange mounting)**	2	4

Motor flange details

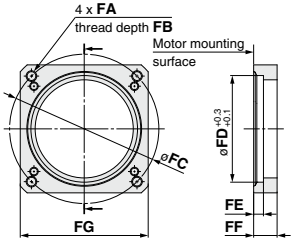
Size: 25, 32



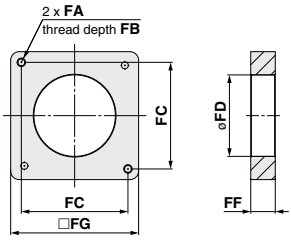
Size 25: NM2



Size: 63



Size 32: NM2



Dimensions

[mm]

Size	Motor type	FA	FB	FC	FD	FE	FF	FG	M1	T1	M2	T2	PD	PP
25	**NZ**	M4 x 0.7	7.5	46	30	3.7	11	42	M2.5 x 10	1.0	M3 x 8	0.63	8	7.5
	NY	M3 x 0.5	5.5	45	30	5	11	42	M2.5 x 10	1.0	M3 x 8	0.63	8	7.5
	NX	M4 x 0.7	7	46	30	3.7	11	42	M2.5 x 10	1.0	M3 x 8	0.63	8	4.5
	NM2	ø3.4	7	31	30	3.7	8.5	42	M2.5 x 10	1.0	M3 x 8	0.63	6	4.8
32	**NZ**	M5 x 0.8	8.5	70	50	4.6	13	60	M3 x 12	1.5	M4 x 12	1.5	14	4.5
	NY	M4 x 0.7	7	70	50	4.6	13	60	M3 x 12	1.5	M4 x 12	1.5	11	4.5
	NW	M5 x 0.8	8.5	70	50	4.6	13	60	M4 x 12	2.5	M4 x 12	1.5	9	4.5
	NU	M5 x 0.8	8.5	70	50	4.6	13	60	M3 x 12	1.5	M4 x 12	1.5	11	4.5
	NT	M5 x 0.8	8.5	70	50	4.6	17	60	M3 x 12	1.5	M4 x 12	1.5	12	8.5
	NM2	M4 x 0.7	8	50	38.2	—	11.5	60	M3 x 12	1.5	M4 x 12	2.7	10	12
63	**NZ**	M5 x 0.8	9	70	50	4.6	11	60	M4 x 12	3.6	M4 x 12	2.7	14	4.5
	NY	M4 x 0.7	8	70	50	4.6	11	60	M4 x 12	3.6	M4 x 12	2.7	14	4.5
	NW	M5 x 0.8	9	70	50	4.6	11	60	M4 x 12	3.6	M4 x 12	2.7	9	4.5
	NT	M5 x 0.8	9	70	50	4.6	14.5	60	M4 x 12	3.6	M4 x 12	2.7	12	8

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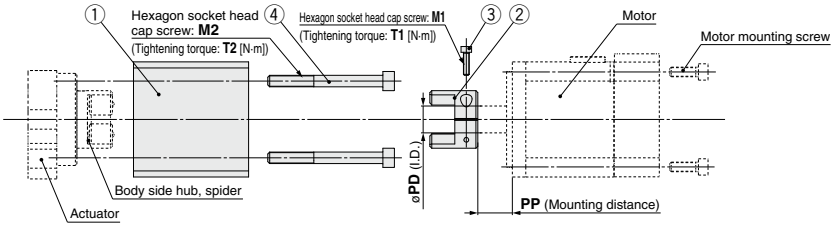
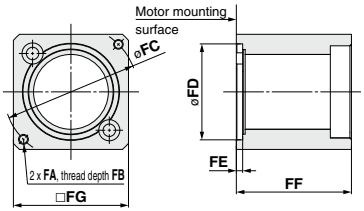
Dimensions: Motor Flange Option

Motor mounting position: In-line [Size: 25, 32]



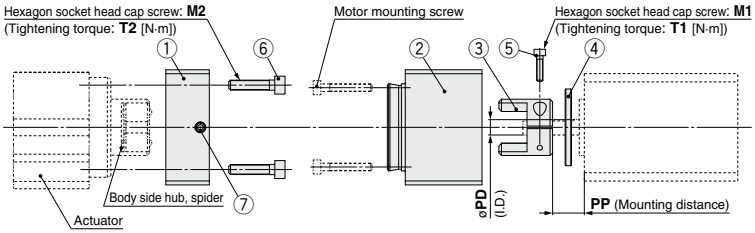
Motor flange details



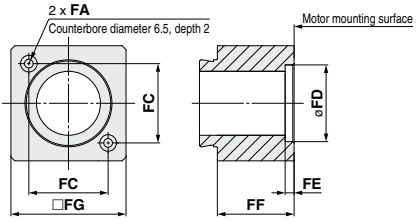
Component Parts

No.	Description	Quantity
1	**Motor flange**	1
2	**Motor hub**	1
3	**Hexagon socket head cap screw (for hub fixing)**	1
4	**Hexagon socket head cap screw (for motor block mounting)**	2

Motor type: NM2



Motor flange B details



Component Parts

No.	Description	Quantity
1	**Motor flange A**	1
2	**Motor flange B**	1
3	**Motor hub**	1
4	**Ring spacer**	1
5	**Hexagon socket head cap screw (for hub fixing)**	1
6	**Hexagon socket head cap screw (for motor flange A mounting)**	2
7	**Hexagon socket head set screw (for motor flange B fixing)**	2

Dimensions [mm]

Size	Motor type	FA	FB	FC	FD	FE	FF	FG	M1	T1	M2	T2	PD	PP
25	**NZ**	M4 x 0.7	7.5	46	30	3.7	47	45	M2.5 x 10	1.0	M4 x 40	1.5	8	12.5
	NY	M3 x 0.5	6	45	30	4.2	47	45	M2.5 x 10	1.0	M4 x 40	1.5	8	12.5
	NX	M4 x 0.7	7.5	46	30	3.7	47	45	M2.5 x 10	1.0	M4 x 40	1.5	8	7
	NM2	ø3.4	28	31	30	3.5	50	45	M2.5 x 10	1.0	M4 x 40	1.5	6	12.4
32	**NZ**	M5 x 0.8	8.5	70	50	3.3	60	60	M3 x 12	1.5	M6 x 60	5.2	14	18
	NY	M4 x 0.7	8	70	50	3.3	60	60	M4 x 12	3.6	M6 x 60	5.2	11	18
	NX	M5 x 0.8	8.5	63	40	3.5	63	60	M4 x 12	3.6	M6 x 60	5.2	9	5
	NW	M5 x 0.8	8.5	70	50	3.3	60	60	M4 x 12	3.6	M6 x 60	5.2	11	12
	NV	M4 x 0.7	8	63	40	3.3	63	60	M4 x 12	3.6	M6 x 60	5.2	9	5
	NU	M5 x 0.8	8.5	70	50	3.3	60	60	M4 x 12	3.6	M6 x 60	5.2	11	12
	NT	M5 x 0.8	8.5	70	50	3.3	60	60	M3 x 12	1.5	M6 x 60	5.2	12	18
	NM2	M4 x 0.7	8	50	36	3.3	60	60	M4 x 12	3.6	M6 x 60	5.2	10	3

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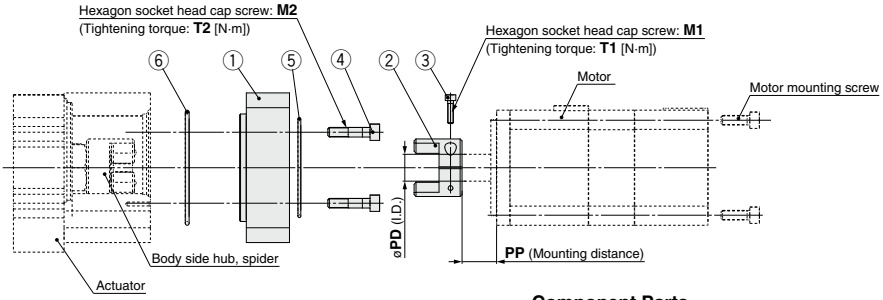
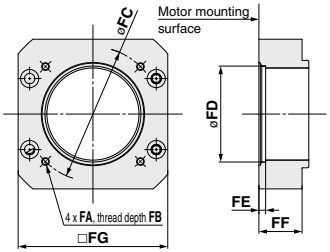
Dimensions: Motor Flange Option

Motor mounting position: In-line [Size: 63]



Motor flange details



Component Parts

No.	Description	Quantity
1	**Motor flange**	1
2	**Motor hub**	1
3	**Hexagon socket head cap screw (for hub fixing)**	1
4	**Hexagon socket head cap screw (for motor adapter mounting)**	4
5	**O-ring (Wire diameter ø1.5)**	1
6	**O-ring (Wire diameter ø2.0)**	1

Dimensions [mm]

Size	Motor type	FA	FB	FC	FD	FE	FF	FG	M1	T1	M2	T2	PD	PP
63	**NZ**	M5 x 0.8	10	70	50	3.5	22.5	78	M3 x 12	1.5	M5 x 22	3	14	17.7
	NY	M4 x 0.7	8	70	50	3.5	22.5	78	M3 x 12	3.6	M5 x 22	3	14	17.7
	NX	M5 x 0.8	10	63	40	3.5	27.5	78	M4 x 12	3.6	M5 x 22	3	9	6.7
	NW	M5 x 0.8	10	70	50	3.5	22.5	78	M4 x 12	3.6	M5 x 22	3	9	11.7
	NV	M4 x 0.7	8	63	40	3.5	27.5	78	M4 x 12	3.6	M5 x 22	3	9	6.7
	NU	M5 x 0.8	10	70	50	3.5	22.5	78	M4 x 12	3.6	M5 x 22	3	11	11.7
	NT	M5 x 0.8	10	70	50	3.5	22.5	78	M3 x 12	1.5	M5 x 22	3	12	17.7

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Solid State Auto Switch
Direct Mounting Type
D-M9N(V)/D-M9P(V)/D-M9B(V)

RoHS

Refer to SMC website for the details of the products conforming to the international standards.

Grommet

- **2-wire load current is reduced (2.5 to 40 mA).**
- **Using flexible cable as standard spec.**

Auto Switch Specifications

PLC: Programmable Logic Controller

D-M9□, D-M9□V (With indicator light)						
Auto switch model	D-M9N	D-M9NV	D-M9P	D-M9PV	D-M9B	D-M9BV
Electrical entry direction	In-line	Perpendicular	In-line	Perpendicular	In-line	Perpendicular
Wiring type	3-wire				2-wire	
Output type	NPN		PNP		—	
Applicable load	IC circuit, Relay, PLC				24 VDC relay, PLC	
Power supply voltage	5, 12, 24 VDC (4.5 to 28 V)				—	
Current consumption	10 mA or less				—	
Load voltage	28 VDC or less		—		24 VDC (10 to 28 VDC)	
Load current	40 mA or less				2.5 to 40 mA	
Internal voltage drop	0.8 V or less at 10 mA (2 V or less at 40 mA)				4 V or less	
Leakage current	100 μA or less at 24 VDC				0.8 mA or less	
Indicator light	Red LED illuminates when turned ON.					
Standard	CE marking, RoHS					

Oilproof Heavy-duty Lead Wire Specifications

Auto switch model		D-M9N(V)	D-M9P(V)	D-M9B(V)
Sheath	Outside diameter [mm]	2.6		
Insulator	Number of cores	3 cores (Brown/Blue/Black)		2 cores (Brown/Blue)
	Outside diameter [mm]	0.88		
Conductor	Effective area [mm²]	0.15		
	Strand diameter [mm]	0.05		
Minimum bending radius [mm] (Reference values)		17		

Note 1) Refer to Best Pneumatics No. 2-1 for solid state auto switch common specifications.
Note 2) Refer to Best Pneumatics No. 2-1 for lead wire lengths.

⚠Caution

Precautions

Fix the auto switch with the existing screw installed on the auto switch body. The auto switch may be damaged if a screw other than the one supplied is used.

Weight

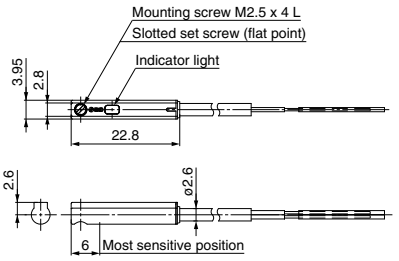
(g)

Auto switch model		D-M9N(V)	D-M9P(V)	D-M9B(V)
Lead wire length	0.5 m (**Nil**)	8		7
	1 m (**M**)	14		13
	3 m (**L**)	41		38
	5 m (**Z**)	68		63

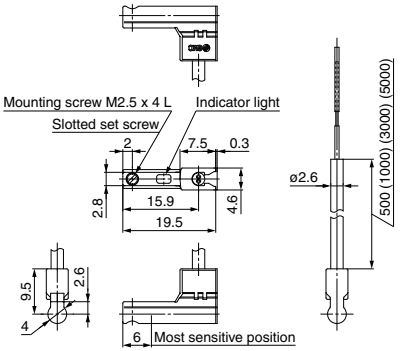
Dimensions

(mm)

D-M9□



D-M9□V



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2-Color Indicator Solid State Auto Switch Direct Mounting Type
D-M9NW(V)/D-M9PW(V)/D-M9BW(V)

RoHS

Refer to SMC website for the details of the products conforming to the international standards.

Grommet

- **2-wire load current is reduced (2.5 to 40 mA).**
- **Using flexible cable as standard spec.**
- **The proper operating range can be determined by the color of the light. (Red → Green ← Red)**

⚠Caution

Precautions

Fix the auto switch with the existing screw installed on the auto switch body. The auto switch may be damaged if a screw other than the one supplied is used.

Auto Switch Specifications

PLC: Programmable Logic Controller

D-M9□W, D-M9□WV (With indicator light)						
Auto switch model	D-M9NW	D-M9NWV	D-M9PW	D-M9PWV	D-M9BW	D-M9BWV
Electrical entry direction	In-line	Perpendicular	In-line	Perpendicular	In-line	Perpendicular
Wiring type	3-wire				2-wire	
Output type	NPN		PNP		—	
Applicable load	IC circuit, Relay, PLC				24 VDC relay, PLC	
Power supply voltage	5, 12, 24 VDC (4.5 to 28 V)				—	
Current consumption	10 mA or less				—	
Load voltage	28 VDC or less		—		24 VDC (10 to 28 VDC)	
Load current	40 mA or less				2.5 to 40 mA	
Internal voltage drop	0.8 V or less at 10 mA (2 V or less at 40 mA)				4 V or less	
Leakage current	100 μA or less at 24 VDC				0.8 mA or less	
Indicator light	Operating range ····· Red LED illuminates. Proper operating range ····· Green LED illuminates.					
Standard	CE marking, RoHS					

Oilproof Flexible Heavy-duty Lead Wire Specifications

Auto switch model		D-M9NW(V)	D-M9PW(V)	D-M9BW(V)
Sheath	Outside diameter [mm]	2.6		
Insulator	Number of cores	3 cores (Brown/Blue/Black)		2 cores (Brown/Blue)
	Outside diameter [mm]	0.88		
Conductor	Effective area [mm²]	0.15		
	Strand diameter [mm]	0.05		
Minimum bending radius [mm] (Reference values)		17		

Note 1) Refer to Best Pneumatics No. 2-1 for solid state auto switch common specifications.
Note 2) Refer to Best Pneumatics No. 2-1 for lead wire lengths.

Weight

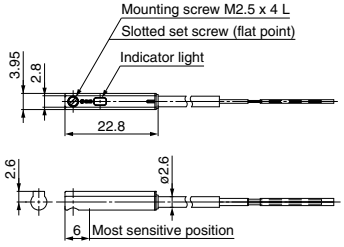
(g)

Auto switch model		D-M9NW(V)	D-M9PW(V)	D-M9BW(V)
Lead wire length	0.5 m (**Nil**)	8		7
	1 m (**M**)	14		13
	3 m (**L**)	41		38
	5 m (**Z**)	68		63

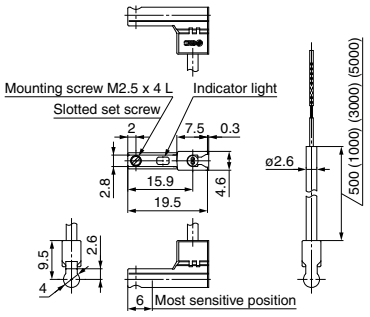
Dimensions

(mm)

D-M9□W



D-M9□WV



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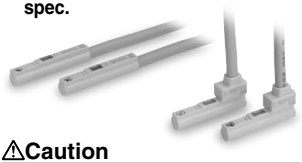
Water Resistant 2-Color Indicator
Solid State Auto Switch: Direct Mounting Type
D-M9NA(V)/D-M9PA(V)/D-M9BA(V)

CE RoHS

Grommet

- **Water (coolant) resistant type**
- **2-wire load current is reduced (2.5 to 40 mA).**
- **The proper operating range can be determined by the color of the light. (Red → Green ← Red)**
- **Using flexible cable as standard spec.**



⚠Caution

Precautions

Fix the auto switch with the existing screw installed on the auto switch body. The auto switch may be damaged if a screw other than the one supplied is used.
Please consult with SMC if using coolant liquid other than water based solution.

Weight

(g)

Auto switch model		D-M9NA(V)	D-M9PA(V)	D-M9BA(V)
Lead wire length	0.5 m (**Nil**)	8	8	7
	1 m (**M**)	14	13	13
	3 m (**L**)	41	38	38
	5 m (**Z**)	68	63	63

Auto Switch Specifications

PLC: Programmable Logic Controller

D-M9□A, D-M9□AV (With indicator light)						
Auto switch model	**D-M9NA**	**D-M9NAV**	**D-M9PA**	**D-M9PAV**	**D-M9BA**	**D-M9BAV**
Electrical entry direction	In-line	Perpendicular	In-line	Perpendicular	In-line	Perpendicular
Wiring type	3-wire				2-wire	
Output type	NPN		PNP		—	
Applicable load	IC circuit, Relay, PLC				24 VDC relay, PLC	
Power supply voltage	5, 12, 24 VDC (4.5 to 28 V)				—	
Current consumption	10 mA or less				—	
Load voltage	28 VDC or less		—		24 VDC (10 to 28 VDC)	
Load current	40 mA or less				2.5 to 40 mA	
Internal voltage drop	0.8 V or less at 10 mA (2 V or less at 40 mA)				4 V or less	
Leakage current	100 μA or less at 24 VDC				0.8 mA or less	
Indicator light	Operating range ..... Red LED illuminates. Proper operating range ..... Green LED illuminates.					
Standard	CE marking, RoHS					

Oilproof Flexible Heavy-duty Lead Wire Specifications

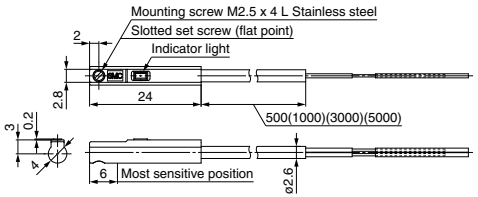
Auto switch model		D-M9NA□	D-M9NAV□	D-M9PA□	D-M9PAV□	D-M9BA□	D-M9BAV□
Sheath	Outside diameter [mm]	2.6			2.7 x 3.2 (ellipse)	2.6	
Insulator	Number of cores	3 cores (Brown/Blue/Black)				2 cores (Brown/Blue)	
	Outside diameter [mm]	0.88			0.9	0.88	
Conductor	Effective area [mm²]	0.15					
	Strand diameter [mm]	0.05					
Minimum bending radius [mm] (Reference values)		17			20	17	

Note 1) Refer to Best Pneumatics No. 2-1 for solid state auto switch common specifications.
Note 2) Refer to Best Pneumatics No. 2-1 for lead wire lengths.

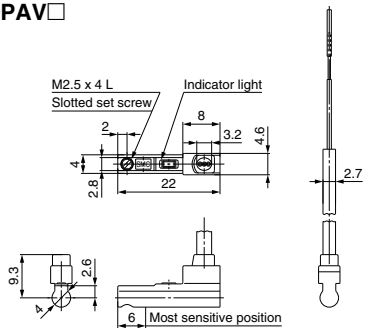
Dimensions

(mm)

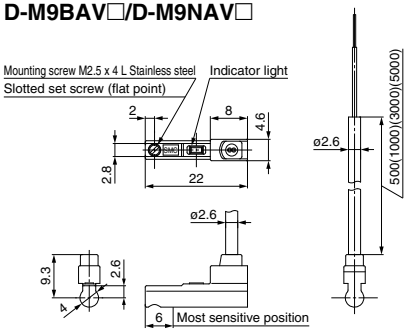
D-M9□A



D-M9PAV□



D-M9BAV□/D-M9NAV□



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LEY/LEYG Series
Electric Actuators
Specific Product Precautions 1

Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions and pages 3 to 8 for Electric Actuator Precautions.

Design / Selection

⚠Warning

1. Do not apply a load in excess of the specification limits.

Select a suitable actuator by work load and allowable lateral load on the rod end. If the product is used outside of the specification limits, the eccentric load applied to the piston rod will be excessive and have adverse effects such as creating play on the sliding parts of the piston rod, degrading accuracy and shortening the life of the product.

2. Do not use the product in applications where excessive external force or impact force is applied to it.

This can cause a failure.

3. When used as a stopper, select the LEYG series "Sliding bearing" for a stroke of 30 mm or less.

4. When used as a stopper, fix the main body with a guide attachment ("Top mounting" or "Bottom mounting").

If the end of the actuator is used to fix the main body (end mounting), the excessive load acts on the actuator, which adversely affects the operation and life of the product.

Handling

⚠Caution

1. When using the pushing operation, be sure to set to force/speed control, and use within the specified pushing speed range for each series.

Do not allow the piston rod to hit the workpiece and end of the stroke in the position control. The lead screw, bearing and internal stopper may be damaged and lead to malfunction.

2. For pushing operation, the maximum torque value of the motor to be used should be set to 90% or less of the rated torque of the reference motor. For the LEY63, 150% or less.

It may lead to damage and malfunction.

3. The maximum speed of this actuator is affected by the product stroke.

Check the model selection section of the catalog.

4. Do not apply a load, impact or resistance in addition to the transferred load during return to origin.

Additional force will cause the displacement of the origin position.

5. Do not scratch or dent the sliding parts of the piston rod, by striking or attaching objects.

The piston rod and guide rod are manufactured to precise tolerances, even a slight deformation may cause a malfunction.

6. When an external guide is used, connect it in such a way that no impact or load is applied to it.

Use a freely moving connector (such as a floating joint).

7. Do not operate by fixing the piston rod and moving the actuator body.

Excessive load will be applied to the piston rod, leading to damage to the actuator and reduced the life of the product.

Handling

⚠Caution

8. When an actuator is operated with one end fixed and the other free (ends tapped or flange type), a bending moment may act on the actuator due to vibration generated at the stroke end, which can damage the actuator. In such a case, install a mounting bracket to suppress the vibration of the actuator body or reduce the speed so that the actuator does not vibrate at the stroke end.

Also, use a mounting bracket when moving the actuator body or when a long stroke actuator is mounted horizontally and fixed at one end.

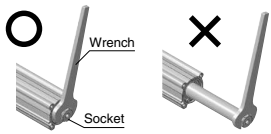
9. Avoid using the electric actuator in such a way that rotational torque would be applied to the piston rod.

This may cause deformation of the non-rotating guide, abnormal responses of the auto switch, play in the internal guide or an increase in the sliding resistance.

Refer to the table below for the approximate values of the allowable range of rotational torque.

Allowable rotational torque [N·m] or less	LEY25□	LEY32	LEY63
	1.1	1.4	2.8

When screwing in a bracket or nut to the piston rod end, hold the flats of the end of the "socket" with a wrench (the piston rod should be fully retracted). Do not apply tightening torque to the non-rotating mechanism.



10. When using auto switch with the guide rod type LEYG series, the following limits will be in effect. Select the product while paying attention to this.

- Insert the auto switch from the front side with rod (plate) sticking out.
- The auto switches with perpendicular electrical entry cannot be used.
- For the parts hidden behind the guide attachment (Rod stick out side), the auto switch cannot be fixed.
- Please consult with SMC when using auto switch on the rod stick out side.

Enclosure

IP – □□

First characteristic numeral ● ●**Second characteristic numeral**

● **First Characteristics: Degrees of protection against solid foreign objects**

0	Non-protected
1	Protected against solid foreign objects of 50 mmø and greater
2	Protected against solid foreign objects of 12 mmø and greater
3	Protected against solid foreign objects of 2.5 mmø and greater
4	Protected against solid foreign objects of 1.0 mmø and greater
5	Dust-protected
6	Dust-tight

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LEY/LEYG Series
Electric Actuators
Specific Product Precautions 2

Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions and pages 3 to 8 for Electric Actuator Precautions.

Enclosure

● **Second Characteristics: Degrees of protection against water**

0	Non-protected	—
1	Protected against vertically falling water drops	Dripproof type 1
2	Protected against vertically falling water drops when enclosure tilted up to 15°	Dripproof type 2
3	Protected against rainfall when enclosure tilted up to 60°	Rainproof type
4	Protected against splashing water	Splashproof type
5	Protected against water jets	Water-jet-proof type
6	Protected against powerful water jets	Powerful water-jet-proof type
7	Protected against the effects of temporary immersion in water	Immersible type
8	Protected against the effects of continuous immersion in water	Submersible type

Example) IP65: Dust-tight, Water-jet-proof type
"Water-jet-proof type" means that no water intrudes inside an equipment that could hinder from operating normally by means of applying water for 3 minutes in the prescribed manner. Take appropriate protection measures, since a device is not usable in an environment where a droplet of water is splashed constantly.

Mounting

⚠Caution

1. When mounting workpieces or jigs to the piston rod end "socket," hold the flats of the "socket" with a wrench so that the piston rod does not rotate. The bolt should be tightened within the specified torque range.

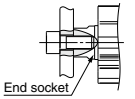
This may cause abnormal responses of the auto switch, play in the internal guide or an increase in the sliding resistance.

2. When mounting the product and/or a workpiece, tighten the mounting screws within the specified torque range.

Tightening the screws with a higher torque than recommended may cause a malfunction, whilst the tightening with a lower torque can cause the displacement of the mounting position or in extreme conditions the actuator could become detached from its mounting position.

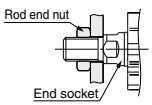
<LEY Series>

Workpiece fixed/Rod end female thread

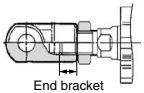


Model	Screw size	Max. tightening torque [N·m]	Max. screw-in depth [mm]	End socket width across flats [mm]
LEY25	M8 x 1.25	12.5	13	17
LEY32	M8 x 1.25	12.5	13	22
LEY63	M16 x 2	106	21	36

Workpiece fixed/Rod end male thread (When "Rod end male thread" is selected.)



Model	Thread size	Max. tightening torque [N·m]	Effective thread length [mm]	End socket width across flats [mm]
LEY25	M14 x 1.5	65.0	20.5	17
LEY32	M14 x 1.5	65.0	20.5	22
LEY63	M18 x 1.5	97.0	26	36



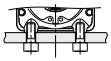
Model	Rod end nut		End bracket
	Width across flats [mm]	Length [mm]	screw-in depth [mm]
LEY25	22	8	8 or more
LEY32	22	8	8 or more
LEY63	27	11	11 or more

∗ Rod end nut is an accessory.

Mounting

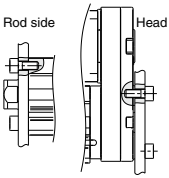
⚠Caution

Body fixed/Body bottom tapped type (When "Body bottom tapped" is selected.)



Model	Screw size	Max. tightening torque [N·m]	Max. screw-in depth [mm]
LEY25	M5 x 0.8	3.0	6.5
LEY32	M6 x 1.0	5.2	8.8
LEY63	M8 x 1.25	12.5	10

Body fixed/Rod side/Head side tapped type

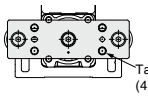


∗ Except the LEY□D

Model	Screw size	Max. tightening torque [N·m]	Max. screw-in depth [mm]
LEY25	M5 x 0.8	3.0	8
LEY32	M6 x 1.0	5.2	10
LEY63	M8 x 1.25	12.5	14

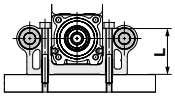
<LEYG Series>

Workpiece fixed/Plate tapped type



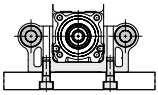
Model	Screw size	Max. tightening torque [N·m]	Max. screw-in depth [mm]
LEYG25$^{M}_{L}$	M6 x 1.0	5.2	11
LEYG32$^{M}_{L}$	M6 x 1.0	5.2	12

Body fixed/Top mounting



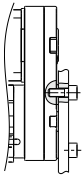
Model	Screw size	Max. tightening torque [N·m]	Length: L [mm]
LEYG25$^{M}_{L}$	M5 x 0.8	3.0	40.5
LEYG32$^{M}_{L}$	M5 x 0.8	3.0	50.5

Body fixed/Bottom mounting



Model	Screw size	Max. tightening torque [N·m]	Max. screw-in depth [mm]
LEYG25$^{M}_{L}$	M6 x 1.0	5.2	12
LEYG32$^{M}_{L}$	M6 x 1.0	5.2	12

Body fixed/Head side tapped type



Model	Screw size	Max. tightening torque [N·m]	Max. screw-in depth [mm]
LEYG25$^{M}_{L}$	M5 x 0.8	3.0	8
LEYG32$^{M}_{L}$	M6 x 1.0	5.2	10

SMC
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Electric Actuators Specific Product Precautions 3

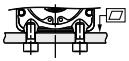
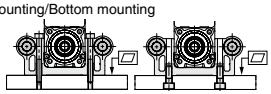
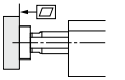
Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions and pages 3 to 8 for Electric Actuator Precautions.

Mounting

⚠Caution

3. Keep the flatness of the mounting surface within the following ranges when mounting the actuator body and workpiece.

Unevenness of a workpiece or base mounted on the body of the product may cause an increase in the sliding resistance.

Model	Mounting position	Flatness
LEY□	Body/Body bottom 	0.1 mm or less
LEYG□	Top mounting/Bottom mounting 	0.05 mm or less
	Workpiece/Plate mounting 	0.05 mm or less

Maintenance

⚠Warning

1. Ensure that the power supply is stopped and the workpiece is removed before starting maintenance work or replacement of the product.

- **Maintenance frequency**

Perform maintenance according to the table below.

Frequency	Appearance check	Belt check
Inspection before daily operation	○	—
Inspection every 6 months/ 250 km/5 million cycles*	○	○

* Select whichever comes first.

- **Items for visual appearance check**

1. Loose set screws, Abnormal dirt
2. Check of flaw and cable joint
3. Vibration, Noise

- **Items for belt check**

Stop operation immediately and replace the belt when belt appear to be below. Further, ensure your operating environment and conditions satisfy the requirements specified for the product.

a. Tooth shape canvas is worn out.
Canvas fiber becomes fuzzy. Rubber is removed and the fiber becomes whitish. Lines of fibers become unclear.

b. Peeling off or wearing of the side of the belt
Belt corner becomes round and frayed thread sticks out.

c. Belt partially cut
Belt is partially cut. Foreign objects caught in teeth other than cut part causes flaw.

d. Vertical line of belt teeth
Flaw which is made when the belt runs on the flange.

e. Rubber back of the belt is softened and sticky.

f. Crack on the back of the belt

2. For IP65 equivalent type, apply grease on the piston rod periodically. Grease should be applied at 1 million cycles or 200 km, whichever comes first.

· Grease pack order number: GR-S-010 (10 g)/GR-S-020 (20 g)

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